

CLASS 1 NOTES - THE RASPBERRY PI 2 (RaPi)

INTRODUCTION

The Linux Distribution

In the interest of time, the Raspberry Pi 2 Model B has been pre-configured with a working copy of Raspian-Wheezy (the operating system based on Linux Debian) and the OpenCV and a custom Python environments are already installed. Installing the OS and OpenCV from scratch would take far longer than the time available for the first class, and would detract from the main thrust of the class, to provide an environment for sensing on the Arduino and Raspberry Pi.

Accessing the RaPi2

There are three common ways to work with the RaPi2:

1. Using a keyboard, mouse (touchpad) and monitor (HDMI) - note there are HDMI->VGA adaptors available.
2. Connecting to an external computer (PC or laptop) via an ethernet cable
3. Connecting to an external computer via WiFi

Each of these have their advantages and disadvantages.

What we Did to get a Raspberry Pi 2 Boot Disk

The procedure we followed to create your boot disk with OpenCV is the following:

1. We created a Raspbian boot disk from the disk image 2015-05-05-raspbian-wheezy.img (See Appendix A1)
2. We followed the procedure in the link below to install OpenCV

<http://www.pyimagesearch.com/2015/02/23/install-opencv-and-python-on-your-raspberry-pi-2-and-b/>

Note that for this class it is not necessary for the students to carry out this procedure, since we have done the heavy lifting prior to the class, and carrying out these steps takes many many hour. The first time it took one of us a couple of days to get this right.

Creating a Backup Boot Disk for the Raspberry Pi 2

We recommend that you purchase a spare micro-SD card (8 GB) and create a backup boot disk (see Appendix A2). The procedure for creating this disk with the requisite boot image is described in Appendix A1.

Booting up the Raspberry Pi 2 for First Time (Direct Connection)

Do the following:

1. Make sure there is a micro-SD boot disk with Raspbian installed, mounted in the micro-SD slot
2. Connect a mouse and a keyboard to the Raspberry Pi 2
3. Connect a suitable HDMI monitor (or a TV)
4. Plug in power; you should see the unit boot up; it will boot into the user space.

Communicating with the RaPi from Laptop

If you know the IP address of the RaPi by one of the following means:

1. You have given it a static IP address as described in Appendix A3
2. It is configured for DHCP and you are on a network and you have determined it's IP address by some other means.

then it is possible to access directly as described in Appendix A4.

Mounting the Camera

This should be done with the unit powered down.

Username and Password

Username: pi

Password: r2

Remember Pythagoras

TESTING THE CAMERA

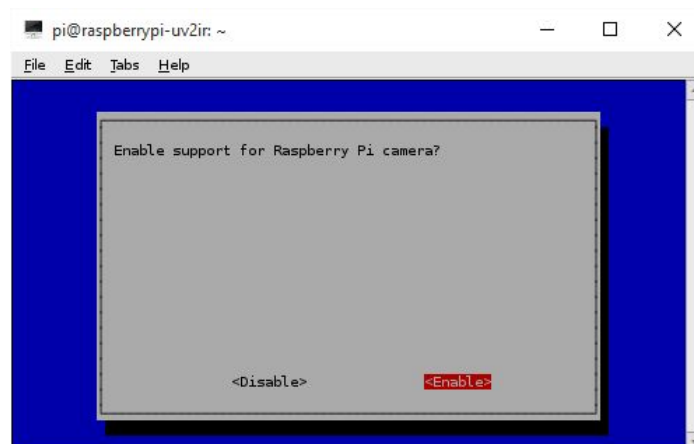
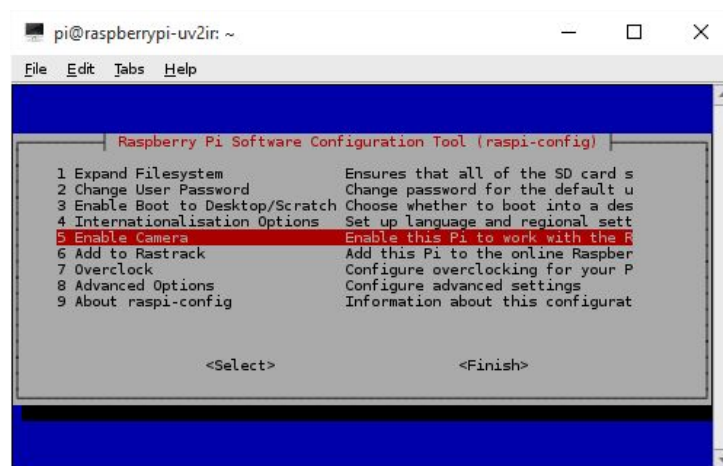
Hooking up the Camera

