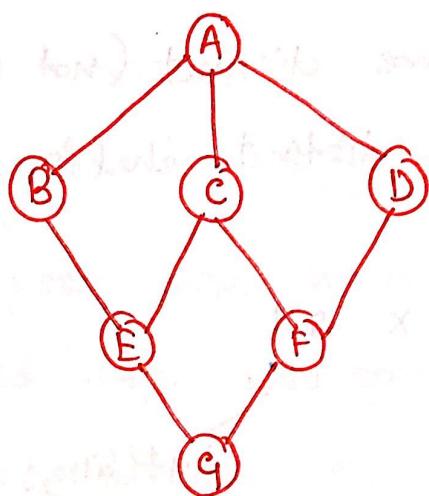


Graph Traversal :- (BFS & DFS)



Visited vertices array:-

0	0	0	0	0	0	0
A	B	C	D	E	F	G

not visited

- once an ~~not~~ vertex is visited , corresponding value of ~~A~~ array is set to 1.

Adjacency matrix

Adjacency list

	A	B	C	D	E	F	G
A	0	1	1	1	0	0	0
B	0	0	0	0	1	0	0
C	1	0	0	0	1	1	0
D	1	0	0	0	0	1	0
E	0	1	1	0	0	0	1
F	0	0	1	1	0	0	1
G	0	0	0	0	1	1	0

	A	B	C	D	E	F	G
A		B, C, D					
B			A, E				
C				A, E, F			
D					A, F		
E					B, C, G		
F						C, D, G	
G							E, F

$$O(V \times V) = O(V^2)$$

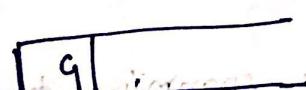
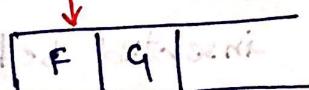
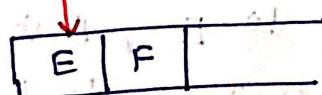
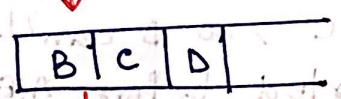
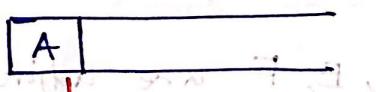
Implementation complexity

Traversal

(1) Breadth First Search (BFS) :-

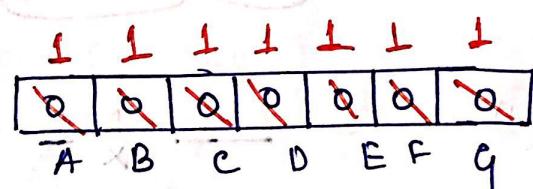
(ways of traversal)

- Take any vertex (let A), and insert it in array (Queue)
- Make corresponding array element in visited array = 1.
- Once it visited, delete it and add its adjacent element (not visited) inside the queue.
- Repeat all these steps until all vertices are visited. (all array elements become 1).



Queue

when queue empty, BFS stopped



visited vertices array

NOTE:- It is implemented using Queue.

It is also known as level order traversing

Time complexity	Adjacency matrix	Adjacency list
$O(V^2)$		$O(V+E)$

{ Graph → more than one BFS or DFS possible (due to cycle)
 Tree → Traversing is unique (no cycle)

Q. Which of the following are possible BFT:

(a) A B C D E F ✓ (Horizontal traversal)

(b) A C B D E F ✓ (Horizontal traversal)

(c) A E F B C D ✓

(d) C A E D F ✗

A, E, F are adjacent to C, so D can't be inserted before A, E, F.

(e) F C D A E B ✓

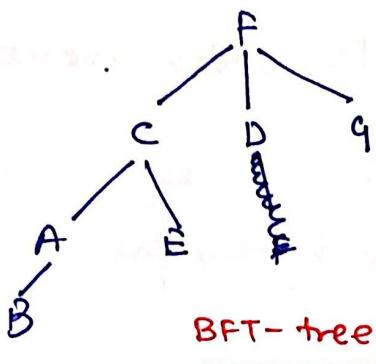
(f) E F A B C D ✗

B, C are adjacent to E, A is not so it can't be inserted before B, C.

NOTE :- BFS will give BFT-tree or spanning tree

for a graph.

