

# Differential Equations in Bioscience

## Simulations of Gierer-Meinhardt Model with Source Density

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MSc Scientific Computing

- [1] Meinhardt, H. (2012) “Turing’s theory of morphogenesis of 1952 and the subsequent discovery of the crucial role of local self-enhancement and long-range inhibition,” *Interface focus*, 2(4), pp. 407–416.
- [2] Meinhardt, H. (1993) “A model for pattern formation of hypostome, tentacles, and foot in hydra: how to form structures close to each other, how to form them at a distance,” *Developmental biology*, 157(2), pp. 321–333.
- [3] Gierer, A. and Meinhardt, H. (1972) “A theory of biological pattern formation”. *Kybernetik* 12, 30–39

- **Morphogenesis:**

- Biological process allowing an organism to develop its form
- Studies mechanism by which distribution of cell space occurs
- Example: during the process of embryonic development

- **Activator-Inhibitor Systems:**

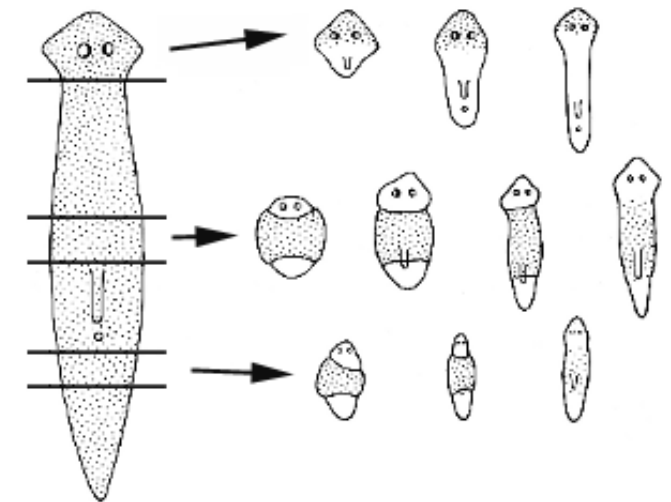
- Reaction-diffusion equations
- Explain many pattern formation processes in nature

- **Why do we study them?**

- Polarity retention during regeneration in hydra
- Understanding congenital cardiac malformations



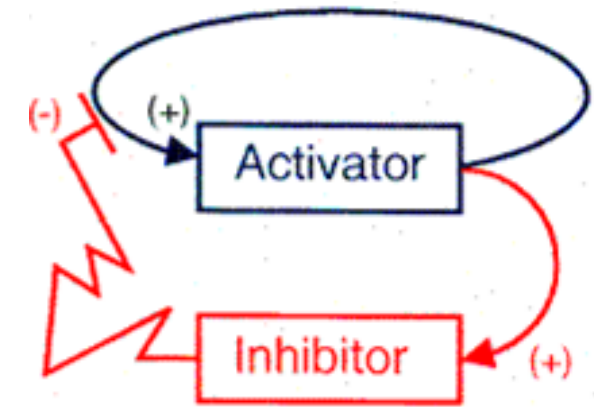
Schleich, Jean-Marc, and Jean-Louis Dillenseger. 'Virtual Imaging for Teaching Cardiac Embryology'. *Circulation* 104.24 (2001): e134–e134. Web.



<https://sites.google.com/site/flatwormsjfr2/defense-protection>

- **Activator-Inhibitor System [1]:**

- Two substances that act on each other
- Activator stimulates its own production (autocatalysis)
- Activator also produces the inhibitor
- Inhibitor represses the production of the activator



Hans Meinhardt (2006) Gierer-Meinhardt model. Scholarpedia, 1(12):1418.

