



Bahria University
Discovering Knowledge

Computer Architecture and Logic Design (CALD)

Lecture 03

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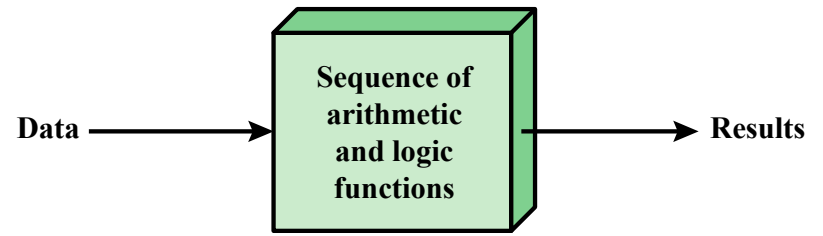
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Computer Function and Interconnection

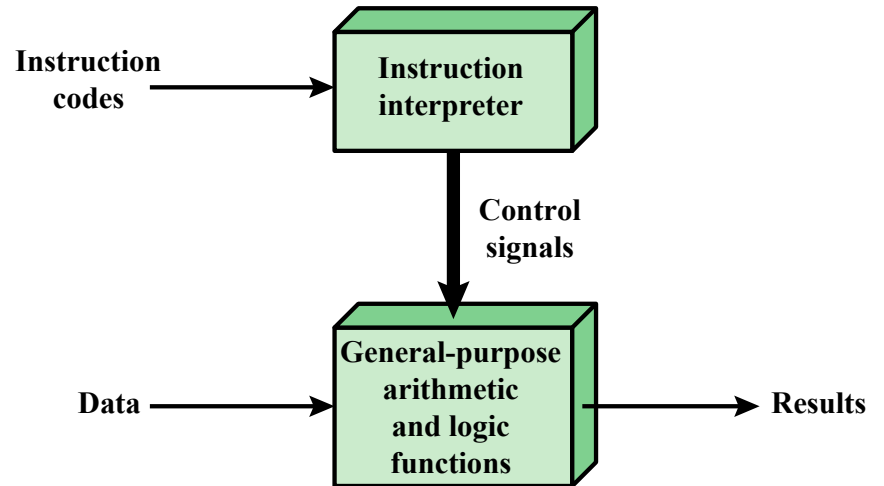
Computer Components

- Contemporary computer designs are based on concepts developed by John von Neumann at the Institute for Advanced Studies, Princeton
- Referred to as the *von Neumann architecture* and is based on three key concepts:
 - Data and instructions are stored in a single read-write memory
 - The contents of this memory are addressable by location, without regard to the type of data contained there
 - Execution occurs in a sequential fashion (unless explicitly modified) from one instruction to the next
- *Hardwired program*
 - The result of the process of connecting the various components in the desired configuration

Hardware and Software Approaches



(a) Programming in hardware



(b) Programming in software

Figure 3.1 Hardware and Software Approaches

Software

- A sequence of codes or instructions
- Part of the hardware interprets each instruction and generates control signals
- Provide a new sequence of codes for each new program instead of rewiring the hardware

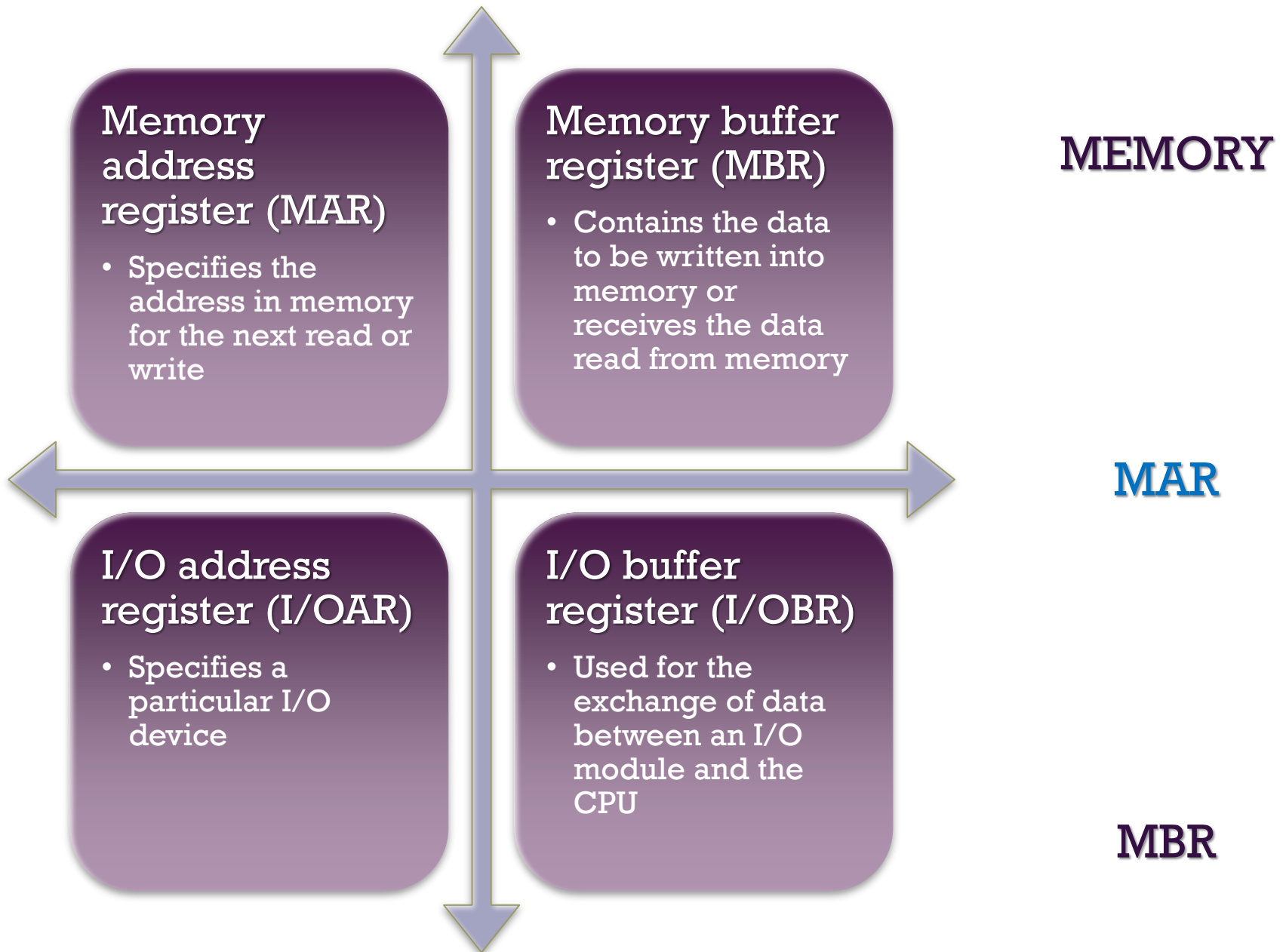
Major components:

- CPU
 - Instruction interpreter
 - Module of general-purpose arithmetic and logic functions
- I/O Components
 - Input module
 - Contains basic components for accepting data and instructions and converting them into an internal form of signals usable by the system
 - Output module
 - Means of reporting results