Follow these instructions:

<https://www.raspberrypi.org/documentation/usage/camera/README.md>

Make sure the camera is Activated

Type ***sudo raspi-config*** in a terminal and make sure the camera is enabled. This should only have to be set once, and you will have to reboot after carrying out the initialization.



A Simple Camera Test

First change the directory to the Desktop:

```
cd Desktop
```

then type the following:

```
raspistill -o tst-cam.jpg
```

After a few seconds, a file named **tst-cam.jpg** will appear on the desktop. Right click on the file and click **Open** to display.



WORKING WITH PYTHON

Setting Up & Testing

- Open a terminal
- Type the following:

```
source ~/.profile  
workon cv
```

You should see the prompt change with **(cv)** being placed at the beginning of the prompt. This indicates that we are in the virtual python environment (it is possible to run multiple versions for python in this way).

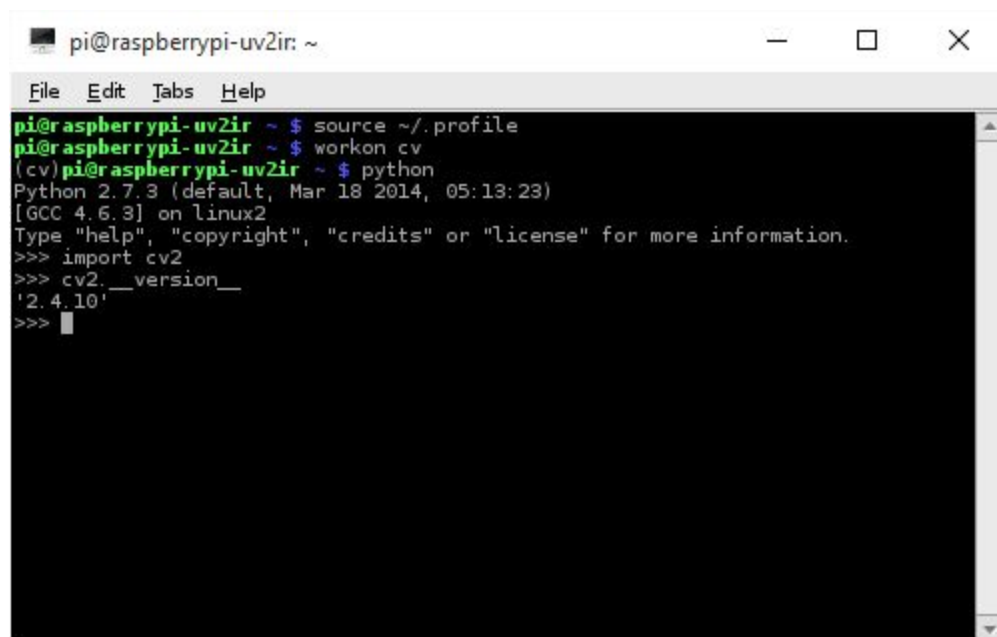
Type

```
python
```

to enter the python environment (prompt changes to **>>>**) and type the following two lines:

```
import cv2  
cv2.__version__
```

The OpenCV version number should be returned.



```
pi@raspberrypi-uv2ir: ~  
File Edit Tabs Help  
pi@raspberrypi-uv2ir ~ $ source ~/.profile  
pi@raspberrypi-uv2ir ~ $ workon cv  
(cv)pi@raspberrypi-uv2ir ~ $ python  
Python 2.7.3 (default, Mar 18 2014, 05:13:23)  
[GCC 4.6.3] on linux2  
Type "help", "copyright", "credits" or "license" for more information.  
>>> import cv2  
>>> cv2.__version__  
'2.4.10'  
>>>
```

Test the Camera with Python

open a terminal and type the following:

```
source ~/.profile  
workon cv  
cd python-dev/  
python test-image.py
```

Within a few seconds an image should appear on the screen.

