Blue Waters Petascale Semester Curriculum v1.0 Unit 9: Optimization

Lesson 1: Cache Efficient Matrix Multiplication

Developed by Paul F. Hemler

for the Shodor Education Foundation, Inc.

Except where otherwise noted, this work by The Shodor Education Foundation, Inc. is licensed under CC BY-NC 4.0. To view a copy of this license, visit https://creativecommons.org/licenses/by-nc/4.0

Browse and search the full curriculum at http://shodor.org/petascale/materials/semester-curriculum

We welcome your improvements! You can submit your proposed changes to this material and the rest of the curriculum in our GitHub repository at https://github.com/shodor-education/petascale-semester-curriculum

We want to hear from you! Please let us know your experiences using this material by sending email to petascale@shodor.org

Effective Caching for Matrix Multiplication

Cache Memory

- An important part of the memory hierarchy in any computer system
- Utilizes different technology compared to RAM
 - Faster
 - Uses more power
 - Costs more
- ▶ Gives the illusion of a large (RAM size), fast (cache speed) memory
- Compromise between cost, access time and size
- Program execution depends on efficiently utilizing the cache

Matrix Multiplication

- Matrices and matrix multiplication are very common in a variety of Engineering and Scientific Computing problems
- ▶ An n X n matrix A is mathematically written as:

$$A = \begin{bmatrix} a_{0,0} & a_{0,1} & \cdots & a_{0,n-1} \\ a_{1,0} & a_{1,1} & \cdots & a_{1,n-1} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n-1,0} & a_{n-1,1} & \cdots & a_{n-1,n-1} \end{bmatrix}$$

Matrix multiplication is mathematically written as:

$$C = AB$$

▶ Where A, B and C are all n X n matrices

Matrix Multiplication

- \triangleright Each element in C requires n multiplications and n-1 additions
- ► Each element in *C* is computed by multiplying a row of matrix *A* with a column of matrix *B*, for example,

$$\begin{bmatrix} c_{0,0} & c_{0,1} & \cdots & c_{0,n-1} \\ \hline c_{1,0} & c_{1,1} & \cdots & c_{1,n-1} \\ \vdots & \vdots & \ddots & \vdots \\ c_{n-1,0} & c_{n-1,1} & \cdots & c_{n-1,n-1} \end{bmatrix} = \begin{bmatrix} a_{0,0} & a_{0,1} & \cdots & a_{0,n-1} \\ \hline a_{1,0} & a_{1,1} & \cdots & a_{1,n-1} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n-1,0} & a_{n-1,1} & \cdots & a_{n-1,n-1} \end{bmatrix} * \begin{bmatrix} b_{0,0} \\ b_{1,0} \\ \vdots \\ b_{n-1,0} \end{bmatrix} & b_{0,1} & \cdots & b_{0,n-1} \\ b_{1,1} & \cdots & b_{1,n-1} \\ \vdots & \ddots & \vdots \\ b_{n-1,1} & \cdots & b_{n-1,n-1} \end{bmatrix}$$

- ightharpoonup c_{1,0} is the sum of the products of the elements of row 1 of matrix A and column 0 of matrix B
- Or more generally,

$$c_{i,j} = \sum_{k=0}^{n-1} a_{i,k} b_{k,j}$$

Matrix Memory Access

- ▶ The main memory of a computer system can be thought of as a long linear array, where elements are stored at consecutive memory locations
- ► A matrix is stored in memory either by rows (row major order) or columns (column major order)
- ▶ The **C** language uses row major order, while Fortran uses column major order
- A matrix in C is stored as:

Row 0 Row 1 . . . Row n - 1

- Optimal cache utilization occurs when sequential memory elements are accessed
 - ▶ For the matrix multiplication example above, matrix A is efficiently accessed but matrix B is not