Software

I/O
Components





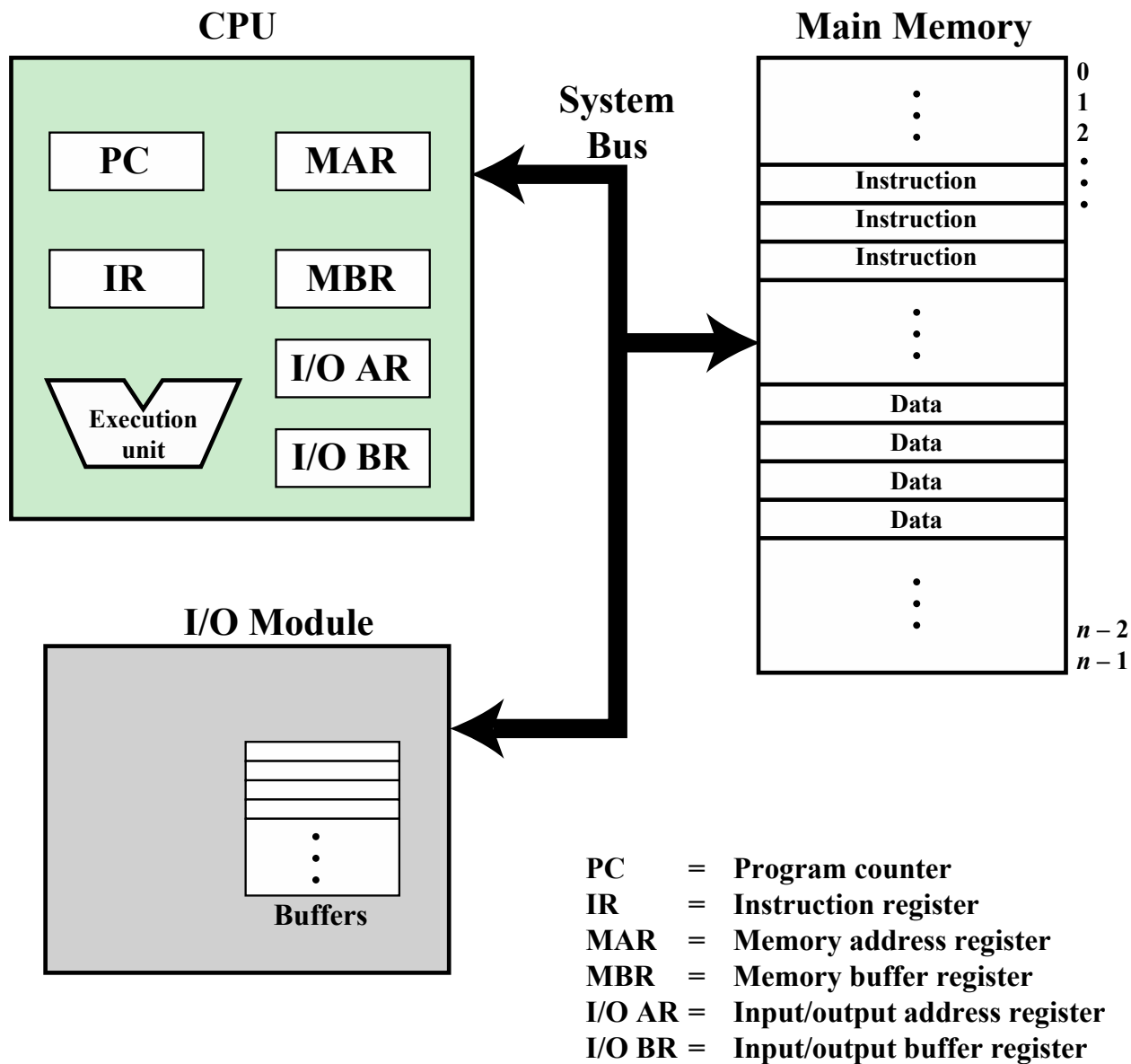


Figure 3.2 Computer Components: Top-Level View

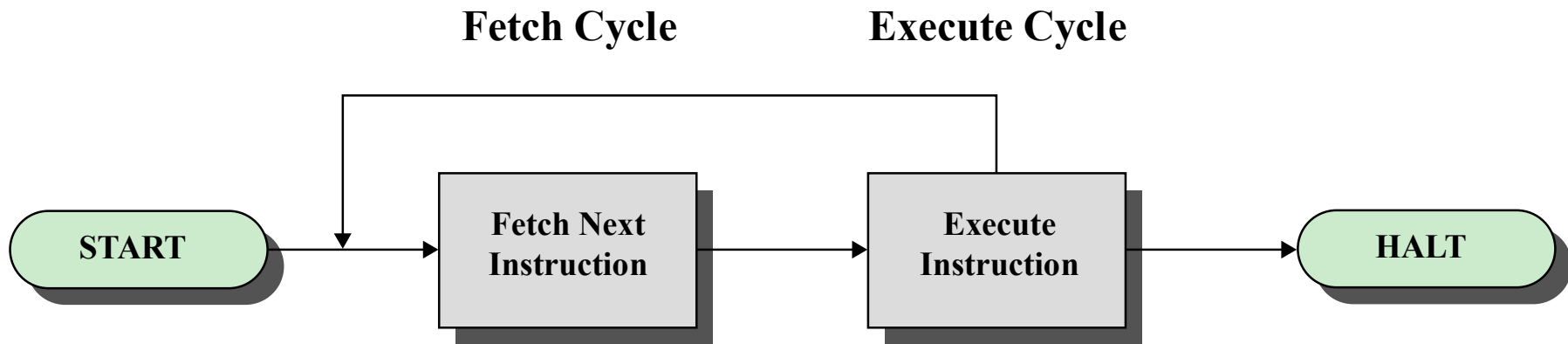
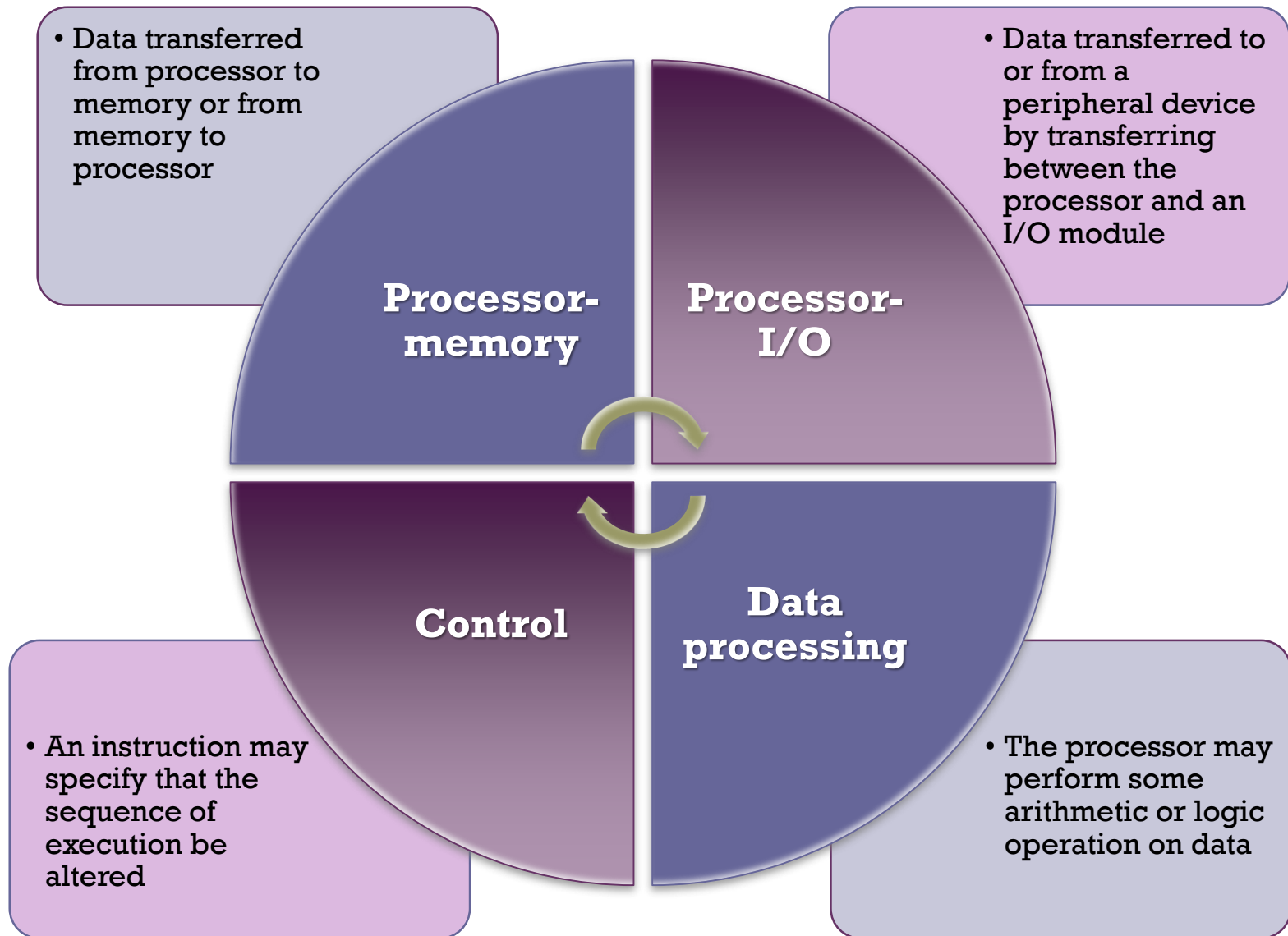


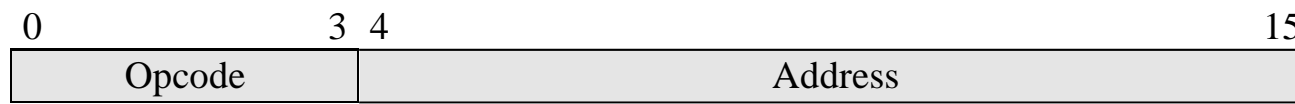
Figure 3.3 Basic Instruction Cycle

Fetch Cycle

- At the beginning of each instruction cycle the processor fetches an instruction from memory
- The program counter (PC) holds the address of the instruction to be fetched next
- The processor increments the PC after each instruction fetch so that it will fetch the next instruction in sequence
- The fetched instruction is loaded into the instruction register (IR)
- The processor interprets the instruction and performs the required action

Action Categories





(a) Instruction format



(b) Integer format

Program Counter (PC) = Address of instruction
 Instruction Register (IR) = Instruction being executed
 Accumulator (AC) = Temporary storage

(c) Internal CPU registers

0001 = Load AC from Memory
 0010 = Store AC to Memory
 0101 = Add to AC from Memory

(d) Partial list of opcodes

Figure 3.4 Characteristics of a Hypothetical Machine

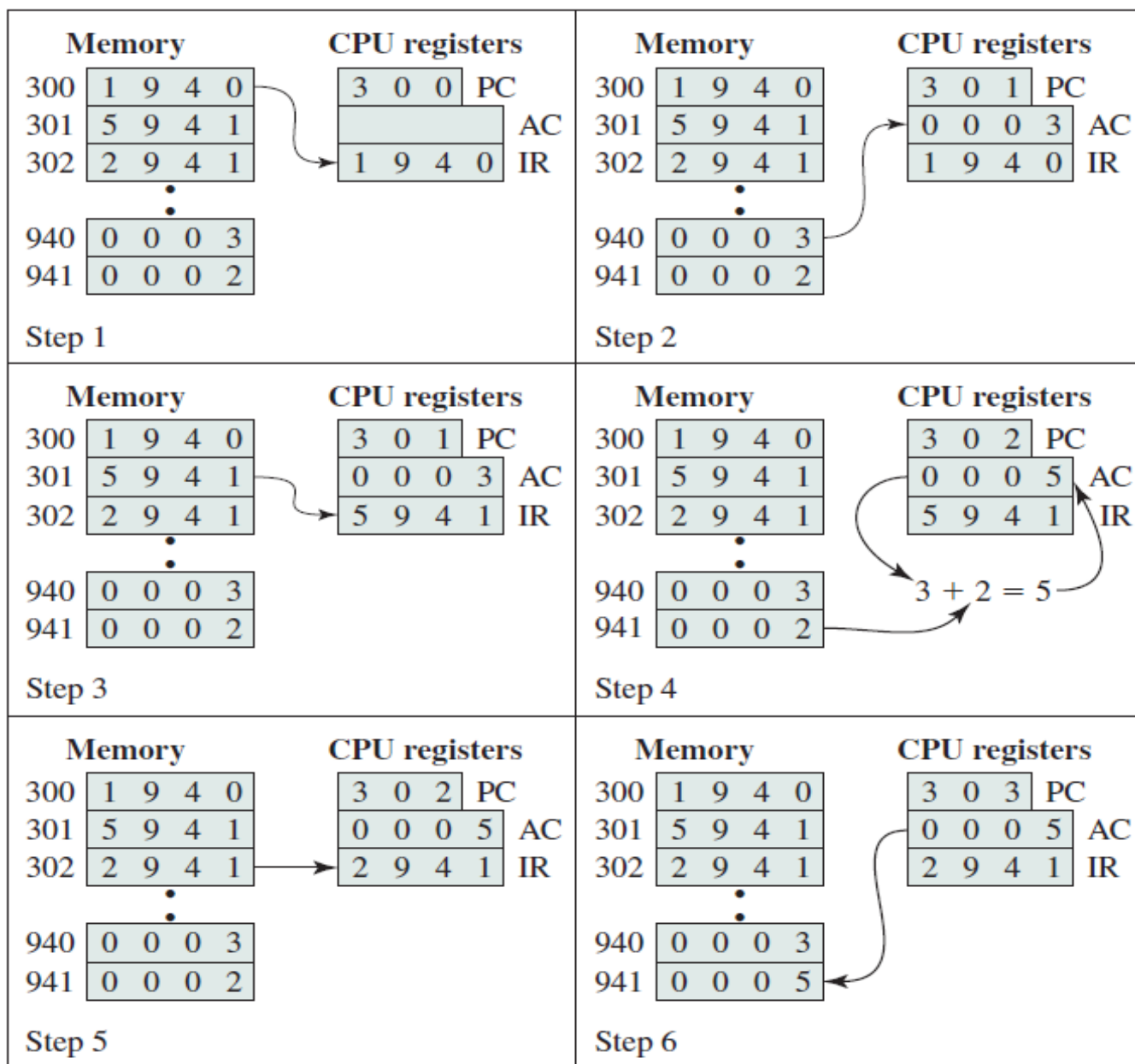


Figure 3.5 Example of Program Execution (contents of memory and registers in hexadecimal)

