

```

import tensorflow as tf
from keras import layers, datasets, models
import numpy as np
from matplotlib import pyplot as plt
from IPython import display
import time

2024-06-16 11:36:31.304385: E
external/local_xla/xla/stream_executor/cuda/cuda_dnn.cc:9261] Unable
to register cuDNN factory: Attempting to register factory for plugin
cuDNN when one has already been registered
2024-06-16 11:36:31.304481: E
external/local_xla/xla/stream_executor/cuda/cuda_fft.cc:607] Unable to
register cuFFT factory: Attempting to register factory for plugin
cuFFT when one has already been registered
2024-06-16 11:36:31.427123: E
external/local_xla/xla/stream_executor/cuda/cuda_blas.cc:1515] Unable
to register cuBLAS factory: Attempting to register factory for plugin
cuBLAS when one has already been registered

(X_train, y_train), (X_test, y_test) =
datasets.fashion_mnist.load_data()

Downloading data from https://storage.googleapis.com/tensorflow/tf-
keras-datasets/train-labels-idx1-ubyte.gz
29515/29515 _____ 0s 0us/step
Downloading data from https://storage.googleapis.com/tensorflow/tf-
keras-datasets/train-images-idx3-ubyte.gz
26421880/26421880 _____ 2s 0us/step
Downloading data from https://storage.googleapis.com/tensorflow/tf-
keras-datasets/t10k-labels-idx1-ubyte.gz
5148/5148 _____ 0s 1us/step
Downloading data from https://storage.googleapis.com/tensorflow/tf-
keras-datasets/t10k-images-idx3-ubyte.gz
4422102/4422102 _____ 1s 0us/step

train_data = np.concatenate((X_train, X_test), axis = 0)
train_labels = np.concatenate((y_train, y_test), axis = 0)

print(f"X_train.shape = {X_train.shape}")
print(f"X_test.shape = {X_test.shape}")
print(f"Concatenated train data shape = {train_data.shape}")

X_train.shape = (60000, 28, 28)
X_test.shape = (10000, 28, 28)
Concatenated train data shape = (70000, 28, 28)

train_data.max()

255

```

```

train_data = (train_data - 127.5) / 127.5
# Batch and shuffle the data

batch_size = 256
buffer_size = train_data.shape[0]

batched_train_data =
tf.data.Dataset.from_tensor_slices(train_data).shuffle(buffer_size).ba
tch(batch_size)

len(batched_train_data)
274

train_data.shape[0]/batch_size
273.4375

def sbplt(rows, cols, data, labels):
    plt.figure(figsize = (rows*2,cols*2))

    for i in range (rows*cols):
        plt.subplot(rows, cols, i+1)
        plt.imshow(data[i], cmap = 'gray')
        if len(labels)!=0 :
            plt.title(labels[i])
            plt.axis('off')

    plt.tight_layout()
    plt.show()
    return

sbplt(5,5,train_data, train_labels)

```



Generator

```
noise_dim = 100

def build_generator():
    model = models.Sequential(name = 'generator')
    model.add(layers.Dense(128*7*7, activation='relu',
input_shape=(noise_dim,)))
    model.add(layers.Reshape((7,7,128)))
    model.add(layers.UpSampling2D())
    model.add(layers.BatchNormalization(momentum=0.9))
```

```

        model.add(layers.Conv2D(128, activation='relu',padding='same',
kernel_size=(3,3)))
        model.add(layers.BatchNormalization(momentum=0.8))
        model.add(layers.UpSampling2D())

        model.add(layers.Conv2D(64, activation='relu',padding='same',
kernel_size=(3,3)))
        model.add(layers.BatchNormalization(momentum=0.8))
        model.add(layers.Conv2D(1, activation='tanh',padding='same',
kernel_size=(3,3), name = 'output_layer'))

    return model

```

```

generator = build_generator()
generator.summary()

```

```

/opt/conda/lib/python3.10/site-packages/keras/src/layers/core/
dense.py:87: UserWarning: Do not pass an `input_shape`/`input_dim`
argument to a layer. When using Sequential models, prefer using an
`Input(shape)` object as the first layer in the model instead.
  super().__init__(activity_regularizer=activity_regularizer,
**kwargs)

