Approximating All-Pairs Similarity Search by Rademacher Average

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1 Introduction

All-pairs similarity search (APSS) has received extensive research interest recently [5, 35, 1, 30]. To improve performance, many approximation approaches have been proposed [13, 11, 17, 10]. This paper considers two approximation methods for cosine similarity based search [29, 35, 1, 30], and SimRank based search [18, 20, 12, 19] respectively. The approximation error of each our algorithm is upper bounded by using Rademacher average [4, 23, 3].

2 Related Works

All-pairs similarity search (APSS) is recently a popular research topic in the community of information retrieval [5, 35, 1, 30]. Given a big set of objects, the goal of APSS is to efficiently compute (or approximate) the similarities between each pair of objects. Many similarity measures have been proposed [29], e.g., Cosine Similarity [31], SimRank [18], Jaccard Index [14], Metric Distance [29], Pearson Correlation [6], etc. For similarity search, Cosine Similarity and SimRank are very popular ([31, 35, 1, 30] for Cosine, and [20, 12, 19, 36] for SimRank). A major challenge of APSS is the large volume of computation: given n objects, without any assumption on the similarity distribution (e.g., the similarity matrix is sparse), the time complexity is at least $O(n^2)$. To compute more efficiently, the state-of-art research works often use parallelism [9, 15] and dissimilarity detection [1, 30]. If only approximations are needed, how to efficiently sample with negligible error for similarity search is another research focus [13, 11, 17, 10]. This paper focuses on the approximation problem.

We may treat the similarity approximation as a learning problem over large scaled data, and we need to upper bound the learning error for the worst case. In statistical learning theory, such upper bounds are usually called risk bounds [32]. There are two classical methods to compute the risk bounds: by VapnikChervonenkis (VC) dimension [33, 34, 32] and by Rademacher average [23, 4, 3]. Many approximation algorithms that use these two techniques have been proposed [25, 26, 27, 28]. Riondato and Kornaropoulos [25, 26] proposed algorithms that use VC dimension to upper bound the sample size that is sufficient to approximate the betweenness centralities [8] of all nodes in a graph with guaranteed error bounds. One limitation of the VC-based algorithms is that the upper bounds of some characteristic quantities (e.g., the maximum length of any shortest path) are needed [25, 26, 28]. But such bounds are not always available. One year later, Riondato and Upfal used Rademacher average to approximate the frequent itemsets [27] and betweenness centralities [28]. They also found that by using Rademacher average, we can avoid the aforementioned limitation of VC-based solutions. It has been proved that Rademacher average can be applied to various approximation problems, which are out of the scope of classical learning framework. This paper basically follows this idea. To the best of our knowledge, there is no research work connecting similarity approximation with Rademacher average. We attempt to fill this void.

3 Problem Formulation and Preliminaries

3.1 Cosine Similarity

We consider the cosine similarity based all-pairs similarity search. Suppose there are n vectors (each vector can represent a user profile or a web page). Each vector contains m non-negative features. Define the cosine similarity between two vectors u and v as

$$Sim(u, v) = \frac{1}{||u|| \cdot ||v||} \sum_{i=1}^{m} u_i \cdot v_i,$$

where u_i, v_i denotes the i-th feature value of u, v. For simplicity, we assume all the vectors are adjusted with the same norm: $||v|| = \sqrt{m}$ for every v in the n vectors. Then the equation above can be simplified as

$$Sim(u, v) = \frac{1}{m} \sum_{i=1}^{m} u_i \cdot v_i.$$

That is, the similarity is defined as the average on the corresponding feature products between the vectors.

To do the all-pairs similarity search (APSS), we need to compute the similarity between each pair of vectors. Since there are $n(n-1)$ pairs, and for each pair we need m times of multiplication, the total complexity of a naiive algorithm is $O(n^2 m)$. Fortunately, there are many methods to detect dissimilar pairs (two vectors without sharing any feature) [1, 30, 21], which can save a lot of computation. For the state-of-art works, to compute all the pairs, the complexity can be lowered to $O(nkm)$, where k is much less than n. However, to the best of our knowledge, there were few discussions on the size of features m. If we can only consider a part of the m features without significantly deteriorating the accuracy, then the total computation time for APSS can be lowered significantly (note that nk is still large for very big dataset). We can approximating the similarity by sampling on the features.