F, C, D, G, A, E, B



* BFT - tree is just spanning tree
(not minimum spanning tree)

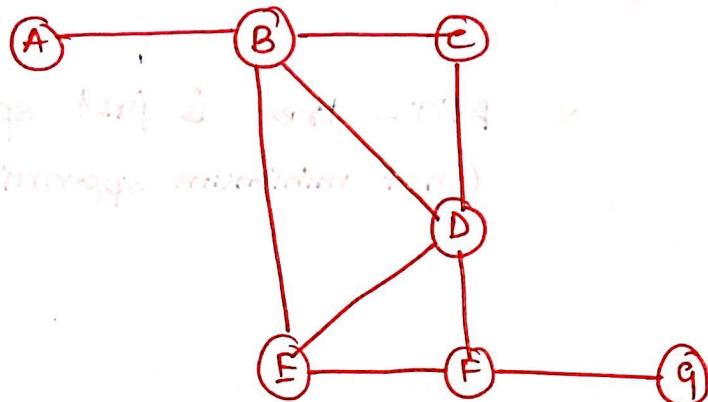
NOTE:-

Graph \rightarrow Minimum spanning tree ~~X~~ (Kruskall's or Prims algo) $O(V+E \log V)$

Graph \rightarrow Spanning tree: (BFS) $O(V+E)$

	Time complexity	Space complexity
BFS algorithm	$O(V+E)$ adjacency list $O(V^2)$ adjacency matrix	$\begin{matrix} 0 & 0 & 0 & 1 & 1 \\ 2 & 1 & 1 & 0 & 0 \\ 3 & 0 & 0 & 1 & 0 \\ 4 & 1 & 0 & 0 & 1 \\ 5 & 0 & 1 & 0 & 0 \end{matrix}$ $3V+E$ $O(V+E)$

Q.



which of the following
BFS order are valid:

~~(a)~~ D B C E F G A

~~(b)~~ A B C D E F G

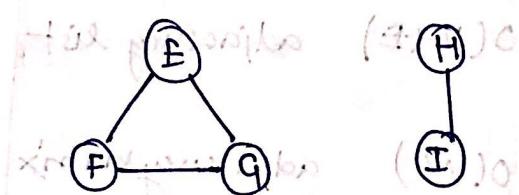
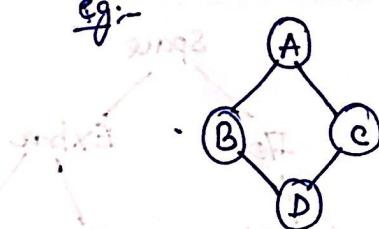
~~(c)~~ G F E D C B A

~~(d)~~ M B A C D F E G

Application of BFT

i) To check whether graph is connected or disconnected.

e.g:-



1	1	1	1	0	0	0	0	0
A	B	C	D	E	F	G	H	I

all are not visited
so, graph is
disconnected.

ii) Can find out no. of connected components (maximum subgraph connected) of a graph.

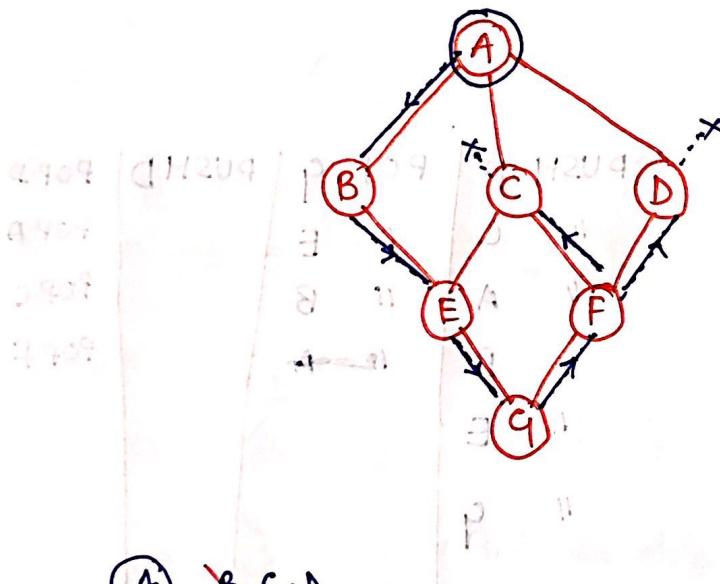
$O(V+E)$ ($K = \text{no. of times BFT applied for visit}$
all vertices.)