**D1-D2** are growth rates, **μ-v** are decay rates, **a-b** are production rates,  $\Delta$  is Laplace operator

$$\partial_t u = D_1 \Delta u + \frac{au^2}{v} - \mu u$$

$$\partial_t v = D_2 \Delta v + bu^2 - \nu v$$

activator (**u**), inhibitor (**v**) **eq1**

- **Source Density:**

- Meinhardt used source density for hydra model in 1993 [1]
- It describes ability of cells to perform the autocatalytic reaction
- Higher source density increases activation concentration
- Source density gradient can determine polarity of pattern

$$\partial_t u = D_1 \Delta u + \frac{au^2}{v} S - \mu u$$

$$\partial_t v = D_2 \Delta v + bu^2 S - \nu v$$

$$\partial_t S = d \Delta S + u - \delta S$$

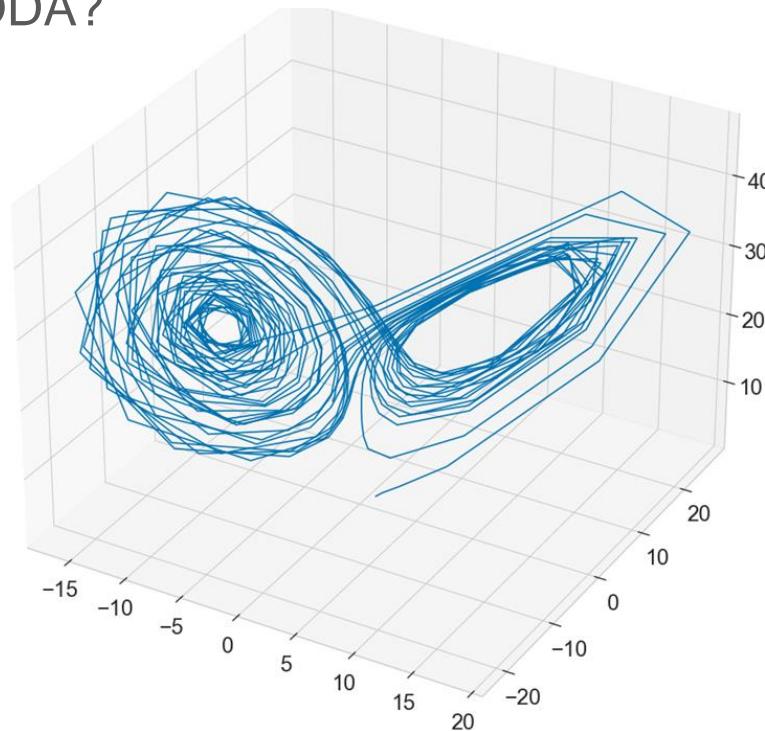
activator (**u**), inhibitor (**v**), source density (**S**) **eq2**

# ODE Solver 1: LSODA

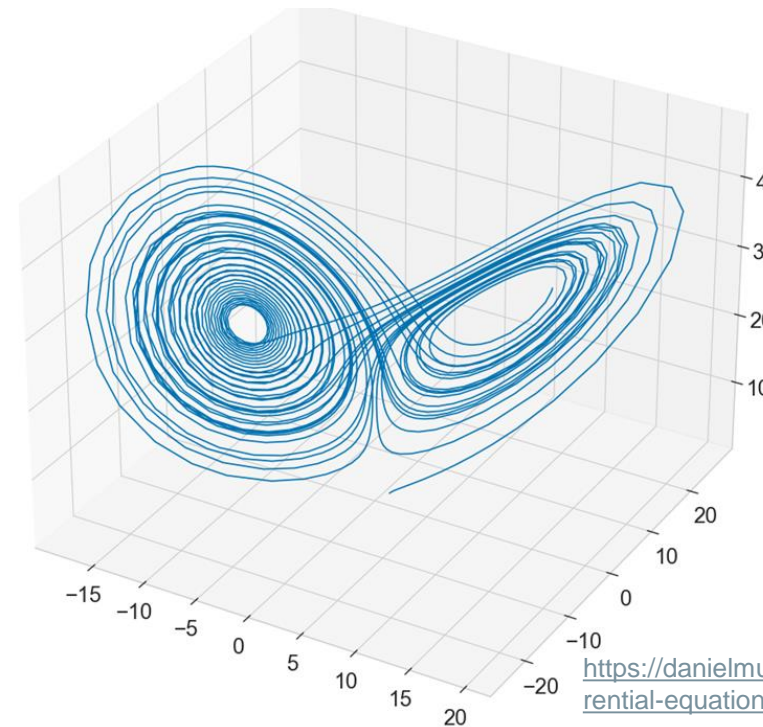
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- **LSODA**: Solver for Ordinary Differential Equations
  - FORTRAN ODE solver by Hindmarsh [1] imported to python by scipy [3]
  - Switches between stiff BDF and non-stiff Adams methods [2]
  - Why LSODA?