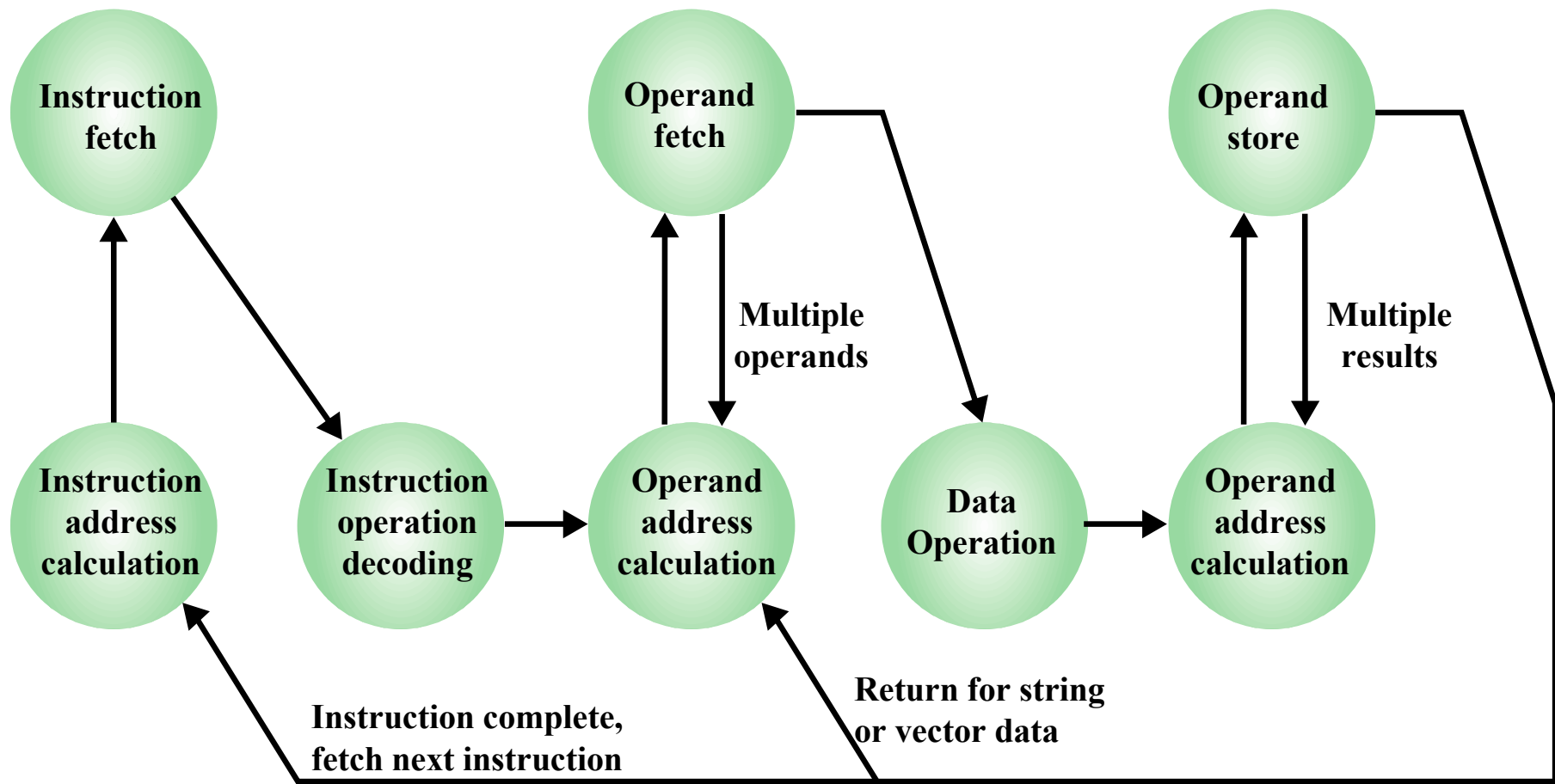


Figure 3.6 Instruction Cycle State Diagram

Classes of Interrupts

Program	Generated by some condition that occurs as a result of an instruction execution, such as arithmetic overflow, division by zero, attempt to execute an illegal machine instruction, or reference outside a user's allowed memory space.
Timer	Generated by a timer within the processor. This allows the operating system to perform certain functions on a regular basis.
I/O	Generated by an I/O controller, to signal normal completion of an operation, request service from the processor, or to signal a variety of error conditions.
Hardware failure	Generated by a failure such as power failure or memory parity error.

