



Reconstructing and Synthesizing Spatio-Temporal Super-Resolution Data Through Machine Learning

Shourya Verma

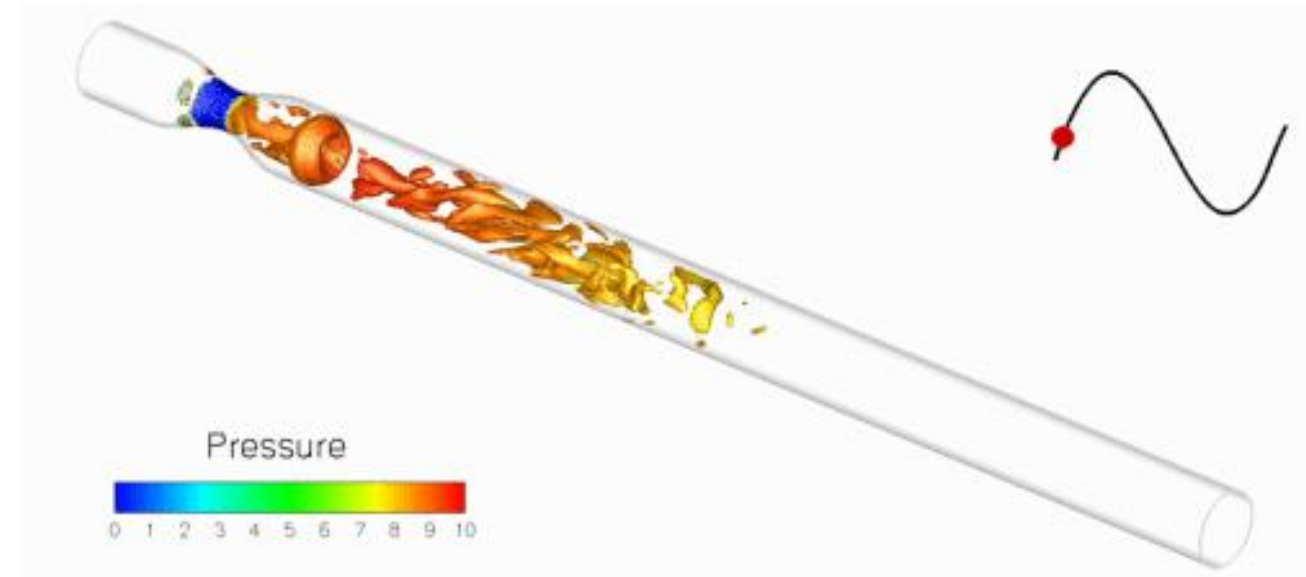
Fukami, K., Fukagata, K., & Taira, K. (2021). Machine-learning-based spatio-temporal super resolution reconstruction of turbulent flows. *Journal of Fluid Mechanics*, 909, A9. doi:10.1017/jfm.2020.948

J. Han, H. Zheng, D. Z. Chen and C. Wang, "STNet: An End-to-End Generative Framework for Synthesizing Spatiotemporal Super-Resolution Volumes," in *IEEE Transactions on Visualization and Computer Graphics*

Motivation

- 2D or 3D fluid dynamics simulations
- Problems:
 - Data storage – big data
 - Data sharing – between scientists
- Topic explores:
 - Data reduction and recovery
 - Turbulent vector and scalar data
 - Reconstructing and synthesizing data
 - Machine learning techniques
 - Super resolution spatio-temporal data

Fluid dynamic simulation

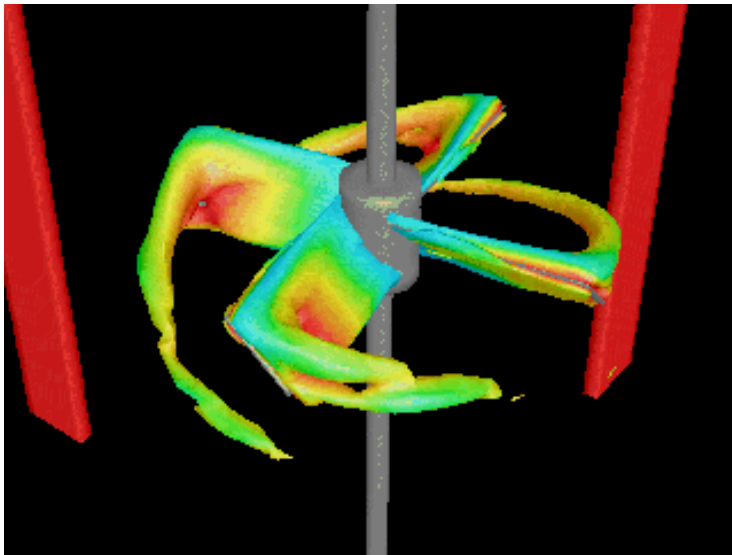


<https://engineering.purdue.edu/CFDLAB/>

Example

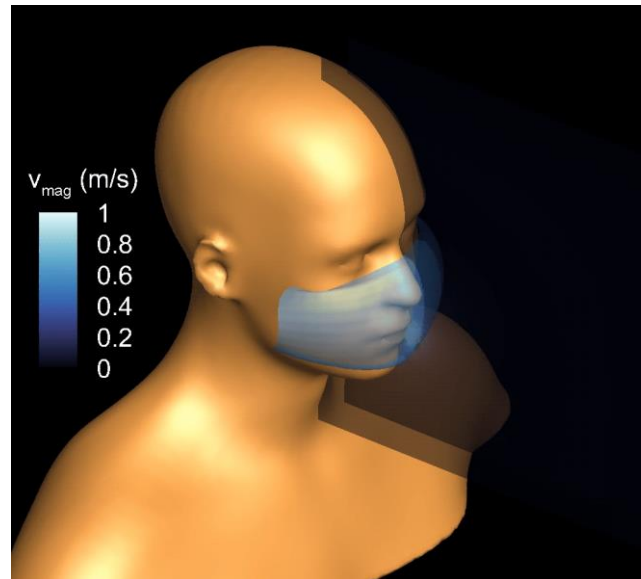
- Why fluid dynamic simulations?

Industrial turbines



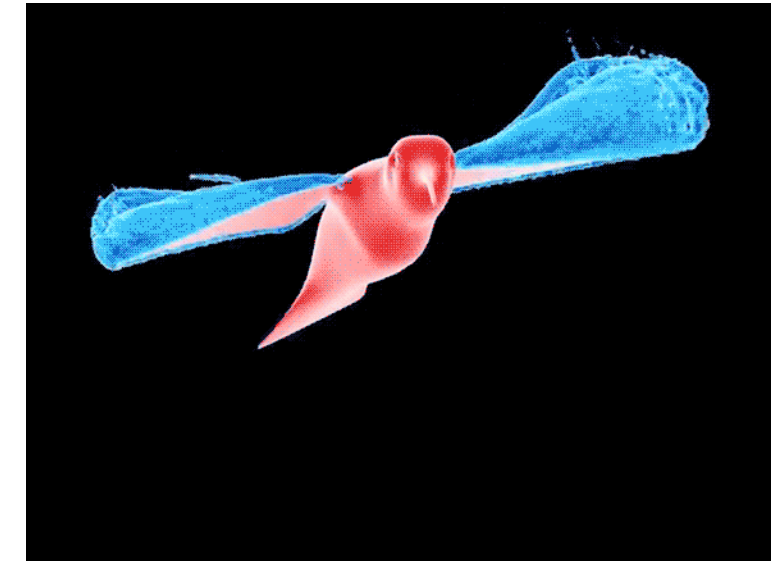
<https://www.bakker.org/cfm/a5-3.gif>

Coughing airflow



<https://scx2.b-cdn.net/gfx/news/2020/whatfluiddyn.gif>

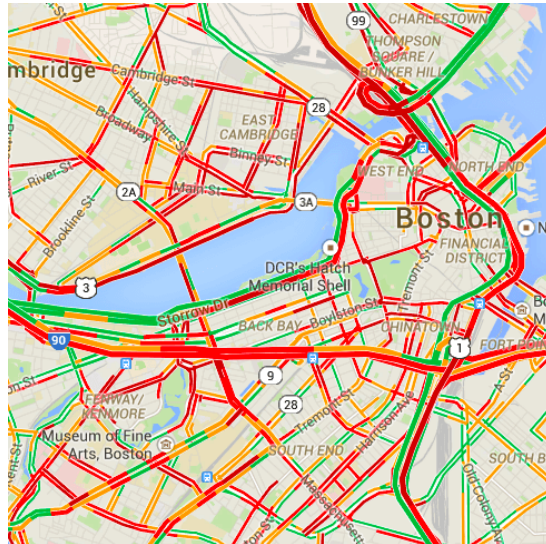
Bird wings



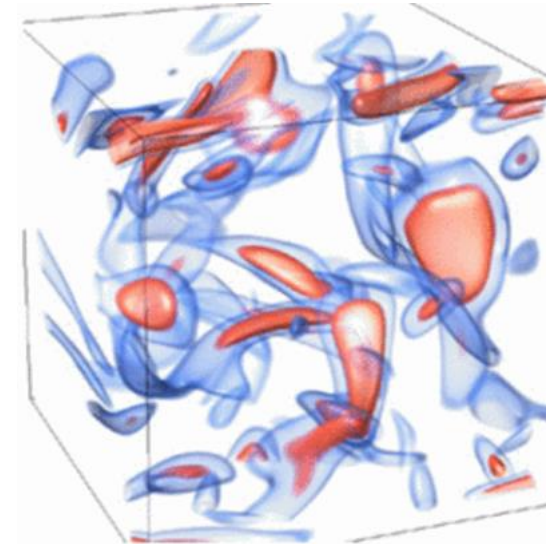
<https://i.pinimg.com/originals/b5/28/c2/b528c22e8d18ed271bf4b8f3687a6e62.gif>

Spatio-Temporal (ST) Data

- Spatio-temporal data is data relating to both space and time, represented as vector (x, t)
- Some examples:
 - *2D space + 1D time*: Traffic Volume data
 - *3D space + 1D time*: Particle Flow Field data



3D Traffic Volume data [1]



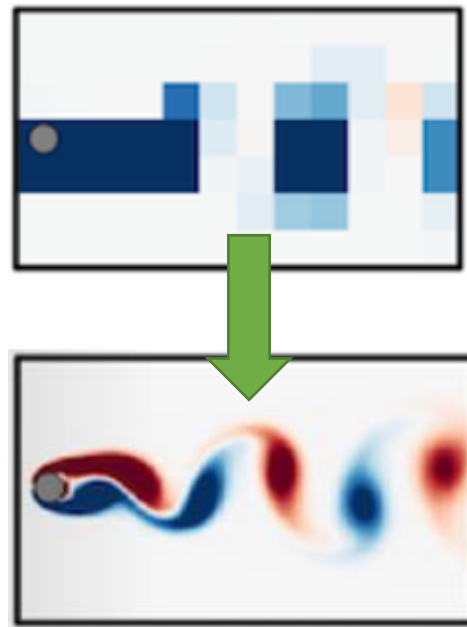
4D Particle Flow Field data [2]

[1] https://medium.com/@imtechpros_87395/where-does-google-maps-get-its-traffic-data-from-2562f984d82f