**Runge-Kutta 45**



**LSODA**



[https://danielmuellerkomorowska.com/2021/02/16/differential-equations-with-scipy-odeint-or-solve\\_ivp](https://danielmuellerkomorowska.com/2021/02/16/differential-equations-with-scipy-odeint-or-solve_ivp)

[1] A. C. Hindmarsh, "ODEPACK, A Systematized Collection of ODE Solvers," IMACS Transactions on Scientific Computation, Vol 1., pp. 55-64, 1983.

[2] L. Petzold, "Automatic selection of methods for solving stiff and nonstiff systems of ordinary differential equations", SIAM Journal on Scientific and Statistical Computing

[3] <https://docs.scipy.org/doc/scipy/reference/generated/scipy.integrate.LSODA.html>

- **Adams:**

- Implicit method for the numerical integration of ODEs
- Linear multistep methods, takes function and time
- Replacing the integrand with polynomial that interpolates  $f(t, y)$
- Coefficients determined by previously calculated data points

$$y' = f(t, y), \quad y(t_0) = y_0. \quad \text{initial value problem}$$

$$y_{n+r} = y_{n+r-1} + h \sum_{k=1}^r \lambda_k f_{n+r-k} \quad \text{Adams general formula} \quad \sum_{k=1}^r \lambda_k = 1$$

- $h$  denotes time step,  $k$  denotes step size,  $f$  is the function and  $y$  is the solution at time  $t$

- **Backward differentiation formula (BDF):**
  - Implicit methods for the numerical integration of ODEs
  - Linear multistep method, takes function and time
  - Approximate the derivative of function using previously computed information
  - Increasing the accuracy of the approximation

$$y' = f(t, y), \quad y(t_0) = y_0. \quad \text{initial value problem}$$

$$\sum_{k=0}^s a_k y_{n+k} = h\beta f(t_{n+s}, y_{n+s}), \quad \text{BDF general formula}$$

- $h$  denotes time step,  $k$  denotes step size,  $\mathbf{a}$  and  $\beta$  are chosen so that method achieves maximum order  $s$ ,  $f$  is the function and  $y$  is the solution at time  $t$

# Code 1: Libraries

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- The code was written in python 3.

- Solving differential equations:

```
import numpy as np  
from scipy.integrate import solve_ivp
```

- Solve IVP function solves initial value problem for system of ODEs.

- Visualizations for simulations:

```
import matplotlib.pyplot as plt  
from celluloid import Camera
```

- Animating values at each instance was possible through them.



# Code 2: Equations

$$\begin{aligned}\partial_t u &= D_1 \Delta u + \frac{au^2}{v} S - \mu u \\ \partial_t v &= D_2 \Delta v + bu^2 S - \nu v \\ \partial_t S &= d \Delta S + u - \delta S\end{aligned}$$

activator (**u**), inhibitor (**v**), source density (**S**) **eq2**

```
#activator eq2
def activator(y):
    activator = D1* delta2d(y[:dim],dx) + a*u(y)**2/v(y) * S(y) - mu*u(y)
    return(activator)

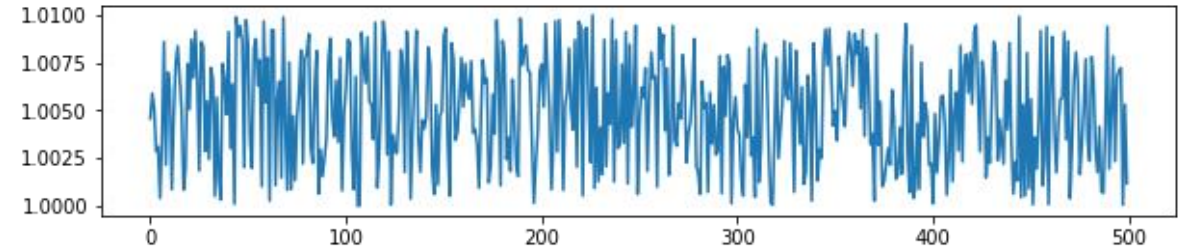
#inhibitor eq2
def inhibitor(y):
    inhibitor = D2* delta2d(y[dim:2*dim],dx) + b*u(y)**2 * S(y) - nu*v(y)
    return(inhibitor)

#source density
def source(y):
    source = d* delta2d(y[2*dim:3*dim],dx) + u(y) - delta * S(y)
    return(source)
```

