

# **Upcoming Assignments and Assessments**

- **Homework Assignment #1 is due Sunday 2/2\***
- **Quiz #1 will be administered during this week's recitation**

**\*All future HW Assignments will be due on Fridays**

# **Row Reduction and Free Variables Part II**

# Row Reduction: Pivot Position and Pivot Columns <sup>(10)</sup>

**Definition:** A **pivot position** of a matrix is an entry that is a pivot of a row echelon form of that matrix (an entry that eventually becomes a leading 1). A **pivot column** of a matrix is a column that contains a pivot position.

## Example 1

Find the pivot positions and pivot columns of the given matrix.

$$\begin{array}{c}
 \begin{bmatrix} 3 & 2 & 1 & 9 \\ 5 & -1 & -1 & 2 \\ 1 & 1 & 1 & 1 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_3} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 5 & -1 & -1 & 2 \\ 3 & 2 & 1 & 9 \end{bmatrix} \xrightarrow{\substack{R_2 - 5R_1 \\ R_3 - 3R_1}} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & -6 & -6 & -3 \\ 0 & -1 & -2 & 6 \end{bmatrix} \xrightarrow{-\frac{1}{6}R_2} \\
 \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & \frac{1}{2} \\ 0 & -1 & -2 & 6 \end{bmatrix} \xrightarrow{R_3 + R_2} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & \frac{1}{2} \\ 0 & 0 & -1 & \frac{13}{2} \end{bmatrix} \xrightarrow{-R_3} \begin{bmatrix} \textcircled{1} & 1 & 1 & 1 \\ 0 & \textcircled{1} & 1 & \frac{1}{2} \\ 0 & 0 & \textcircled{1} & -\frac{13}{2} \end{bmatrix} \quad \begin{array}{l} \text{pivot positions} \\ \text{are circled} \\ \text{pivot columns:} \\ 1, 2, 3. \end{array} \\
 \xrightarrow{\substack{R_1 - R_3 \\ R_2 - R_3}} \begin{bmatrix} 1 & 1 & 0 & \frac{15}{2} \\ 0 & 1 & 0 & 7 \\ 0 & 0 & 1 & -\frac{13}{2} \end{bmatrix} \xrightarrow{R_1 - R_2} \begin{bmatrix} 1 & 0 & 0 & \frac{1}{2} \\ 0 & 1 & 0 & 7 \\ 0 & 0 & 1 & -\frac{13}{2} \end{bmatrix} \quad \begin{array}{l} x_1 = \frac{1}{2} \\ x_2 = 7 \\ x_3 = -\frac{13}{2} \\ (\frac{1}{2}, 7, -\frac{13}{2}) \end{array} \\
 \text{all columns except the last one are} \\
 \text{pivot columns} \Rightarrow \text{unique solution}
 \end{array}$$

# Row Reduction: Pivot Position and Pivot Columns <sup>(11)</sup>

**Definition:** A **pivot position** of a matrix is an entry that is a pivot of a row echelon form of that matrix (an entry that eventually becomes a leading 1). A **pivot column** of a matrix is a column that contains a pivot position.

## Example 2

Solve the linear system:

$$\begin{aligned} 2x + 10y &= -1 \\ 3x + 15y &= 2 \end{aligned}$$

Make a note of the pivot column(s)

$$\begin{bmatrix} 2 & 10 & -1 \\ 3 & 15 & 2 \end{bmatrix} \xrightarrow{\frac{1}{2}R_1} \begin{bmatrix} 1 & 5 & -\frac{1}{2} \\ 3 & 15 & 2 \end{bmatrix} \xrightarrow{R_2 - 3R_1} \begin{bmatrix} 1 & 5 & -\frac{1}{2} \\ 0 & 0 & \frac{7}{2} \end{bmatrix} \xrightarrow{\frac{2}{7}R_2}$$

$$\begin{bmatrix} 1 & 5 & -\frac{1}{2} \\ 0 & 0 & 1 \end{bmatrix}$$

Pivot columns:

1 and 3

If the augmented (last) column is pivot column  
 $\Rightarrow$  No solutions

$$0x + 0y = 1 \quad \text{No solution}$$

the system is inconsistent.

# Row Reduction: Pivot Position and Pivot Columns (12)

**Row echelon form of an inconsistent system.** An augmented matrix corresponds to an inconsistent system of equations if and only the last column (the augmented column) is a pivot column.

