

I N D E X

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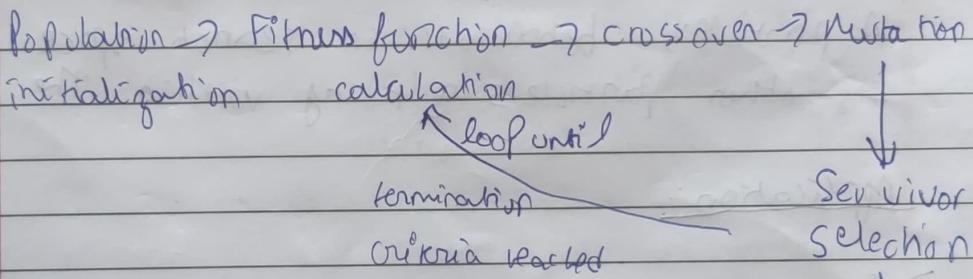
Algorithm - I -

Genetic Algorithm for optimization problem

GA (Genetic Algorithm) is a method for solving both constrained & unconstrained optimization problems.

GA is a natural selection process that mimics biological evolution.

GA generates a population of points at each iteration. The best point in the population approaches an optimal solution. Over successive generations, the population evolves to an optimal solution.



Applications:

- 1) Task scheduling - GA algorithm is used to determine optimal solution based on certain constraints.
- 2) Financial markets - finding an optimal combination of parameters that can affect trader or market rules.
- 3) Robotics - Generating optimal routes for a robot so that it uses least amount of resources to get to the desired position.

Algo 2

Particle swarm optimization Algorithm

PSO is a population-based algorithm for search

It is a simulation to discover the pattern in which birds fly & their formations and grouping during flying activity

In PSO, every individual is considered to be a particle in some high-dimen search space
PSO is inspired by psychological tendencies of people to tend to copy from other people's success

A particle's behaviour in search space is influenced by other particle's acting within the swarm.

Application:

- 1) Energy storage optimization
- 2) Scheduling electrical loads
- 3) Flood control & routing
- 4) Water quality monitoring
- 5) Disease detection & classification

Also 3

Ant Colony Optimization for Travelling Salesman problem

Protocols used by ants to communicate and plan routes. They do so by coordinating through pheromone message (chemical trails)

Procedure Ant Colony Optimization :

Initialize necessary parameters and pheromone trails

while

do:

Generate ant population

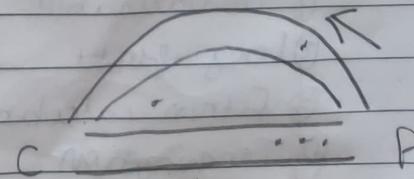
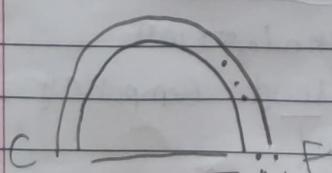
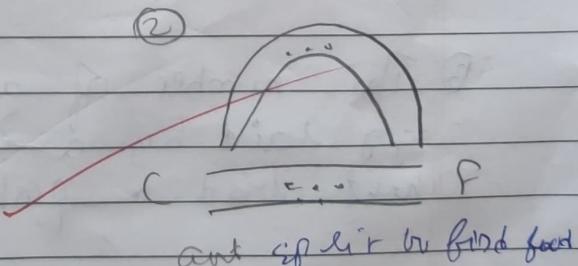
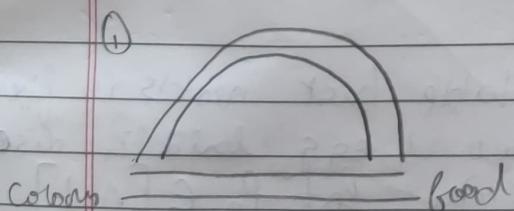
calculation of fitness of each ant
find best solution through selection method

Update pheromone trail

end while

end procedure

To this, TSP can be applied



shortest path reach
first & increase pheromones

more ants returning faster
to C because more
pheromones

Applications:

- (1) Scheduling problems
- (2) Image processing
- (3) Data mining

Algorithm 4 - Cuckoo search (CS)Introduction:

• CS is an evolutionary optimization algorithm & was inspired by species of bird - cuckoo & their aggressive reproduction strategy

- They lay their eggs in nests of others host birds & host bird recognizes eggs as not their own, they will throw it away or build a new one