The python program test-image.py is shown in the box below.

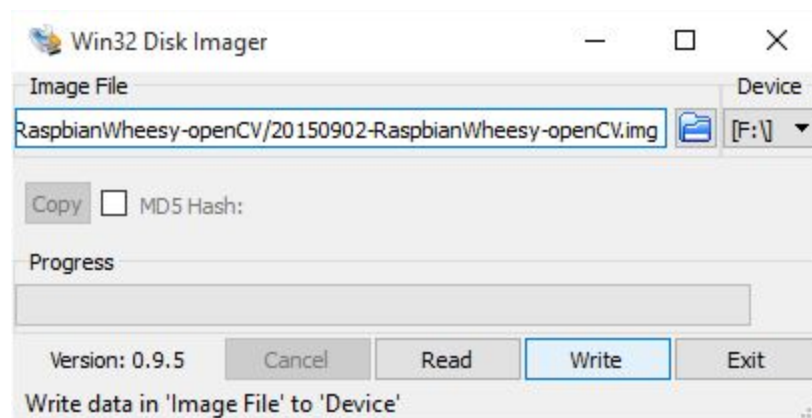
```
import the necessary packages  
from picamera.array import PiRGBArray  
from picamera import PiCamera  
import time  
import cv2  
  
# initialize the camera and grab a reference to the raw camera capture  
camera = PiCamera()  
rawCapture = PiRGBArray(camera)  
  
# allow the camera to warmup  
time.sleep(0.1)  
  
# grab an image from the camera  
camera.capture(rawCapture, format="bgr")  
image = rawCapture.array  
  
# display the image on screen and wait for a keypress  
cv2.imshow("Image", image)  
cv2.waitKey(0)
```

APPENDIX A: RASPBERRY PI

A1: Creating a Raspberry Pi 2 Boot Disk from and img File

Carry out the following steps:

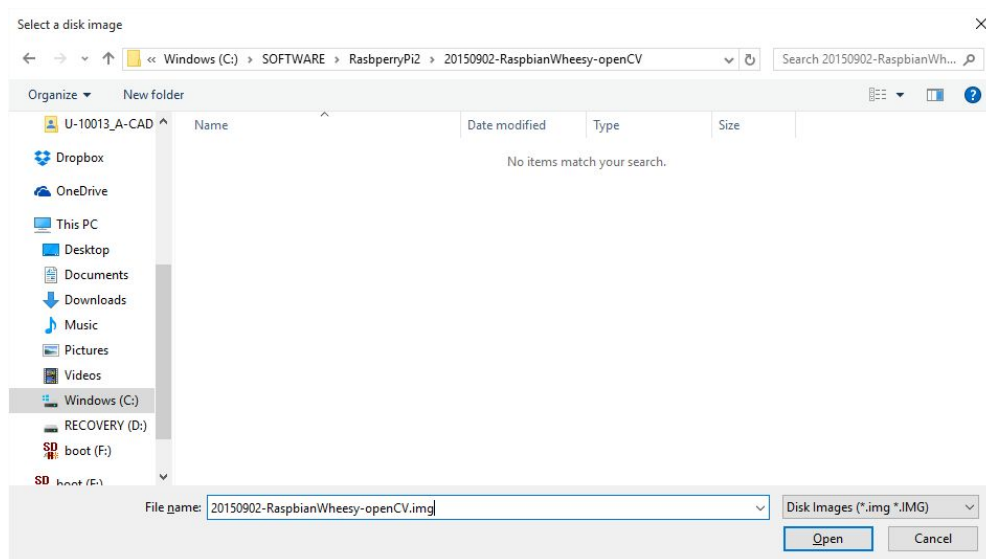
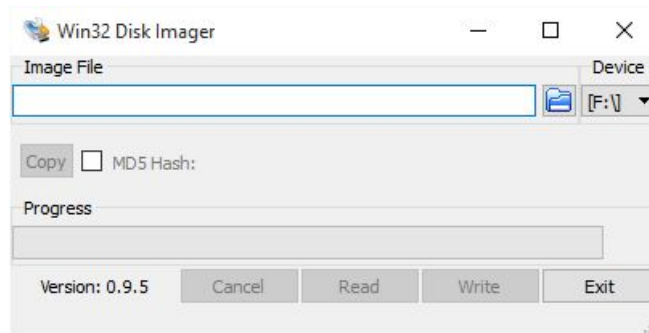
1. Place a blank micro-SD card in card reader (this shows up as **F:** in this Win 10 machine)
2. Run program **Win32DiskImager**
3. Select the appropriate image files (e.g. 20150902-RaspbianWheesy-openCV.img)
4. Click **Write** to create the bootable disk
5. Place the disk in the Raspberry Pi 2 and boot up



