

Ass: 9

1. Find the closest point in the subspace spanned by  $v_1$  and  $v_2$  to the point  $x$ , where

$$v_1 = \begin{bmatrix} 3 \\ 5 \\ 2 \end{bmatrix}, v_2 = \begin{bmatrix} -5 \\ 4 \\ 5 \end{bmatrix}, \text{ \& } x = \begin{bmatrix} 3 \\ -4 \\ 1 \end{bmatrix}$$

Solution:

check for orthogonality:

$$v_1 \cdot v_2 = v_1^T \cdot v_2 = \begin{bmatrix} 3 & 5 & 2 \end{bmatrix} \begin{bmatrix} -5 \\ 4 \\ 5 \end{bmatrix} = -15 + 20 + 10 = 15$$

$\{v_1, v_2\}$  is non-orthogonal, since  $v_1$  nor  $v_2$  is 0, they mean  $\{v_1, v_2\}$  is linearly independent.

$$\text{Closest point} = \frac{x \cdot v_1}{v_1 \cdot v_1} v_1 + \frac{x \cdot v_2}{v_2 \cdot v_2} v_2$$

$$x \cdot v_1 = \begin{bmatrix} 3 & -4 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 5 \\ 2 \end{bmatrix} = 9 - 20 + 2 = -9$$

$$v_1 \cdot v_1 = \begin{bmatrix} 3 & 5 & 2 \end{bmatrix} \begin{bmatrix} 3 \\ 5 \\ 2 \end{bmatrix} = 9 + 25 + 4 = 38$$

$$x \cdot v_2 = \begin{bmatrix} 3 & -4 & 1 \end{bmatrix} \begin{bmatrix} -5 \\ 4 \\ 5 \end{bmatrix} = -15 - 16 + 5 = -26$$

$$v_2 \cdot v_2 = \begin{bmatrix} -5 & 4 & 5 \end{bmatrix} \begin{bmatrix} -5 \\ 4 \\ 5 \end{bmatrix} = 25 + 16 + 20 = 61$$

$$= \frac{-9}{38} v_1 + \left( \frac{-26}{61} \right) v_2$$

$$= \frac{-9}{38} \begin{bmatrix} 3 \\ 5 \\ 2 \end{bmatrix} + \left( \frac{-26}{61} \right) \begin{bmatrix} -5 \\ 4 \\ 5 \end{bmatrix} = \begin{bmatrix} -0.710526 \\ -1.184211 \\ -0.473684 \end{bmatrix} + \begin{bmatrix} 2.131147541 \\ -0.0976581 \\ -0.03882655 \end{bmatrix}$$

$$\begin{bmatrix} 1.4206 \\ -1.261 \\ -0.512 \end{bmatrix}$$

According to the Gram-Schmidt process:

$$\vec{u}_k = \vec{v}_k - \sum_{j=1}^{k-1} \text{proj}_{\vec{u}_j}(\vec{v}_k), \text{ where}$$

$$\text{proj}_{\vec{u}_j}(\vec{v}_k) = \frac{\vec{u}_j \cdot \vec{v}_k}{|\vec{u}_j|^2} \vec{u}_j, \text{ is a projection vector.}$$

The normalized vector is  $\vec{e}_k = \frac{\vec{u}_k}{|\vec{u}_k|}$

$$\vec{u}_1 = \vec{v}_1 = \begin{bmatrix} 4 \\ 6 \\ -1 \\ -4 \end{bmatrix}$$

$$\vec{e}_1 = \frac{\vec{u}_1}{|\vec{u}_1|} = \begin{bmatrix} 2\sqrt{58}/29 \\ 5\sqrt{58}/58 \\ -\sqrt{58}/58 \\ -2\sqrt{58}/29 \end{bmatrix}$$

$$\begin{bmatrix} -75/29 \\ -14/29 \\ 26/29 \\ -29/29 \end{bmatrix}$$

$$\vec{u}_2 = \vec{v}_2 - \text{proj}_{\vec{u}_1}(\vec{v}_2) =$$

$$\vec{e}_2 = \frac{\vec{u}_2}{|\vec{u}_2|} = \begin{bmatrix} -75\sqrt{16298}/16298 \\ -7\sqrt{16298}/8149 \\ 13\sqrt{16298}/8149 \\ -99\sqrt{16298}/16298 \end{bmatrix}$$

Therefore, set of orthonormal vector is:

$$\left\{ \begin{bmatrix} 2\sqrt{58}/29 \\ 5\sqrt{58}/58 \\ -\sqrt{58}/58 \\ -2\sqrt{58}/29 \end{bmatrix}, \begin{bmatrix} -75\sqrt{16298}/16298 \\ -7\sqrt{16298}/8149 \\ 13\sqrt{16298}/8149 \\ -99\sqrt{16298}/16298 \end{bmatrix} \right\}$$



$$A = \begin{bmatrix} 1 & 0 & 4 \\ -2 & 3 & -2 \\ -2 & 0 & 6 \end{bmatrix}$$

want:

$$A = QR$$

Orthogonal  
matrix  
(orthonormal  
columns)

upper  
triangular  
matrix

Step 1:

columns of  $A \rightarrow$  orthonormal set  
(using Gram-Schmidt process).

Use Gram-Schmidt process to find an orthogonal basis for the column space of  $A$ .  
Segregate the columns of matrix as  $x_1, x_2, x_3$ .