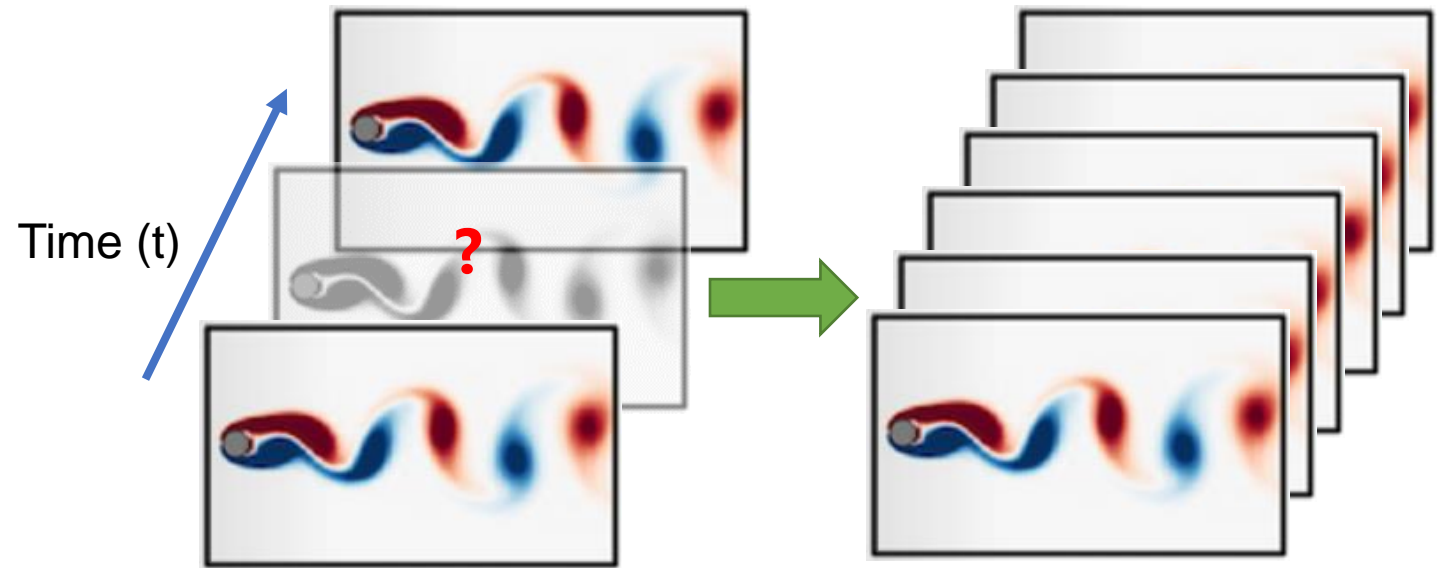
[2] J. Han, H. Zheng, D. Z. Chen and C. Wang, "STNet: An End-to-End Generative Framework for Synthesizing Spatiotemporal Super-Resolution Volumes," in *IEEE Transactions on Visualization and Computer Graphics*

Spatio Temporal Super Resolution (STSR) Data

- Low-resolution ($128 \times 128 \times 50$) \rightarrow Super-resolution ($512 \times 512 \times 200$) ($x \times y \times t$)
- *In space*: resolution is upscaled so visualizations appear at higher resolution
- *In time*: sequences are found between first and last frames of time-series



spatial super resolution



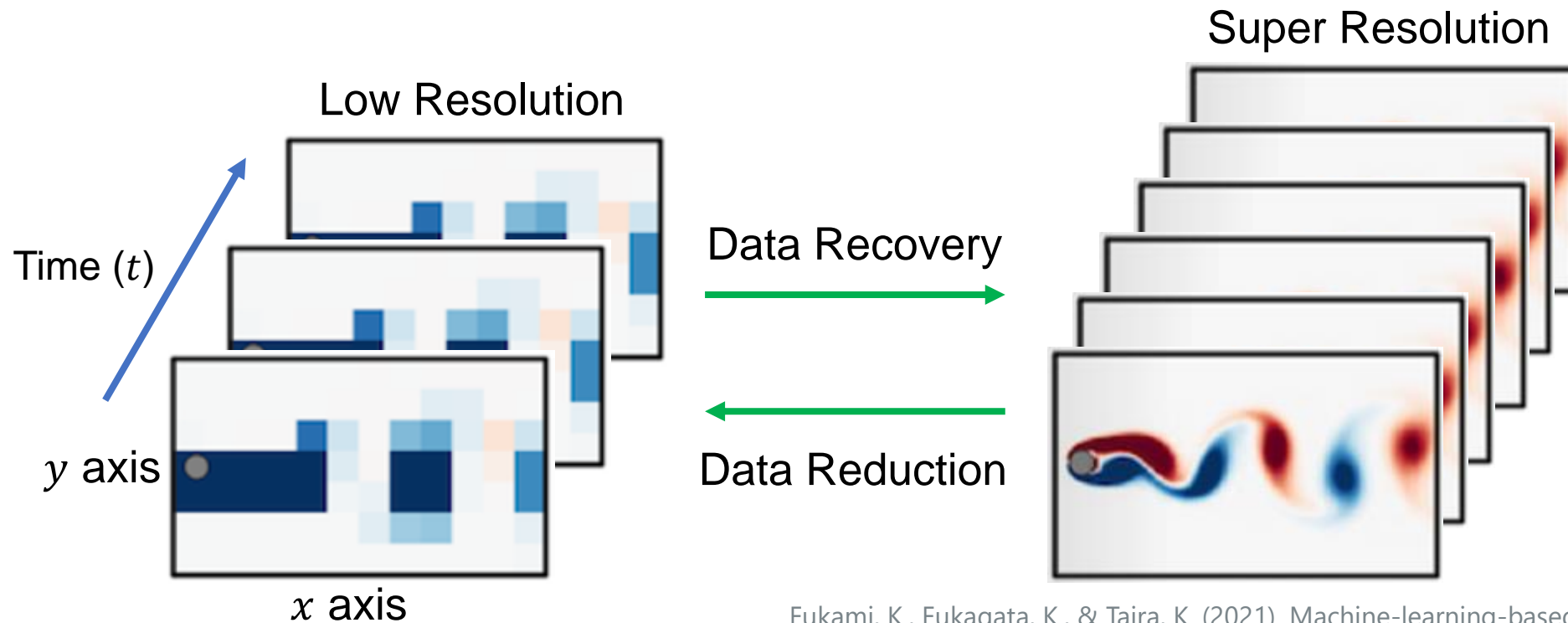
temporal inbetweening

Fukami, K., Fukagata, K., & Taira, K. (2021). Machine-learning-based spatio-temporal super resolution reconstruction of turbulent flows. *Journal of Fluid Mechanics*, 909, A9. doi:10.1017/jfm.2020.948

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Problem Setting

- How to reconstruct and synthesize spatio-temporal super-resolution data?
- Visual computing problem in *data reduction* and *data recovery*
- Dealing with spatio-temporal data → dimensions like 3D (x, y, t) or 4D (x, y, z, t)
- Machine learning (ML) to create *super-resolution* output from *low-resolution* input



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Machine Learning based Spatio-Temporal Super Resolution Reconstruction of Turbulent Flows

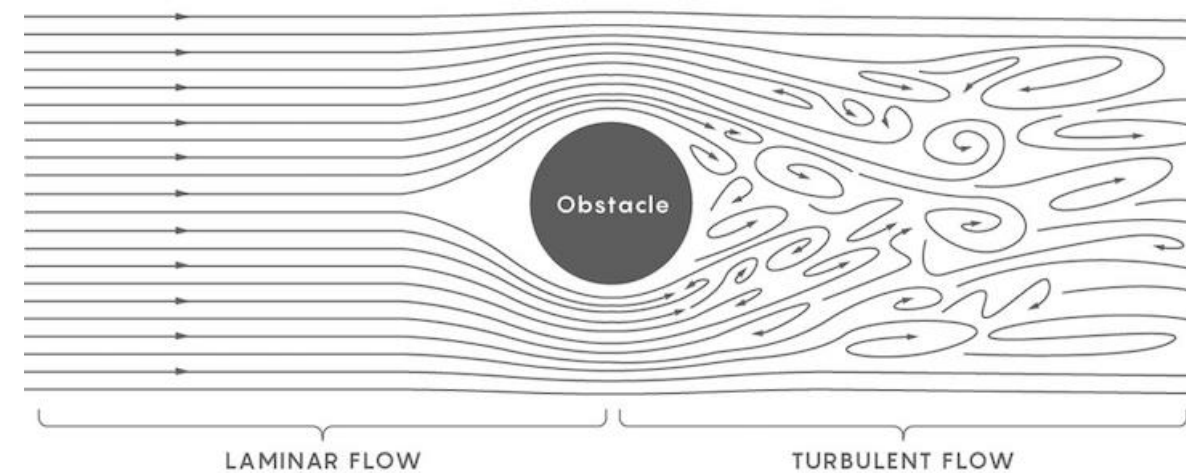
Fukami, K., Fukagata, K., and Taira, K.

Journal of Fluid Mechanics, 909, A9, 2021

ML based STSR Reconstruction of Turbulent Flows

- Why turbulent flows?

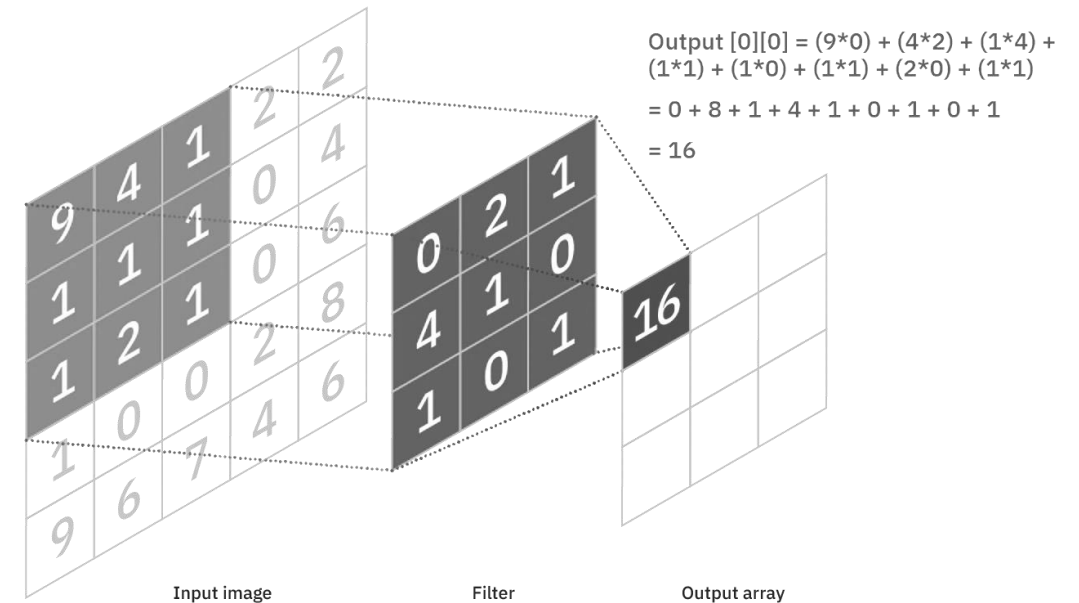
- Large eddy simulations in fluid dynamics
- Aerospace, automotive, and energy industries
- Simulate airflow and atmospheric currents



<https://nautil.us/what-makes-the-hardest-equations-in-physics-so-difficult-7006/>

- Why machine learning for reconstruction?