A2: Backing Up a Raspberry Pi 2 Boot Disk to an img File

Carry out the following steps:

1. Place micro-SD card in card reader (this shows up as **F:** in this Win 10 machine)
2. Run program **Win32DiskImager**
3. Choose a path and a name for the file (append .img to name)
4. Click **Read** to create the image file



A3: Setting up a Static IP Address on RaPi2

A3.1 Temporary Change (until Reboot)

Open a terminal and type:

```
sudo ifconfig eth0 192.168.100.21
```

test that the change has taken place by typing ifconfig

This change will not survive a reboot.

A 3.2 Permanent IP Address Change (will survive reboot)

A static IP address should already have been set up on your RaPi2. If for any reason you need to change it, or if it is set up for DHCP do the following:

Run LXTerminal and type the following:

```
sudo leafpad /etc/network/interfaces
```

Note that sudo designated that you are carrying out the action as the superuser (you may have to enter the password r2).

In the interfaces file look for a line such as:

```
iface eth0 inet dhcp
```

or

```
iface eth0 inet manual
```

Comment out this line (place # at beginning of line) and type the following

```
iface eth0 inet static  
address 192.168.100.21  
netmask 255.255.255.0
```

Save the file and reboot

Note that we recommend that you set your PC to a static address such as 192.168.100.20

A4: Accessing X11 Remotely from PC

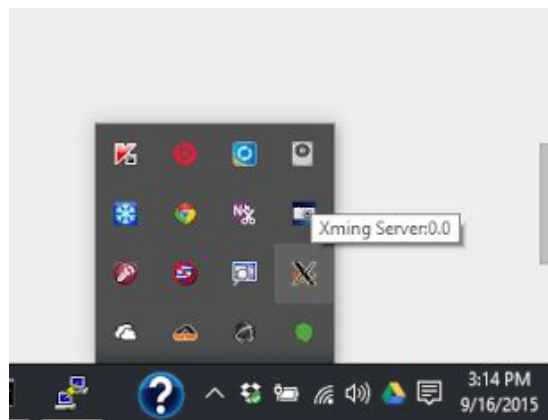
The Raspberry Pi 2 is a UNIX backbone which out of the box can serve up X11 remote windows.

Install the following programs on a Windows machine:

- putty - <http://www.putty.org/>
- Xming - <http://sourceforge.net/projects/xming/>

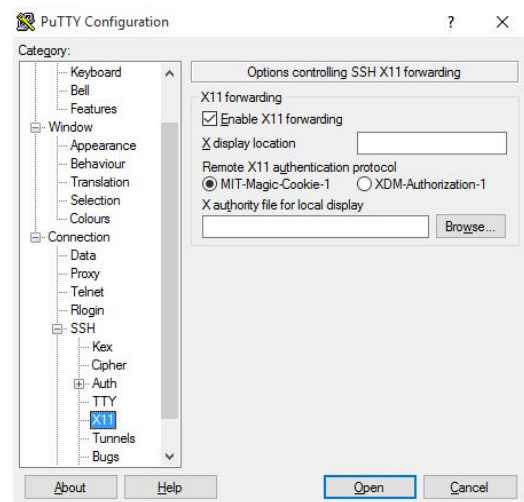
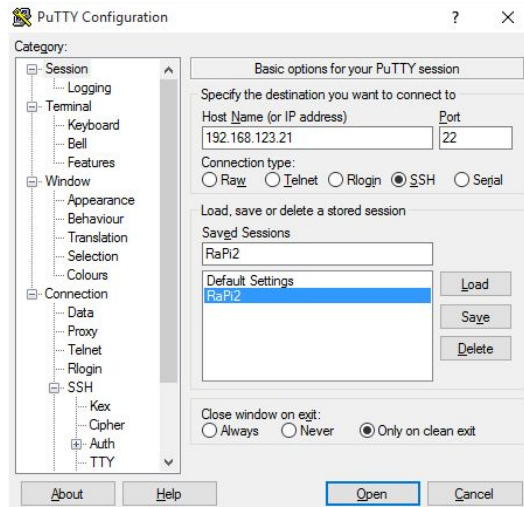
Run Xming