(iii) Using BFT, we can verify given graph contain cycle or not.

(iv) we can findout single source shortest path in given unweighted graph.

(v) we can verify given graph is Bipartite or not.

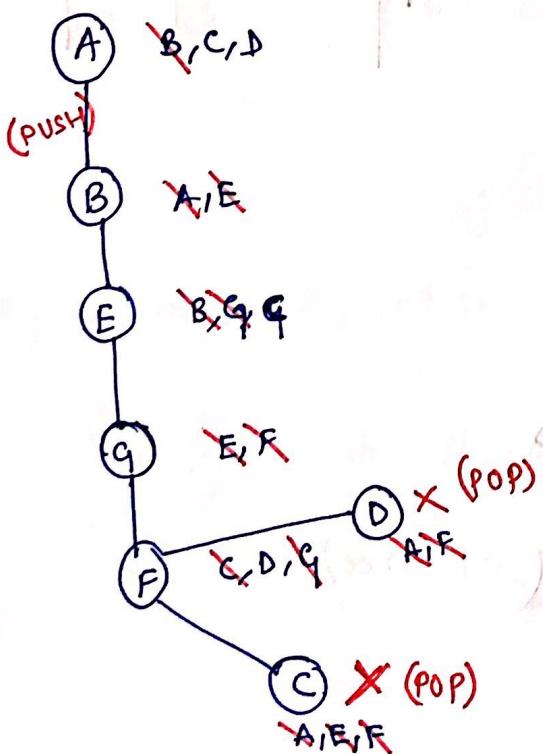
(2) Depth First Traversal :-



- Visited array required -

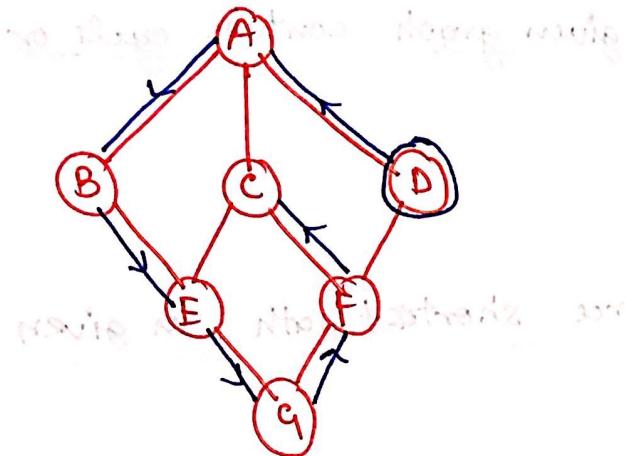
Q	Q	Q	Q	Q	Q	Q	Q
A	B	C	D	E	F	G	

- stack is used for implementation.