- Neural networks learn feature representations
- Convolutional networks effective for 3D spatial data
- Dot product of input and filter gives output array



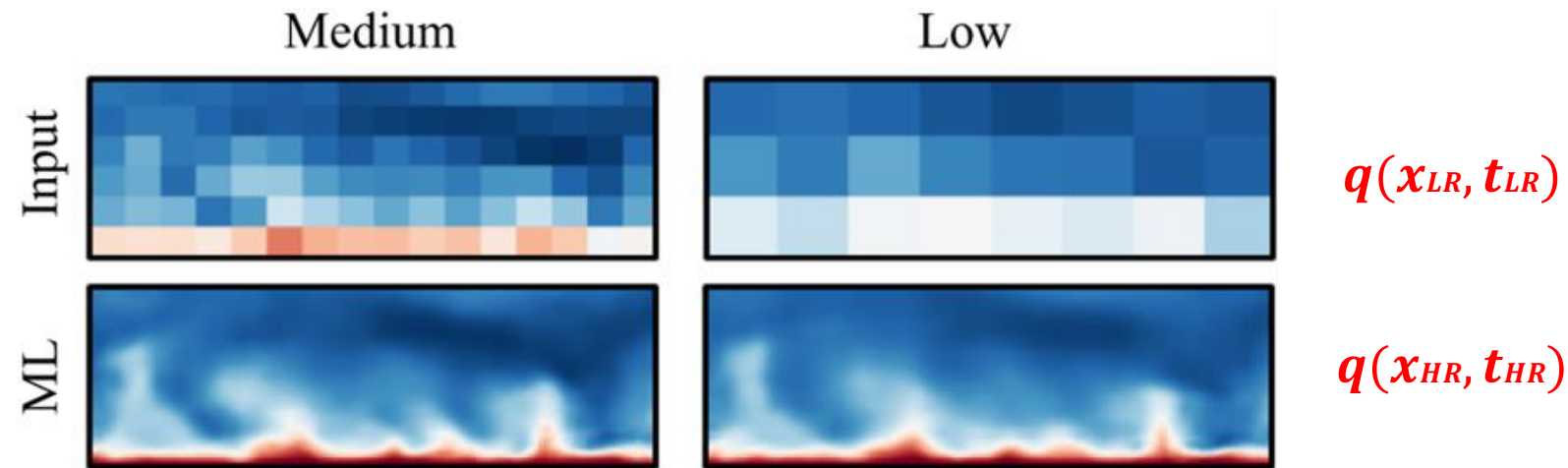
ML based STSR Reconstruction of Turbulent Flows

- Turbulent flow data reconstruction task using ML.
- Reconstructs low resolution (LR) to high resolution (HR) flow field data

$$q(\mathbf{x}_{LR}, t_{LR})$$

$$q(\mathbf{x}_{HR}, t_{HR})$$

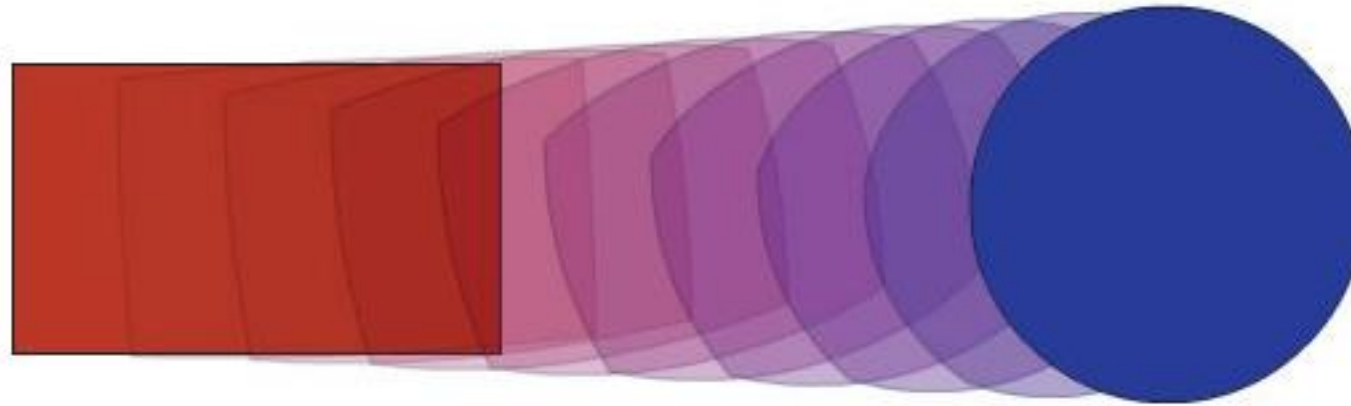
- Sequential *spatial SR* and *temporal inbetweening* ML techniques



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Temporal Inbetweening

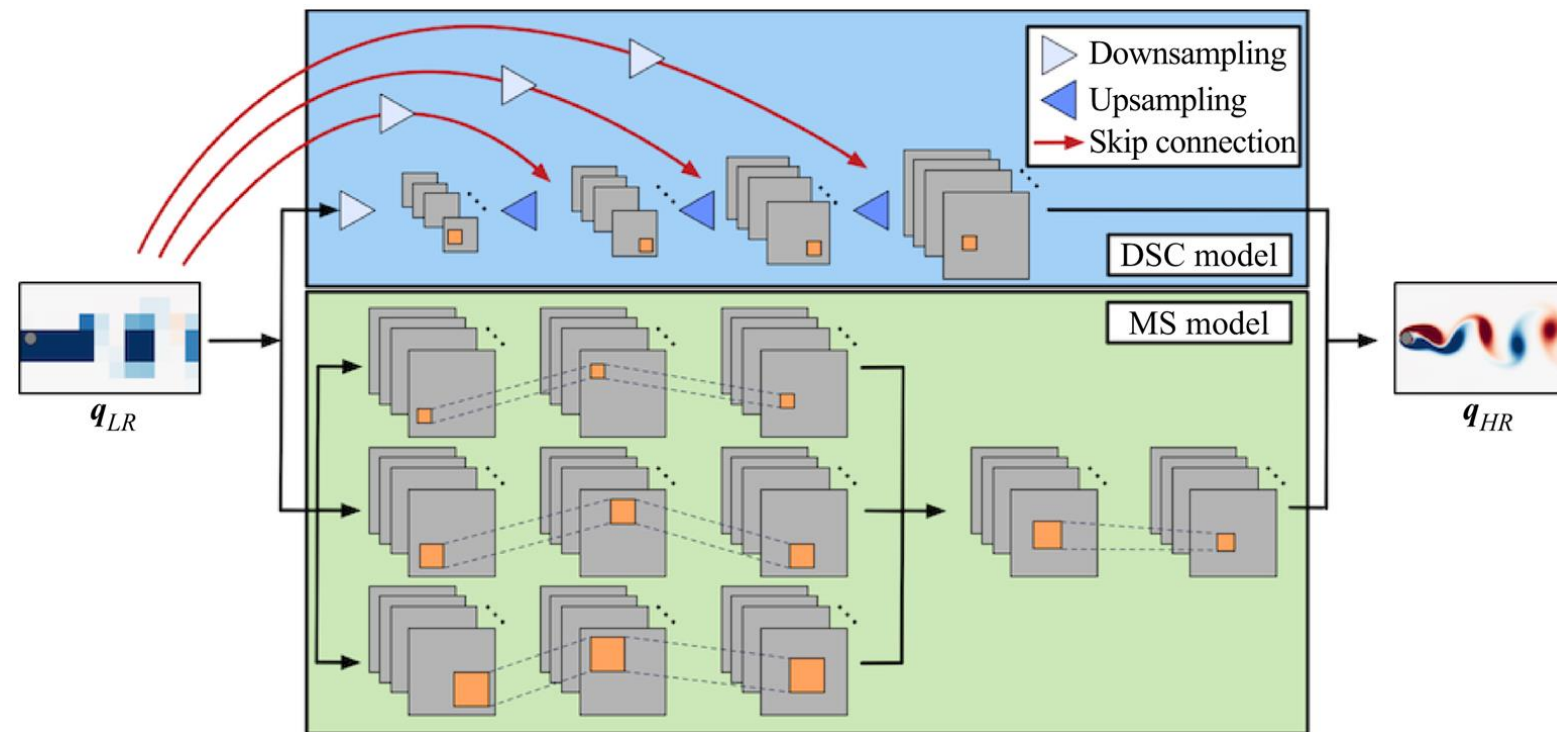
- Process of creating intermediate frames between two frames
- Creates the visualization of movement
- Smoothly transitioning one image into another at different time intervals
- Machine learning models generate as much as 14 frames between 2 given frames



<https://www.slideshare.net/fatyalsaadi/lesson-4-shape-tween>

Hybrid Machine Learning Model

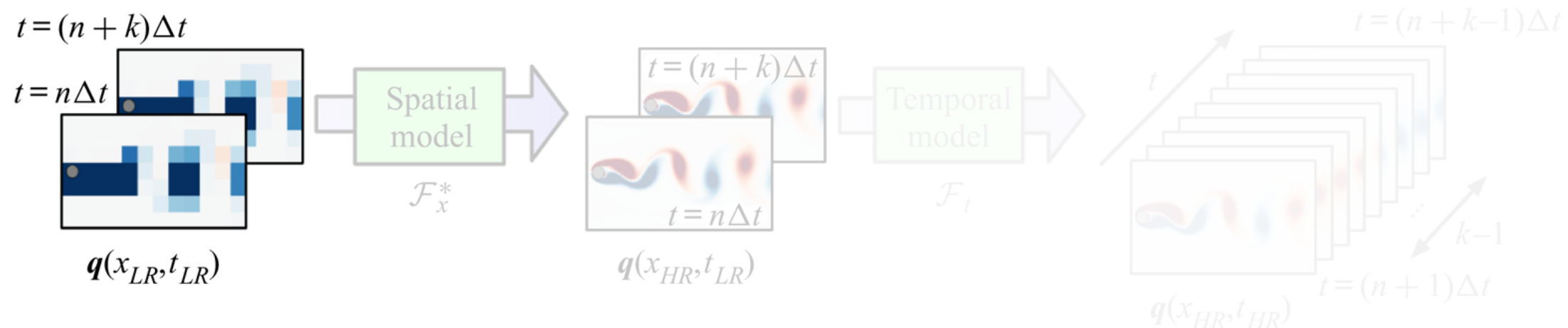
- The DSC model robust against rotation and translation
 - Combines compression procedures and skip-connection structures
- MS model useful for learning the property of flow field
 - It utilizes multiple channels of convolutional neural network layers



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Data Reconstruction Framework