```

Model: "generator"

Layer (type) Param #	Output Shape	
dense (Dense) 633,472	(None, 6272)	
reshape (Reshape) 0	(None, 7, 7, 128)	
up_sampling2d (UpSampling2D) 0	(None, 14, 14, 128)	
batch_normalization 512 (BatchNormalization)	(None, 14, 14, 128)	
conv2d (Conv2D)	(None, 14, 14, 128)	

147,584				
		batch_normalization_1	(None, 14, 14, 128)	
512		(BatchNormalization)		
		up_sampling2d_1 (UpSampling2D)	(None, 28, 28, 128)	
0				
		conv2d_1 (Conv2D)	(None, 28, 28, 64)	
73,792				
		batch_normalization_2	(None, 28, 28, 64)	
256		(BatchNormalization)		
		output_layer (Conv2D)	(None, 28, 28, 1)	
577				

Total params: 856,705 (3.27 MB)

Trainable params: 856,065 (3.27 MB)

Non-trainable params: 640 (2.50 KB)

Discriminator

```
input_shape = (28,28,1)
```

```
def build_discriminator():
```

```
    model = models.Sequential(name = 'discriminator')
    model.add(layers.Conv2D(filters = 32,
                             kernel_size=(3,3),
                             strides=(2,2),
                             activation=layers.LeakyReLU(0.2),
                             kernel_initializer = 'he_uniform',
                             padding='same',
                             input_shape = input_shape))
    model.add(layers.Dropout(0.25))
```

```

model.add(layers.Conv2D(filters = 64,
                        kernel_size=(3,3),
                        strides=(2,2),
                        kernel_initializer = 'he_uniform',
                        padding='same',
                        input_shape = input_shape))
model.add(layers.ZeroPadding2D(padding=((0,1),(0,1))))
model.add(layers.BatchNormalization(momentum=0.8))
model.add(layers.LeakyReLU(0.2))
model.add(layers.Dropout(0.25))

model.add(layers.Conv2D(filters = 128,
                        kernel_size=(3,3),
                        strides=(2,2),
                        kernel_initializer = 'he_uniform',
                        padding='same',
                        input_shape = input_shape))
model.add(layers.BatchNormalization(momentum=0.8))
model.add(layers.LeakyReLU(0.2))
model.add(layers.Dropout(0.25))

model.add(layers.Conv2D(filters = 256,
                        kernel_size=(3,3),
                        strides=(2,2),
                        kernel_initializer = 'he_uniform',
                        padding='same',
                        input_shape = input_shape))
model.add(layers.BatchNormalization(momentum=0.8))
model.add(layers.LeakyReLU(0.2))
model.add(layers.Dropout(0.25))

model.add(layers.Flatten())
model.add(layers.Dense(1, activation = 'sigmoid', name =
'output_layer'))

return model

discriminator = build_discriminator()
discriminator.summary()

/opt/conda/lib/python3.10/site-packages/keras/src/layers/
convolutional/base_conv.py:107: UserWarning: Do not pass an
`input_shape`/`input_dim` argument to a layer. When using Sequential
models, prefer using an `Input(shape)` object as the first layer in
the model instead.
  super().__init__(activity_regularizer=activity_regularizer,
**kwargs)

Model: "discriminator"

```

Layer (type) Param #	Output Shape	
conv2d_2 (Conv2D) 320	(None, 14, 14, 32)	
dropout (Dropout) 0	(None, 14, 14, 32)	
conv2d_3 (Conv2D) 18,496	(None, 7, 7, 64)	
zero_padding2d (ZeroPadding2D) 0	(None, 8, 8, 64)	
batch_normalization_3 256 (BatchNormalization)	(None, 8, 8, 64)	
leaky_re_lu_1 (LeakyReLU) 0	(None, 8, 8, 64)	
dropout_1 (Dropout) 0	(None, 8, 8, 64)	
conv2d_4 (Conv2D) 73,856	(None, 4, 4, 128)	
batch_normalization_4 512 (BatchNormalization)	(None, 4, 4, 128)	
leaky_re_lu_2 (LeakyReLU) 0	(None, 4, 4, 128)	