{A B E G F C D}

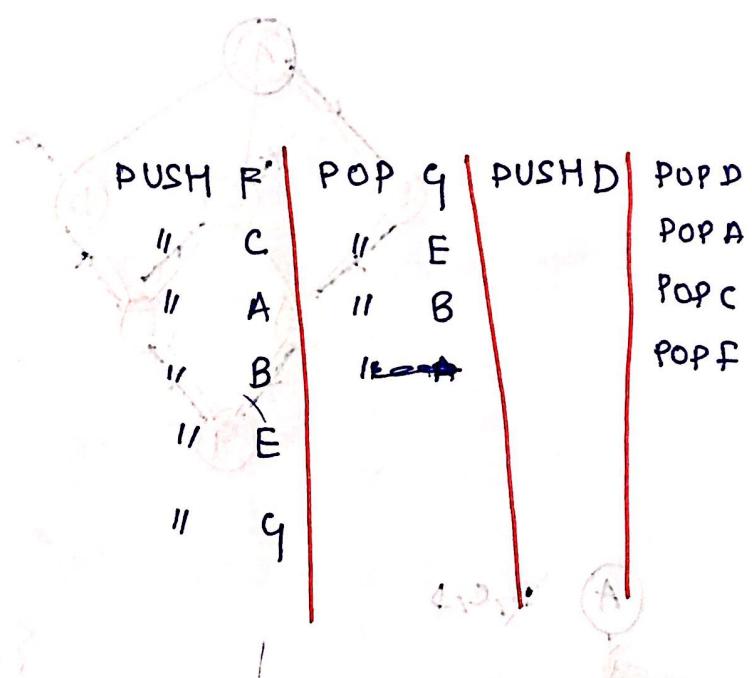
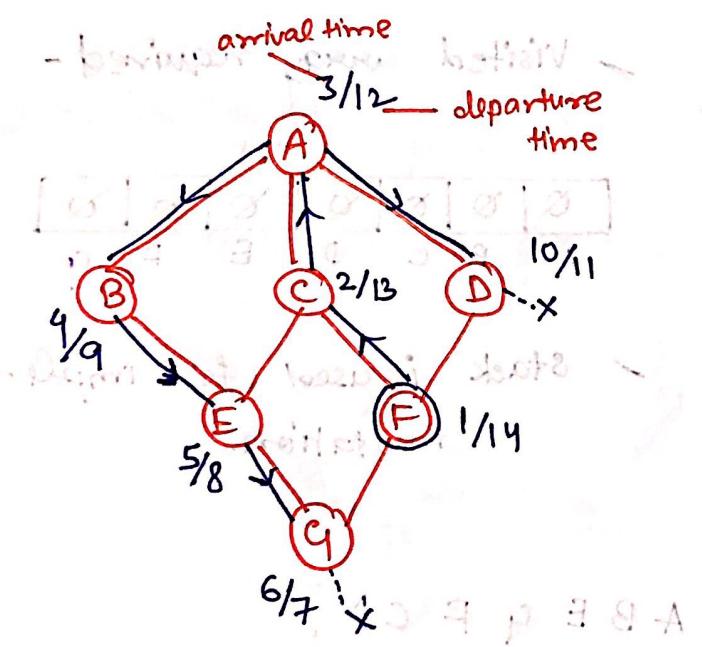
PUSH A	POP F
" B	POP G
" E	POP E
" G	POP B
" F	POP A
" C	
POP C	
PUSH D	
POP D	



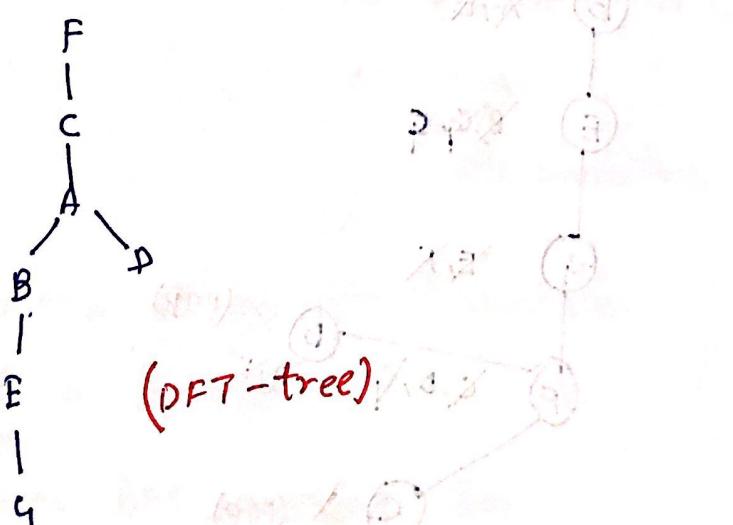
PUSH D	POP C
" A	" F
" B	" G
" E	" E
" G	" B
" F	" A
" C	" D

{D A B E G F C} — continuous PUSH and then POP
(it will use max stack size)

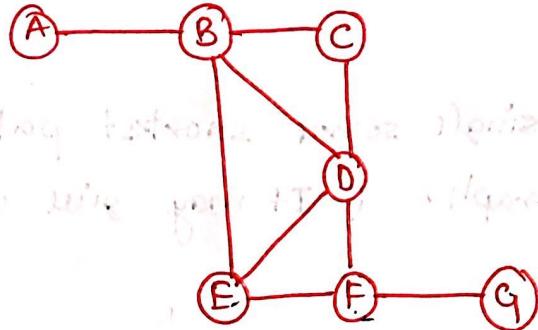
- If we have in b/w PUSH & POP opⁿ then we can not use max stack size.



{F C A B E G D}



Q.