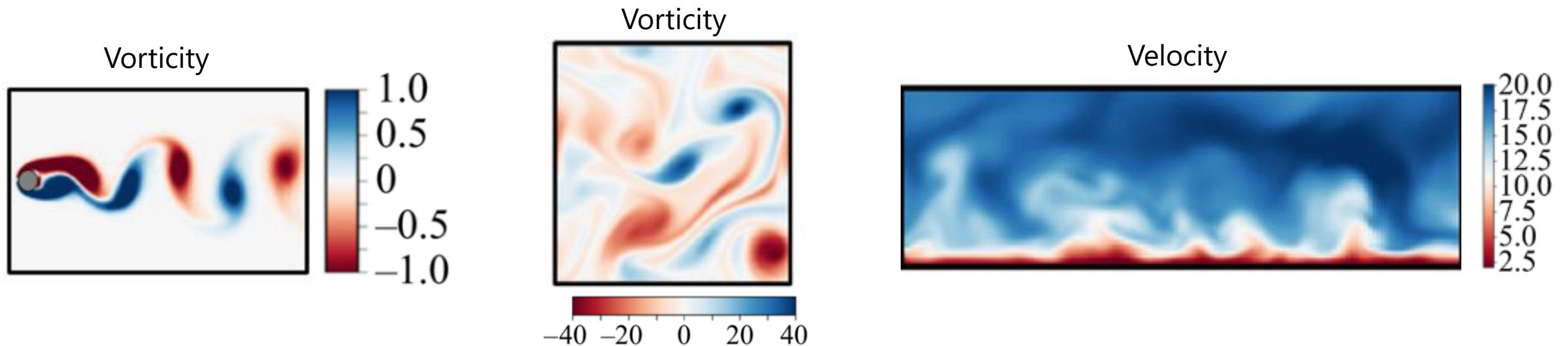
- Reconstruction framework by applying *spatial SR* Fx then *temporal inbetweening* Ft
 - Two models were applied in sequence:
 - Error ϵx from Fx model accumulated into error ϵt from Ft model
 - ϵtx is the *total error*
 - Spatio-temporal HR reconstruction:
 - $q(x_{HR}, t_{HR}) = Ft(Fx(q(x_{LR}, t_{LR}))) + \epsilon tx$
- Δt is time step between the first and last frames
 n and k are number of snapshots



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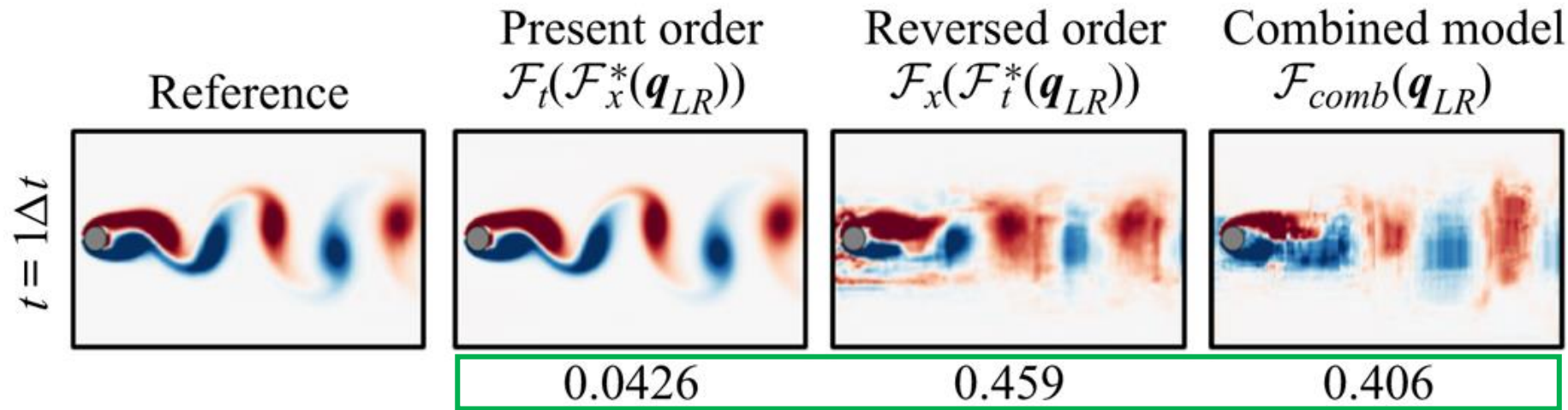
Datasets

- Generated by 2D direct numerical simulation
- Incompressible Navier–Stokes equation simulate data
- Variables include velocity, vorticity, pressure and viscosity
 - Pressure: force per unit area
 - Vorticity: rotation of a fluid (curl of the velocity)
 - Viscosity: resistance to deformation at a given rate



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Sequential vs Combined Model



$$\mathbf{q}(\mathbf{x}_{HR}, t_{HR}) = \mathbf{F}_{comb}(\mathbf{q}(\mathbf{x}_{LR}, t_{LR}))$$

Root Mean Square Error Norm

$$\epsilon = |\omega_{DNS} - \omega_{ML}|_2 / |\omega_{DNS}|_2$$

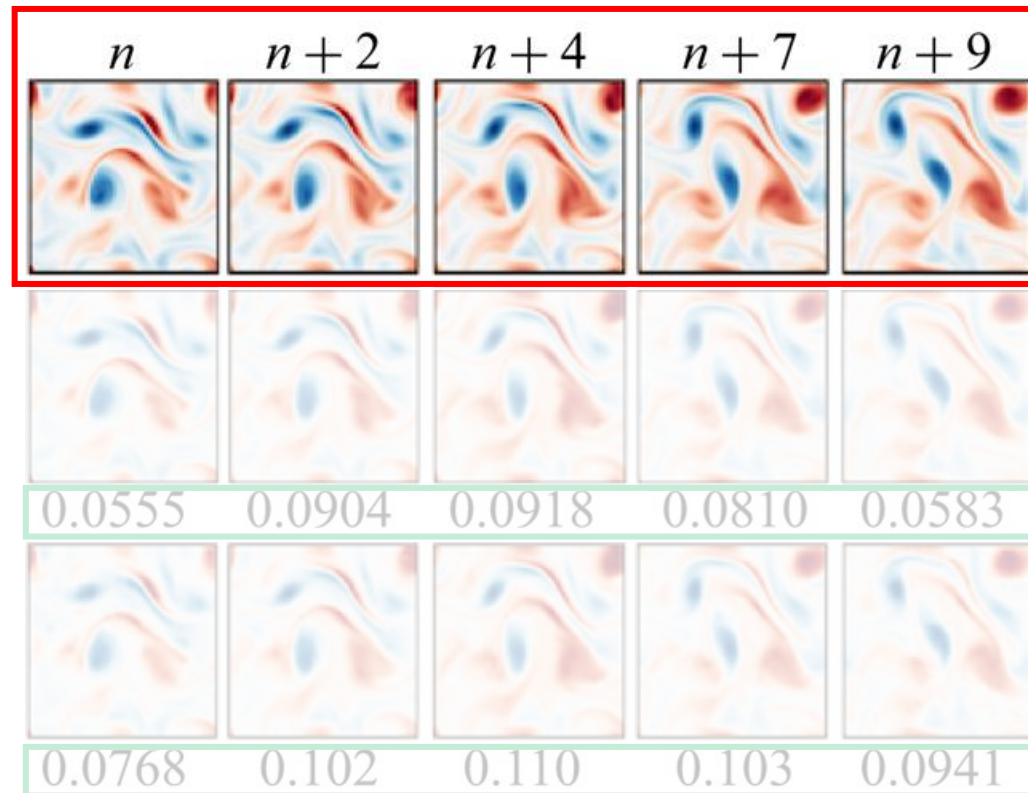
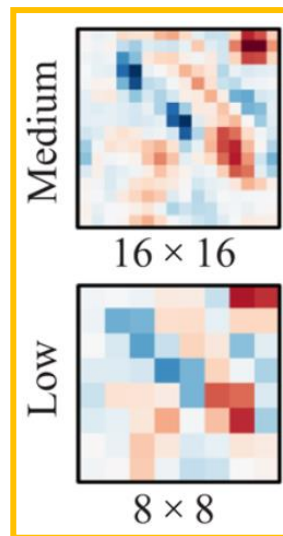
optimized weights ω

- Examine utilizing a single combined model
- The flow field cannot be reconstructed well
- This is caused by:
 - Difficulty in weight updates while training ML model
 - Error accumulation

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Results – Vorticity Contours

Coarse Input Medium
and Low Resolution



Reference
128x128

Root Mean Square Error Norm

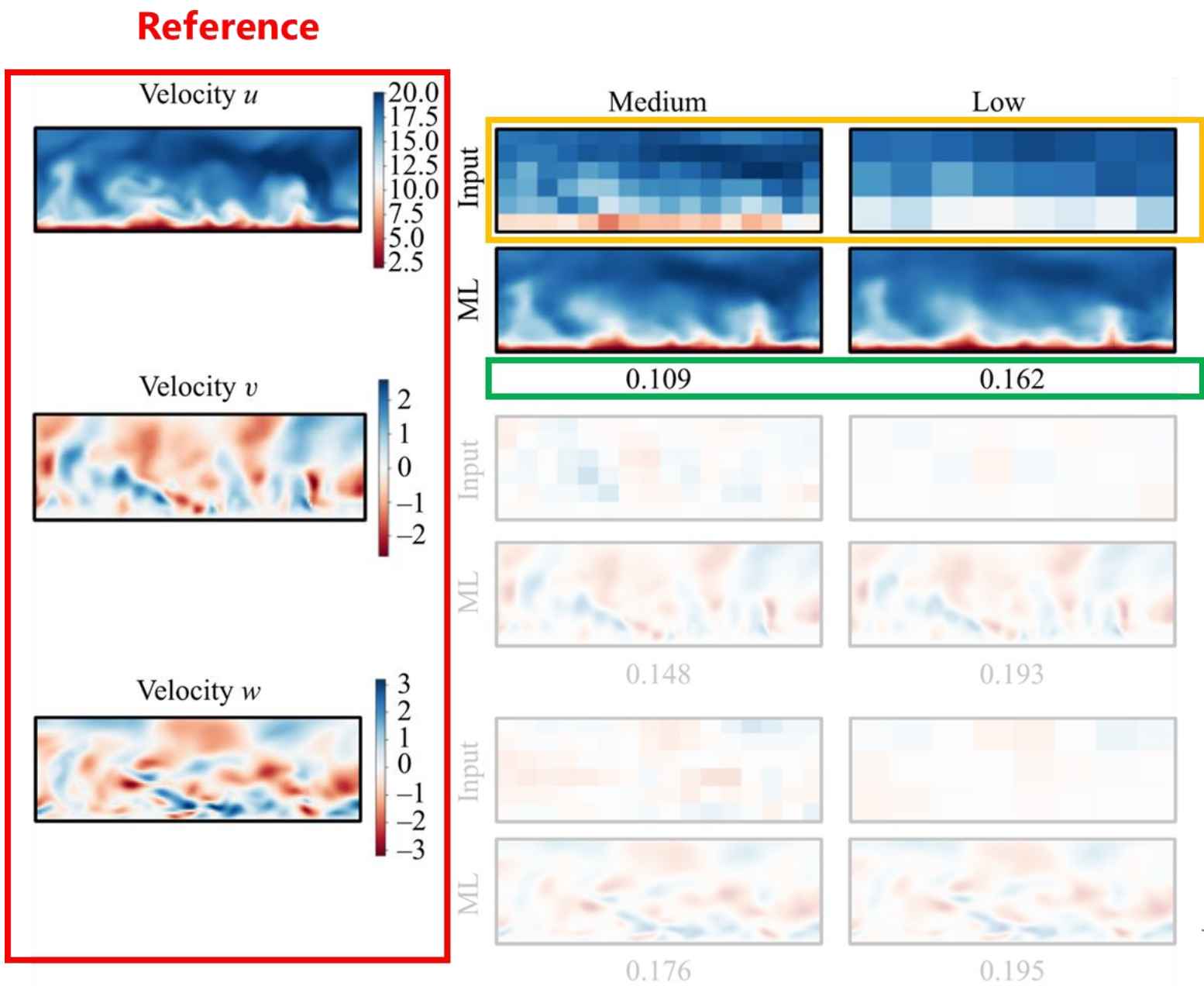
$$\epsilon = |\omega_{DNS} - \omega_{ML}|_2 / |\omega_{DNS}|_2$$

optimized weights ω

- Reconstructed from various coarse input
- Accurately reconstructed by ML models
- Reconstruction agreement with reference data.