0	dropout_2 (Dropout)	(None, 4, 4, 128)	
295,168	conv2d_5 (Conv2D)	(None, 2, 2, 256)	
1,024	batch_normalization_5	(None, 2, 2, 256)	
	(BatchNormalization)		
0	leaky_re_lu_3 (LeakyReLU)	(None, 2, 2, 256)	
0	dropout_3 (Dropout)	(None, 2, 2, 256)	
0	flatten (Flatten)	(None, 1024)	
1,025	output_layer (Dense)	(None, 1)	

Total params: 390,657 (1.49 MB)

Trainable params: 389,761 (1.49 MB)

Non-trainable params: 896 (3.50 KB)

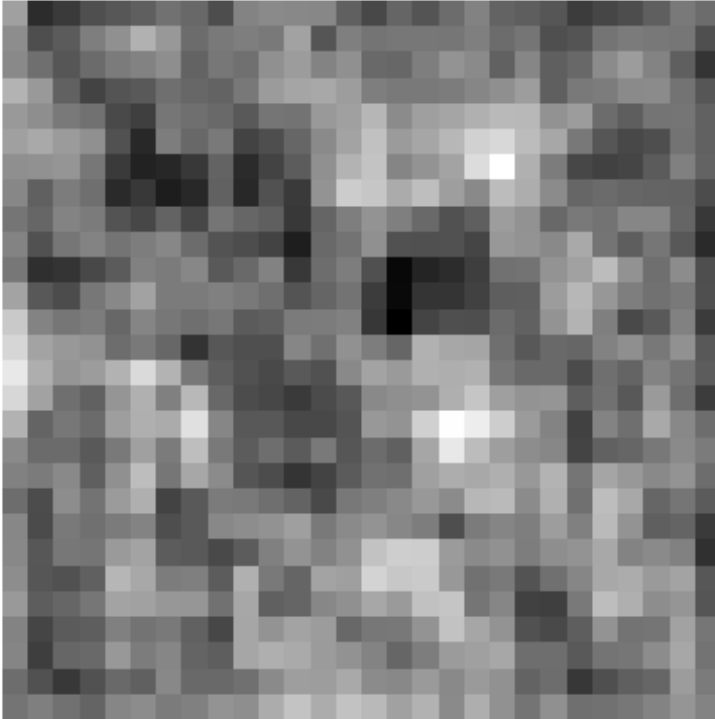
Testing for random noises

```

num_samples = 1
noises = tf.random.normal([num_samples, noise_dim])
gen_img = generator(noises, training = False)
plt.imshow(gen_img[0, :, :, 0]*127.5 + 127.5, cmap = 'gray')
plt.axis('off')
print(discriminator(gen_img, training = False))
plt.show()

tf.Tensor([[0.45838943]], shape=(1, 1), dtype=float32)

```

Optimizers for Generator and Discriminator

```
generator_optimizer = tf.keras.optimizers.Adam(learning_rate = 0.0001,  
beta_1 = 0.5)  
discriminator_optimizer = tf.keras.optimizers.Adam(learning_rate =  
0.0001, beta_1 = 0.5)
```

Loss functions of Generator and Discriminator

```
def discriminator_loss(real_output, fake_output):  
    real_loss = tf.reduce_mean(tf.nn.relu(1.0 - real_output))  
    fake_loss = tf.reduce_mean(tf.nn.relu(1.0 + fake_output))  
    return real_loss + fake_loss  
  
def generator_loss(fake_output):  
    return -tf.reduce_mean(fake_output)
```