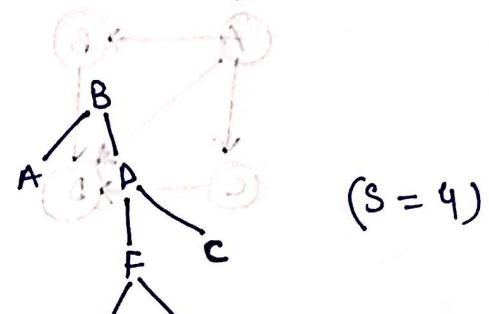
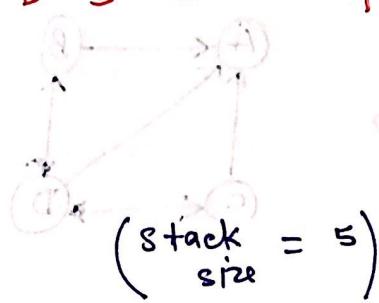
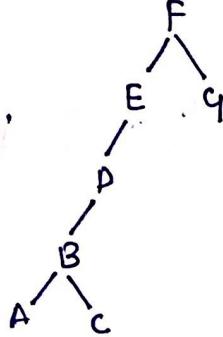
Storing above vertices depth first search (DFT) which of the following

are in lexicographical order of nodes visited in DFT are valid:

(a) E, D, B, A, C, G, F (b) B, A, D, F, G, E, C

(c) E, B, A, D, F, C, G (d) B, D, F, G, C, E, A

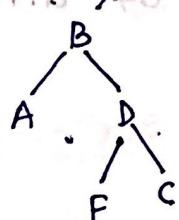
(a) F E D B A C G (b) B A D F G E C



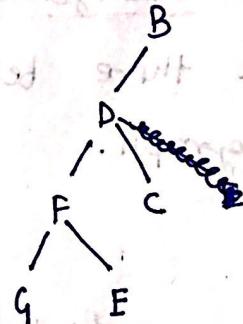
(c) ~~E B A D F C G~~

(d) ~~B D F G C E A~~

Not possible as B is not visited before A, D, F.



• G not reachable



Not possible as B is not visited before D, F.

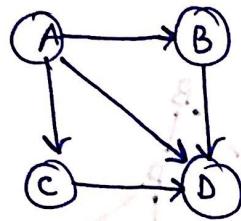
= Applications of DFT :-

- Check whether given graph is connected or not
- Findout no. of connected components in a given graph.

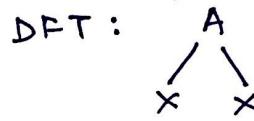
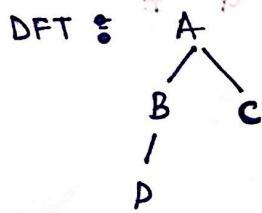
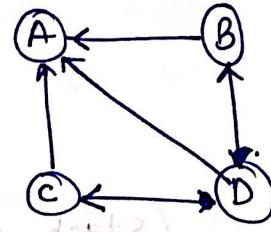
(iii) Verify given graph contain cycle or not.

(iv) we can't find out single source shortest path in given unweighted graph. (It may give or may not)

(v) Verify graph is strongly connected or not.