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Results – Velocity Contours



Coarse Input Medium and Low Resolution

Root Mean Square Error Norm

$$\epsilon = |\omega_{DNS} - \omega_{ML}|_2 / |\omega_{DNS}|_2$$

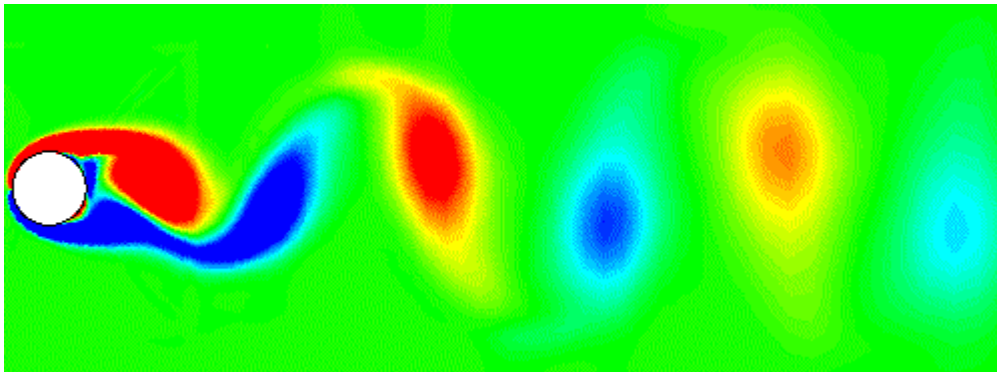
optimized weights ω

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What can be improved?

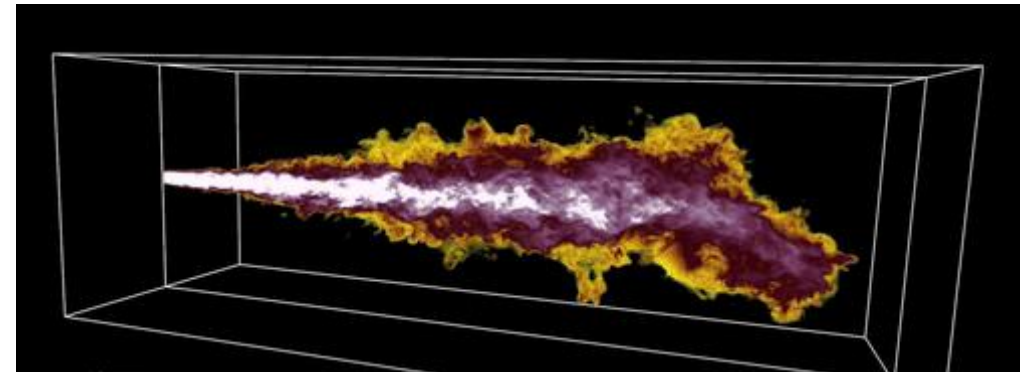
- Sequential model does not provide high fidelity results
 - Due to error accumulation
- Data space interpolation computationally heavy
 - Inbetweening of high resolution
- Turbulent vector data difficult for volumes
 - Computationally heavy

2D turbulent flow



<https://engineering.purdue.edu/CFDLAB/>

3D turbulent flow



<https://thumbs.gfycat.com/UnsungDistinctHochstettersfrog-max-1mb.gif>



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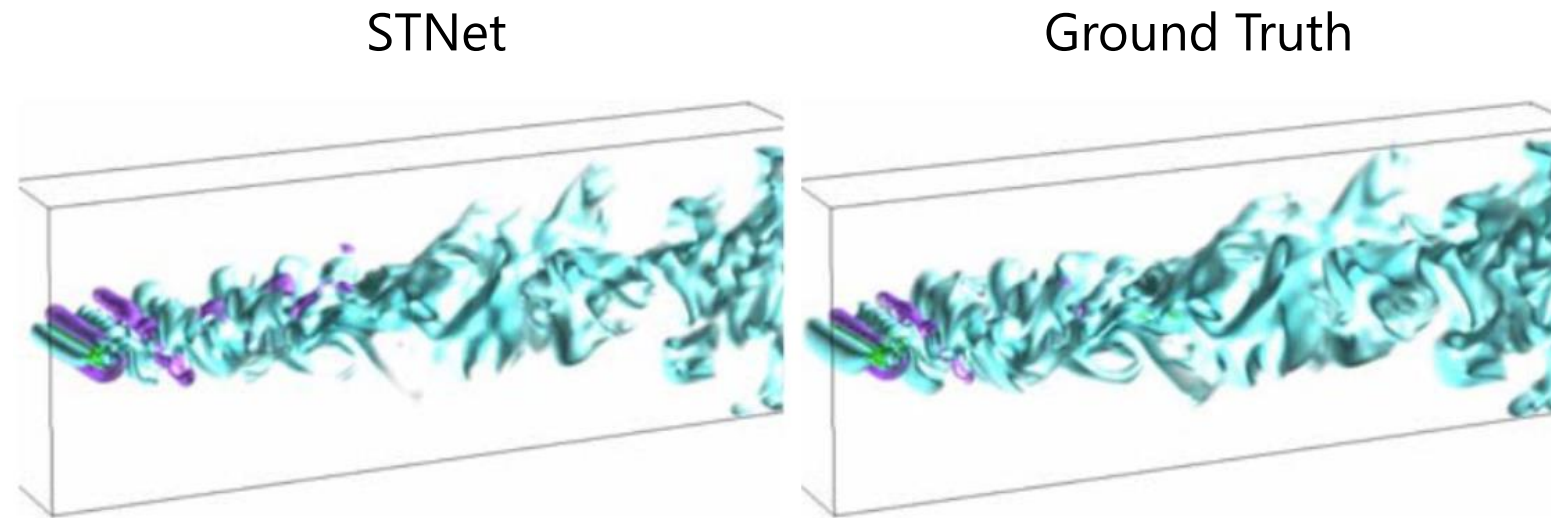
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IEEE Transactions on Visualization and Computer Graphics, vol. 28, no. 1, pp. 270-280, Jan. 2022

STNet: End to End Generative Framework for STSR Volumes

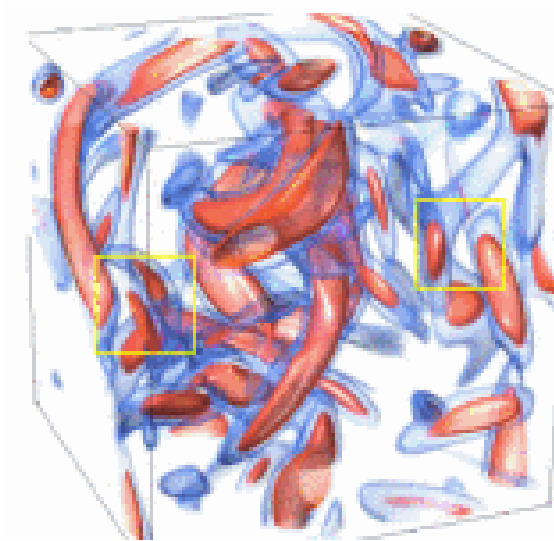
- Synthesizing STSR volumes using end-to-end ML
- *End-to-end* generative architecture critical for avoiding error accumulation
- Leverages *feature interpolation* instead of data interpolation
- Network uses *fine-tuning* stage for better generalizability



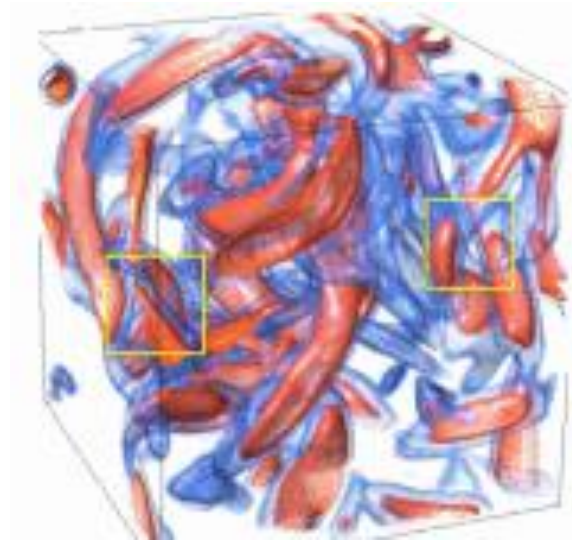
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End to End Network

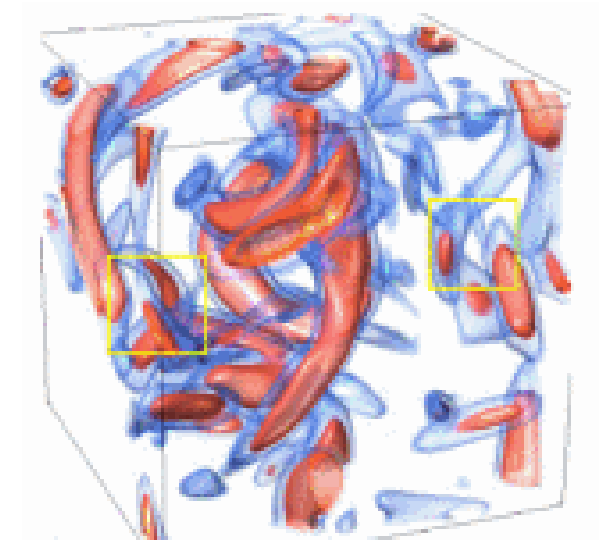
- *Single training phase*, instead of building sequential spatial and temporal models
- Errors do not accumulate from different sequential stages
- Yields much higher quality results
- STNet upscale volumes at both spatial and temporal dimensions simultaneously



Ground Truth



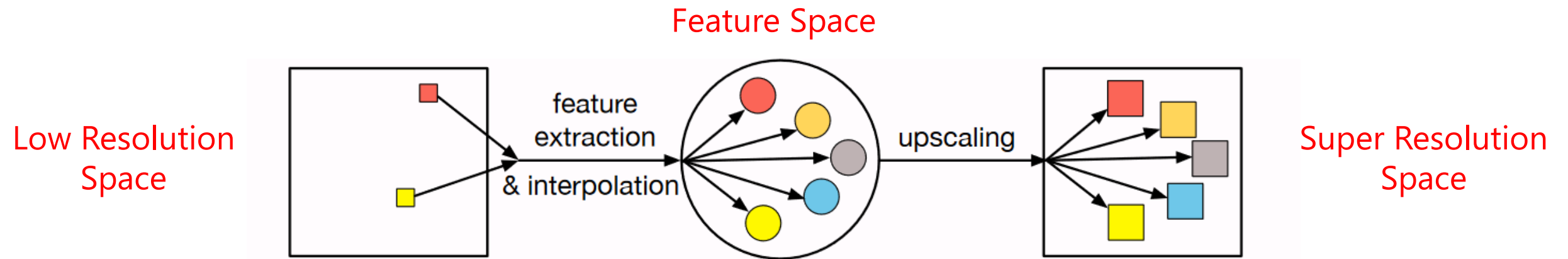
Spatial + Temporal



STNet

Feature Interpolation

- Feature-space interpolation:
 - Feature extraction and interpolation through ML
 - Generates feature of each intermediate time step individually
 - Upscales all time steps to super resolution after feature generation
- Post-upsampling brings two benefits:
 - *Speed*: Low computation cost, fewer operations occur in high-dimensional space
 - *Performance*: No issue in upscaling, convolutions occur in low-dimensional space