Training

```
noise_dim = noise_dim  
batch_size = batch_size  
  
print(f"batch_size = {batch_size}")  
print(f"noise_dim = {noise_dim}")  
  
batch_size = 256  
noise_dim = 100
```

```

@tf.function
def train_step (real_images):

    noise = tf.random.normal([batch_size, noise_dim])

    with tf.GradientTape() as gen_tape, tf.GradientTape() as disc_tape:
        generated_images = generator(noise, training = True)
        fake_outputs = discriminator(generated_images, training = True)
        real_outputs = discriminator(real_images, training = True)

        gen_loss = generator_loss(fake_outputs)
        disc_loss = discriminator_loss(real_output = real_outputs,
fake_output = fake_outputs)

        generator_gradients = gen_tape.gradient(gen_loss,
generator.trainable_variables)
        discriminator_gradients = disc_tape.gradient(disc_loss,
discriminator.trainable_variables)

        generator_optimizer.apply_gradients(zip(generator_gradients,
generator.trainable_variables))
        discriminator_optimizer.apply_gradients(zip(discriminator_gradients,
discriminator.trainable_variables))

    return disc_loss, gen_loss

# Test generator on following noises throughout training
num_samples = 16
test_noises = tf.random.normal([num_samples, noise_dim])

def generate_and_save_image(model, epoch, test_input):
    rows = 4
    cols = 4

    plt.figure(figsize=(rows*2, cols*2))
    plt.suptitle(f"Epoch = {epoch}")

    generated_images = model(test_input)

    for i in range(rows * cols):
        ax = plt.subplot(rows, cols, i + 1)
        ax.axis('off')
        ax.imshow(generated_images[i, :, :, 0] * 127.5 + 127.5,
cmap='gray')

    plt.tight_layout()

    if not os.path.exists("images"):