reverse edges

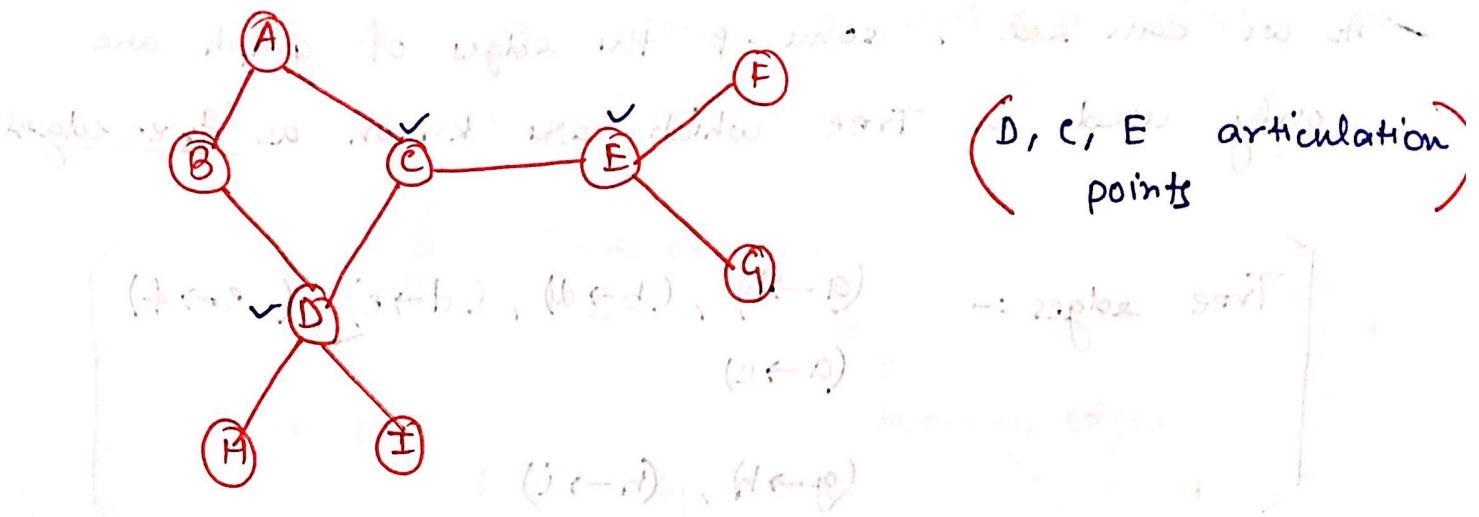


Not Strongly connected.

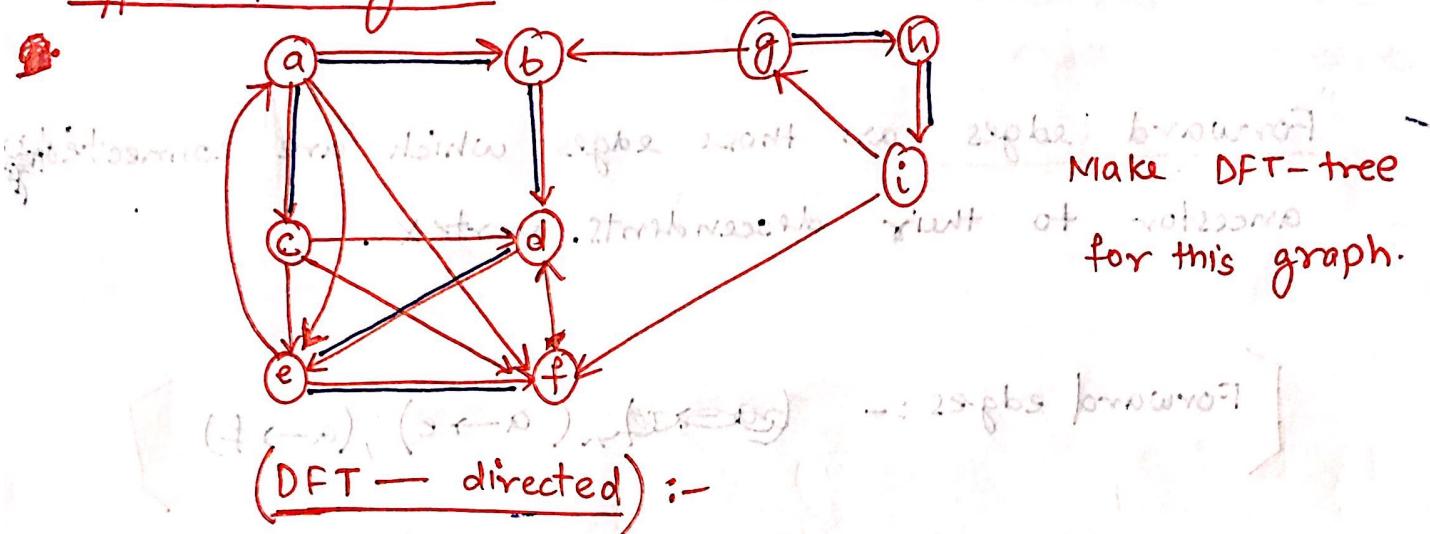
* For strongly connected graph, DFT - tree should be there before and after reversing of directed graph.

(vi) We can't find out no. of articulation points present in given graph.

Articulation point : By deleting any vertex with its edges and graph becomes disconnected.