• Rules

- ① Each cuckoo lays 1 egg at a time and randomly chooses nest
- ② Best nest with highest quality eggs will carry over to next generation
- ③ The number of available host nest's is fixed
egg laid by a cuckoo & egg laid in discovered host bird a probability $P \in [0, 1]$

Steps

- ① Initialization
- ② Levy flight
- ③ Fitness calculation
- ④ Termination

Applications

- ① Optimization
- ② Cloud Computing
- ③ IoT
- ④ Pattern Recognition

Algorithm 5 : Grey wolf optimizer (GWO)

Introduction :-

- Nature inspired metaheuristic based on the behaviour of pack of wolves to find optimal solution
- Hunt in large packs & rely on cooperation among individual wolves
 - (1) Social hierarchy (2) hunting mechanism
- Complex Social hierarchy includes delta, gamma, beta & alpha values representing best solution candidates at each iteration
- To find best answer, the hunting behaviour of grey wolves are picked. The beta & gamma wolves follow the alpha wolf's lead where they catch their meal, delta wolf attacks first.

Workflow :

Initialization → Fitness Evaluation → Greasing Prey

↓

Stopping ← Check Criterion ← Update Position ← Attack

↓

Output

Application :

- (1) Data Mining
- (2) Image & signal processing
- (3) Energy management
- (4) Machine learning

Algorithm 6: Parallel Cellular Algorithm.

Introduction:

- Parallel cellular algorithm are computation model based on the idea of dividing a problem into smaller units or cells that operate simultaneously & often independently
- Inspired by cellular automata, where the cells interact with their neighbours based on local rules
- Parallelization in cellular algorithm is achieved by distributing these cells across multiple processing units allowing for concurrent execution of many operations

Two main concepts

- ① Cellular automata
- ② Parallel processing

Applications:

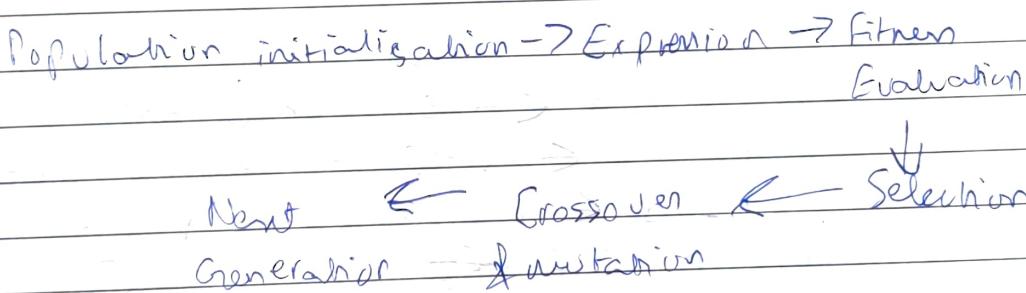
- ① Image Processing
- ② Fluid dynamics
- ③ Biological System
- ④ Physics simulation

Algorithm 7: Optimization via Genetic Expressions Algorithms

Introduction:

- GEA is inspired by biological processes, particularly,
- GEA's optimize problems by mimicking the way genes in DNA express the metric to develop specific traits in organisms.

Optimization Process:



Application:

- (1) Machine learning
- (2) Data mining
- (3) Resource allocations
- (4) Engineering optimization

Algorithm for Genetic Algorithm:

function objective(x):

return ~~$x[0]^2 + 2 * x[0] + 1 + x[1] * x[2]$~~

function initialize_population(bounds, n)

return random uniform from bound[0], bound[1]

function evaluate_fitness(population)

return objective(index) for index in population

be

function roulette_wheel_selection(population, scores)

total_fitness \leftarrow sum of (scores)

probabilities \leftarrow 1 - score/total_fitness for each score

select_index \leftarrow random choice p/sum(p)

return population[select_index]

function crossover($p1, p2, \alpha$)

if

if random() < α

return

return offspring = $\alpha * p1[0] + (1-\alpha) * p2[0]$

function mutation(individual, bounds, rate)

if random() < rate

return random([bound[0], bound[1]])

return individual

function genetic_algorithm(bounds, n_iter, n_pop, rate)

population \leftarrow initialize_population(bounds, n_pop)
 best, best_eval \leftarrow pop[0], objective(pop[0])

for gen in n_iter:

scores \leftarrow evaluate_fitness(population)

for each n_pop:

