Shosuke Kiami

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EDUCATION

University of Washington - Seattle WA

Sep 2020 - Jun 2025

- B.S. in Mechanical Engineering, B.S. in Computer Science, B.A. in Mathematics (GPA: **3.99**/4.00)
- Honors: Annual Dean's List, Phi Beta Kappa Academic Honor Society

SKILLS

- Engineering: Certified in SolidWorks (CSWA), CNC Mill, Lathe, 3D Printing, CAM, FEA, PDM
- Programming: Python, MATLAB, C/C++, Java, JavaScript, HTML/CSS, ROS, PyTorch, NumPy, Git

EXPERIENCE

Suspension Engineer - UW Formula Motorsports, Seattle WA

Mar 2023 - Present

- Leading the design/manufacturing of the team's **first** autonomous steering actuator (a BLDC motor, planetary gearbox, clutch, ball screw, and actuator link) that can provide over **700 lb** of steering force.
- Conducted data analysis and calculations to ensure optimal performance and unobtrusive integration.
- Machined parts on the 3-axis CNC Mill and Lathe with 100% part acceptance and 0% tool damage.

Robotics Researcher - Transformative Robotics Lab, Seattle WA

Oct 2023 - Present

- Helping develop a soft-body continuum catheter <u>surgical robot</u> for minimally invasive heart surgery.
- Designing, prototyping, and validating geometric metamaterials, actuation mechanisms, and controls.

Software Engineering Intern - Apple, San Diego CA

Jun 2023 - Sep 2023

- Built a GUI tool for generating HTTP Live Streaming playlists, reducing internal dev time by 200%.
- Created a web service to inspect playlist errors improving internal/external dev time by another 50%.

Robotics Researcher - WEIRD Lab, Seattle WA

Jan 2023 - Jun 2023

- Used generative models + imitation learning to improve a robot's success rate on new tasks by 40%.
- Co-authored a paper that placed top 3% and Best System Paper Finalist at the RSS 2023 conference.

Driverless Engineer - UW Formula Motorsports, Seattle WA

Jan 2023 - Mar 2023

• Led the development of planning/control algorithms including a custom pure-pursuit and PID controller <u>algorithm</u> that resulted in the team's **first-ever** successful autonomous lap completion.

Software Engineering Intern - Microsoft, Redmond WA

Jun 2022 - Sep 2022

• Developed a <u>Virtual Camera</u> that enables apps such as Teams and Zoom to access a larger selection of camera effects as well as a **20-70x** speed increase and **200 mW** power reduction in existing effects.

Computer Vision Researcher - Makeability Lab, Seattle WA

Sep 2021 - Jun 2022

• Co-authored a <u>paper</u> publishing the performance effects of filtered vs. unfiltered and single-city vs. cross-city training data and how our models can label new cities with a promising **80-90%** accuracy.

PROJECTS

Drawing Robot

Aug 2023 - Present

- Designing and manufacturing a robotic arm that can draw any image of your choice.
- Uses a Raspberry Pi that runs custom edge-detection/segmenter algorithms and low-level controls.

DanceTime

May 2021 - Jul 2023

- Created a multiplayer <u>dance-based rhythm game</u> in C++ inspired by Just Dance and FaceTime.
- Built a custom 30 Hz pose estimation library and an original regression-based scoring algorithm.

AlphaFour

Jun 2022 - Jul 2023

• Developed an <u>AI</u> that learns how to play Connect 4 from **0%** to **90%** optimality via self-play deep reinforcement learning inspired by AlphaZero and can even generalize to other board games.

GeoKnowr

Nov 2022 - Dec 2022

• Used Google Street View API and PyTorch to develop the data collection, training, and evaluation pipeline for a lightweight GeoGuessr AI that can reliably guess within 2000 km of the ground truth.