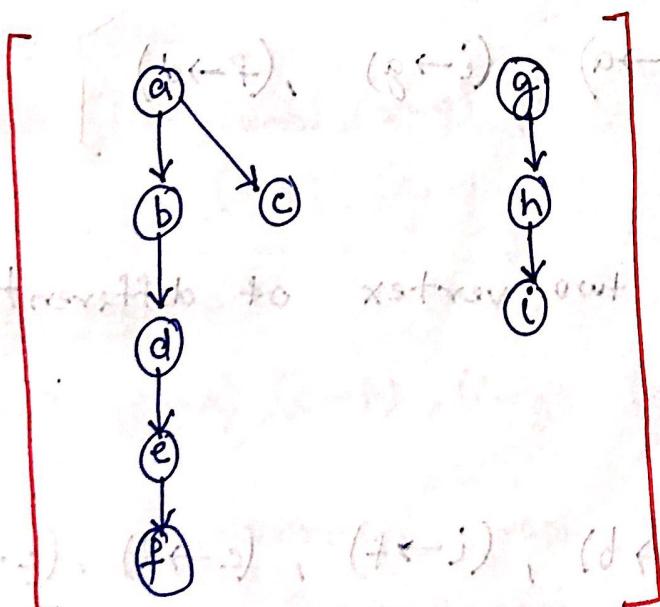


Types of Edges:-



since it is a graph so more than one DFT-tree
are possible.

DFT-tree



Since $K=2$ so

2 components.

- As we can see, some of the edges of graph are only used in Tree which are known as "tree edges".

[Tree edges :- $(a \rightarrow b)$, $(b \rightarrow d)$, $(d \rightarrow e)$, $(e \rightarrow f)$
 $(a \rightarrow c)$
 $(g \rightarrow h)$, $(h \rightarrow i)$]

- "Forward edges" are those edges which are connecting ancestor to their descendants vertex.

[Forward edges :- ~~(a → b)~~, $(a \rightarrow e)$, $(a \rightarrow f)$]

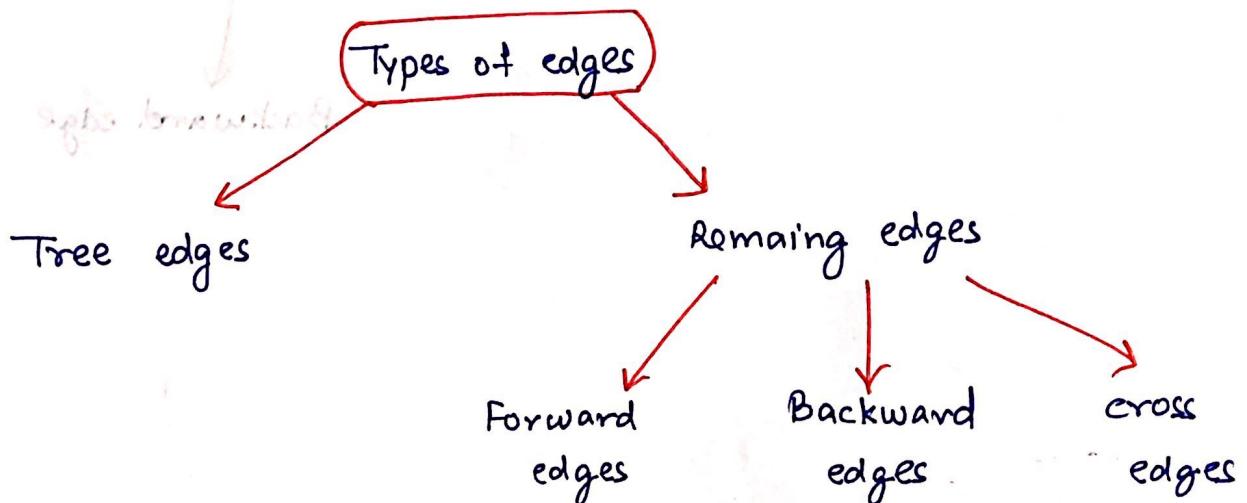
- "Back edge" are the edges which connects descendent vertex to their ancestor vertex.