Table 3.1

Classes of Interrupts

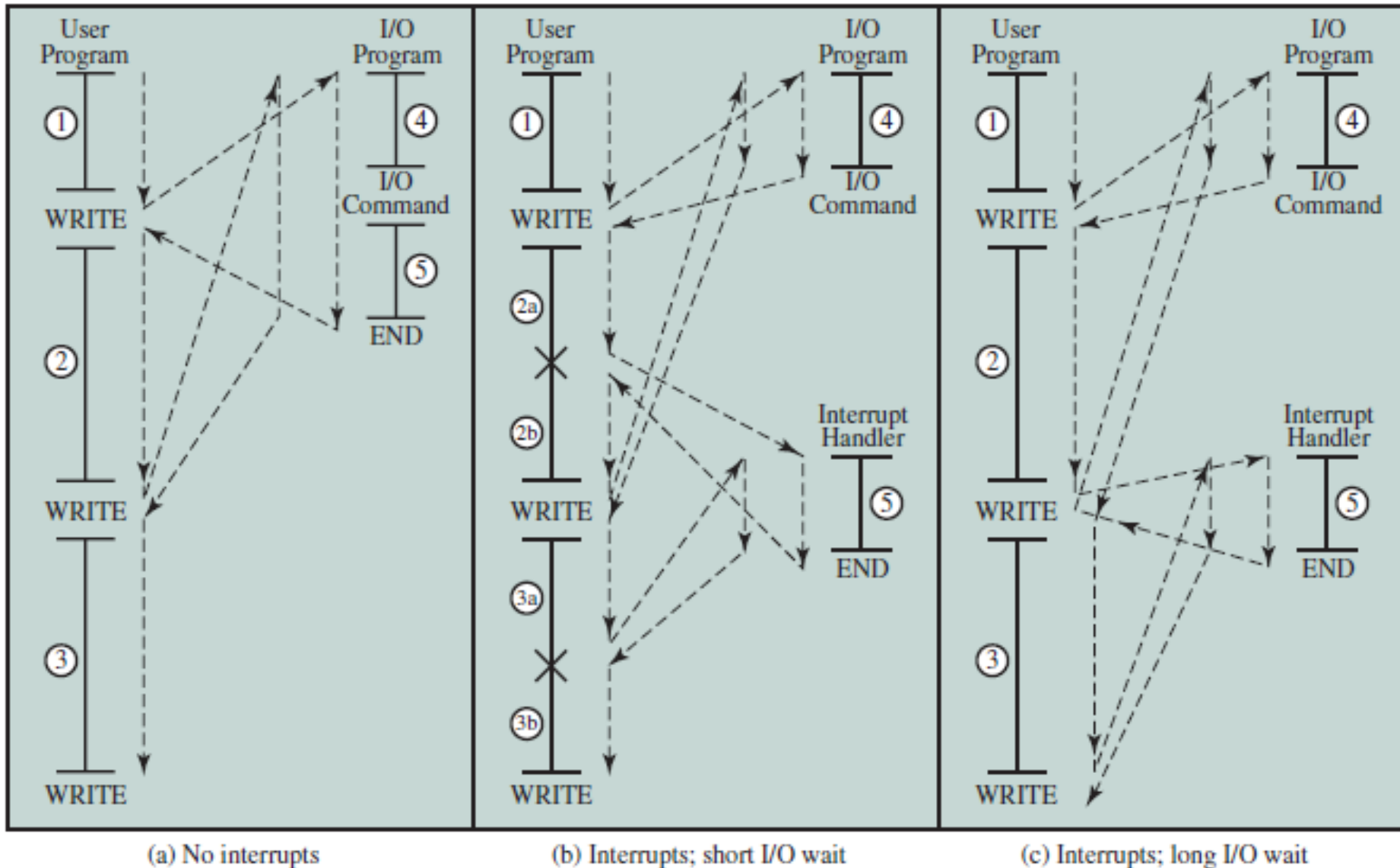


Figure 3.7 Program Flow of Control without and with Interrupts

Transfer of Control via Interrupts

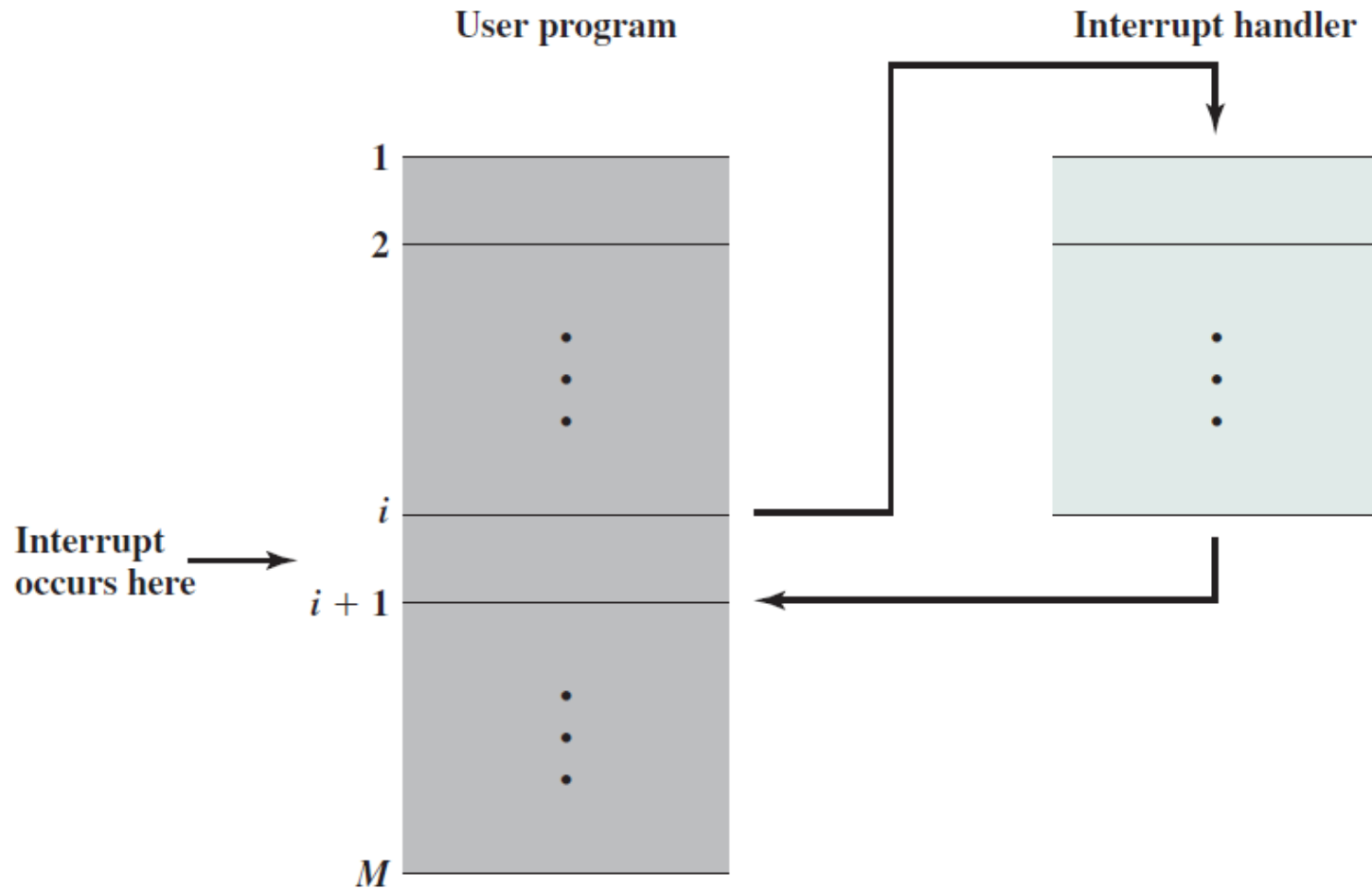


Figure 3.8 Transfer of Control via Interrupts

Instruction Cycle with Interrupts

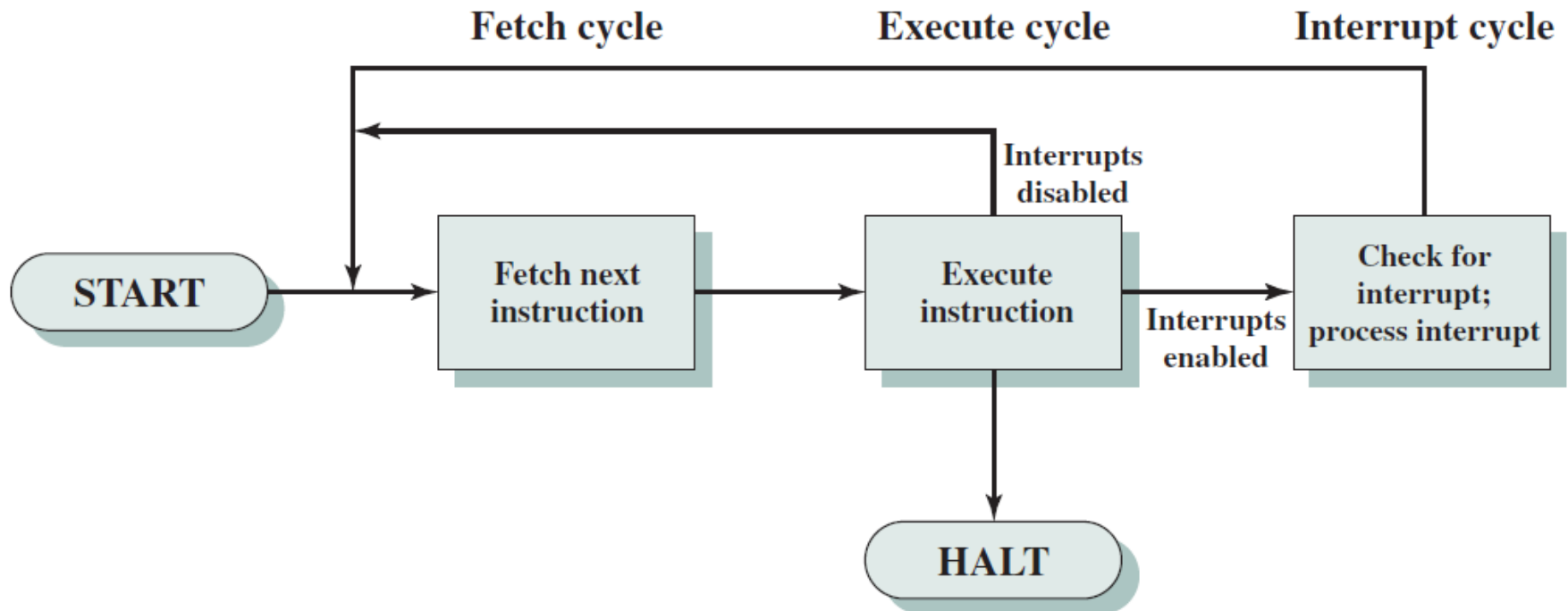
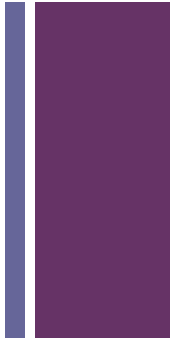


Figure 3.9 Instruction Cycle with Interrupts



Instruction Cycle with Interrupts



- Added to instruction cycle
- Processor checks for interrupt
 - Indicated by an interrupt signal
- If no interrupt, fetch next instruction
- If interrupt pending:
 - Suspend execution of current program
 - Save context
 - Set PC to start address of interrupt handler routine
 - Process interrupt
 - Restore context and continue interrupted program

Instruction Cycle with Interrupts

- If any interrupt occurs the processor does the following:
 - It suspends execution of the current program being executed and saves its **context**.
 - This means saving the address of the next instruction to be executed (current contents of the program counter) and any other data relevant to the processor's current activity.
 - It sets the program counter to the starting address of an **interrupt handler routine**.
- The interrupt handler program is generally part of the operating system. Typically, this program determines the nature of the interrupt and performs whatever actions are needed.

