# Shosuke Kiami

shokiami.com \* kiami.sho@gmail.com \* (206) 383-5764 \* linkedin.com/in/shokiami

### **EDUCATION**

### **University of Washington - Seattle WA**

Sep 2020 - Jun 2025

- B.S. in Mechanical Engineering, B.S. in Computer Science, B.A. in Mathematics (GPA: **3.99**/4.00)
- Honors: Annual Dean's List, Phi Beta Kappa Academic Honor Society

#### **SKILLS**

- Engineering: Certified in SolidWorks (CSWA), CNC Mill, Lathe, 3D printing, CAM, FEA, PDM
- Programming: Python, MATLAB, C/C++, Java, Javascript, HTML/CSS, ROS, PyTorch, NumPy, Git

### **EXPERIENCE**

# Suspension Engineer - UW Formula Motorsports, Seattle WA

Mar 2023 - Present

- Leading the design and manufacturing of a driverless steering system (consisting of a stepper motor, custom planetary gearbox, and double-sided steering rack) with the goal of unobtrusive integration.
- Machined parts on the CNC Mill and Lathe with 100% part acceptance and 0% tool breakage.

### Robotics Researcher - UW WEIRD Lab, Seattle WA

Jan 2023 - Present

- Introduced generative models as an effective <u>data augmentation technique</u> for imitation learning, improving our depth camera + robotic arm's success rate on unseen manipulation tasks by **40%**.
- Co-authored a paper that placed top 3% and Best System Paper Finalist at the RSS 2023 conference.

# Software Engineering Intern - Apple, San Diego CA

Jun 2023 - Present

- Built a GUI for generating HTTP Live Streaming playlists, reducing internal dev time by 200%.
- Developed a tool to inspect playlist errors improving internal and external dev time by another 50%.
- Co-founded and pitched an Apple Pay feature that streamlines splitting bills with nearby contacts.

# Driverless Engineer - UW Formula Motorsports, Seattle WA

Jan 2023 - Mar 2023

- Led the development of planning/control algorithms including a custom pure-pursuit and PID controller <u>algorithm</u> that resulted in the team's **first-ever** successful autonomous lap completion.
- Used SolidWorks to design, analyze, prototype, and machine a mount for the steering stepper motor.

### Software Engineering Intern - Microsoft, Redmond WA

Jun 2022 - Sep 2022

- Developed a <u>Virtual Camera</u> that enables apps such as Teams and Zoom to access a larger selection of camera effects as well as a **20-70x** speed increase and **200 mW** power reduction in existing effects.
- Designed a custom interpolation/blending algorithm and reduced its runtime from 80 ms to 0.5 ms.

# Computer Vision Researcher - UW Makeability Lab, Seattle WA

Sep 2021 - Jun 2022

- Co-founded an initiative to use <u>deep learning</u> for <u>automatic sidewalk accessibility evaluation</u>.
- Co-authored a <u>paper</u> publishing the performance effects of filtered vs. unfiltered and single-city vs. cross-city training data and how our models can label new cities with a promising **80-90%** accuracy.

#### **PROJECTS**

**Drawing Robot** 

Aug 2023 - Present

- Designing and manufacturing a robotic arm that can draw any image of your choice.
- Uses a Raspberry Pi that runs custom edge-detection/segmenter algorithms and low-level controls.

#### **DanceTime**

May 2021 - Jul 2023

- Created a multiplayer dance-based rhythm game in C++ inspired by Just Dance and FaceTime.
- Built a custom 30 Hz pose estimation library and an original regression-based scoring algorithm.

### AlphaFour

Jun 2022 - Jul 2023

• Developed an AI that learns how to play Connect 4 from 0% to 90% optimality via self-play deep reinforcement learning inspired by AlphaZero and can even generalize to other board games.

#### GeoKnowr

Nov 2022 - Dec 2022

• Used Google Street View API and PyTorch to develop the data collection, training, and evaluation pipeline for a lightweight GeoGuessr AI that can reliably guess within 2000 km of the ground truth.