```

```

        os.makedirs("images")

    plt.savefig(f"images/image-at-epoch-{epoch:04d}.png")
    plt.show()

import os

# Define checkpoint directory and checkpoint prefix
checkpoint_dir = './training_checkpoints'
checkpoint_prefix = os.path.join(checkpoint_dir, "ckpt")

# Create a checkpoint object
checkpoint = tf.train.Checkpoint(generator_optimizer =
                                discriminator_optimizer =
                                discriminator_optimizer,
                                generator = generator,
                                discriminator = discriminator)

# Restore the latest checkpoint if available
latest_checkpoint = tf.train.latest_checkpoint(checkpoint_dir)
if latest_checkpoint:
    checkpoint.restore(latest_checkpoint)
    print("Checkpoint restored:", latest_checkpoint)

def train(dataset, epochs):
    disc_losses = []
    gen_losses = []

    for epoch in range(1, epochs + 1):
        start = time.time()

        for real_image_batch in dataset:
            disc_loss, gen_loss = train_step(real_image_batch)

        disc_losses.append(disc_loss)
        gen_losses.append(gen_loss)

        display.clear_output(wait=True)
        print(f"Epoch = {epoch}, disc_loss = {disc_loss}, gen_loss = {gen_loss}, time_taken = {time.time() - start} seconds")
        generate_and_save_image(model=generator, epoch=epoch,
                                test_input=test_noises)

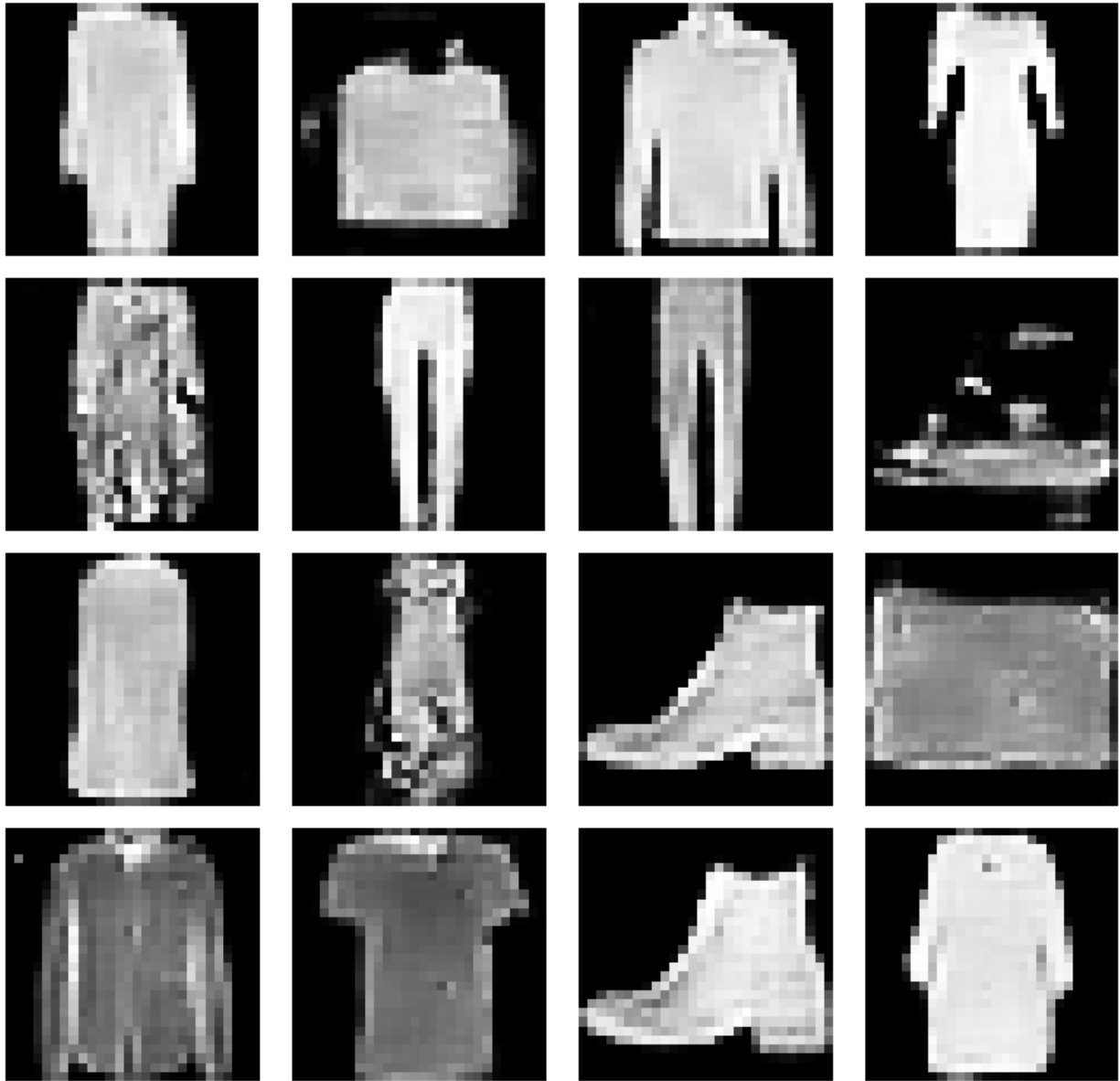
        if epoch % 5 == 0:
            checkpoint.save(file_prefix=checkpoint_prefix)
            print(f"checkpoint saved for epoch = {epoch}")

    history = {

```

```
        'discriminator_losses': disc_losses,  
        'generator_losses': gen_losses  
    }  
  
    print(f"history of epoch = {epoch} saved")  
    print(f"epoch = {epoch+1} started")  
  
    return history  
  
epochs = 100  
history = train(batched_train_data, epochs = epochs)  
  
Epoch = 100, disc_loss = 1.8447736501693726, gen_loss = -  
0.41264939308166504, time_taken = 11.497250318527222 seconds
```