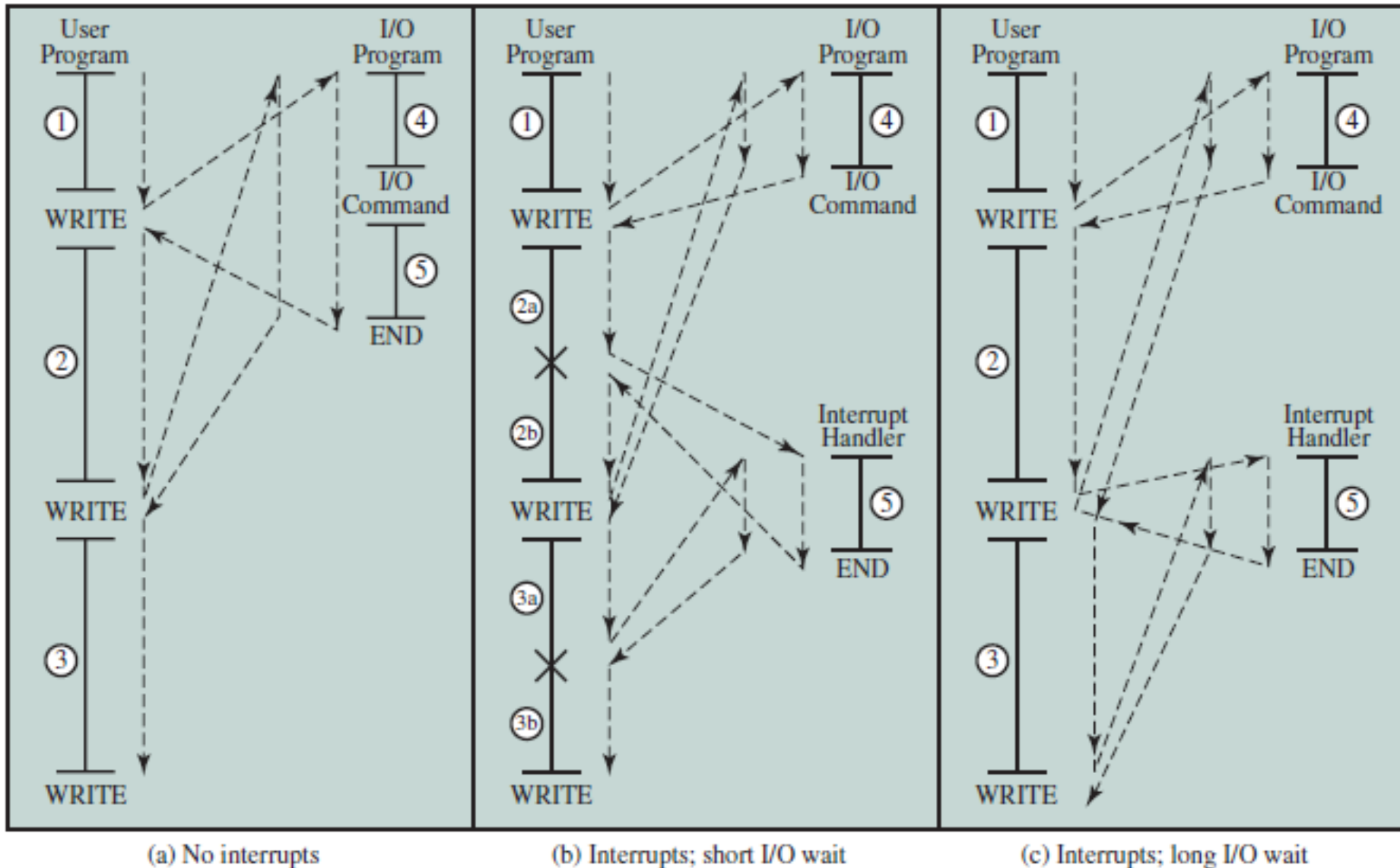


Figure 3.7 Program Flow of Control without and with Interrupts

Program Timing

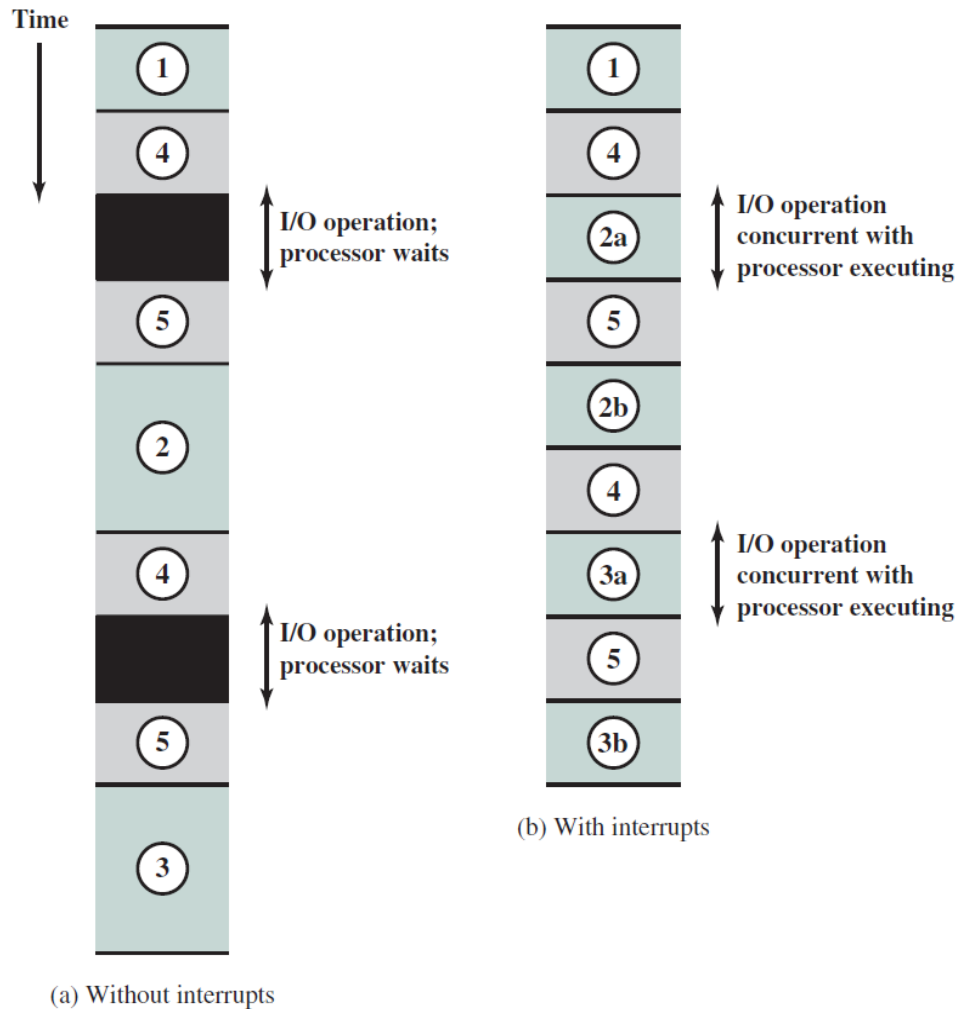


Figure 3.10 Program Timing: Short I/O Wait

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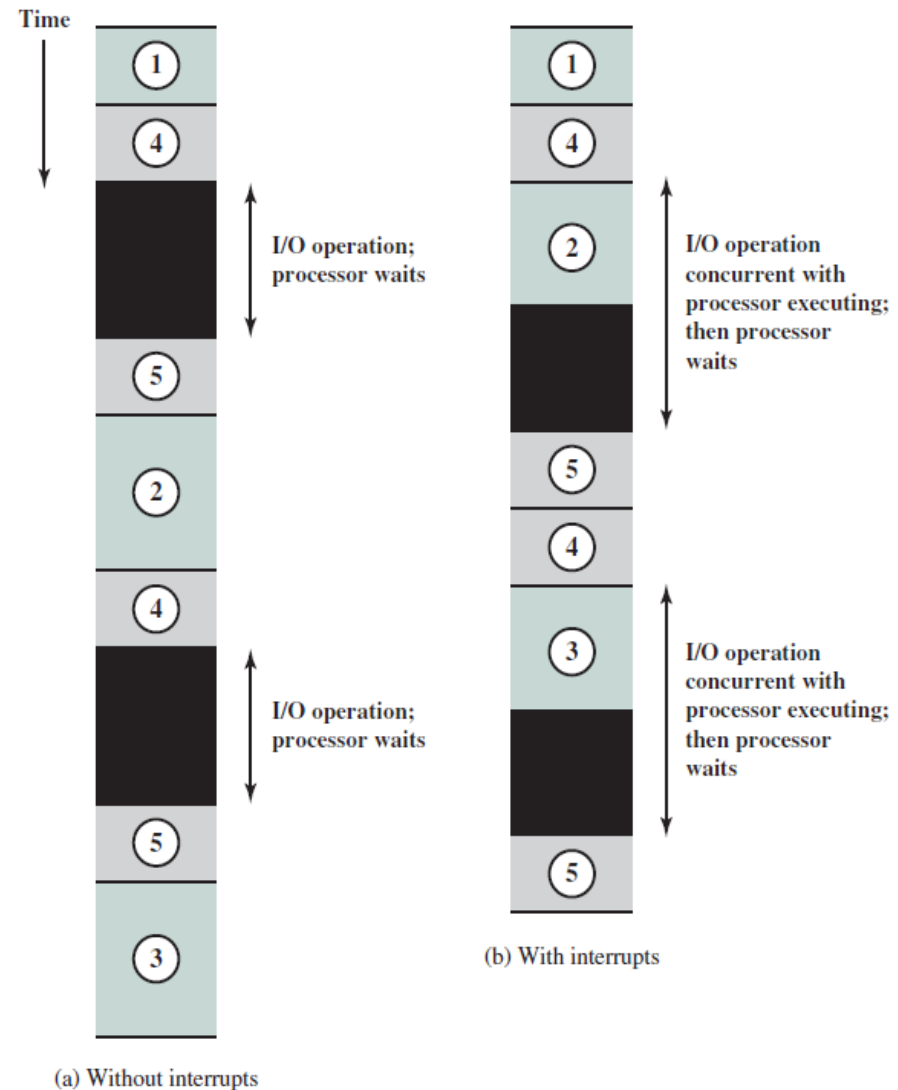