$A = QR$ , multiply both sides of matrix equation with  $Q^T$ .

$$Q^T A = Q^T Q R$$

$$Q^T A = R \quad \text{since columns of } Q \text{ are orthonormal}$$

$$Q^T A = R$$

$Q$  from Python script:

$$Q = \begin{bmatrix} -0.33333333 & -0.2981424 & 0.89442719 \\ 0.66666667 & -0.74535599 & 0.0 \\ 0.66666667 & 0.59628479 & 0.4472136 \end{bmatrix}$$

Transpose of  $Q$ :

$$Q^T = \begin{bmatrix} -0.33333333 & 0.66666667 & 0.66666667 \\ -0.2981424 & -0.74535599 & 0.59628479 \\ 0.89442719 & 0.59628479 & 0.4472136 \end{bmatrix}$$

Determine:  $Q^T A$  to get  $R$ :

$$Q^T A = \begin{bmatrix} 0.33333333 & 0.66666667 & 0.66666667 \\ 0.2981424 & -0.74535599 & 0.59628479 \\ 0.89442719 & 0.0 & 0.4472136 \end{bmatrix}$$

$$Q^T K \begin{bmatrix} 1 & 0 & 4 \\ -2 & 3 & -2 \\ -2 & 0 & 6 \end{bmatrix}$$

$$= \begin{bmatrix} \cancel{3} & 0 & 4 \\ 2 & 3 & -2 \\ 2 & 0 & 6 \end{bmatrix}$$

$$= \begin{bmatrix} -3.000000001 & 2.000000001 & 1.333333336 \\ 0 & -2.23606797 & 3.87585112 \\ 0.000000001 & 0 & 6.26099035 \end{bmatrix}$$

this is equivalent to the  $Q$  produced by  
the python script using `scipy.linalg.qr`.  
verified

3. Compute QR factorization of the given matrix A using

4. Find the least squares solution given A and b.

$$A = \begin{bmatrix} 1 & 3 \\ 1 & -1 \\ 1 & 1 \end{bmatrix}, \text{ and } b = \begin{bmatrix} 5 \\ 1 \\ 0 \end{bmatrix}$$

Solution:

Compute  $A^T A$

$$A^T A = \begin{bmatrix} 1 & 1 & 1 \\ 3 & -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 1 & -1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 3 & 3 \\ 3 & 11 \end{bmatrix}$$

$$A^T b = \begin{bmatrix} 1 & 1 & 1 \\ 3 & -1 & 1 \end{bmatrix} \begin{bmatrix} 5 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 6 \\ 14 \end{bmatrix}$$

The equation  $A^T A x = A^T b$

$$\begin{bmatrix} 3 & 3 \\ 3 & 11 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 6 \\ 14 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 & 3 & 6 \\ 3 & 11 & 14 \end{bmatrix} \xrightarrow{\text{row}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

7. Find a basis for the eigenspace corresponding to each listed eigenvalue.

$$A = \begin{bmatrix} 4 & 0 & 1 \\ -2 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix}, \lambda = 1, 2, 3$$

Solution:

An Eigen vector of  $n \times n$  matrix  $A$  is a nonzero vector  $x$  such that  $Ax = \lambda x$  for some scalar  $\lambda$ . The  $\lambda$  is Eigen value and  $x$  Eigen vector corresponding  $\lambda$ .

Consider the matrix:  $\begin{bmatrix} 4 & 0 & 1 \\ -2 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix}$

The scalar 1 is Eigen value iff the equation  $Ax = \lambda x$ , has a non-trivial solution.  
 $(A - I)x = 0$

The matrix  $A - I = \begin{bmatrix} 4 & 0 & 1 \\ -2 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$$A - I = \begin{bmatrix} 4-1 & 0 & 1 \\ -2 & 1-1 & 0 \\ -2 & 0 & 1-1 \end{bmatrix}$$

$$A - I = \begin{bmatrix} 3 & 0 & 1 \\ -2 & 0 & 0 \\ -2 & 0 & 0 \end{bmatrix}$$

$$R_2 - R_1 \rightarrow R_2$$

$$A - I = \begin{bmatrix} 3 & 0 & 1 \\ -2 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$



2. on row reducing:

$$A - 2I = \begin{bmatrix} -2 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

free variables: 2

$$x_3 = k \quad \& \quad -2x_1 - x_2 = 0$$

$$-x_2 + x_3 = 0$$

$$x_2 = x_3$$

$$-2x_1 - k = 0$$

$$x_1 = -k/2$$

$$\text{So, } \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = -k \begin{bmatrix} 1 \\ -2 \\ -1 \end{bmatrix}$$

The scalar 3 is ~~equivalent~~ Eigen value  
if & only if Equation  $Ax = \lambda x$ , has a  
non-trivial solution.

$$(A - 3I)x = 0$$

$$\text{The matrix: } A - 3I = \begin{bmatrix} 4 & 0 & 1 \\ -2 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

$$A - 3I = \begin{bmatrix} 1 & 0 & 1 \\ -2 & -2 & 0 \\ -2 & 0 & -2 \end{bmatrix}$$

on row-reduction:

$$A - 3I = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

one free variable:

$$x_3 = k, \quad x_1 + x_3 = 0$$

$$x_2 - x_3 = 0$$

$$x_2 = x_3$$

$$x_1 + k = 0$$

$$x_1 = -k$$

$$\text{So, } \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -k \\ k \\ k \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = k \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

Then basis is  $\left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \right\}$ .