# Code 3: Solve ODEs

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- **IC** is vector representation of initial state
  - Uniform Gaussian noise
    - Mean = 1
    - Variance = 0.01
- **tc** is timespan of solver i.e. it integrates from time 0 to 100
- **solve\_ivp** takes the function, timespan and initial state and solves ODEs



```
IC = 1+0.01*np.random.rand(3*dim)
tc = [0,100]

gms_rhs = lambda t,y: [activator(y),inhibitor(y),source(y)]
sol = solve_ivp(gms_rhs,tc,IC,method='LSODA',vectorized=True)

t = sol.t
y = sol.y.T
```

# Code 4: Visualization

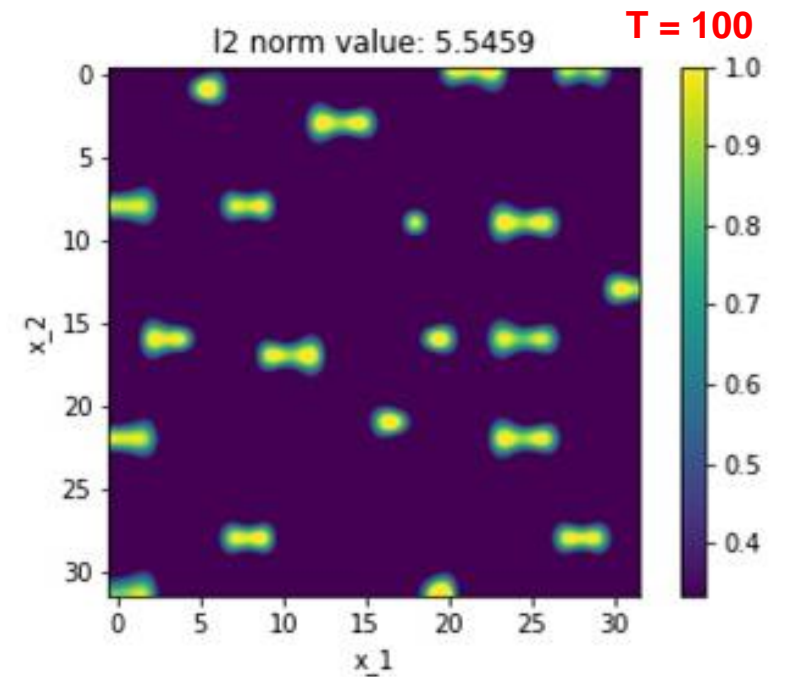
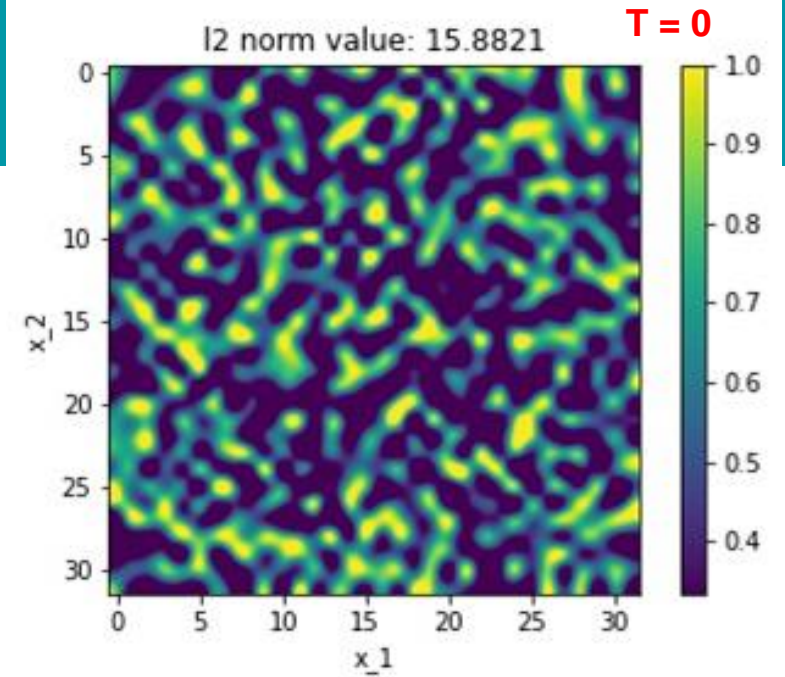
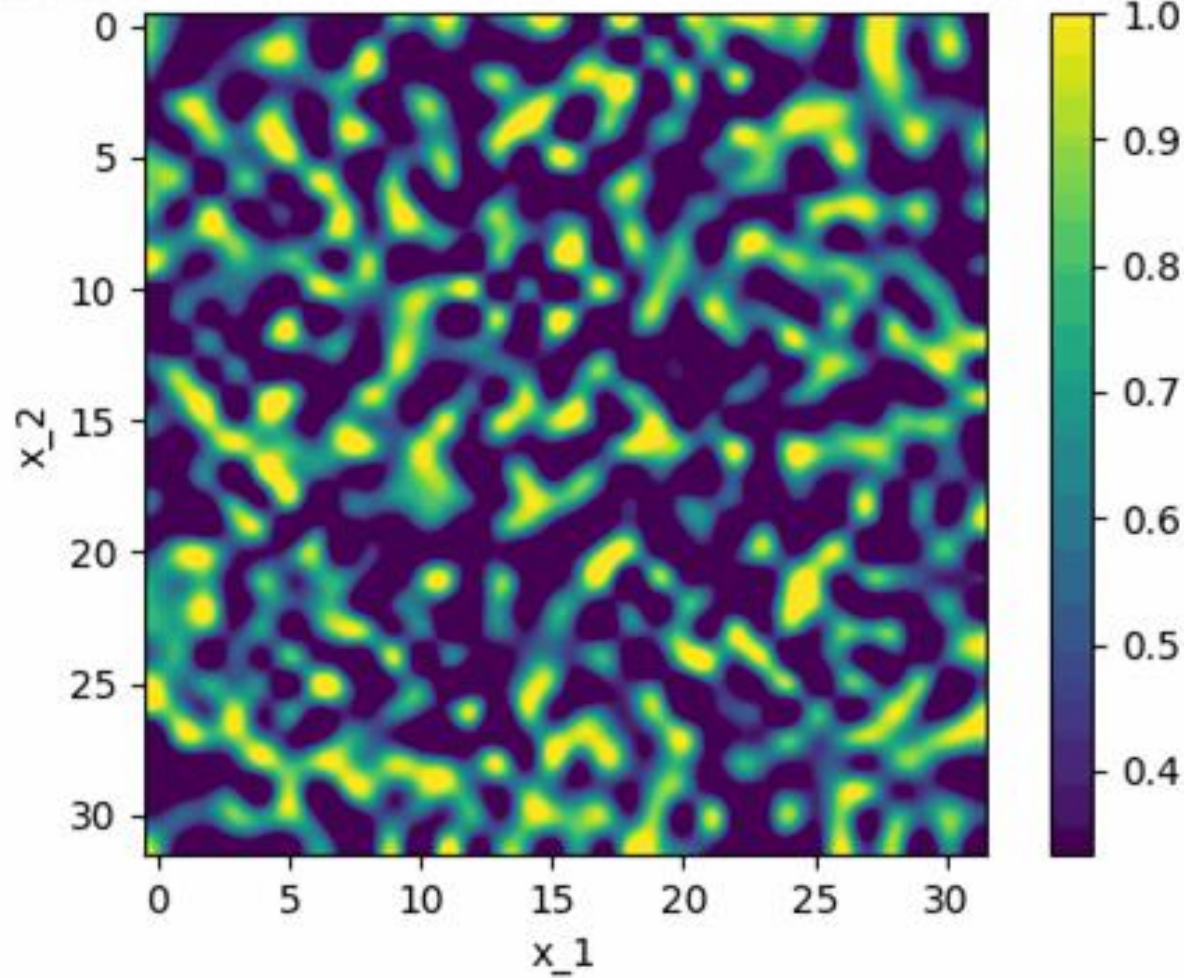
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- **Loop** through the solutions for each instance
- **plt.imshow** creates 2D surface plot of solution
- **Camera** captures current slice of result using snap function
- **animate** function arranges all snaps of instances into a gif file

```
fig = plt.figure(dpi=100)
camera = Camera(fig)
for i in range(len(y)):
    image = y[i,:dim].reshape((N,N))
    image = minmax_scale(image)
    plt.imshow(image,interpolation='sinc',vmin=np.max(image)/3)
    plt.xlabel('x_1')
    plt.ylabel('x_2')
    plt.title('Activator Concentrations of Gierer-Meinhardt Model')
    camera.snap()
plt.colorbar()
animation = camera.animate()
animation.save('simulation3.gif', writer='pillow', fps=60)
```

