

E9 205 – Machine Learning for Signal Processing

Homework # 3

Due date: May. 16, 2021

Analytical in writing and report scanned and submitted.

Source code also need to be included.

Name of file should be “Assignment3.FullName.pdf” submitted to teams channel.

Assignment should be solved individually without consent.

May 3, 2021

1. **Kernel LDA** Deepak has learnt about linear discriminant analysis in his course. In a job interview, he is asked to find a way to perform dimensionality reduction in non-linear space. Specifically, he is given a set of N data points $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N\}$ and a non-linear transformation $\phi(\mathbf{x})$ of the data. When he is asked is to define LDA in the non-linear space, he defines the within-class and between-class scatter matrices for a two-class problem as,

$$\begin{aligned} \mathbf{S}_B &= (\mathbf{m}_2^\phi - \mathbf{m}_1^\phi)(\mathbf{m}_2^\phi - \mathbf{m}_1^\phi)^T \\ \mathbf{S}_W &= \sum_{k=1}^2 \sum_{n \in C_k} [\phi(\mathbf{x}_n) - \mathbf{m}_k^\phi][\phi(\mathbf{x}_n) - \mathbf{m}_k^\phi]^T \end{aligned}$$

where $\mathbf{m}_k^\phi = \frac{1}{N_k} \sum_{n \in C_k} \phi(\mathbf{x}_n)$ for $k = 1, 2$ and C_k denotes the set of data points belonging to class k . He also defines the Fisher discriminant as

$$J = \frac{\mathbf{w}^T \mathbf{S}_B \mathbf{w}}{\mathbf{w}^T \mathbf{S}_W \mathbf{w}}$$

where \mathbf{w} denotes the projection vector. He goes on to say that he can solve the generalized eigen value problem to find \mathbf{w} which maximizes the Fisher discriminant. At this point, the interviewer suggests that $\phi(\mathbf{x})$ can be infinite dimensional and therefore LDA suggested by Deepak cannot be performed. Deepak counters by saying that he could solve for the LDA using kernel function $k(\mathbf{x}_i, \mathbf{x}_j) = \phi(\mathbf{x}_i)^T \phi(\mathbf{x}_j)$. He goes on and shows that LDA can indeed be formulated in a kernel space and the projection of a new data point can be done using kernels (without computing $\phi(\mathbf{x})$). How would you have found these two solutions if you were Deepak ? (Points 20)

2. By definition, a kernel function $k(\mathbf{x}, \hat{\mathbf{x}}) = \phi(\mathbf{x})^T \phi(\hat{\mathbf{x}})$. A necessary and sufficient condition for defining a kernel function is that the Gram matrix \mathbf{K} is positive definite. Using

either of these definitions, prove the following kernel rules

$$\begin{aligned}
 k(\mathbf{x}, \hat{\mathbf{x}}) &= ck_1(\mathbf{x}, \hat{\mathbf{x}}) \\
 k(\mathbf{x}, \hat{\mathbf{x}}) &= f(\mathbf{x})k_1(\mathbf{x}, \hat{\mathbf{x}})f(\hat{\mathbf{x}}) \\
 k(\mathbf{x}, \hat{\mathbf{x}}) &= \mathbf{x}^T \mathbf{A} \hat{\mathbf{x}} \\
 k(\mathbf{x}, \hat{\mathbf{x}}) &= k_1(\mathbf{x}, \hat{\mathbf{x}}) + k_2(\mathbf{x}, \hat{\mathbf{x}}) \\
 k(\mathbf{x}, \hat{\mathbf{x}}) &= k_1(\mathbf{x}, \hat{\mathbf{x}})k_2(\mathbf{x}, \hat{\mathbf{x}})
 \end{aligned}$$

where k_1, k_2 denote valid kernel functions, $c > 0$ is any scalar, $f(\mathbf{x})$ is any scalar function and \mathbf{A} is symmetric positive definite matrix.

(Points 10)

3. **One-class SVM** Let $\mathbf{X} = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_l\}$ be dataset defined in \mathbb{R}^n . An unsupervised outlier detection method consist of finding a center \mathbf{a} and radius R of the smallest sphere enclosing the dataset in the high dimensional non-linear feature space $\phi(\mathbf{x})$. In a soft margin setting, non-negative slack variables ζ_j (for $j = 1, \dots, l$) can be introduced such that, $\|\phi(\mathbf{x}_j) - \mathbf{a}\|^2 \leq R^2 + \zeta_j$

The objective function in this case is to minimize radius of the sphere with a weighted penalty for slack variables, i.e., $R^2 + C \sum_{j=1}^l \zeta_j$ where C is a penalty term for allowing a trade-off between training errors (distance of points outside the sphere) and the radius of the smallest sphere.

- Give the primal form Lagrangian and the primal constraints for the one-class SVM. (Points 5)
- Find the dual form in terms of kernel function and the KKT constraints for the one-class SVM. What are the support vectors ? Will support vectors change when $C > 1$ is chosen ? Give a numerically stable estimate of R (Points 15)
- For a new data point \mathbf{x} , how will we identify whether it is an outlier or not (using kernel functions) ? (Points 5)

4. Use the following data source for the remaining two questions

leap.ee.iisc.ac.in/sriram/teaching/MLSP21/assignments/data/Data.tar.gz

Implementing Linear SVMs - 15 subject faces with happy/sad emotion are provided in the data. Each image is of 100×100 matrix. Perform PCA to reduce the dimension from 10000 to K . Implement a classifier on the training images with linear kernel based support vector machine. One potential source of SVM implementation is the LIBSVM package

<http://www.csie.ntu.edu.tw/~cjlin/libsvm/>

- Use the SVM to classify the test images. How does the performance change for various choice of kernels, parameter C and ϵ . How does the performance change as a function of K .
- Compare the SVM classifier with LDA classifier and comment on the similarity and differences in terms of the problem formulation as well as the performance.

(Points 15)

5. **Supervised Sentiment Analysis** - Download the movie review data (each line is a individual review)

[http : //www.leap.ee.iisc.ac.in/sriram/teaching/MLSP21/assignments/movieReviews1000.txt](http://www.leap.ee.iisc.ac.in/sriram/teaching/MLSP21/assignments/movieReviews1000.txt)

- a Split the data into two subsets. One for training (first 3000 reviews) and the other for testing (last 1000 reviews).
- b Use TF-IDF features and train PCA (using the training data) to reduce the data to 10 dimensions.
- c Train a SVM model. And check the performance on the test set in terms of review classification accuracy.
- d Compare different kernel choices - linear, polynomial and radial basis function. Report the number of support vectors used and the classification performance for different kernel choices.

(Points 30)