3.2 SimRank

SimRank [18] is a popular measure of the similarity between two nodes in a graph based on the idea that similar nodes are often referred by other similar nodes. Denote by $s(a, b)$ the SimRank between nodes a and b. If $a = b$, then $s(a, b)$ is defined to be 1. Otherwise,

$$s(a, b) = \frac{c}{|I(a)| \cdot |I(b)|} \sum_{i \in I(a)} \sum_{j \in I(b)} s(i, j),$$

where c is a constant in $(0, 1)$ and $I(a)$ denotes the in-neighbors of a. If there is an edge from a to b, then a is an in-neighbor of b. An important fact is that SimRank can be equivalently built upon Random Surfer-Pairs Model [18]. That is, $s(a, b)$ can also be written as follows:

$$s(a, b) = \sum_{t:(a,b)(x,x)} P[t] \cdot c^{L(t)},$$

where t is a pair of random walks with the same number of steps, which lead a and b to meet at one node x, and $P[t]$ denotes the probability when t is chosen, and $L(t)$ denotes the number of steps of each walk in t. Here we take random walks from the reversed graph, in which each edge is reversed compared with the original graph. A random walk works as follows: in the tour at any node, which has k out-edges, we take one of the k edge with equal probability $1/k$ as our next step. Note that as the length of random walk grows, its contribution to $s(a, b)$ decreases exponentially. Hence in practice, we only need to consider relatively short walks, e.g., with length no more than T.

3.3 Rademacher Average

This section proposes our approximation algorithm and its analysis. Suppose we want to compute the cosine similarities between a fixed vector u and other vectors v_1, v_2, $\cdots$, v_n. We take the m features as the sample space S:

$$S = \{s_1, \cdots, s_k\} \subseteq D$$

where k is the number of samples we take, and D is the feature space: $D = \{1, 2, \cdots, m\}$. Let F be a collection of functions from the features D to the interval $[0, m]$. For each function $f \in F$, define the *true average* $A_D(f)$ and *sampled average* $A_S(f)$ as follows:

$$A_D(f) = \frac{1}{m}\sum_{i=1}^{m} f(i), \quad A_S(f) = \frac{1}{k}\sum_{i=1}^{k} f(s_i).$$

Define the *uniform deviation* [24] of F given S as

$$U_S(F) = \sup_{f\in F}[A_S(f) - A_D(f)].$$

Note that if F is a finite set (in this paper we will see this is true), supreme can be replaced by maximum:

$$U_S(F) = \max_{f\in F}[A_S(f) - A_D(f)].$$

Define the *Rademacher average* [23, 4, 24] of F given S as

$$R_S(F) = \mathbb{E}_\sigma\left[\sup_{f\in F}\frac{2}{k}\sum_{i=1}^{k}\sigma_i f(s_i)\right],$$

where each σ_i is a random variable uniformly distributed over $\{-1, 1\}$, and the mean $\mathbb{E}_\sigma$ takes randomness over all the σ_i's conditionally on S. Again, one can replace supreme by maximum.

The main motivation of our algorithm is that the difference between true average and sampled average is upper bounded by the Rademacher average as follows. We leave the proofs to the Appendix.

Theorem 1. Let F be a collection of functions f mapping D to $[0, m]$. With probability at least $1 - \delta$, we have

$$\sup_{f\in F}|A_S(f) - A_D(f)| \le R_S(F) + \left(m + m\sqrt{\frac{8}{k}\log\frac{2}{\delta}} + m\sqrt{\frac{8}{k}\log\frac{2}{\delta} + \frac{8R_S(F)}{m}}\right)\sqrt{\frac{\log\frac{8}{\delta}}{2k}}.$$

The remaining item we need to upper bound is $R_S(F)$. Our result is similar to Massart's lemma [2].

Theorem 2.

$$R_S(F) \le \frac{\ell}{k}\sqrt{8\log|F|},$$

where $\ell^2 = \sup_{f\in F}\sum_{i=1}^{k} f(s_i)^2$.

By the above two theorems, we can bound our approximation error even for the worst case.