Figure 3.11 Program Timing: Long I/O Wait

Instruction Cycle with Interrupts

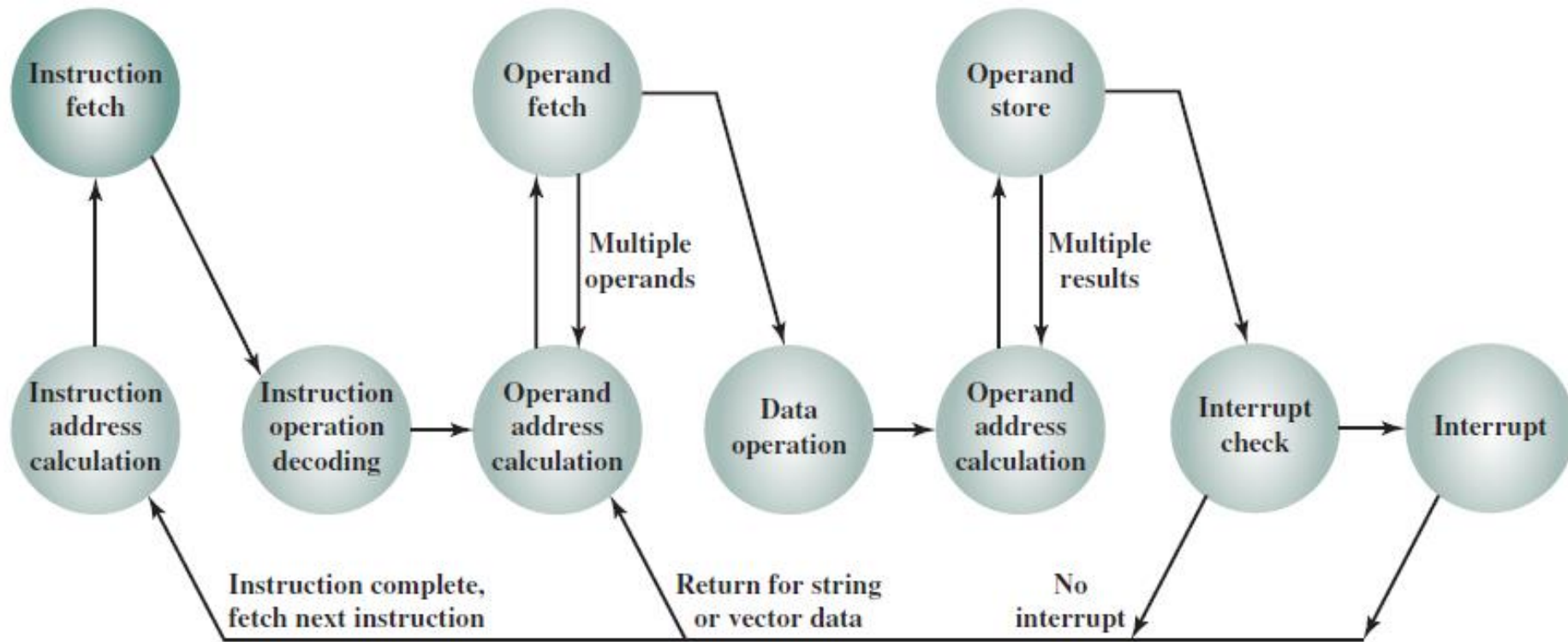
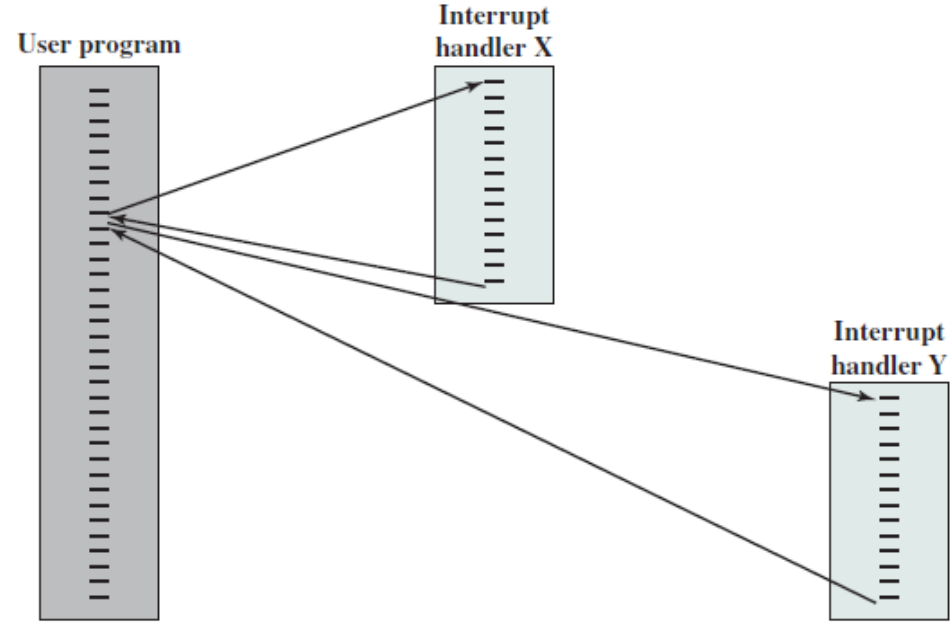
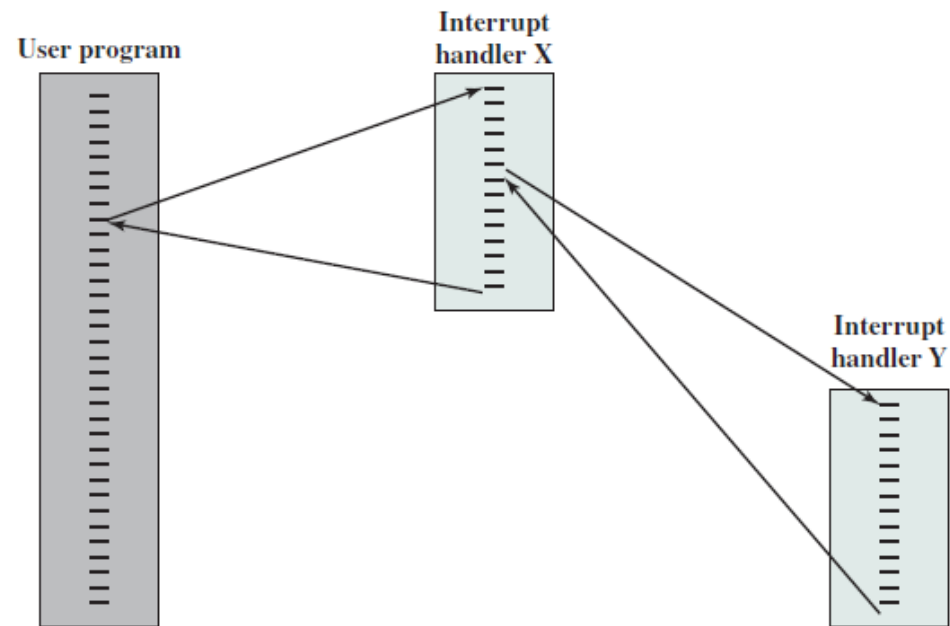


Figure 3.12 Instruction Cycle State Diagram, with Interrupts

Multiple Interrupts



(a) Sequential interrupt processing



(b) Nested interrupt processing

Multiple Interrupts

■ Sequential Interrupt Processing

- Disabled interrupt:
- User program executing -> interrupt occurs -> disable other interrupts -> execute interrupt handler routine -> enable interrupts -> check for additional interrupts -> user program.
- Drawback: No priority for time-critical needs.

■ Nested Interrupt Processing

- Define priorities for interrupts
- Allow an interrupt of higher priority to cause a lower-priority interrupt handler to be itself interrupted

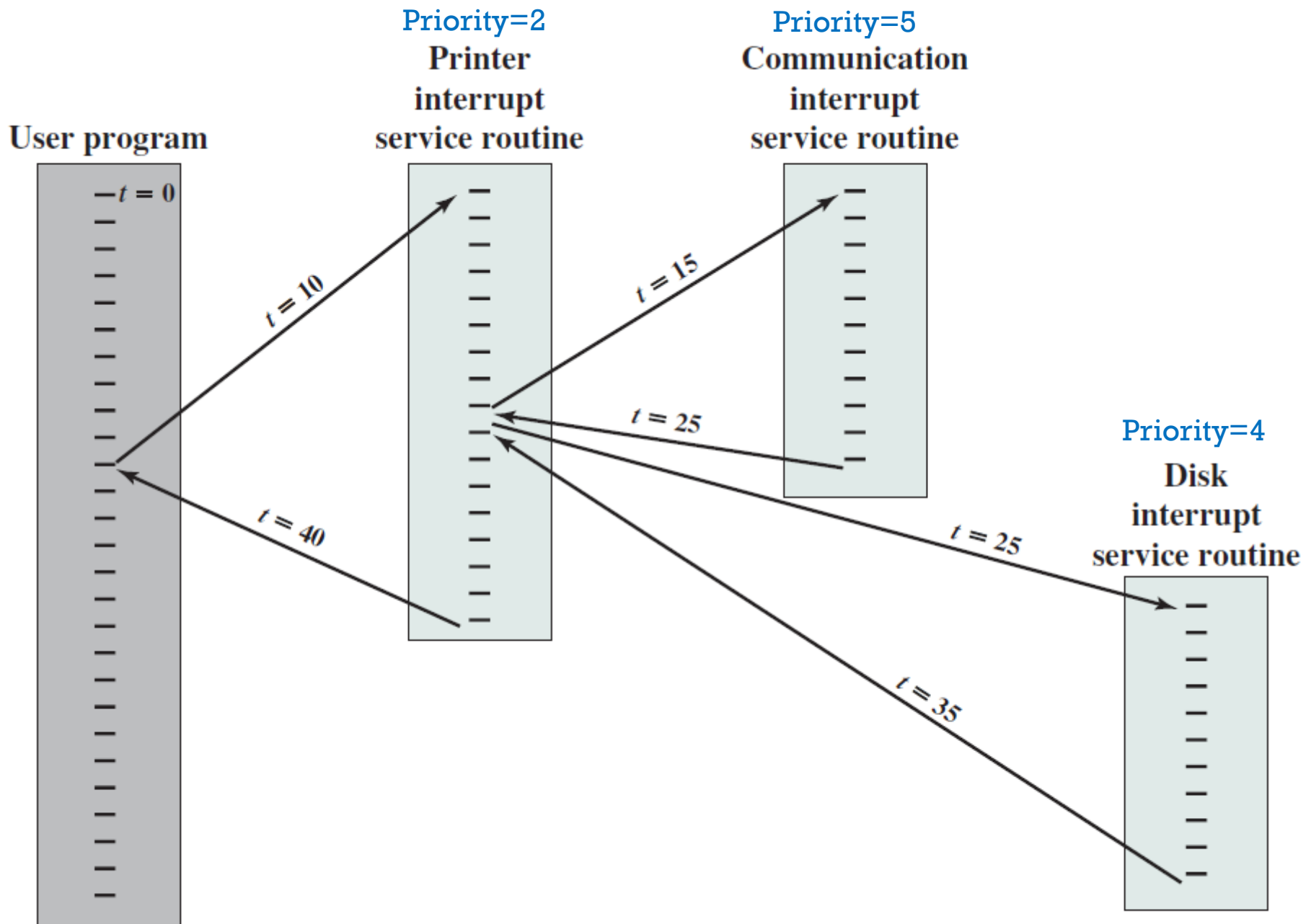


Figure 3.14 Example Time Sequence of Multiple Interrupts

I/O Function

- I/O module can exchange data directly with the processor
- Processor can read data from or write data to an I/O module
 - Processor identifies a specific device that is controlled by a particular I/O module
 - I/O instructions rather than memory referencing instructions
- In some cases it is desirable to allow I/O exchanges to occur directly with memory
 - The processor grants to an I/O module the authority to read from or write to memory so that the I/O memory transfer can occur without tying up the processor
 - The I/O module issues read or write commands to memory relieving the processor of responsibility for the exchange
 - This operation is known as **direct memory access (DMA)**



Interconnection Structures



- Computer Modules or Components:
 - Processor
 - Memory
 - I/O
- There must be paths for connecting the modules.
- The collection of paths connecting the various modules is called the **interconnection structure**.

