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```
% Implementation of Dijkstra's method using a Matlab sparse matrix
as an adjacency matrix. Zero entries represent non-existent edges.
Uses linear search for simplicity

% Usage
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% [path , pathcost] = dijkstra(A , s , d);

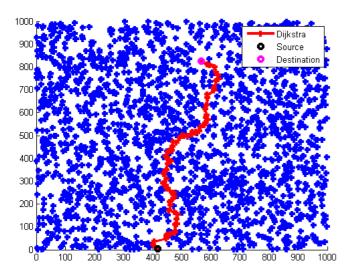
Inputs
-----

% A Sparse adjacency matrix (N x N)
s Source node index in [1,...,N]
d Destination node index in [1,...,N]

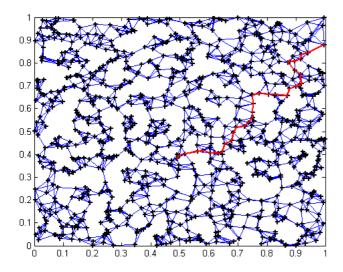
% Outputs
------
% path Distance vector from Dijkstra (1 x m)
pathcost Cost of the path
```

## Example 1: Adjacency matrix build R-radius neightbours

```
clear, close all hidden
close all
                             = 2000;
                             = 1000 \cdot
R
                              = 2*L/sqrt(N);
                                            %starting node
d
                             = 10:
                                            %end node
                             = L*rand(2 , N);
                             = Radjacency(X , R);
[path , pathcost]
                             = dijkstra(A , s , d);
hold on, h=plot(X(1 , :) , X(2 , :) , '+' , X(1 , path) , X(2 , path) , 'r-+' , X(1 , s) , X(2 , s) , 'ko' , X(1 , d) , X(2 , d) , 'mo' , 'linewidth' , 3
legend(h(2:4) , 'Dijkstra' , 'Source' , 'Destination')
```



## **Example 2 : Adjacency matrix build K-neightbourg**



## **Example 3 : User problem**

```
s = 2;

d = 12;

I=[2,11,1,3,2,17,19,26,4,5,6,...

7,8,9,1,10,11,12,13,14,20,15,...

22,3,18,17,4,16,23,15,21,20,...

16,24,19,25,22,23,4];

J=[1,1,2,2,3,3,4,4,5,6,7,8,9,...

10,11,11,12,13,14,15,15,...

16,16,17,17,18,19,19,19,20,...

20,21,22,22,23,23,24,25,26];

V=[1.6000,6.0000,2.6667,1.6000,...

2.6667,1.2000,7.2240,4.2000,...

3.6000,3.2000,3.2000,2.6000,...

2.8000,2.6000,3.6000,7.2240,...

2.4000,3.2000,2.7120,2.0000,...

1.2000,2.0000,7.2240,4.8000,...

2.7120,4.8533,0.4000,0.6667,...

4.5200,0.4000,4.5200,0.4000,...

0.6667,0.6667,7.0000];

pcost = sparse(I,J,V,length(I),length(I));

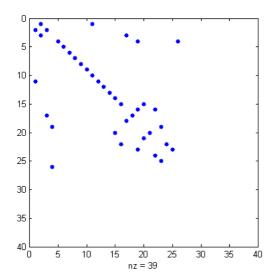
[path cost] = dijkstra(pcost,s,d)

figure(3)

spy(pcost)

path =
```

56.7147



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