4 Approximating Cosine Similarities

The approximation algorithm takes as input a collection of n vectors V and two parameters (ϵ, δ) whose values are between 0 and 1. The algorithm outputs a set $C = \{\tilde{S}(u, v) : u, v \in V, u \ne v\}$, where $\tilde{S}(u, v)$ is the (ϵ, δ)- approximation of cosine similarity between u and v, i.e., with probability at least $1 - \delta$, the worst approximation error in C is at most ϵ. Each vector in V contains m features. We take the m features as

Algorithm 1 Cosine Similarity Approximation

Input: vectors V ($|V| = n$); features U ($|U| = m$); $\epsilon \in (0, 1)$; $\delta \in (0, 1)$.
Output: $Sim(u, v)$ for each $u, v \in V$ s.t. $u \neq v$.

```
k ← 0;
S ← ∅;
S(u, v) ← 0 for each u, v ∈ V s.t. u ≠ v;
while k ≤ m do
    k' ← next − sample − size(k);
    for i from k to k' − 1 do
        Uniformly sample a feature s from U \ S;
        S(u, v) ← S(u, v) + u[s] · v[s];
        S ← S ∪ {s};
    end for
    Δ ← 4ℓ√(log n)/k + (m + m√((8/k) log(2/δ) + m√((8/k) log(2/δ) + 32ℓ√(log n)/(mk)))) √((log(8/δ))/(2k));
    if Δ ≤ ε then
        break the while loop;
    end if
end while
S ← {S(u, v)/k : u, v ∈ V, u ≠ v}.
return S.
```

the sample space $D = \{1, \cdots, m\}$. For each feature $s \in D$, let $f_{u,v}(s) = u_s \cdot v_s$, where u_s is the s-th feature value of the vector u. Let $F = \{f_{u,v} : u, v \in V, u \neq v\}$. Thus $|F| < n^2/2$ since symmetry of cosine similarity. It is clear that the true average of $f_{u,v}$ equals to the cosine similarity between u and v. Given the sampled features, the upper bound of $R_S(F)$ is

$$R_S(F) \leq \frac{\ell}{k}\sqrt{8 \log |F|} < \frac{4\ell\sqrt{\log n}}{k},$$

where $\ell = \sqrt{\max_{f \in F} \sum_{i=1}^{k} f(s_i)^2}$. Since F is finite, we can replace supreme by maximum.

4.1 The Algorithm

The approximation algorithm works in an iterative mode. For each iteration, we sample some new features s_i's among D and aggregate the feature products given by $f_{u,v}(s_i)$ for each $f_{u,v}$ in F. Then we compute the error upper bound:

$$\Delta = \frac{4\ell\sqrt{\log n}}{k} + \left(m + m\sqrt{\frac{8}{k}\log\frac{2}{\delta}} + m\sqrt{\frac{8}{k}\log\frac{2}{\delta} + \frac{32\ell\sqrt{\log n}}{mk}}\right)\sqrt{\frac{\log\frac{8}{\delta}}{2k}},$$

where $\ell = \sqrt{\max_{f \in F} \sum_{i=1}^{k} f(s_i)^2}$, and k is the number of aggregated samples. If $\Delta \leq \epsilon$, then we stop and return the averages $\frac{1}{k}\sum_{s_i \in S} f_{u,v}(s_i)$ for each pair u, v. Otherwise, we continue to the next round, where we will sample more features. If $\Delta \leq \epsilon$ can never be satisfied, at the end we will sample all the m features and return the averages as the exact solution. Algorithm 1 gives the pseudocode of our solution.

It is clear to verify the correctness of our algorithm by Theorem 1 and Theorem 2.

4.2 Improving the Upper Bound

Note that in the upper bound Δ of Algorithm 1, m is a dominating variable: it is proportional to Δ. Usually m can be quite large, e.g., from 100 to 10K. Thus it is worth investigating how to mitigate the negative effect