## The two cases discussed thus far

When the reduced row echelon form of a matrix has a pivot in every nonaugmented column, then it corresponds to a system with a unique solution

When the reduced row echelon form of a matrix has a pivot in the last column (augmented column), then it corresponds to a system with no solutions

### Example 3

$$\begin{bmatrix} 1 & 0 & 0 & 5 \\ 0 & 1 & 0 & -4 \\ 0 & 0 & 1 & 3 \end{bmatrix} \longrightarrow \begin{array}{rcl} x & = & 5 \\ y & = & -4 \\ z & = & 3 \end{array}$$

### Example 4

$$\begin{bmatrix} 2 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

The last line translates to  $0 = 4$  which indicates that there are no solutions to this system

# Row Reduction: Free Variables (13)

Consider the following reduced row echelon form of a given matrix:

Example:  $\begin{bmatrix} 1 & 0 & 3 & 4 \\ 0 & 1 & 2 & -1 \\ \hline 0 & 0 & 0 & 0 \end{bmatrix} \longrightarrow \begin{array}{l} \underline{x_1} + 3x_3 = 4 \\ \underline{x_2} + 2x_3 = -1 \end{array}$

The equation that corresponds to the last row,  $0x_1 + 0x_2 + 0x_3 = 0$ , can be omitted since it places no restrictions on the unknowns

Since  $x_1$  and  $x_2$  correspond to the leading 1's in the augmented matrix, we call these the **leading variables**. The remaining variables (in this case  $x_3$ ) are called **free variables**. Solving for the leading variables in terms of the free variables gives

$$\begin{aligned} x_1 &= 4 - 3x_3 \\ x_2 &= -1 - 2x_3 \end{aligned}$$

Treating  $x_3$  as a parameter and assigning to it any arbitrary value  $t$  determines the values of the other two variables. So, the solution set is given by the **parametric** equations (in **parametric form**)

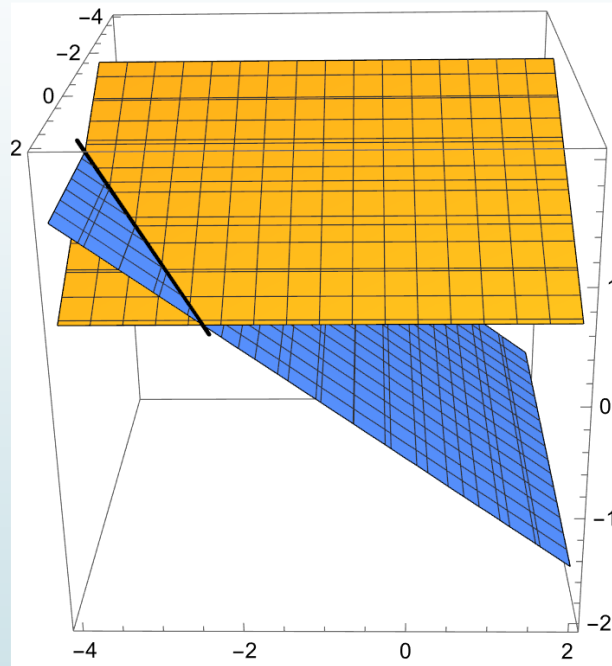
$$x_1 = 4 - 3t, \quad x_2 = -1 - 2t, \quad x_3 = t$$

# Row Reduction: Free Variables (14)

$$\begin{aligned}x_1 &= 4 - 3x_3 \\x_2 &= -1 - 2x_3\end{aligned}$$



$$x_1 = 4 - 3t, \quad x_2 = -1 - 2t, \quad x_3 = t$$



To obtain a specific solution to the system above, simply replace the free variable with a real number. Or equivalently choose that real number to be the value of the parameter  $t$ . So, for example, setting  $t = 0$  gives the specific solution  $(4, -1, 0)$

# Row Reduction: Free Variables and Parametric Form <sup>(15)</sup>

The **parametric form** of the solution set of a consistent system of linear equations is obtained as follows:

- Write the system as an augmented matrix
- Row reduce to reduced row echelon form
- Write the corresponding (now solved) system of linear equations
- Move all free variables to the right side of the equations

\*Free variables may be relabeled if you prefer, to emphasize that they are parameters