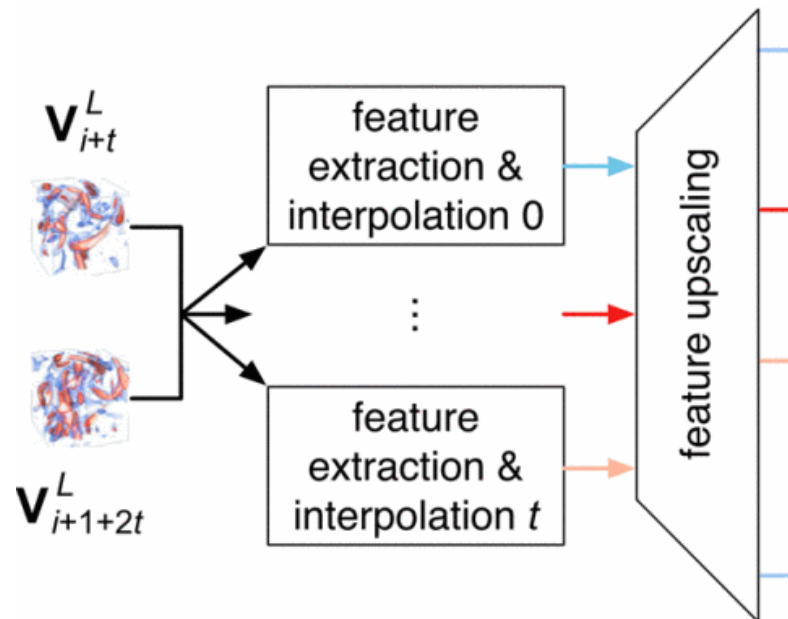


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Data Synthesizing Framework

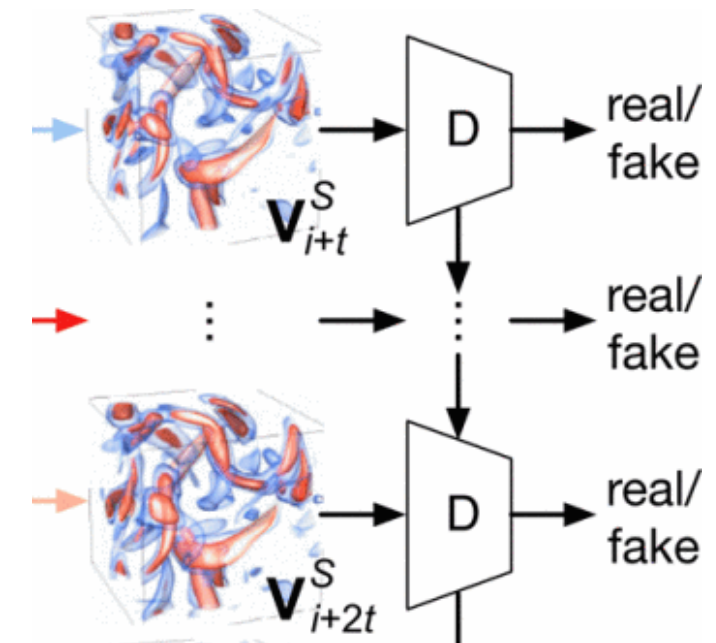
Generator

- Feature extraction interpolation module
 - Takes low resolution input
 - Performs interpolation in feature space
 - Convolutional layers extract features
- Feature upscaling module
 - Upscales all intermediate frames



Discriminator

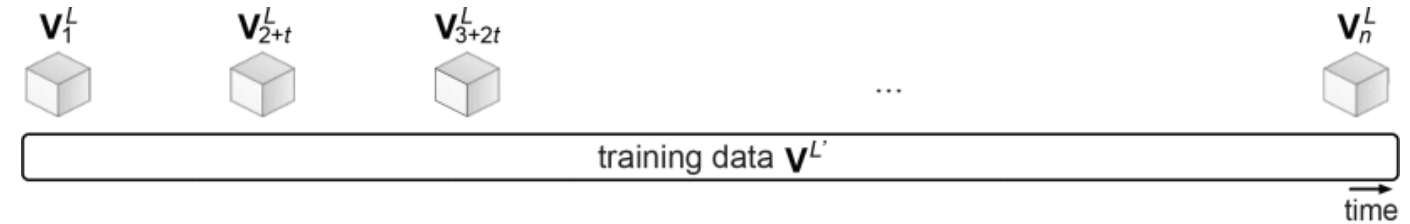
- Judge closeness and realness of volumes
 - Convolutional layers extract features
 - Features compressed to single value
- Scores assigned to each value
 - Closeness to original volume
 - Real or Fake



Pre-training and Fine-tuning

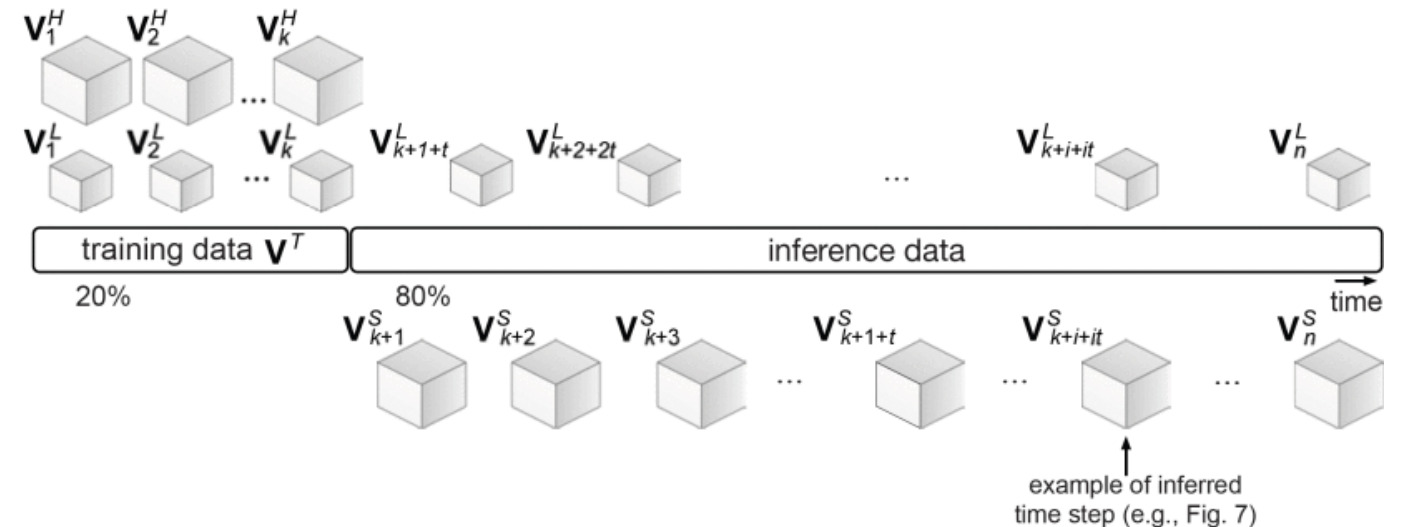
Pre-training

- Avoids model to be stuck in a local minimum
- Avoids overfitting of training data
- *Cycle loss* to optimize model



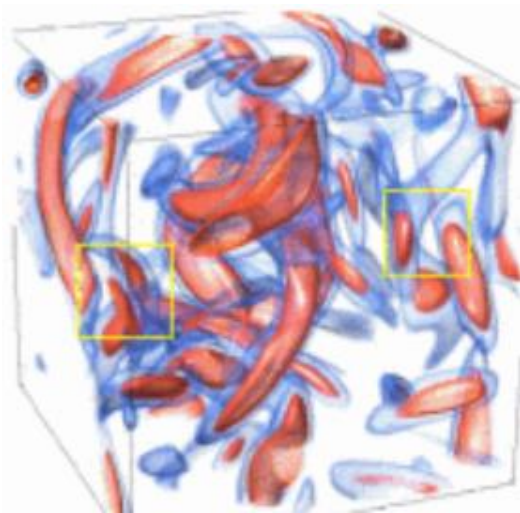
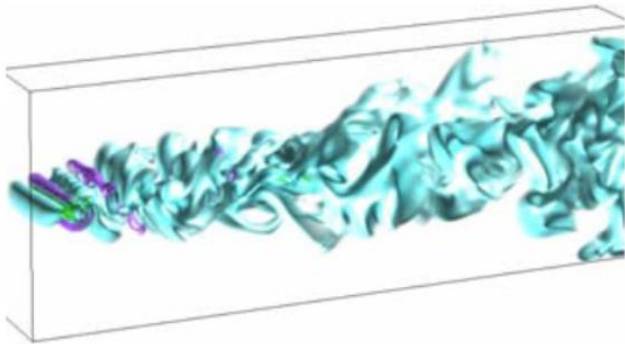
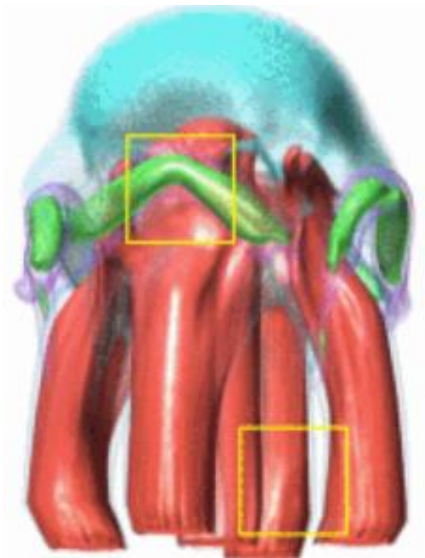
Fine-tuning

- Enhances network fit
- Improves generalizability of the model
- *Volumetric loss* to measure closeness
- *Adversarial loss* to measure realness



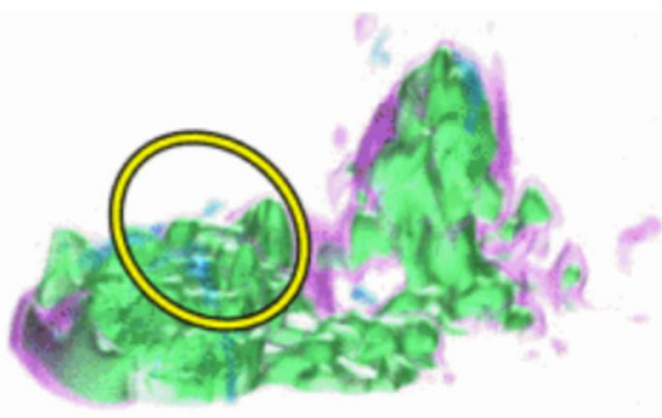
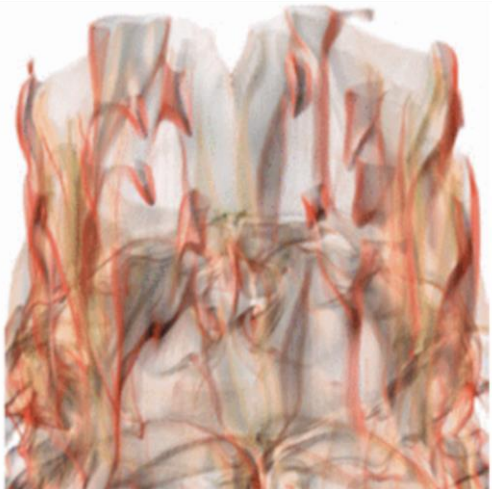
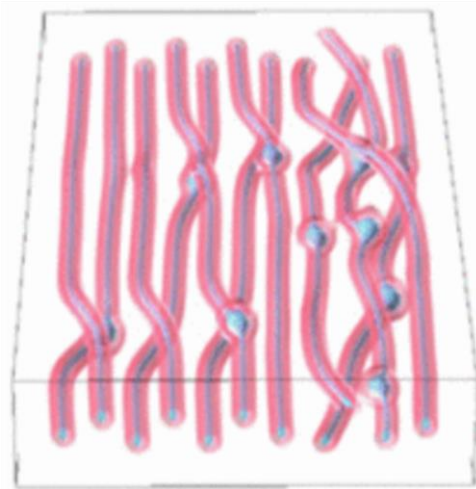
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Datasets