if score[index] < best_eval:

best, best_eval = population[i], score[i]

print new best func[index]

child create children

for each n_pop:

p1 \leftarrow roulette-wheel_selection(population, scores)

p2 \leftarrow roulette-wheel_selection(population, scores)

offspring \leftarrow crossover(p1, p2)

offspring \leftarrow mutation(offspring, bound, rate)

append offspring to children

~~Population \leftarrow children~~

Applications

1. Optimization Problem: ~~Freiburg, 24/10/24~~

TSP, Scheduling Problem

2. ML: Hyperparameter tuning, Feature selection

3. Engineering design: Structural optimization

Algorithm for Particle Swarm -

Function rastrigin function (x)

$n \leftarrow \text{length}(x)$

$A \leftarrow \text{constant}$,

return $A + n + \sum (x^2 - A \cos(2\pi * x))$

Particle class:

class constructor to initialize particle pos, vel
(self, dimension, min, max)

self.position \leftarrow position random(min, max)

self.velocing \leftarrow random velocity (-1, 1, dim)

self.best_pos \leftarrow copy of position

~~fitness~~

function evaluate (self, fitfun, rastrigin function)

self.fitness \leftarrow fitfun(self.pos)

if self.fitness $<$ self.best_fitness
exchange the fitnesses

function PSO(fitfun, func, dim, population_size, max_iter, min_val, max_val, w=0.6, c1=1.5, c2=1.5)

for i in range(population_size):

swarm = [Particle(dim, min_val, max_val)]

for gen in range(maximum Iteration):

avg_best_particle_fitness = 0

for i in range(population size):

swarm[i].velocity = confuse velocity
using the constants

swarm[i].pos = updated position

swarm[i].evaluate(fitness func)

if swarm[i].fitness < best_fitness_swarm:
update global best position

avg_best_particle = swarm[i].best_fitness

avg_best_particle /= N

~~return best_pos_swarm, best_fitness_swarm,
avg_particle_fitness,
max_iter~~

Applications:

- Energy Storage Optimization
- Scheduling Electrical Loads
- Flood Control & Routing

Ant Colony Optimization

Algorithm:

function Input - city coordinates () :

Input: number of cities, n and x and y coordinates
 Output: 2D array of city coordinates

function calculate - Euclidean distance (point1, point2) :

Input: Point1, Point2

Output: distance b/w point1 and point2

distance \leftarrow square root of $(\text{Point1} - \text{Point2})^2$ for each coordinate

function construct - solution (n - points, pheromone (points, alpha), beta) :

visited \leftarrow list of false values of length n points
 current_point \leftarrow random starting city index
 Set visited[current_point] \leftarrow True
 path \leftarrow list containing current_point
 path_length \leftarrow 0

while there are unvisited cities:

unvisited \leftarrow indices of cities not visited
 probabilities \leftarrow array of zeroes

for each unvisited city:

pheromone_value \leftarrow Phermone [current_point, unvisited_city]
 squared to alpha

distance_value \leftarrow distance (points[current_point],
 points[unvisited_point])
 * beta

Probabilities $[i] \leftarrow$ pheromone val / distance val

probabilities \leftarrow sum of probabilities / probability val

next point \leftarrow random (unvisited, probability)

append next point

path length \leftarrow path length + distance

set visited of next point to true and
update current point \leftarrow next point

return path, path-length

def function update-pheromone (pheromone, path,
path-lengths, evaporation-rate, I):

Evaporate all pheromones by setting pheromone
 \leftarrow pheromone * evaporation
 \sim rate

for each path in paths:

for each pair of consecutive cities in
 the path:

increment pheromone

increment pheromone for the last to first city in the
 path to close the loop

function ant_colony_optimizing(
 points, n_ants, n_iterations,
 beta, evaporation_rate):

n_points <= length of points
 minimize_phenomenon <= matrix of ones with
 shape(n_points, n_points)

best_path = None
 best_path_length = infinite

for each iteration in range(n_iterations):

path = empty list
 path_lengths = empty list

for each ant in range(n_ants):

call construct_path_solution() to get
 path and path_length

Apped path to paths and path lengths
 if path_length < best_path_length:

best_path = path

best_path_length = path_length

Cell Update Phenomenon() with phenomena_update_rate

~~Print current iteration and best path length~~

Applications:

- Logistics & Supply Chain Problems
- Vehicle Routing Problem
- File communication in Network security