Algorithm 2 Random Walk Generation

Input: reversed graph $\overline{G}$, sequence $(s_1, \cdots, s_T) \in [0,1]^T$, starting node a.
Output: a random walk $W = (a, \cdots)$ starting from a.

```
Let W be a sequence of length T + 1;
W[0] ← a;
for i from 1 to T do
    I ← {b : there is an edge in Ḡ from W[i − 1] to b};
    k ← |I|;
    if k=0 then
        W[i] ← W[i − 1];
    else
        Sort I in lexicographical order: (I[0], ··· , I[k − 1]);
        x ← ⌊s_{i−1} ∗ k⌋;
        W[i] ← I[x];
    end if
end for
return W.
```

of large m. The idea comes from Theorem 1, which assumes the range of each function f is $[0, m]$. However in reality, most feature products $u[s] \cdot v[s]$ are close to zero due to sparsity, and its maximum value shall be much less than m. To further lower the upper bound Δ, a variant of Algorithm 1 may maintain a variable

$$\hat{m} = \max_{s \in S, u, v \in V, u \neq v} u[s] \cdot v[s],$$

where S is the set of sampled features, and V is the set of all vectors. Intuitively, $\hat{m}$ is the maximum value of all the sampled feature products. Then we may choose the upper bound as follows:

$$\Delta = \frac{4\ell\sqrt{\log n}}{k} + \hat{m}\left(1 + \sqrt{\frac{8}{k}\log\frac{2}{\delta}} + \sqrt{\frac{8}{k}\log\frac{2}{\delta} + \frac{32\ell\sqrt{\log n}}{\hat{m}k}}\right)\sqrt{\frac{\log\frac{8}{\delta}}{2k}}.$$

We use experiments to show that the improvement of the variant above is significant.

5 Approximating SimRank

We approximate SimRank scores on the nodes in the digraph $G = (V, E)$. The basic idea is similar to the case of cosine similarity approximation, but the sample space D is changed to the $2T$-dimensional manifold $[0,1]^{2T}$, where $[0,1]$ is the interval of real numbers between 0 and 1, and F is now defined as

$$F = \{f_{a,b} : a, b \in V, a \neq b\},$$

where given any two nodes a, b, the function $f_{a,b}$ takes a sample $s_i \in D$ as input and outputs a value in the interval $[0, c]$. Algorithm 2 shows how to generate a random walk given a sample from $[0,1]^T$ and a starting node a. It is clear that the random walk chosen by Algorithm 2 is uniformly distributed if the sample is uniformly drawn from $[0,1]^T$. Thus given two nodes a, b and a sample $s_i \in [0,1]^{2T}$, we can generate two random walks W_a, W_b starting from a and b respectively. Let

$$l_{a,b}(s_i) = \min\{j : 1 \leq j \leq T, W_a[j] = W_b[j]\},$$

i.e., the number of steps before two surfers starting from a, b meet at some node. If W_a and W_b never meet within T steps, $l_{a,b}(s_i)$ is defined to be 0.

The function $f_{a,b}(s_i)$ is defined as

$$f_{a,b}(s_i) = \begin{cases} 0 & \text{if } l_{a,b}(s_i) = 0, \\ c^{l_{a,b}(s_i)} & \text{otherwise.} \end{cases}$$

It is clear that the true average $A_D(f_{a,b})$ equals to the SimRank between the nodes a and b. Thus a similar approximation idea based on Rademacher average can be applied. We still need to upper bound the worst approximation error. The new bound is stated as follows.

Theorem 3. Let F be a collection of functions f mapping D to $[0, c]$. With probability at least $1 - \delta$, we have

$$\sup_{f \in F} |A_S(f) - A_D(f)| \leq R_S(F) + \left(c + c\sqrt{\frac{8}{k} \log \frac{2}{\delta}} + c\sqrt{\frac{8}{k} \log \frac{2}{\delta} + \frac{8R_S(F)}{c}} \right) \sqrt{\frac{\log \frac{8}{\delta}}{2k}}.$$

The proof is essentially the same as the proof of Theorem 1. We leave the discussions to the Appendix. Also the upper bound of $R_S(F)$ given by Theorem 2 remains unchanged.

Our approximation algorithm works as follows. For each iteration, we sample some new features s_i's among D, generate random walks W_a, W_b from nodes a, b given s_i and aggregate $f_{a,b}(s_i)$ for each $f_{a,b}$ in F. Then we compute the error upper bound:

$$\Delta = \frac{4\ell\sqrt{\log n}}{k} + \left(c + c\sqrt{\frac{8}{k} \log \frac{2}{\delta}} + c\sqrt{\frac{8}{k} \log \frac{2}{\delta} + \frac{32\ell\sqrt{\log n}}{ck}} \right) \sqrt{\frac{\log \frac{8}{\delta}}{2k}},$$

where $\ell = \sqrt{\max_{f \in F} \sum_{i=1}^{k} f(s_i)^2}$, and k is the aggregated samples. If $\Delta \leq \epsilon$, then we stop and return the averages $\frac{1}{k} \sum_{s_i \in S} f_{a,b}(s_i)$ for each pair u, v. Otherwise, we continue to the next round, where we will sample more features. If $\Delta \leq \epsilon$ can never be satisfied with a certain number of iterations, we return the approximated SimRank scores of node pairs, with the message that the input parameters (ϵ, δ) cannot be satisfied by our algorithm.