Epoch = 100



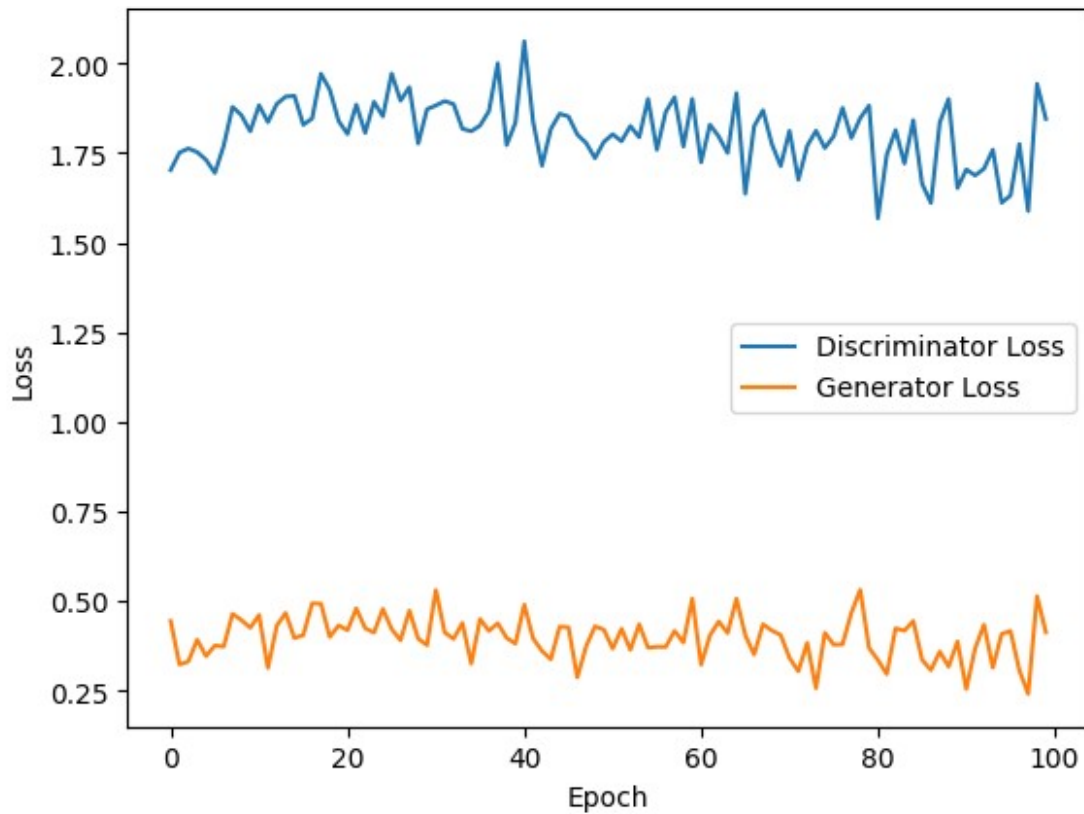
```
checkpoint saved for epoch = 100  
history of epoch = 100 saved  
epoch = 101 started
```

```
import os  
import pickle
```

```
# Ensure the output directory exists  
output_dir = '/kaggle/working/'  
os.makedirs(output_dir, exist_ok=True)
```

```
# Save the history object to the output directory
```

```
output_path = os.path.join(output_dir, 'drgan-fashion-mnist-history-  
loss-hingeloss.pkl')  
with open(output_path, 'wb') as pickle_file:  
    pickle.dump(history, pickle_file)  
  
# Load the history from the pickle file  
with open('drgan-fashion-mnist-history-loss-hingeloss.pkl', 'rb') as  
pickle_file:  
    loaded_history_pickle = pickle.load(pickle_file)  
  
# Access the loaded history  
discriminator_losses = loaded_history_pickle['discriminator_losses']  
generator_losses = loaded_history_pickle['generator_losses']  
  
generator.save("generator-fashion-mnist-hingeloss.h5")  
  
neg_generator_losses = []  
  
for i in generator_losses:  
    neg_generator_losses.append(abs(i))  
  
plt.plot(discriminator_losses, label='Discriminator Loss')  
plt.plot(neg_generator_losses, label='Generator Loss')  
plt.xlabel('Epoch')  
plt.ylabel('Loss')  
plt.legend()  
plt.show()
```



```
import shutil

# Define the directory containing the images and the output zip file
images_dir = '/kaggle/working/images'
output_zip = '/kaggle/working/images-fashion-mnist-hingeloss.zip'

# Zip the directory
shutil.make_archive(output_zip.replace('.zip', ''), 'zip', images_dir)

print(f"Zipped {images_dir} to {output_zip}")

Zipped /kaggle/working/images to /kaggle/working/images-fashion-mnist-hingeloss.zip
```