# Simulation 1: eq2

Activator Concentrations of Gierer-Meinhardt Model

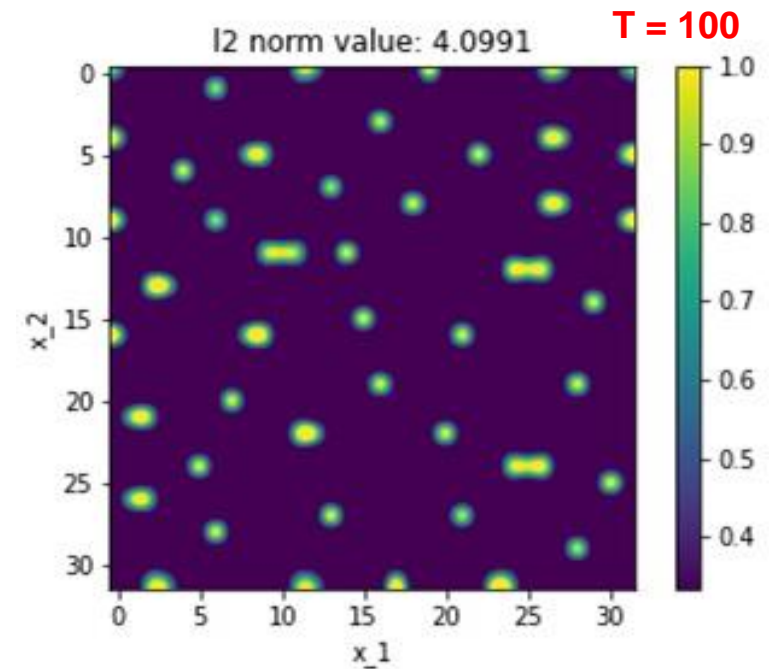