It is clear to verify the correctness of our algorithm by Theorem 3 and Theorem 2.

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Algorithm 3 SimRank Approximation

Input: reversed graph $\overline{G}$; $\epsilon \in (0,1)$; $\delta \in (0,1)$; maximum random walk length T; maximum number of iterations R; SimRank constant c.
Output: $\mathsf{SimRank}(u,v)$ for each $u,v \in V$ s.t. $u \neq v$.

```
k ← 0;
S(u,v) ← 0 for each u,v ∈ V s.t. u ≠ v;
for count from 1 to R do
    k' ← next − sample − size(k);
    for i from k to k' − 1 do
        Uniformly sample a feature s from [0,1]^{2T};
        for each a,b ∈ V × V s.t. a ≠ b do
            W_a ← Random Walk Generation(s[1 ··· T]);
            W_b ← Random Walk Generation(s[(T+1) ··· 2T]);
            L ← {j : 1 ≤ j ≤ T, W_a[j] = W_b[j]};
            if |L| > 0 then
                l_{a,b} ← min L;
                S(u,v) ← S(u,v) + c^{l_{a,b}};
            end if
        end for
    end for
    Δ ← 4ℓ√(log n)/k + ( c + c√((8/k) log(2/δ)) + c√((8/k) log(2/δ) + 32ℓ√(log n)/(ck)) ) √((log(8/δ))/(2k));
    if Δ ≤ ε then
        break the while loop;
    end if
end for
S ← {S(u,v)/k : u,v ∈ V, u ≠ v}.
if count = R then
    show a message that (ε,δ) cannot be satisfied.
end if
return S.
```


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6 Appendix

6.1 Proof of Theorem 1

In this section, we show our main result (Theorem 1). We start from the definition of self bounding function [24].

Definition 1. *Let $s_1, s_2, \cdots, s_k$ be independent random variables taking values from a set D. A function $f : D^k \to [0, +\infty]$ is a self bounding function if there exists a constant c and a function $g : D^{k-1} \to \mathbb{R}$ such that for any $s_1, \cdots, s_{j-1}, s_{j+1}, \cdots, s_k \in D$, the following conditions hold:*

$$0 \leq f(s_1, \cdots, s_k) - g(s_1, \cdots, s_{j-1}, s_{j+1}, \cdots, s_k) \leq c,$$

$$\sum_{j=1}^{k} [f(s_1, \cdots, s_k) - g(s_1, \cdots, s_{j-1}, s_{j+1}, \cdots, s_k)] \leq f(s_1, \cdots, s_k).$$

The following concentration inequality can be achieved for self bounding functions [7].

Lemma 1. *[7] If a function $Z = f(s_1, \cdots, s_k)$ is a self bounding function with constant c, then for $t \leq \mathbb{E}Z$,*

$$\Pr[\mathbb{E}Z - Z \geq t] \leq \exp\left(-\frac{t^2}{2c\mathbb{E}Z}\right).$$

For $t > \mathbb{E}Z$, the left probability is zero trivially. Here we take randomness over $s_1, s_2, \cdots, s_k$.

By using the above lemma, we can show a similar inequality for Rademacher average.

Lemma 2.

$$\Pr[\mathbb{E}R_S(F) \geq R_S(F) + t] \leq \exp\left(-\frac{kt^2}{4m\mathbb{E}R_S(F)}\right),$$

where $\mathbb{E}$ takes randomness over the samplings $s_1, s_2, \cdots, s_k$.