Matrix Multiplication Transpose

- \triangleright Element access to matrix B can be made cache efficient by storing matrix B in column major order
- ▶ This is the same as computing the *transpose* of *B*
- ▶ In this case, the elements of the rows of matrix *A* are multiplied by the elements of the rows of matrix *B*

$$\begin{bmatrix} c_{0,0} & c_{0,1} & \cdots & c_{0,n-1} \\ c_{1,0} & c_{1,1} & \cdots & c_{1,n-1} \\ \vdots & \vdots & \ddots & \vdots \\ c_{n-1,0} & c_{n-1,1} & \cdots & c_{n-1,n-1} \end{bmatrix} = \begin{bmatrix} a_{0,0} & a_{0,1} & \cdots & a_{0,n-1} \\ a_{1,0} & a_{1,1} & \cdots & a_{1,n-1} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n-1,0} & a_{n-1,1} & \cdots & a_{n-1,n-1} \end{bmatrix} * \begin{bmatrix} b_{0,0} & b_{1,0} & \cdots & b_{n-1,0} \\ b_{0,1} & b_{1,1} & \cdots & b_{n-1,0} \\ \vdots & \vdots & \ddots & \vdots \\ b_{0,n-1} & b_{1,n-1} & \cdots & b_{n-1,n-1} \end{bmatrix}$$

$$c_{i,j} = \sum_{k=0}^{n-1} a_{i,k} b_{j,k}$$

Matrix Multiplication

- Matrix multiplication using the transpose of the B matrix more efficiently utilizes the cache
- ▶ Both matrix multiplication techniques inefficiently use the cache because the data must be brought into the cache multiple times
 - \blacktriangleright Each row of matrix A is multiplied by each row of matrix B
 - ▶ When the matrices are large, the rows of matrix *B* will need to be brought into the cache for each row in matrix *A*

Block Matrix Multiplication

- ► A better way of utilizing the cache is to perform block matrix multiplication, where the matrices are broken into blocks or tiles
- For example, a 4 X 4 matrix A can be made of 2 X 2 blocks or tiles each of size 2 X 2

$$A = \begin{bmatrix} a_{0,0} & a_{0,1} & a_{0,2} & a_{0,3} \\ a_{1,0} & a_{1,1} & a_{1,2} & a_{1,3} \\ a_{2,0} & a_{2,1} & a_{2,2} & a_{2,3} \\ a_{3,0} & a_{3,1} & a_{3,2} & a_{3,3} \end{bmatrix} = \begin{bmatrix} a_{0,0} & a_{0,1} \\ a_{1,0} & a_{1,1} \end{bmatrix} \begin{bmatrix} a_{0,2} & a_{0,3} \\ a_{1,2} & a_{1,3} \end{bmatrix} = \begin{bmatrix} A_{0,0} & A_{0,1} \\ a_{2,0} & a_{2,1} \\ a_{3,0} & a_{3,1} \end{bmatrix} \begin{bmatrix} a_{2,2} & a_{2,3} \\ a_{3,2} & a_{3,3} \end{bmatrix}$$

Block matrix multiplications is

$$\begin{bmatrix} C_{0,0} & C_{0,1} \\ C_{1,0} & C_{1,1} \end{bmatrix} = \begin{bmatrix} A_{0,0} & A_{0,1} \\ A_{1,0} & A_{1,1} \end{bmatrix} \begin{bmatrix} B_{0,0} & B_{0,1} \\ B_{1,0} & B_{1,1} \end{bmatrix}$$

Block Matrix Multiplication

► The product matrix

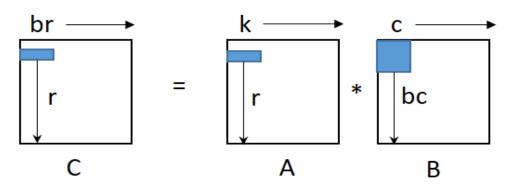
$$C_{0,0} = A_{0,0}B_{0,0} + A_{0,1}B_{1,0}$$