Dataset	Five Jets	Half Cylinder	Vortex
Variable	Intensity	Velocity Magnitude	Vorticity Magnitude

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Dataset	Supercurrent	Ionization (H)	Tangaroa
Variable	Rho	H	Velocity Magnitude

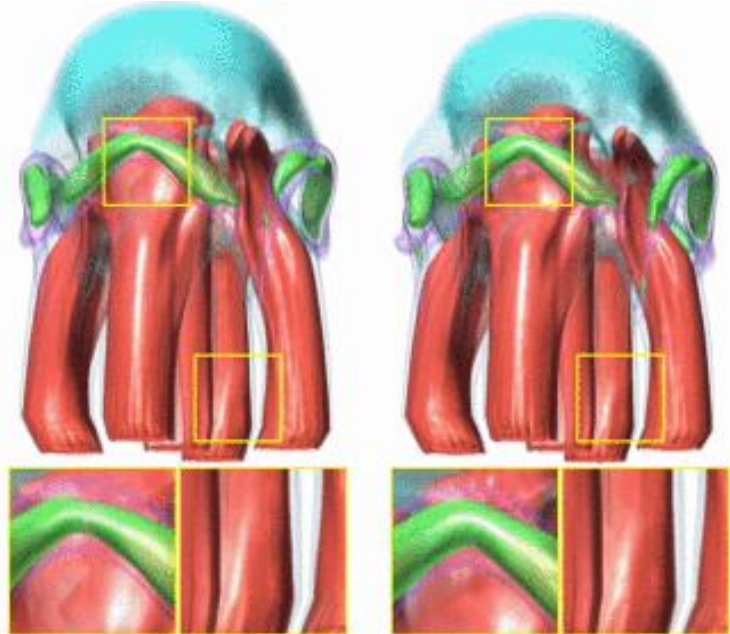
Results – Volume Rendering

- Peak signal-to-noise (PSNR)
 - Ratio of signal power and corrupting noise
- Image-level structural similarity index (SSIM)
 - Quantifies image quality degradation

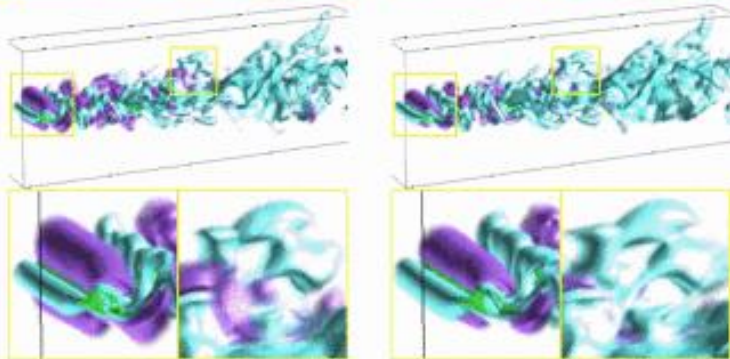
Dataset	PSNR	SSIM
Five Jets	39.63	0.901
Half Cylinder	36.84	0.944
Vortex	32.73	0.720

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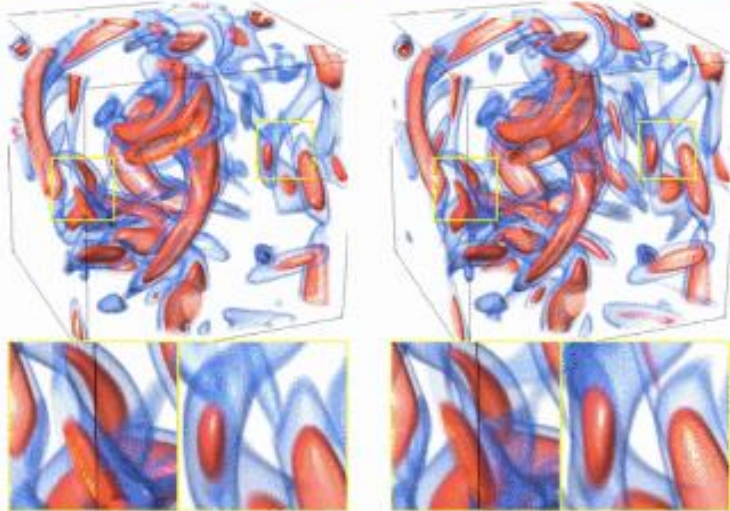
Five Jets



Half Cylinder



Vortex



(d) STNet

(e) GT

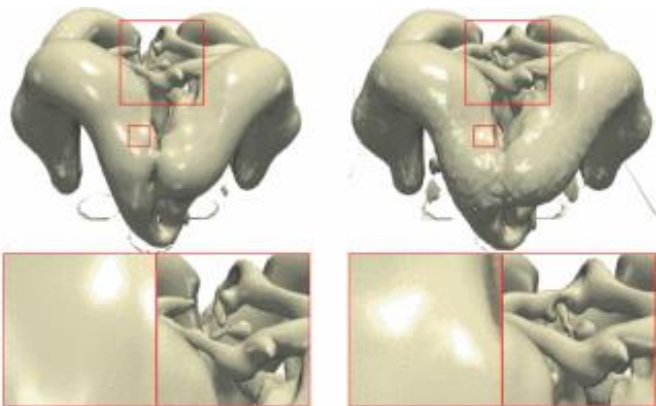
Results – Iso-surface Rendering

- Iso-surface similarity index (IS)
 - Quantifies image quality degradation

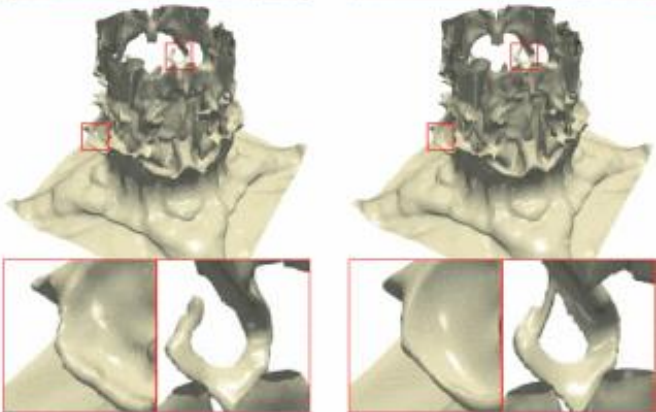
Dataset	IS
Five Jets	0.88
Ionization (H)	0.81
Tangaroa	0.75
Supercurrent	0.96

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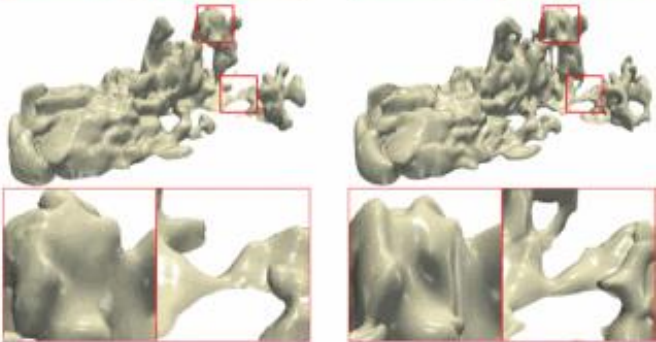
Five Jets



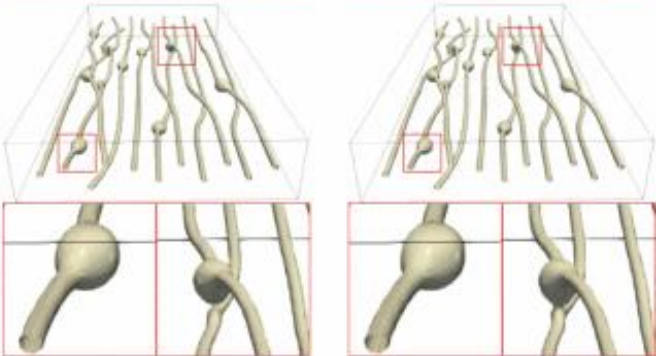
Ionization (H)