Proof. It suffices to show that $R_S(F)$ is a self bounding function with constant $c = 2m/k$. Define

$$Z = R_S(F) = \mathbb{E}_\sigma \sup_{f \in F} \left[\frac{2}{k} \sum_{i=1}^{k} \sigma_i f(s_i) \right],$$

$$G_j = \mathbb{E}_\sigma \sup_{f \in F} \left[\frac{2}{k} \sum_{i \neq j} \sigma_i f(s_i) \right].$$

It is clear that Z is non-negative:

$$Z \geq \sup_{f \in F} \left[\mathbb{E}_\sigma \frac{2}{k} \sum_{i=1}^{k} \sigma_i f(s_i) \right] = 0.$$

Also it is clear that $Z \geq G_j$ for each j: suppose $\tilde{f}$ achieves the supreme of G_j. Then

$$\begin{aligned} G_j &= \mathbb{E}_\sigma \left[\frac{2}{k} \sum_{i=1}^{k} \sigma_i \tilde{f}(s_i) - \frac{2}{k} \sigma_j \tilde{f}(s_j) \right] \\ &= \mathbb{E}_\sigma \left[\frac{2}{k} \sum_{i=1}^{k} \sigma_i \tilde{f}(s_i) \right] - \mathbb{E}_\sigma \left[\frac{2}{k} \sigma_j \tilde{f}(s_j) \right] \\ &= \mathbb{E}_\sigma \left[\frac{2}{k} \sum_{i=1}^{k} \sigma_i \tilde{f}(s_i) \right] \leq Z. \end{aligned}$$

Next we show $Z - G_j \leq 2m/k = c$:

$$\begin{aligned} G_j &= \mathbb{E}_\sigma \sup_{f \in F} \left[\frac{2}{k} \sum_{i=1}^{k} \sigma_i f(s_i) - \frac{2}{k} \sigma_j f(s_j) \right] \\ &\geq \mathbb{E}_\sigma \sup_{f \in F} \left[\frac{2}{k} \sum_{i=1}^{k} \sigma_i f(s_i) \right] - \mathbb{E}_\sigma \sup_{f \in F} \left[\frac{2}{k} \sigma_j f(s_j) \right] \\ &\geq \mathbb{E}_\sigma \sup_{f \in F} \left[\frac{2}{k} \sum_{i=1}^{k} \sigma_i f(s_i) \right] - \frac{2m}{k}. \end{aligned}$$

Finally we need to verify $\sum_{j=1}^{k} Z - G_j \leq Z$:

$$\begin{aligned} \sum_{j=1}^{k} G_j &= \mathbb{E}_\sigma \sum_{j=1}^{k} \sup_{f \in F} \left[\frac{2}{k} \sum_{i \neq j} \sigma_i f(s_i) \right] \\ &\geq \mathbb{E}_\sigma \sup_{f \in F} \left[\frac{2}{k} \sum_{j=1}^{k} \sum_{i \neq j} \sigma_i f(s_i) \right] \\ &= \frac{2(k-1)}{k} \mathbb{E}_\sigma \sup_{f \in F} \left[\sum_{j=1}^{k} \sigma_i f(s_i) \right] = (k-1)Z. \end{aligned}$$

□

We still need the following lemma on the relation between uniform deviation and Rademacher average.

Lemma 3.

$$\mathbb{E}\sup_{f\in F}[A_S(f)-A_D(f)]\le \mathbb{E}R_S(F),$$
$$\mathbb{E}\sup_{f\in F}[A_D(f)-A_F(f)]\le \mathbb{E}R_S(F).$$

Here we take randomness over the k samplings.

Proof. The proof idea is based on ghost samplings, i.e., independently draw another k samples: $s'_1, \cdots, s'_k$, and then we have

$$A_D(f)=\frac{1}{m}\sum_{i=1}^{m}f(i)=\mathbb{E}\frac{1}{k}\sum_{j=1}^{k}f(s'_j),$$

where $\mathbb{E}$ takes randomness over the k ghost samples. Thus

$$\begin{aligned}\mathbb{E}\sup_{f\in F}[A_S(f)-A_D(f)]&=\mathbb{E}\sup_{f\in F}\left[\frac{1}{k}\sum_{i=1}^{k}f(s_i)-\mathbb{E}\frac{1}{k}\sum_{j=1}^{k}f(s'_j)\right]\\&\le \mathbb{E}\sup_{f\in F}\left[\frac{1}{k}\sum_{i=1}^{k}f(s_i)-\frac{1}{k}\sum_{j=1}^{k}f(s'_j)\right].\end{aligned}$$

