

L-BFGS in Reinforcement Learning

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1 Abstract

In current deep learning literature, first-order methods are much more common due to its computation speed. However, there is a similarity between ADAM and L-BFGS, with computations of different version of “momentum”. With this project, we show that L-BFGS is not an in-place replacement for ADAM and requires a through investigation for the policy to converge.

2 Introduction

In class, we learned the power of second order methods and speed of convergence using those methods. In current deep learning literature, first-order methods are much more common due to its computation speed. The current state of the art first order method, ADAM computes a version of “momentum” using the first and second moment of the gradients, successfully becoming state-of-the-art in terms of convergence. However, we observe the similarity between ADAM and L-BFGS, since L-BFGS computes a different version of “momentum” by satisfying the secant conditions and using an approximation of the Hessian to accelerate convergence. Knowing these two facts, we conduct an in-depth study using both optimizers on deep reinforcement learning tasks.

2.1 Reinforcement Learning

For our reinforcement learning algorithm, we use Q-Learning with temporal difference update. We also use a target network, which helps stabilize learning. For our test environment, we used OpenAI’s CartPole, which is a task to balance a pole on a cart as long as possible.

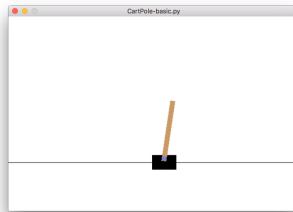


Figure 1. CartPole Environment

2.2 Optimizers

We compare ADAM and L-BFGS. Here, we introduce what guided us to state the similarity between ADAM and L-BFGS.

2.2.1 ADAM Optimizer

The ADAM update uses an estimate of the first and second moments of the gradients, to have either a dampening or multiplicative effect on the gradient update.

ADAM uses the following hyper-parameters:

- β_1 , a mixing coefficient determining the momentum of the first moment estimate
- β_2 , a mixing coefficient determining the momentum of the second moment estimate
- ε , a factor to make sure division by zero does not occur.
- η , the learning rate

These four hyper-parameters create the following rule for the t th update. Suppose θ is the current set of parameters, that we wish to train. Then the update rule for θ is

$$\begin{aligned}
 \theta &\leftarrow \theta_{t-1} \\
 g_t &\leftarrow \nabla_{\theta} f_{\theta}(x) \\
 m_t &\leftarrow \beta_1 \cdot m_{t-1} + (1 - \beta_1) \cdot g_t \\
 v_t &\leftarrow \beta_2 \cdot v_{t-1} + (1 - \beta_2) \cdot g_t^2 \\
 \hat{m}_t &\leftarrow \frac{m_t}{1 - \beta_1^t} \\
 \hat{v}_t &\leftarrow \frac{v_t}{1 - \beta_2^t} \\
 \theta_t &\leftarrow \theta_{t-1} - \eta \cdot \frac{\hat{m}_t}{\sqrt{\hat{v}_t} + \varepsilon}
 \end{aligned}$$

Notice here, that the update rule is not explicitly based off of the gradient calculation g_t by itself. The ADAM calculates estimates for the first and second moments, using those to obtain a some notion of “momentum”.

2.2.2 L-BFGS Optimizer

L-BFGS update on the other hand, uses a rough estimate of the Hessian with some constraints.

Let α be the step size. Typically line search is used, but pytorch’s LBFGS operates on batches and uses fixed-width instead of a line search. In particular, the update for BFGS is as of follows

$$\begin{aligned}
\theta &\leftarrow \theta_t \\
p_k &\leftarrow -B_k^{-1} \nabla_{\theta} \\
s_k &\leftarrow \alpha \cdot p_k \\
x_{k+1} &\leftarrow x_k + s_k \\
y_k &\leftarrow \nabla_{\theta}(x_{k+1}) - \nabla_{\theta}(x_k) \\
B_{k+1} &\leftarrow B_k + \frac{y_k y_k^T}{y_k^T s_k} - \frac{B_k s_k s_k^T B_k}{s_k^T B_k s_k}
\end{aligned}$$

Notice that the step is chosen with an approximation of the inverse Hessian, B_k . Since the approximation of the Hessian is a guaranteed decent direction, due to the secant conditions, it can also be thought of as another version of “momentum”. L-BFGS is another approximation on top of this, without storing the Hessian, and keeping track of the last h steps.

3 Experiments

3.1 Replacing ADAM

We attempt to replace ADAM by finding a set of hyper-parameters that induces stable learning for ADAM, and seeing how well replacing by L-BFGS does.