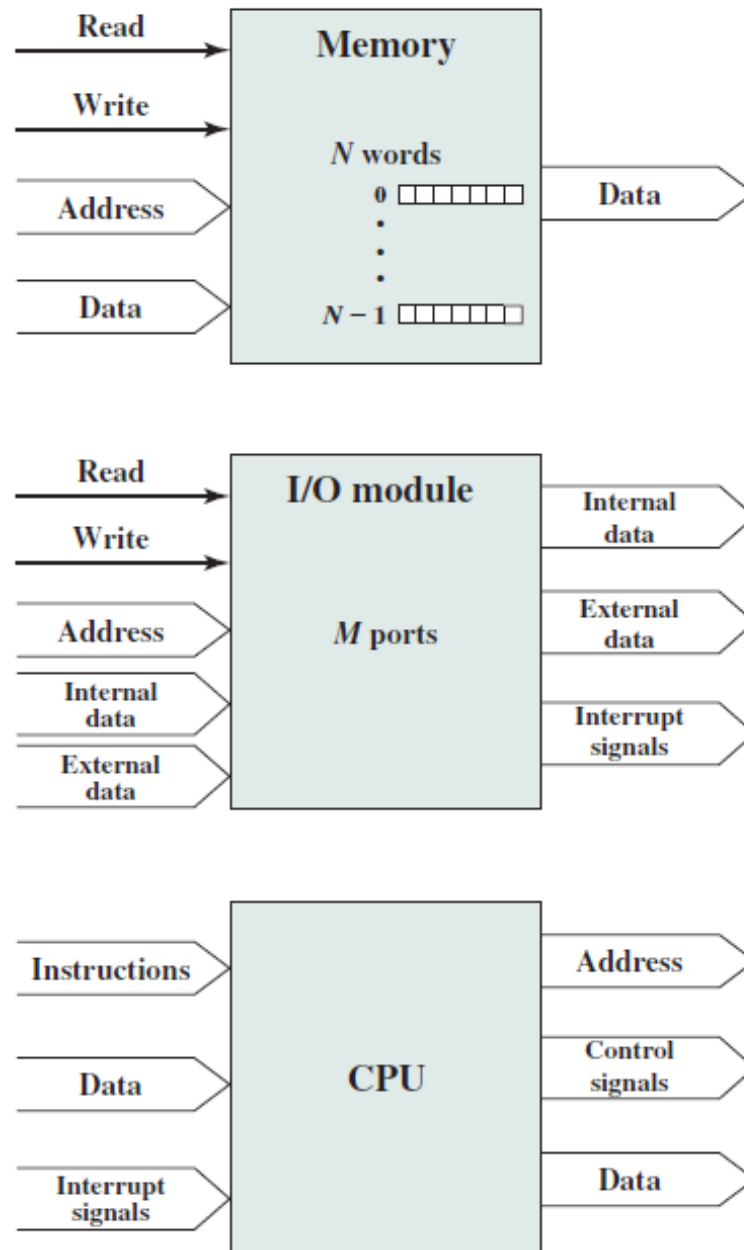
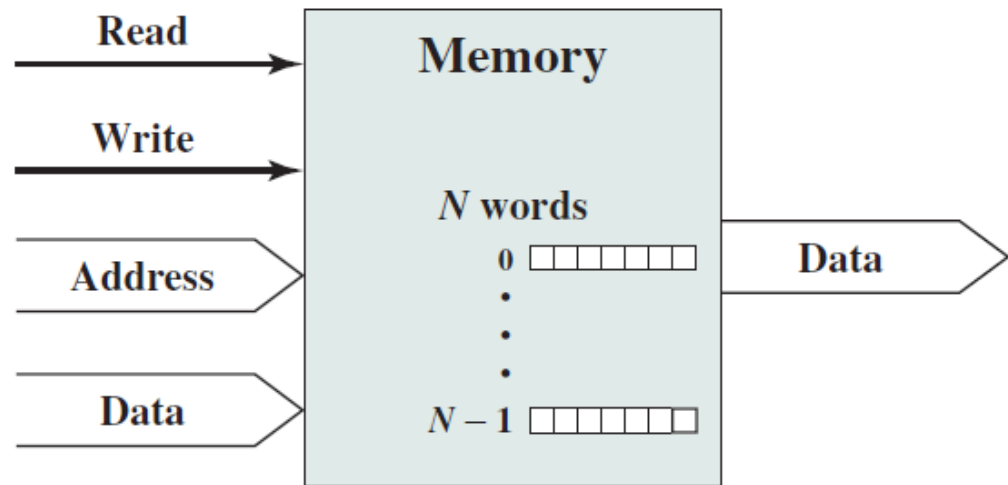


Figure 3.15 Computer Modules

+ Memory

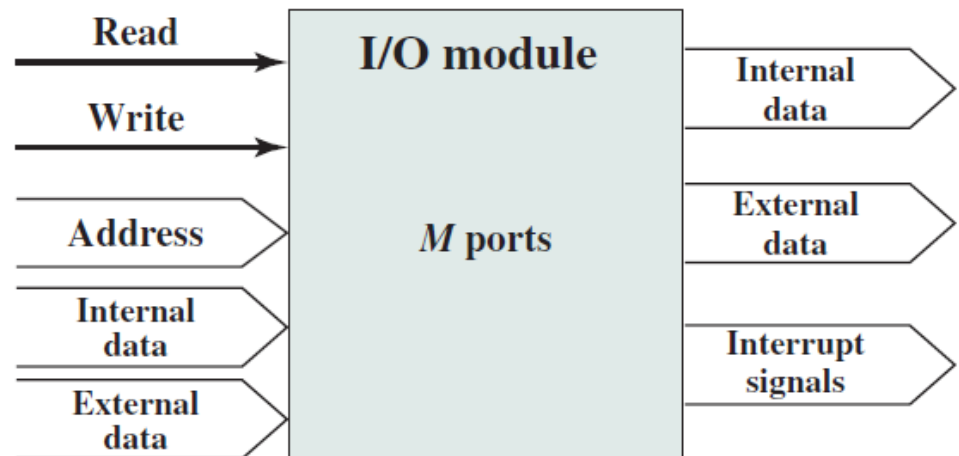
- Typically, a memory module will consist of N words of equal length.
- Each word is assigned a unique numerical address ($0, 1, \dots, N - 1$).
- A word of data can be read from or written into the memory.
- The nature of the operation is indicated by read and write control signals.
- The location for the operation is specified by an address.





I/O Module

- I/O is functionally similar to memory. There are two operations, read and write.
- Further, an I/O module may control more than one external device. We can refer to each of the interfaces to an external device as a port and give each a unique address (e.g., 0, 1, ..., $M - 1$).
- In addition, there are external data paths for the input and output of data with an external device.
- Finally, an I/O module may be able to send interrupt signals to the processor.