Clicking on 'Show Hidden Icons' on the desktop bar should show that the Xming server is running in the background, and running the cursor over the icon should show the message 'Xming Server:0.0'.



Run putty

- Put the static address of the RaPi2 into the "Host Name (or IP address) box
- Keep Port as 22 (unless you know otherwise)
- Enable X11 Forwarding under SSH/X11
- Save session for use at a later time

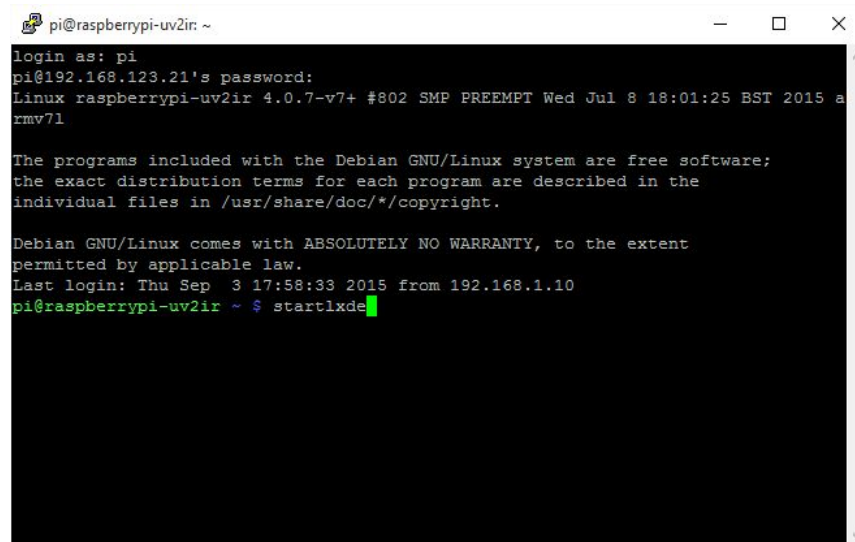


- Press 'Open' to open up a remote terminal on the RaPi2
- Enter your username and password (eg.: pi , r2)



A remote session will open.

- Type `startlxde` into the prompt and press Enter

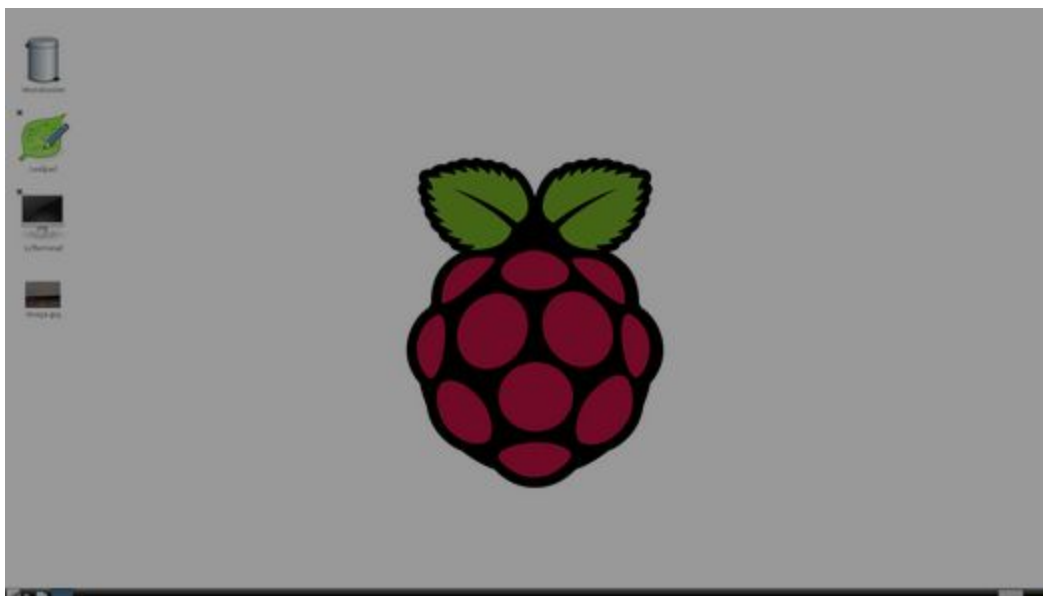
A terminal window titled 'pi@raspberrypi-uv2ir: ~' with standard window controls. It shows a login sequence for user 'pi' at IP '192.168.123.21'. The system is 'Linux raspberrypi-uv2ir 4.0.7-v7+ #802 SMP PREEMPT Wed Jul 8 18:01:25 BST 2015 a' with kernel 'rvmv7l'. It displays the Debian GNU/Linux free software notice and the last login time. The prompt is 'pi@raspberrypi-uv2ir ~ \$' and the command 'startlxde' has been entered, with a green cursor at the end.

```
pi@raspberrypi-uv2ir: ~
login as: pi
pi@192.168.123.21's password:
Linux raspberrypi-uv2ir 4.0.7-v7+ #802 SMP PREEMPT Wed Jul 8 18:01:25 BST 2015 a
rvmv7l

The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/copyright.

Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.
Last login: Thu Sep  3 17:58:33 2015 from 192.168.1.10
pi@raspberrypi-uv2ir ~ $ startlxde
```