$$C_{0,1} = A_{0,0}B_{0,1} + A_{0,1}B_{1,1}$$

$$C_{1,0} = A_{1,0}B_{0,0} + A_{1,1}B_{1,0}$$

$$C_{1,1} = A_{1,0}B_{0,1} + A_{1,1}B_{1,1}$$

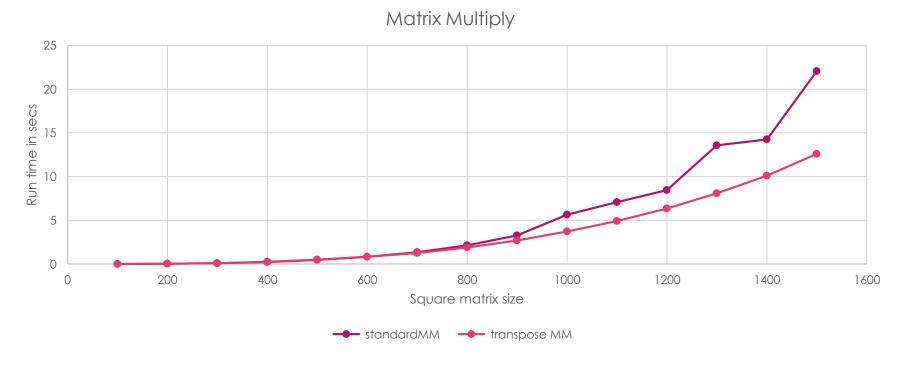
This technique efficiently utilizes the cache because all the elements in a block in matrix *B* are completely used for all computations and are not needed again



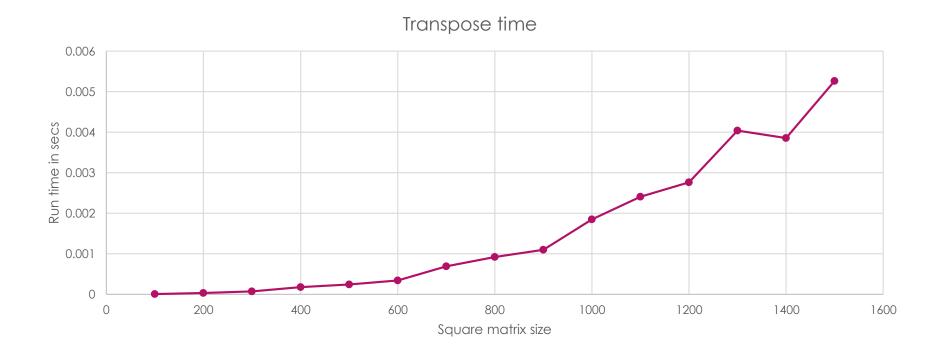
Matrix Multiply Program

- Two programs were written to time the standard matrix multiplication with both the transpose and the block matrix techniques
- Command line arguments are used to determine the size of the matrices
- All matrices utilize double-precision floating-point numbers
- Computational results are compared to ensure the product matrix is correctly determined

► Timing results for standard matrix multiplication compared to transpose matrix multiplication

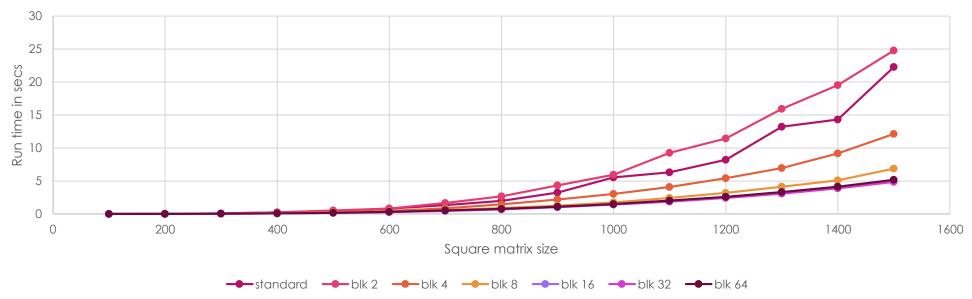


▶ The time to transpose the matrix is negligible



- ▶ The time to perform block matrix multiplication depends on the size of the block
- ▶ Blocks of size 8 X 8 or 16 X 16 appear to give the best performance





▶ Block matrix multiply with blocks of size 16 X 16 appear to give the best performance