Free variables = parameters = *independent* variables

Non-free (leading) variables = *dependent* variables



## Example 3

$$\begin{array}{rcrcrcl} x_1 & + & 3x_2 & + & 2x_3 & + & x_4 & = & 32 \\ 2x_1 & - & 2x_2 & & & + & 4x_4 & = & 16 \\ 3x_1 & + & x_2 & + & 2x_3 & + & 5x_4 & = & 38 \\ x_1 & & -x_2 & & & + & 2x_4 & = & 8 \end{array}$$

$$\rightarrow \begin{bmatrix} 1 & 3 & 2 & 1 & 32 \\ 2 & -2 & 0 & 4 & 16 \\ 3 & 1 & 2 & 5 & 48 \\ 1 & -1 & 0 & 2 & 8 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 3 & 2 & 1 & 32 \\ 0 & -8 & -4 & 2 & -48 \\ 0 & -8 & -4 & 2 & -48 \\ 0 & -4 & -2 & 1 & -24 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 3 & 2 & 1 & 32 \\ 0 & 1 & \frac{1}{2} & -\frac{1}{4} & 6 \\ 0 & -8 & -4 & 2 & -48 \\ 0 & -4 & -2 & 1 & -24 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 3 & 2 & 1 & 32 \\ 0 & 1 & \frac{1}{2} & -\frac{1}{4} & 6 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

# Row Reduction: Free Variables and Parametric Form (17)

## Example 3 (continued)

$$\begin{bmatrix} 1 & 3 & 2 & 1 & 32 \\ 0 & 1 & \frac{1}{2} & -\frac{1}{4} & 6 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Add  $-3$  times row 2 to row 1

*pivot column*

$$\begin{bmatrix} 1 & 0 & \frac{1}{2} & \frac{7}{4} & 14 \\ 0 & 1 & \frac{1}{2} & -\frac{1}{4} & 6 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{aligned} \underline{x_1} + \frac{1}{2}x_3 + \frac{7}{4}x_4 &= 14 \\ \underline{x_2} + \frac{1}{2}x_3 - \frac{1}{4}x_4 &= 6 \end{aligned}$$

The leading variables are  $x_1$  and  $x_2$ . The free variables are  $x_3$  and  $x_4$ .

$$\begin{aligned} x_1 &= 14 - \frac{1}{2}x_3 - \frac{7}{4}x_4 \\ x_2 &= 6 - \frac{1}{2}x_3 + \frac{1}{4}x_4 \end{aligned}$$

$$(14 - \frac{1}{2}x_3 - \frac{7}{4}x_4, 6 - \frac{1}{2}x_3 + \frac{1}{4}x_4, x_3, x_4)$$

Letting  $x_3 = r$  and  $x_4 = s$

$$\begin{aligned} x_1 &= 14 - \frac{1}{2}r - \frac{7}{4}s \\ x_2 &= 6 - \frac{1}{2}r + \frac{1}{4}s \\ x_3 &= r \\ x_4 &= s \end{aligned}$$

# Implicit Equations versus the Parametric Form (18)

Solve the following system using row reduction (the solution set defines a line in  $\mathbb{R}^3$ , - the line of intersection of the planes defined by the initial two equations)

$$\left. \begin{array}{l} 2x + 4y - z = 2 \\ x - 2y + z = 1 \end{array} \right\} \text{Implicit Equations of the line}$$

$$\begin{aligned} \left[ \begin{array}{cccc} 2 & 4 & -1 & 2 \\ 1 & -2 & 1 & 1 \end{array} \right] &\xrightarrow{R_1 \leftrightarrow R_2} \left[ \begin{array}{cccc} 1 & -2 & 1 & 1 \\ 2 & 4 & -1 & 2 \end{array} \right] &\xrightarrow{R_2 - 2R_1} \left[ \begin{array}{cccc} 1 & -2 & 1 & 1 \\ 0 & 8 & -3 & 0 \end{array} \right] &\xrightarrow{\frac{1}{8}R_2} \\ &\left[ \begin{array}{cccc} 1 & -2 & 1 & 1 \\ 0 & 1 & -\frac{3}{8} & 0 \end{array} \right] &\xrightarrow{R_1 + 2R_2} \left[ \begin{array}{cccc} 1 & 0 & \frac{1}{4} & 1 \\ 0 & 1 & -\frac{3}{8} & 0 \end{array} \right] &\begin{array}{l} x + \frac{1}{4}z = 1 \\ y - \frac{3}{8}z = 0 \end{array} \Rightarrow \boxed{\begin{array}{l} x = 1 - \frac{1}{4}z \\ y = \frac{3}{8}z \end{array}} \end{aligned}$$

The initial two equations are called **implicit equations** of the resulting line that is the system's solution set

The parametrized solution set is called the **parametric form** of the resulting line

# Implicit Equations versus the Parametric Form (19)

Another example (a parametrized plane).

