## Lecture 12 Maximum Flow Continued

- Edmonds-Karp algorithm
- Maximum bipartite matching

## Edmonds-Karp Algorithm

- The augmenting path is a shortest path from s to t in the residual network, where each edge has unit weight.
- Time complexity: O(VE<sup>2</sup>)

#### Critical Lemma

#### Lemma 26.8

If the Edmonds-Karp is run on a flow network G=(V, E) with source s and sink t, then for all vertices  $v \in V - \{s,t\}$ , the shortest-path distance  $\delta_f(s,v)$  in the residual network  $G_f$  increases monotonically with each flow augmentation.

### **Proof**

- f: the flow before the first augmentation that decreases some  $\delta_f(s,v)$ .
- f': the flow after the augmentation.
- Let  $v \in V \{s,t\}$  be the vertex with the minimum  $\delta_{f'}(s,v)$  whose distance was decreased by the augmentation, so that  $\delta_{f'}(s,v) < \delta_{f}(s,v)$ .
- $p=s \sim \to u \to v$  be a shortest path from s to v in  $G_f$ , so that  $(u,v) \in E_f$  and  $\delta_f(s,u) = \delta_f(s,v)-1$ .
- We have  $\delta_{f'}(s,u) \ge \delta_{f}(s,u)$
- Now we prove that  $(u,v) \notin E_f$  since otherwise,
- Since  $(u,v) \notin E_f$  and  $(u,v) \in E_f$ , the augmentation must have increased the flow from v to u. As only flows on the shortest path can be increased, then (v,u) is on the shortest path in  $G_f$ , thus we have
- $\delta_f(s,v) = \delta_f(s,u)-1 \le \delta_{f'}(s,u)-1 = \delta_{f'}(s,v)-2$ , contradicts  $\delta_{f'}(s,v) < \delta_f(s,v)$ .
- Such vertex v can not exist.

## Analyze its time complexity

#### • Theorem 26.9

The total number of flow augmentations performed by the Edmonds-Karp algorithm is O(VE).

- critical edge: an edge (u,v) on an augmenting path p with  $c_f(p) = c_f(u,v)$
- There must be at least one critical edge on an augmenting path. After augment the flow, the critical edge disappears from the residual network.
- To prove the theorem, we will show that each edge can become critical at most |V|/2-1 times.

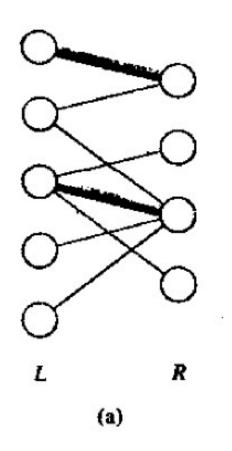
### Proof of the Theorem

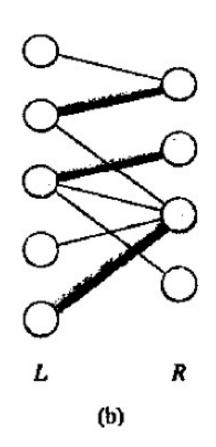
- $(u,v) \in E$ , when (u,v) is critical on an augmenting path for the first time, we have,  $\delta_t(s,v) = \delta_t(s,u) + 1$ .
- Then (u,v) disappears from the residual network. It can not reappear until the flow from u to v is decreased, which occurs only if (v,u) appears on an augmenting path. If f is the flow in G when this event occurs, then we have  $\delta_f(s,u) = \delta_f(s,v)+1$ .
- Since  $\delta_f(s,v) \le \delta_f(s,v)$ , then  $\delta_f(s,u) = \delta_f(s,v) + 1 \ge \delta_f(s,v) + 1 = \delta_f(s,u) + 2$ .
- Consequently, from the time (u,v) becomes critical to the time it next becomes critical, the distance of u increases by at least 2. the distance of u is at most |V|-2. Thus, (u,v) can become critical at most (|V|-2)/2= |V|/2-1 times.
- There are at most O(E) edges and each augmenting path has at least one critical edge.