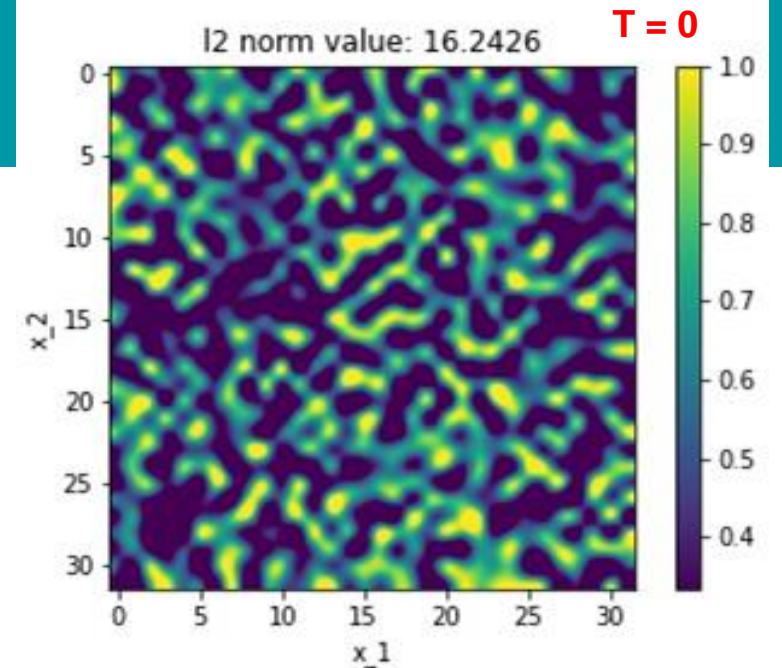
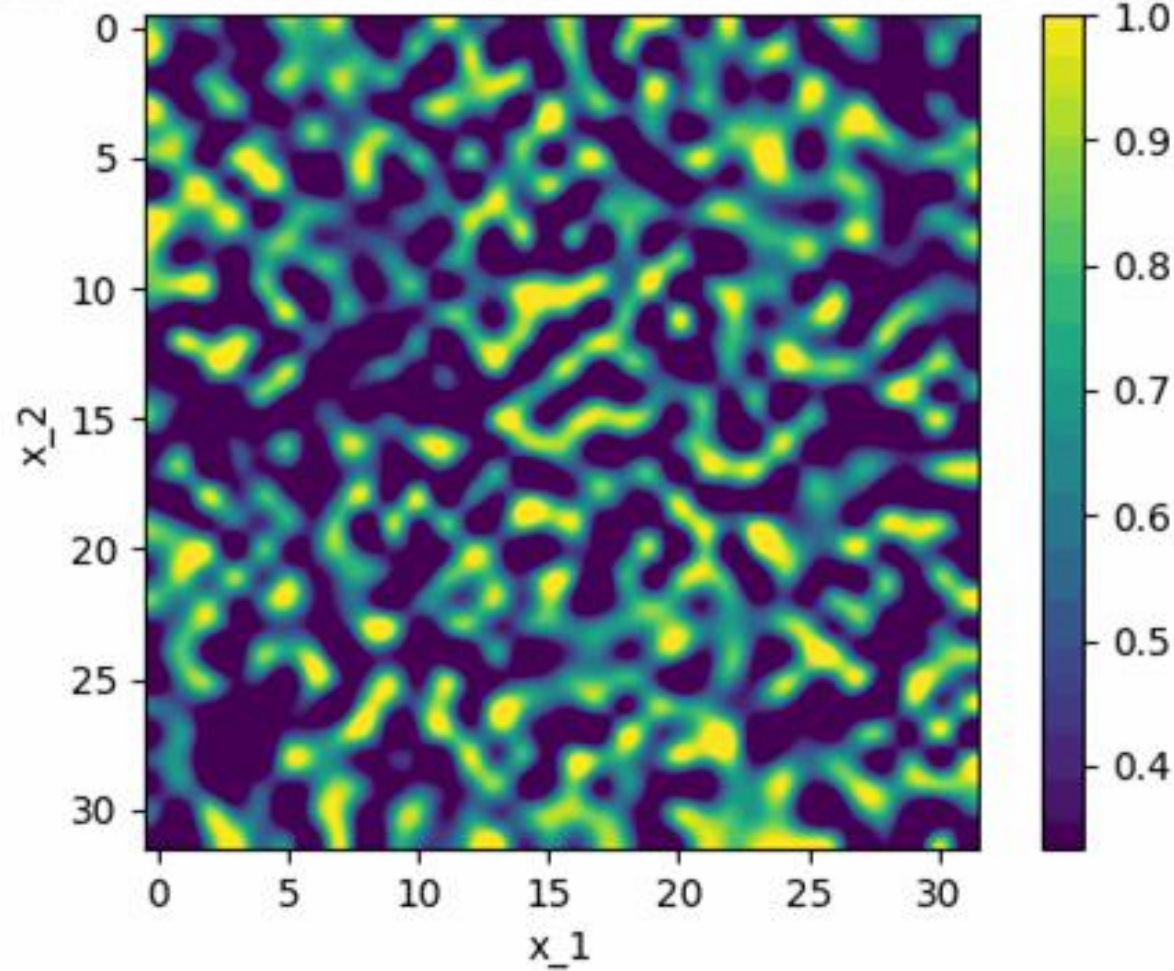