[Back edges :- $(e \rightarrow a)$, $(i \rightarrow g)$, $(f \rightarrow d)$]

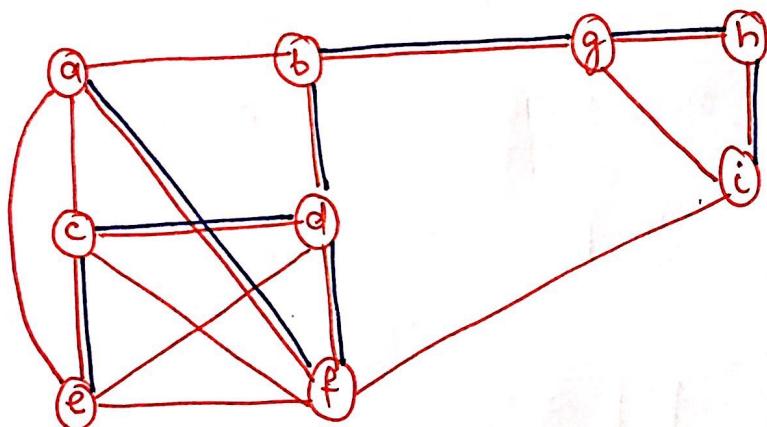
- "Cross edge" connects two vertex of different family

[Cross edge :- $(g \rightarrow b)$, $(i \rightarrow f)$, $(c \rightarrow d)$, $(c \rightarrow f)$]

NOTE:- Ancestor and descendant vertex relationships are find out on the basis of tree.



(DFT - undirected) :-



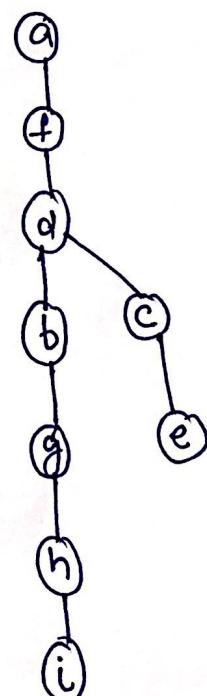
DFT - tree

Tree edges :-

$(a-f)$, $(f-d)$, $(d-b)$, $(b-g)$, $(g-h)$, $(h-i)$
 $(d-c)$, (c,e)

Back edges :-

$(c-a)$, $(e-a)$, $(c-f)$, $(i-g)$, $(b-a)$, $(e-d)$, $(i-f)$



NOTE:- In undirected graph Back-edge & Forward edge are same and Cross edge are not possible.

Types of edges

Tree edges

Remaining edges

Backward edge

graph traversal

edges visit

zero
right
backward
edges

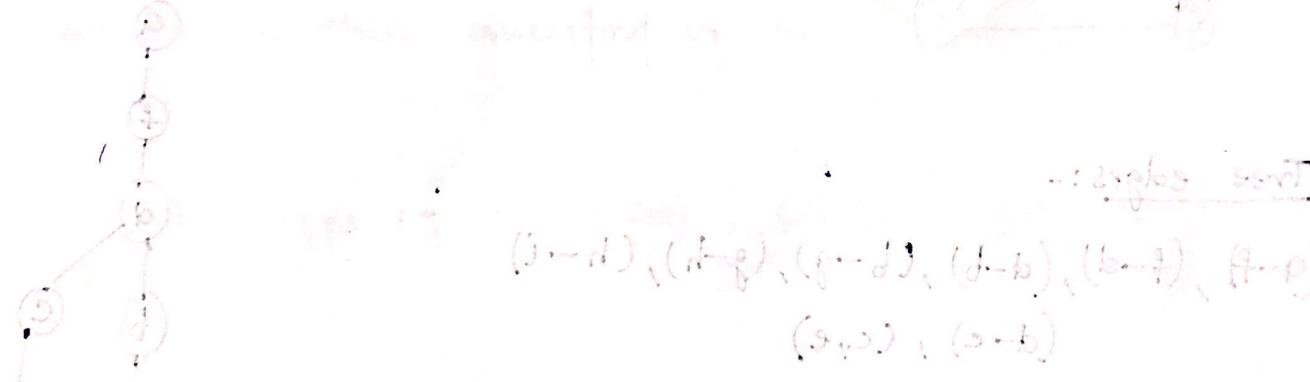
forward
edges

Forward edges are edges which are traversed in the direction of search.

Backward edges are edges which are traversed in the direction opposite to the direction of search.

Self edges are edges which are incident on the same vertex.

• These are classified into two types:



• Self edges are edges which are incident on the same vertex.

(d-d), (b-b), (e-e), (g-g), (j-j), (i-i), (k-k)

• A node having degree zero is called a leaf node.

• The same node can have more than one leaf node.