Algo - 4 - Cuckoo Search

Algorithm

objective function (x):

$$\text{return } x[0]^{**2}$$

levy-flight-function ($\text{num}, \beta = 1.5$):

$$\sigma_u \leftarrow (\gamma(1+\beta) * \sin(\pi * \beta)) / 2$$

$$\gamma((1+\beta)/2) * \beta + (2)^{(\beta-1)/2} \sqrt{\beta}$$

$$u \leftarrow \text{random.normal}(0, \sigma_u, \text{num})$$

$$v \leftarrow \text{random.normal}(0, 1, \text{num})$$

return u

$$|v|^{1/\beta}$$

Cuckoo search (iter num-nests , pa = 0.25):

$$\text{num-dim} \leftarrow 1$$

$$\text{num-nests} \leftarrow \text{random}(\text{num-nests}, \text{num-dim}) * 10^{-5}$$

fitness \leftarrow objective function (num-nests)

best_nest \leftarrow nests [minimum (fitness)]

best_fitness \leftarrow minimum (fitness)

for i in range (0, iter):

for i in range (num-nests):

new_nest \leftarrow nests[i] + levy_flight (num-dim)

new_fitness \leftarrow objective function_1d (new_nest)

if new_fitness < fitness[i]:

nests[i] \leftarrow new_nest

fitness[i] \leftarrow new_fitness

worst_nests \leftarrow sort(fitness)[-int(pa * num_nests):]

for j in worst_nests:

nests[j] \leftarrow random(num_dim) * 10^-5

fitness[j] \leftarrow objective_function_id(nests)

current_best_idx \leftarrow minimum(fitness)

current_best_fitness \leftarrow fitness[current_best_idx]

return best_nest, best_fitness

~~Feb 21/11/24~~

Applications :

- WiFi Network
- Cloud Computing
- IoT

GREY WOLF OPTIMIZATION

function Initialize_wolves (search_space, num_wolves)

dimensions \leftarrow length(search_space)

wolves \leftarrow zeros((num_wolves, dimensions))

for i in range(num_wolves):

wolves[i] = np.random(search_space[:, 0],
search_space[:, 1])

return wolves

function fitness_function(x):

return np.sum(x ** 2)

function gwo_algorithm (search_space, num_wolves,
max_iter):

dimension \leftarrow length(search_space)

wolves \leftarrow initialize_wolves(search_space, num_wolves)

alpha_wolf \leftarrow np.zeros(dimensions)

beta_wolf \leftarrow np.zeros(dimensions)

gamma_wolf \leftarrow zeros(dimensions)

alpha_fitness \leftarrow float('infinity')

beta_fitness \leftarrow float('infinity')

gamma_fitness \leftarrow float('infinity')

beta_fitness \leftarrow float('infinity')

for iteration in range(max_iterations):

a \leftarrow 2 - (iteration/max_iterations) * 2

print(f'iteration {i}/{max_iterations}')

for i in range(num_wolves):

fitness ← fitness_function(wolves[i])

if fitness < alpha_fitness:

gamma_wolf ← beta_wolf.copy()

gamma_fitness ← beta_fitness

beta_wolf ← alpha_wolf.copy()

beta_fitness ← alpha_fitness

alpha_wolf ← wolves[i].copy()

alpha_fitness ← fitness

elif fitness < beta_fitness:

gamma_wolf ← beta_wolf.copy()

gamma_fitness ← beta_fitness

beta_wolf ← wolves[i].copy()

beta_fitness ← fitness

print(f'best {alpha_fitness}')

if alpha_fitness < best_fitness:

best_fitness ← alpha_fitness

for i in range(num_wolves):

for j in range(dimensions):

r1 ← np.random.random()

r2 ← np.random.random()