Since all the samples s, s' are independently identically distributed, flipping the sign of $f(s_i)-f(s'_i)$ will not change the expected supreme, i.e.,

$$\mathbb{E}\sup_{f\in F}\left[\frac{1}{k}\sum_{i=1}^{k}f(s_i)-\frac{1}{k}\sum_{j=1}^{k}f(s'_j)\right]=\mathbb{E}\sup_{f\in F}\frac{1}{k}\sum_{i=1}^{k}\left[\sigma_i(f(s_i)-f(s'_i))\right],$$

where σ_i is uniformly distributed over $\{-1,1\}$. Since

$$\mathbb{E}\sup_{f\in F}\frac{1}{k}\sum_{i=1}^{k}[\sigma_i(f(s_i)-f(s'_i))]\le 2\mathbb{E}\sup_{f\in F}\frac{1}{k}\sum_{i=1}^{k}\sigma_i f(s_i)=\mathbb{E}R_S(F),$$

we have shown the first inequality. The second inequality is analogous. □

We also need McDiarmid's inequality [22].

Lemma 4. *[22] Let $s_1, \cdots, s_k$ be independent random variables taking values from a set D. Suppose a function $h: D^k\to\mathbb{R}$ satisfies*

$$\sup_{x_1,\cdots,x_k,x'_i\in D}|h(x_1,\cdots,x_k)-h(x_1,\cdots,x_{i-1},x'_i,x_{i+1},\cdots,x_k)|\le c_i$$

for some constants c_i and every $1\le i\le k$. Then for any $t>0$, we have

$$\Pr[h(s_1,\cdots,s_k)-\mathbb{E}h(s_1,\cdots,s_k)\ge t]\le\exp\left(-\frac{2t^2}{\sum_{i=1}^{k}c_i^2}\right).$$

By the above three lemmas, we can bound the difference between true average and sampled average as follows.

Lemma 5.

$$\begin{aligned}&\Pr\left[\sup_{f\in F}|A_D(f)-A_S(f)|\ge R_S(F)+t\right]\\\le&4\exp\left(-\frac{2kt^2}{(m+\sqrt{8m\mathbb{E}R_S(F)})^2}\right).\end{aligned}$$

Proof. First by Lemma 3,

$$\begin{aligned}
&\Pr\left[\sup_{f\in F}[A_D(f)-A_S(f)]\geq R_S(F)+t\right]\\
\leq&\Pr\left[\sup_{f\in F}[A_D(f)-A_S(f)]\geq \mathbb{E}\sup_{f\in F}[A_D(f)-A_S(f)]+at\right]\\
&+\Pr\left[\mathbb{E}R_S(F)\geq R_S(F)+(1-a)t\right]
\end{aligned}$$

for any $a\in[0,1]$. Let

$$h(s_1,\cdots,s_k)=A_D(f)-A_S(f)=A_D(f)-\frac{1}{k}\sum_{i=1}^{k}f(s_i).$$

It is clear that

$$\begin{aligned}
&\sup_{x_1,\cdots,x_k,x_i'\in D}|h(x_1,\cdots,x_k)-h(x_1,\cdots,x_{i-1},x_i',x_{i+1},\cdots,x_k)|\\
=&\sup_{x_1,\cdots,x_k,x_i'\in D}\left|\frac{1}{k}\sum_{j=1,j\neq i}^{k}f(x_j)+\frac{1}{k}f(x_i')-\frac{1}{k}\sum_{i=1}^{k}f(x_i)\right|\\
=&\sup_{x_1,\cdots,x_k,x_i'\in D}\left|\frac{1}{k}f(x_i')-\frac{1}{k}f(x_i)\right|\leq\frac{m}{k}.
\end{aligned}$$

By McDiarmid's inequality,

$$\begin{aligned}
&\Pr\left[\sup_{f\in F}[A_D(f)-A_S(f)]\geq \mathbb{E}\sup_{f\in F}[A_D(f)-A_S(f)]+at\right]\\
\leq&\exp\left(-\frac{2a^2t^2}{\sum_{i=1}^{k}m^2/k^2}\right)=\exp\left(-\frac{2ka^2t^2}{m^2}\right).
\end{aligned}$$