Tangaroa



Supercurrent

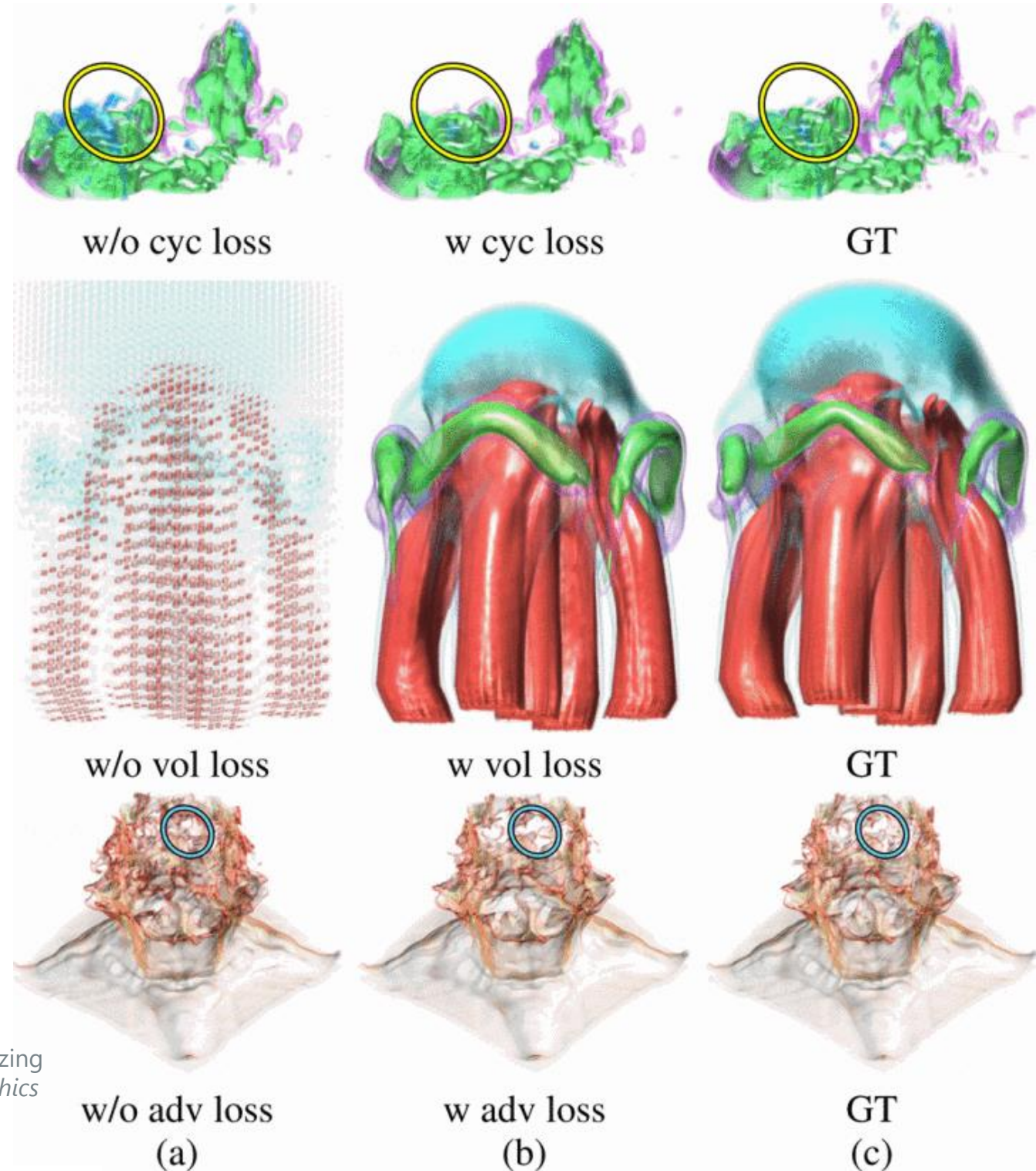


(d) STNet

(e) GT

Results – Different Settings

Dataset	PSNR	SSIM	Method
Tangaroa	32.26	0.883	w/o cycle loss
	33.26	0.892	w cycle loss
Five Jets	22.11	0.621	w/o volumetric loss
	39.63	0.892	w volumetric loss
Ionization (H)	43.80	0.904	w/o adversarial loss
	43.19	0.913	w adversarial loss

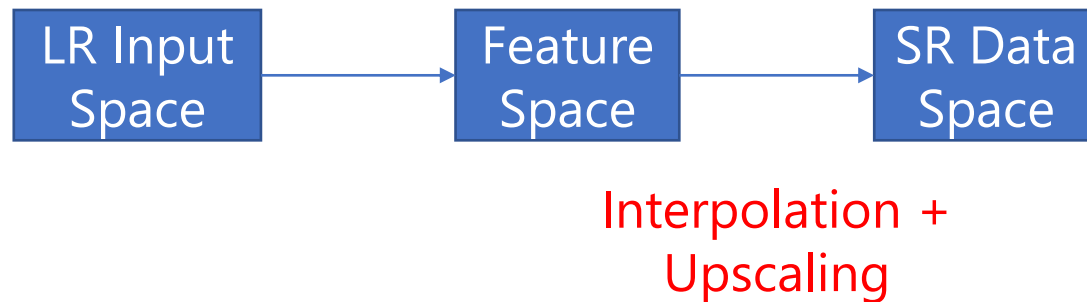


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Reconstruction Task vs Synthesizing Task

Reconstruction Task

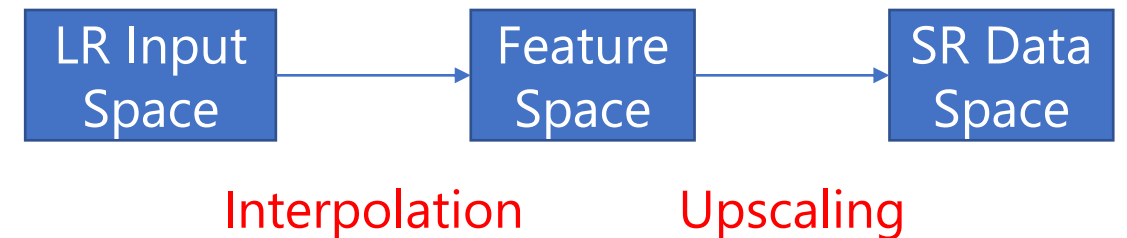
- From medium / low resolution data
- Interpolates in the data space



- Sequential model
- Data variables magnitude and direction

Synthesizing Task

- From low + high resolution data
- Interpolates in the feature space

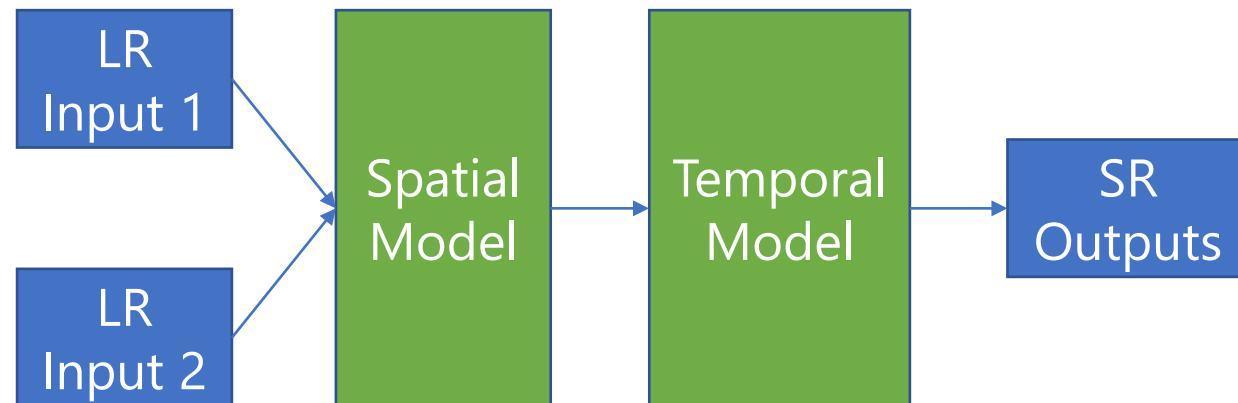


- End to end model
- Data variables magnitude only

Sequential Model vs End to End Model

Sequential Model

- Upscales spatial data then temporal data
- Model accumulates errors and amplifies them



End to End Model

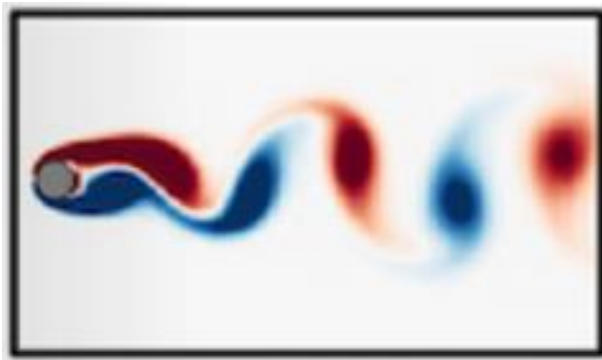
- Upscales spatio-temporal data simultaneously
- No accumulation and amplification of errors



Vector Data vs Scalar Data

Vector Data

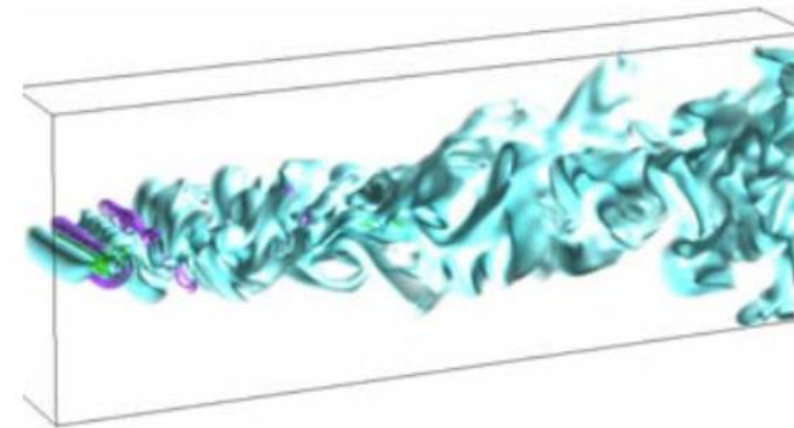
- Velocity, pressure and vorticity
 - direction and magnitude
- 2D and 3D data *plus time*
- Computation heavy



Fukami, K., Fukagata, K., & Taira, K. (2021). Machine-learning-based spatio-temporal super resolution reconstruction of turbulent flows. *Journal of Fluid Mechanics*, 909, A9. doi:10.1017/jfm.2020.948

Scalar Data

- Velocity, pressure, intensity and vorticity
 - magnitude only
- 3D volume data only *plus time*
- Computation lighter



J. Han, H. Zheng, D. Z. Chen and C. Wang, "STNet: An End-to-End Generative Framework for Synthesizing Spatiotemporal Super-Resolution Volumes," in *IEEE Transactions on Visualization and Computer Graphics*

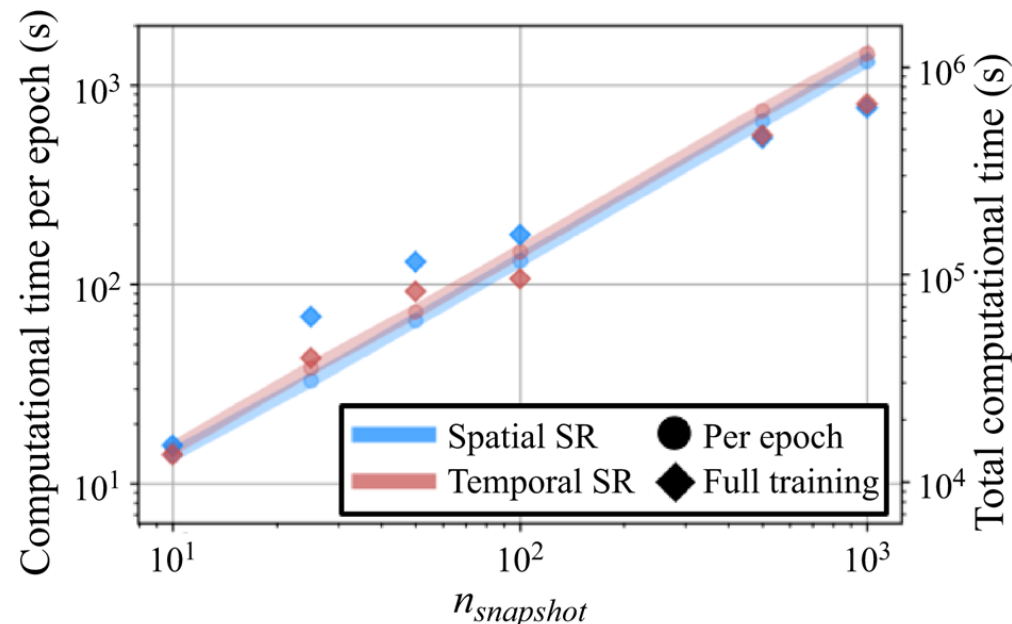
Limitations

Reconstruction Task

- Could not minimize loss well
 - At higher wave-number regions
- High computational time
 - 15 days for training 1000 snapshots

Synthesizing Task

- Temporal sampling uses uniform sampling
 - May not capture dynamic pattern well
- Framework not powerful enough
 - Only upscaled data 4 times each dimension



Future Work

- STNet will explore fully unsupervised techniques to generate STSR data

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Conclusions

- Spatio temporal super resolution data can be reduced and recovered using ML
- End to end models work better than sequential models
- Interpolation in feature space more efficient compared to data space
- Turbulent vector data is much harder to work with compared to laminar or scalar data



Thank you for your attention!

Any Questions?

Shourya Verma