# Maximum Matching in Bipartite Graphs

- Bipartite graph G=(V,E): If  $V=L \cup R$ , and  $L \cap R = \emptyset$ , and E=E(L,R), that is, each edge with one end in L and the other in R.
- Matching: M⊆E, such that no elements in M share common end points.
- Maximum matching M: for any other matching M', there is  $|M| \ge |M'|$

# Matching and Maximum Matching





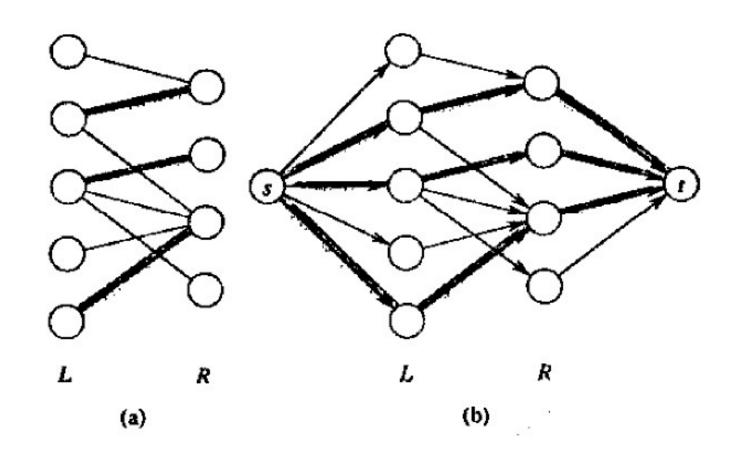
#### Maximum matching in bipartite graph

#### • Problem:

- Input: a bipartite undirected graph  $G=(L \cup R, E)$
- Output: a maximum matching M of G.

#### How?

- Solution: By using maximum flow algorithm.
- Directed graph G'=(V',E'):
  - $V'=\{s,t\} \cup V$
  - $E'=\{(s,u)|u\in L\}\cup\{(v,t)|v\in R\}\cup\{(u,v)|u\in L,v\in R,(u,v)\in E\}$
- Network: G', with source s and sink t, and capacity function f:
  - c(s,u)=1
  - c(v,t)=1
  - c(u,v)=1



## Max. matching VS Max. flow

#### • Lemma 26.10

Let  $G=(V=L\cup R, E)$  be a bipartite graph and G'=(V',E') be its corresponding flow network.

If M is a matching in G, then there is an integer-valued flow f in G' with value |f| = |M|.

Conversely, if f is an integer-valued flow in G, then there is a matching M in G with cardinality |M| = |f|.

#### Proof of the Lemma

- (→) Define f: if  $(u,v) \in M$ , then f(s,u)=f(u,v)=f(v,t)=1 and f(u,s)=f(v,u)=f(t,v)=-1, otherwise f(u,v)=0. f is a flow.
- Each edge  $(u,v) \in M$  corresponds to 1 unit of flow in G' that traverses the path  $s \rightarrow u \rightarrow v \rightarrow t$ , and the paths are disjoint, except for s and t.

Then  $|f| = f(L \cup \{s\}, R \cup \{t\}) = |M|$ 

#### Proof of the Lemma

- ( $\leftarrow$ ) Define M={(u,v):u $\in$ L,v $\in$ R, and f(u,v)>0}. M is a matching.
- Each vertex u has at most one entering edge (s,u), c(s,u)=1. If one unit positive flow does enter, then one unit positive flow must leave. Since f is integer-valued, the one unit flow can enter and leave on at most one edge. Thus if f(s,u)=1, there is exactly one vertex v such that f(u,v)=1, and at most one edge leaving u carries positive flow.
- For every matched vertex  $u \in L$ , f(s,u)=1, and for every edge  $(u,v)\in E-M$ , f(u,v)=0.
- |M| = f(L,R) = f(L,V') f(L,L) f(L,s) f(L,t) = f(s,L) = f(s,V') = |f(s,V')| = |f(

## Why integer-valued flow

#### • Theorem 26.11

If the capacity function c takes on integral values, then the maximum flow produced by Ford-Fulkerson method has the property that |f| is integer-valued. Moreover all f(u,v) is an integer.

# Correctness and Time Complexity

- Corollary 26.12: |M| = |f|. From Lemma 26.10.
- Time complexity: O(VE) why?