A1 ← a * a + r1 - a

C1 ← 2 * r2

D_alpha ← np.abs(C1 * alpha_wolf[i] - a)

wolves[i][j]

$$x_j \leftarrow \text{alpha_wolf}[j] - A^j * D_{\text{alpha}}$$

$$r_1 \leftarrow \text{np.random.random}()$$

$$r_2 \leftarrow \text{np.random.random}()$$

$$f_2 \leftarrow f_2 + a * r_1 - a$$

$$c_2 \leftarrow 2 * r_2$$

$$D_{\text{beta}} \leftarrow \text{np.abs}(c_2 * \text{beta_wolf}[j] - \text{wolves}[i, j])$$

$$x_2 \leftarrow \text{beta_wolf}[j] - p_2 + D_{\text{beta}}$$

$$r_1 \leftarrow \text{np.random.random}()$$

$$r_2 \leftarrow \text{np.random.random}()$$

$$p_3 \leftarrow 2 * a * r_1 - a$$

$$c_3 \leftarrow 2 * r_2$$

$$D_{\text{gamma}} \leftarrow \text{np.abs}(c_3 * \text{gamma_wolf}[j] - \text{wolves}[i, j])$$

$$x_3 \leftarrow \text{gamma_wolf}[j] - p_3 + D_{\text{gamma}}$$

$$\text{wolves}[i, j] \leftarrow (x_1 + x_2 + x_3) / 3$$

$$\text{wolves}[i, j] \leftarrow \text{np.clip}(\text{wolves}[i, j], \text{search space}[j, 0],$$

$$\text{search space}[j, 1])$$

print({alpha_wolf})

print({best_fitness})

search_space $\leftarrow \text{np.array}([-5, 5], [-5, 5])$

num_wolves ← 10

max_iterations ← 100

optimal_solution ← gwo_algorithm (Search space,
num_wolves,
max_iterations)

Print(optimal_solution)

Qasim
Date: 28/11/24

Applications:

- Signal Processing
- Energy Design Optimization
- Control Systems
- Vehicle Routing

PARALLEL CELLULAR ALGORITHMS

Step 1: Function fitneu_func

Define fitneu function

$$f(n) = \sum_{i,j} n_i^j$$

Step 2: Initialize Parameters

Set grid_size = (rows, cols)

Set dimensionality of the search space

Define search space bounds : minx and maxx

Set number of iterations : max_iterations

Step 3: Initialize Population

Create a 3D grid population of size (rows, cols, dim)
to store positions of cells

For each (i, j) in grid:

rand initialize [minx, maxx]

Step 4: Evaluate Fitness

Create a ~~fitneu~~ grid of size (rows, cols)

For each cell (i, j) in grid:

compute fitness value using fitneu func f(position)

Step 5: Update States

Define a function to get the neighbours of a cell (i, j)

For each (i, j) :

identify best neighbour

update cell position to move towards
of best neighbour

- Add a small random perturbation to avoid
stagnation

• Clip the position to ensure it stays within bound.
(min, max)

Step 6: Iteration

1. Repeat the following for max_iterations:

. Evaluate fitness of current position

For each (i, j) :

update cell position based on neighbour

Replace old population with new updated population

Print best fitness value at each iteration.

Step 7: Output best solution

1. find cell with minimum fitness value in grid
2. Output position and corresponding fitness value
of this cell

Application

- Image Processing
- Machine Learning
- Travelling Salesman
- Fluid dynamics
- Heat diffusion Atz Simulation

OPTIMIZATION VIA GENE EXPRESSION ALGORITHM

Algorithm:

Step 1: Define the fitness function

$$f(x) = x^2$$

Step 2: Initialize parameters

Population size, num-genes, lower-bound, upper bound, max generations, mutation-rate, crossover rate

Step 3: Initialize population

- Generate a population of random genetic sequences.
- Each individual has num-genes genes.
- Gene value distributed bw [lower bound, upper bound]

Step 4: Evaluate fitness

For each individual in population:

Calculate its fitness using $f(x)$

Store all the fitness values in an array

Step 5: Perform Selection

1. Compute the selection probability for each individual based on fitness.
 - Normalize fitness values to probabilities

2. Roulette wheel selection to choose a subset of individuals for reproduction.

Population-size // 2 individuals selected

Step 6. Perform Crossover

- For each pair of selected parents:
 - with crossover-rate probability;
 - ↳ choose random crossover point in genes;
 - swap genes after the crossover point to get two offspring.
 - Otherwise:
 - Retain parents without changes.

Add the offspring to the new population

Step 7. Perform Mutation

- with probability mutation-rate:
 - select random gene and assign it in a new random-value in ^{lower}_{upper} bounds

Mutated values remain within bounds

Step 8. Track Best Solution (lowest fitness) and smallest variance

Step 9. Repeat for all generations (Repeat step 4)

Step 10. Output the Results

Applications:

- Engineering Optimizations
- Data Analysis
- Machine Learning
- Bioinformatics
- DNA sequence alignment

Feb 22
Sandeep Patel