By Lemma 2,

$$\Pr\left[\mathbb{E}R_S(F)\geq R_S(F)+(1-a)t\right]\leq\exp\left(-\frac{k(1-a)^2t^2}{4m\mathbb{E}R_S(F)}\right).$$

Let $a=1/(1+\sqrt{8\mathbb{E}R_S(F)/m})$. Then putting everything together, we have

$$\begin{aligned}
&\Pr\left[\sup_{f\in F}[A_D(f)-A_S(f)]\geq R_S(F)+t\right]\\
\leq&2\exp\left(-\frac{2kt^2}{(m+\sqrt{8m\mathbb{E}R_S(F)})^2}\right).
\end{aligned}$$

Similarly one can show

$$\begin{aligned}
&\Pr\left[\sup_{f\in F}[A_S(f)-A_D(f)]\geq R_S(F)+t\right]\\
\leq&2\exp\left(-\frac{2kt^2}{(m+\sqrt{8m\mathbb{E}R_S(F)})^2}\right).
\end{aligned}$$

Thus we have the inequality as desired. □

By the above lemma we have the following important corollary.

Corollary 1. *With probability at least $1-\delta$, we have*

$$\sup_{f\in F}|A_S(f)-A_D(f)|\le R_S(F)+(m+\sqrt{8m\mathbb{E}R_S(F)})\sqrt{\frac{\log\frac{4}{\delta}}{2k}}.$$

We still need to upper bound $\mathbb{E}R_S(F)$. By Lemma 2, with probability at least $1-\delta$,

$$\mathbb{E}R_S(F)\le R_S(F)+\sqrt{4m\mathbb{E}R_S(F)\frac{\log\frac{1}{\delta}}{k}}.$$

Or equivalently,

$$\sqrt{\mathbb{E}R_S(F)}\le\sqrt{\frac{m}{k}\log\frac{1}{\delta}}+\sqrt{\frac{m}{k}\log\frac{1}{\delta}+R_S(F)}.$$

Hence with probability at least $1-2\delta$, we have

$$\sup_{f\in F}|A_S(f)-A_D(f)|\le R_S(F)+\left(m+m\sqrt{\frac{8}{k}\log\frac{1}{\delta}}+m\sqrt{\frac{8}{k}\log\frac{1}{\delta}+\frac{8R_S(F)}{m}}\right)\sqrt{\frac{\log\frac{4}{\delta}}{2k}}.$$

We have shown Theorem 1.

6.2 Proof of Theorem 2

For any $s>0$, by Jensen's inequality,

$$\begin{aligned}\exp(skR_S(F))&=\exp\left(2s\mathbb{E}_\sigma\sup_{f\in F}\sum_{i=1}^k\sigma_i f(s_i)\right)\\&\le\mathbb{E}_\sigma\exp\left(2s\sup_{f\in F}\sum_{i=1}^k\sigma_i f(s_i)\right)\\&\le\mathbb{E}_\sigma\sum_{f\in F}\exp\left(2s\sum_{i=1}^k\sigma_i f(s_i)\right).\end{aligned}$$

By Hoeffding's Lemma [16],

$$\begin{aligned}&\mathbb{E}_\sigma\sum_{f\in F}\exp\left(2s\sum_{i=1}^k\sigma_i f(s_i)\right)\\&\le\sum_{f\in F}\prod_{i=1}^k\exp\left(2s^2f(s_i)^2\right)\\&=\sum_{f\in F}\exp\left(2s^2\sum_{i=1}^k f(s_i)^2\right).\end{aligned}$$

Let $\ell^2=\sup_{f\in F}\sum_{i=1}^k f(s_i)^2$, and then

$$\sum_{f\in F}\exp\left(2s^2\sum_{i=1}^k f(s_i)^2\right)\le|F|\exp\left(2s^2\ell^2\right).$$

Thus

$$R_S(F)\le\frac{1}{sk}(\log|F|+2s^2\ell^2),$$

for any $s > 0$. It turns out that to minimize the right hand side of the above equation, we have

$$s = \sqrt{\frac{\log |F|}{2\ell^2}}.$$

Then

$$R_S(F) \leq \frac{\ell}{k}\sqrt{8 \log |F|}.$$

6.3 Discussions of Theorem 3

Theorem 3 can be treated as a special case of Theorem 1 when $m = c$. All the reasoning will not be affected and thus the desired bound follows.