Model: 2D Shortest-SuperTile via relative-placement spanning tree

Index sets and parameters

$$V = \{1, ..., T\}$$
 (set of tiles)
$$\mathcal{I} = \{1, ..., n\}$$
 (rows inside a tile)
$$\mathcal{J} = \{1, ..., n\}$$
 (cols inside a tile)
$$\mathcal{R} = \{(i, j, k) : 1 \le i, j \le n + 1, 1 \le k \le 4\}$$
 (allowed relative placements)
$$t_{v,a,b} \in \{0,1\}$$
 (or general symbol)
$$\forall v \in V, a \in \mathcal{I}, b \in \mathcal{J}$$

 $\Delta_x(r), \ \Delta_y(r) \in \mathbb{Z}$ (offsets implied by relative placement $r \in \mathcal{R}$).

Remark: The mapping $r = (i, j, k) \mapsto (\Delta_x, \Delta_y)$ is defined by your corner/offset convention (e.g. corner k of tile v placed into grid relative slot (i, j) of tile u). Use whichever integer offsets you defined in your implementation.

Decision variables

$$m \in \mathbb{Z}_+$$
 (side length of the square canvalue $x_v, y_v \in \mathbb{Z}$ $\forall v \in V$ (absolute integer coordinates of the top-left corner of tile v on the canvalue $e_{uvr} \in \{0,1\}$ $\forall u,v \in V,\ u \neq v,\ r \in \mathcal{R}$ (1 if the tree selects a relative placement r that places v w.r.t. v v v v v v v (undirected tree edge indicator; can be derived from v v v v (undirected tree edge indicator)

Objective

Minimize the canvas size:

 $\min m$

Feasibility / domain constraints

$$0 \le x_v \le m - n, \qquad 0 \le y_v \le m - n \qquad \forall v \in V$$

(tiles must lie wholly inside the $m \times m$ canvas).

Tree / connectivity constraints

We enforce that the chosen relative placements form a spanning tree on V.

$$\sum_{u \in V \setminus \{v\}} \sum_{r \in \mathcal{R}} e_{uvr} = 1 \qquad \forall v \in V \setminus \{\text{root}\}$$
 (each non-root has exactly one parent (arborescence))
$$\sum_{v \in V} \sum_{u \in V \setminus \{v\}} \sum_{r \in \mathcal{R}} e_{uvr} = T - 1 \qquad \text{(total edges} = T - 1)$$

(Choose an arbitrary root to break symmetry; above enforces an oriented spanning tree.)

Position propagation (consistency) along chosen edges

If $e_{uvr} = 1$ then the absolute positions must satisfy the relative offset implied by r:

$$e_{uvr} = 1 \implies \begin{cases} x_v = x_u + \Delta_x(r), \\ y_v = y_u + \Delta_y(r). \end{cases}$$
 (position propagation)

(These are logical implications; linearization suggestions are below.)

Global pairwise compatibility constraints

For every pair of distinct tiles $p,q\in V$ we must ensure that whenever they overlap on the canvas, the overlapped cells are compatible (i.e., have no conflicting symbols). Let

$$\mathcal{O}_{(a,b),(c,d)}(p,q) := \text{the event } (x_p + (a-1) = x_q + (c-1) \land y_p + (b-1) = y_q + (d-1)).$$

Then, for every $p \neq q$ and every pair of internal cell indices $(a, b) \in \mathcal{I} \times \mathcal{J}$, $(c, d) \in \mathcal{I} \times \mathcal{J}$ we require:

if
$$\mathcal{O}_{(a,b),(c,d)}(p,q)$$
 holds, then $t_{p,a,b} = t_{q,c,d}$. (compatibility)

Equivalently (compact): for all $p \neq q$,

$$(x_p - x_a, y_p - y_a) = (a - c, b - d) \implies t_{p,a,b} = t_{a,c,d}$$

Alternative formulation using precomputed pairwise compatibility

If you precompute whether two tiles p, q are pairwise compatible under a displacement (δ_x, δ_y) , define the binary parameter

$$\operatorname{Comp}_{pq}^{\delta_x,\delta_y} = \begin{cases} 1 & \text{if } \forall (a,b), (c,d) \text{ with } a+\delta_x=c, \ b+\delta_y=d \text{ we have } t_{p,a,b}=t_{q,c,d}, \\ 0 & \text{otherwise.} \end{cases}$$

Then impose for all $p \neq q$:

$$\operatorname{Comp}_{pq}^{x_p - x_q, \ y_p - y_q} = 1.$$

(Again this is a logical constraint; it says the relative offset produced by (x_p, y_p) must be one of the compatible offsets.)

Remarks on implementability and linearization

- The model above uses logical implications (if $e_{uvr}=1$ then equalities on x,y; and equality tests like $x_p-x_q=\delta_x$ trigger compatibility). To obtain an MILP, linearize as follows:
 - Replace each implication $e_{uvr} = 1 \Rightarrow x_v = x_u + \Delta_x(r)$ with big-M constraints:

$$x_v - x_u - \Delta_x(r) \le M (1 - e_{uvr}), \quad x_v - x_u - \Delta_x(r) \ge -M (1 - e_{uvr}),$$

where M is a sufficiently large constant (e.g. M = m).

- For compatibility: for every possible displacement (δ_x, δ_y) and for every ordered pair (p, q), introduce binary indicator d_{pq}^{δ} that equals 1 iff $(x_p - x_q, y_p - y_q) = (\delta_x, \delta_y)$. Enforce one-of constraints and link to the precomputed $\text{Comp}_{pq}^{\delta}$:

$$d_{pq}^{\delta} = 1 \Rightarrow \operatorname{Comp}_{pq}^{\delta} = 1.$$

Those implications again are linearizable via big-M.

- The number of possible offsets (δ_x, δ_y) is bounded: since all tiles must lie inside an $m \times m$ canvas, $|\delta_x|, |\delta_y| \leq m n$. Precomputing Comp $_{pq}^{\delta}$ for all feasible δ reduces the on-line overlap checking cost.
- Enforcing a spanning tree (acyclic + connected) can be done with standard directed tree/arborescence constraints (e.g. parent variables plus subtour elimination or flow constraints) if you prefer connectivity instead of the simple 'one parent per node' orientation.

Summary (informal)

- Decision variables place each tile at integer coordinates (x_v, y_v) inside an $m \times m$ canvas
- A subset of relative placements e_{uvr} form a spanning tree; chosen edges force relative offsets between tiles and thus propagate absolute positions.
- Global compatibility requires that any two tiles that end up overlapping have equal symbols in all overlapped cells.
- Objective is to minimize m.