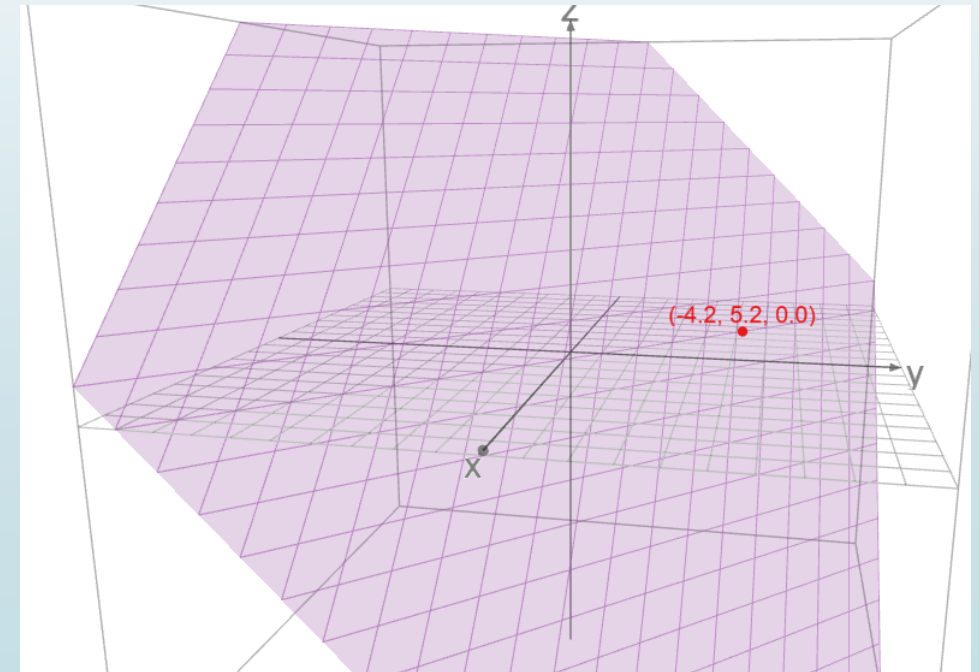
The single equation below defines a plane in  $\mathbb{R}^3$  implicitly.

$$x + y + z = 1$$

The free variables are  $y$  and  $z$ , so the parametric form for the general solution is

$$(x, y, z) = (1 - y - z, y, z)$$

This is referred to as the parametric form of the plane. Note that it has two parameters. So, to find a specific solution we simply need to choose a value for  $y$  and a value for  $z$  and then calculate the corresponding  $x$ -value. That is, any two values of  $y$  and  $z$  define a point in  $\mathbb{R}^3$  and the set of these points make up the plane.



# Number of Solutions (20)

There are *three possibilities* for the reduced row echelon form of the augmented matrix of a linear system.

1. *The last column is a pivot column.* In this case, the system is *inconsistent*. There are zero solutions, i.e., the solution set is empty. For example, the matrix

$$\left( \begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{array} \right)$$

comes from a linear system with no solutions.

2. *Every column except the last column is a pivot column.* In this case, the system has a *unique* solution. For example, the matrix

$$\left( \begin{array}{ccc|c} 1 & 0 & 0 & a \\ 0 & 1 & 0 & b \\ 0 & 0 & 1 & c \end{array} \right)$$

tells us that the unique solution is  $(x, y, z) = (a, b, c)$ .

3. *The last column is not a pivot column, and some other column is not a pivot column either.* In this case, the system has *infinitely many* solutions, corresponding to the infinitely many possible values of the free variable(s). For example, in the system corresponding to the matrix

$$\left( \begin{array}{cccc|c} 1 & -2 & 0 & 3 & 1 \\ 0 & 0 & 1 & 4 & -1 \end{array} \right),$$

any values for  $x_2$  and  $x_4$  yield a solution to the system of equations.

Note that free variables come from the columns without pivots in a matrix in row echelon form.