The X11 windows session will open up.



- To close the session, shut down the terminal window.

```
pi@raspberrypi-uv2ir: ~  
** (lxsession-logout:2613): WARNING **: dbus-interface.c:94: DBUS: The name org.freedesktop.Hal was not provided by any .service files  
** (lxsession-logout:2613): WARNING **: dbus-interface.c:94: DBUS: The name org.freedesktop.Hal was not provided by any .service files  
** (lxsession-logout:2613): WARNING **: dbus-interface.c:94: DBUS: The name org.freedesktop.Hal was not provided by any .service files  
** (lxsession-logout:2613): WARNING **: dbus-interface.c:94: DBUS: The name org.freedesktop.Hal was not provided by any .service files  
(lxsession-logout:2613): GLib-GObject-WARNING **: Attempt to add property GtkSettings::gtk-label-select-on-focus after class was initialised  
(lxsession-logout:2613): GLib-GObject-WARNING **: Attempt to add property GtkSettings::gtk-button-images after class was initialised  
(pcmanfm:2539): GLib-GObject-WARNING **: Attempt to add property GtkSettings::gtk-entry-select-on-focus after class was initialised  
(pcmanfm:2539): GLib-GObject-WARNING **: Attempt to add property GtkSettings::gtk-entry-password-hint-timeout after class was initialised
```

A5: Accessing X11 Remotely from an Apple Mac (OS X)

Since OS X is built on a UNIX backbone, getting the system to run on a mac computer is somewhat easier than for a Windows PC.

- Open a Terminal (Bash) from the Applications/Utilities menu
- Type the following:
 - `ssh -X pi@192.168.100.21` (change username and IP address as appropriate)
- You will be prompted for the RaPi2 user password (corresponding to use pi)
- You are now logged into the RaPi2
- Type `startlxde` to see the remote desktop on the Apple machine

Note that XQuartz is not shipped in newer versions of OS X. You will probably need to download and configure if you are using a Mac. Note also that XQuartz gets clobbered if you upgrade your OS X, so you may have to re-install after a OS X upgrade.

<https://support.apple.com/en-us/HT201341>

A6: Accessing X11 Remotely from an Linux (Ubuntu as Example)

- Open a Terminal
- Type the following:
 - `ssh -X pi@192.168.100.21` (change username and IP address as appropriate)
- You should see the RaPi2 screen on your computer

- Run any program on the RaPi2 by typing in the command to run it (e.g. idle). The program will open up a window on your Linux machine.

A7: Virtual Network Adaptors

This allows one to set up a completely virtual network so that the host OS and the virtual OS can communicate with each other through the network adaptors.

<http://coding4streetcred.com/blog/post/VirtualBox-Configuring-Static-IPs-for-VMs>