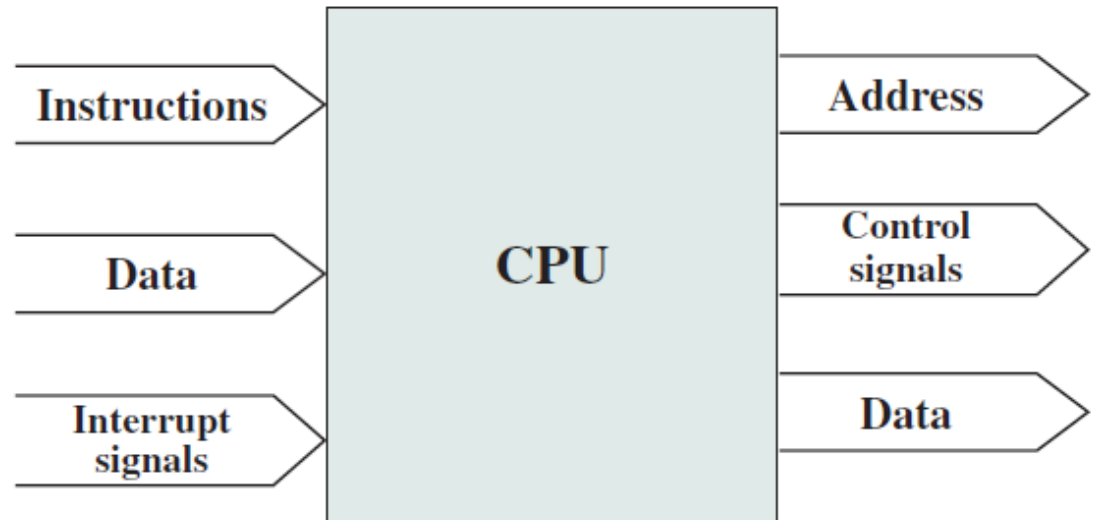




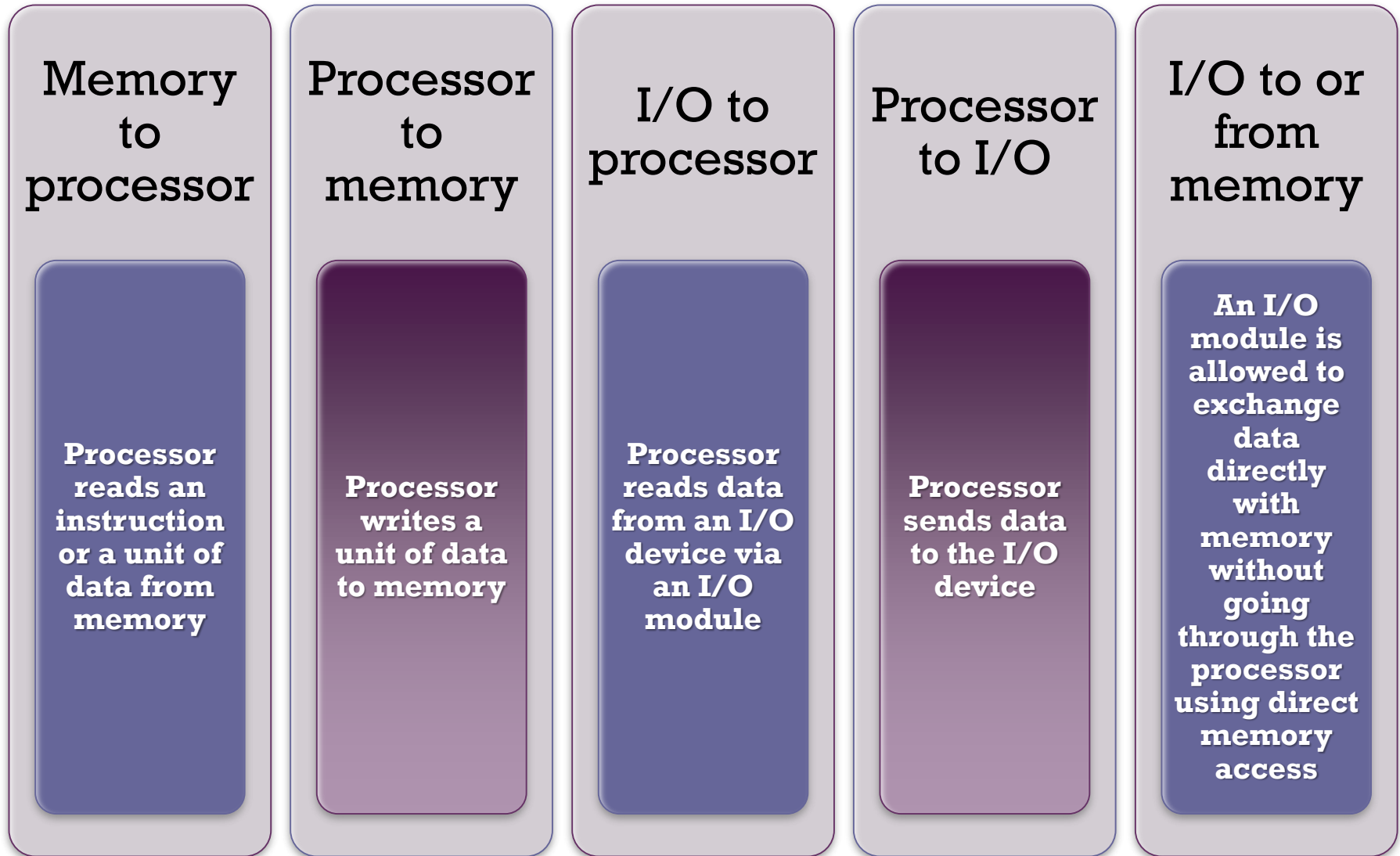
Processor



- The processor reads in instructions and data,
- writes out data after processing,
- and uses control signals to control the overall operation of the system.
- It also receives interrupt signals.



The interconnection structure must support the following types of transfers:



A communication pathway connecting two or more devices

- Key characteristic is that it is a shared transmission medium

Signals transmitted by any one device are available for reception by all other devices attached to the bus

- If two devices transmit during the same time period their signals will overlap and become garbled



Typically consists of multiple communication lines

- Each line is capable of transmitting signals representing binary 1 and binary 0

Computer systems contain a number of different buses that provide pathways between components at various levels of the computer system hierarchy



System bus

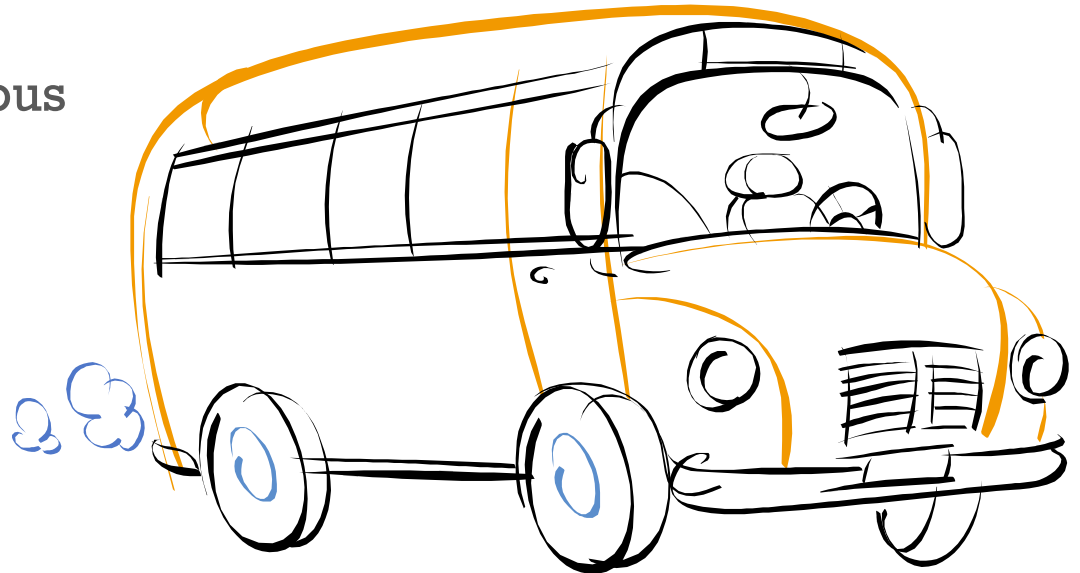
- A bus that connects major computer components (processor, memory, I/O)

The most common computer interconnection structures are based on the use of one or more system buses

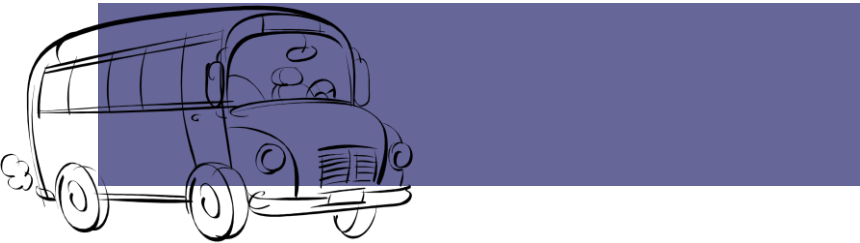
Interconnection Bus

Data Bus

- Data lines that provide a path for moving data among system modules
- May consist of 32, 64, 128, or more separate lines
- The number of lines is referred to as the *width* of the data bus
- The number of lines determines how many bits can be transferred at a time
- The width of the data bus is a key factor in determining overall system performance

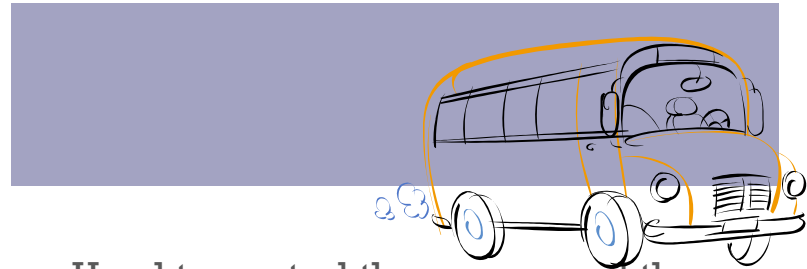


Address Bus



- Used to designate the source or destination of the data on the data bus
 - If the processor wishes to read a word of data from memory it puts the address of the desired word on the address lines
- Width determines the maximum possible memory capacity of the system
- Also used to address I/O ports
 - The higher order bits are used to select a particular module on the bus and the lower order bits select a memory location or I/O port within the module

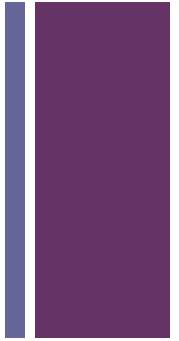
Control Bus



- Used to control the access and the use of the data and address lines
- Because the data and address lines are shared by all components there must be a means of controlling their use
- Control signals transmit both command and timing information among system modules
- Timing signals indicate the validity of data and address information
- Command signals specify operations to be performed



Control Lines



- **Memory write:** causes data on the bus to be written into the addressed location
- **Memory read:** causes data from the addressed location to be placed on the bus
- **I/O write:** causes data on the bus to be output to the addressed I/O port
- **I/O read:** causes data from the addressed I/O port to be placed on the bus
- **Transfer ACK:** indicates that data have been accepted from or placed on the bus



Control Lines



- **Bus request:** indicates that a module needs to gain control of the bus
- **Bus grant:** indicates that a requesting module has been granted control of the bus
- **Interrupt request:** indicates that an interrupt is pending
- **Interrupt ACK:** acknowledges that the pending interrupt has been recognized
- **Clock:** is used to synchronize operations
- **Reset:** initializes all modules

Bus Interconnection Scheme

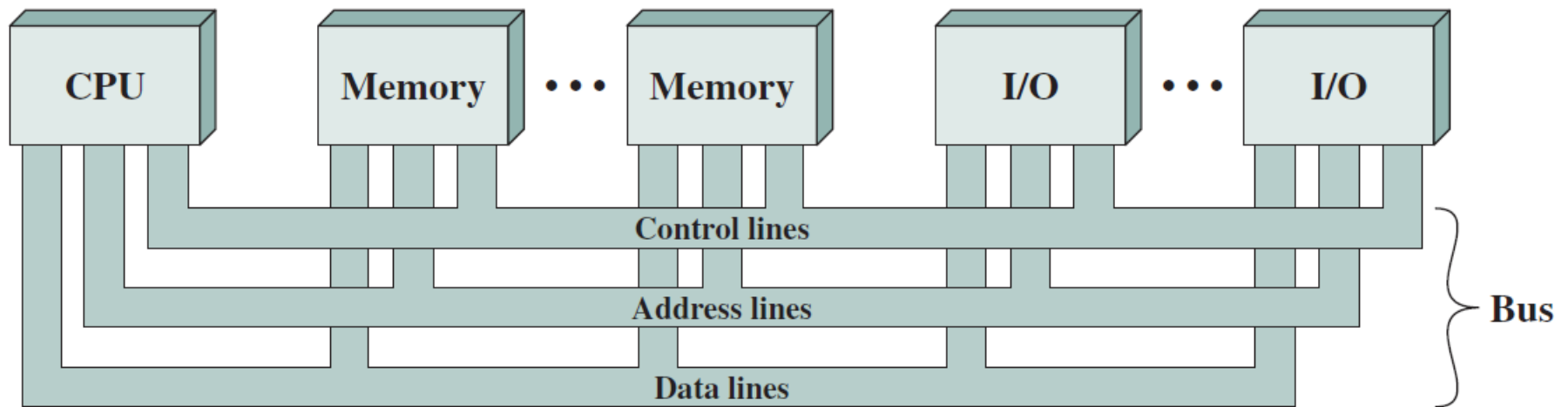


Figure 3.16 Bus Interconnection Scheme

Summary

Chapter 3

A Top-Level View of Computer Function and Interconnection

- Computer components
- Computer function
 - Instruction fetch and execute
 - Interrupts
 - I/O function
- Interconnection structures
- Bus interconnection