'D1', 0.0002, 'D2', 0.01, 'a', 1, 'b', 1, 'mu', 0.5, 'nu', 1, 'd', 0, 'delta', 1



# Simulation 2: eq2

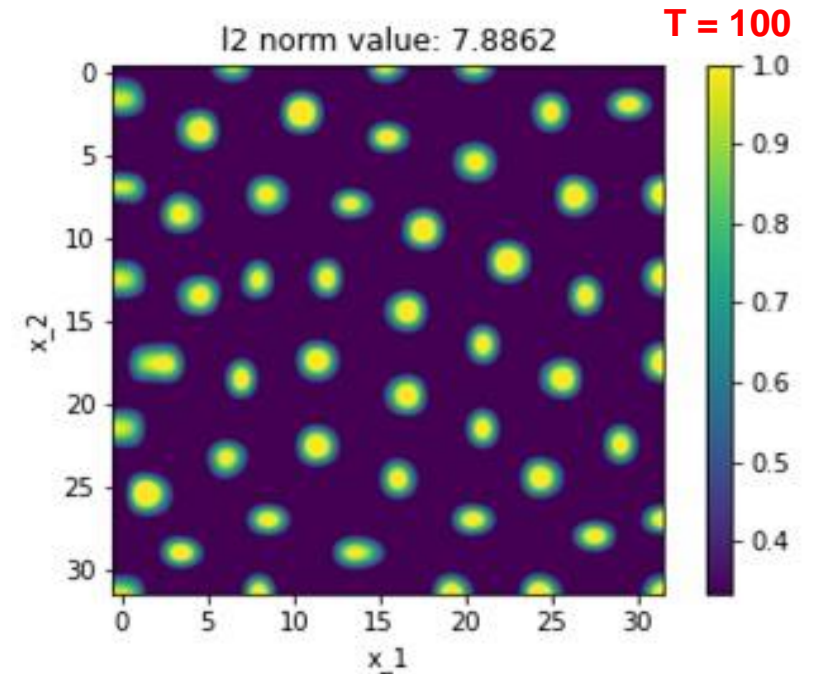
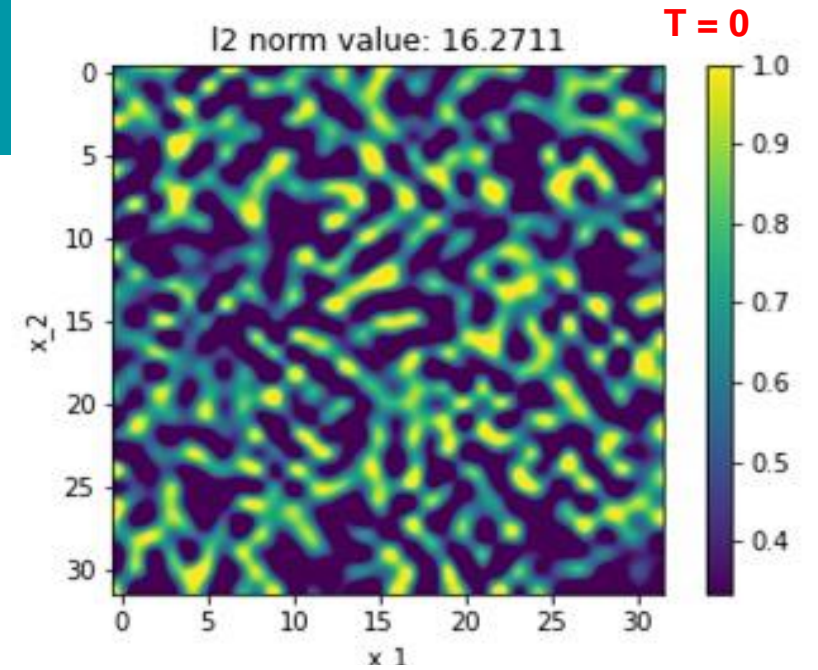
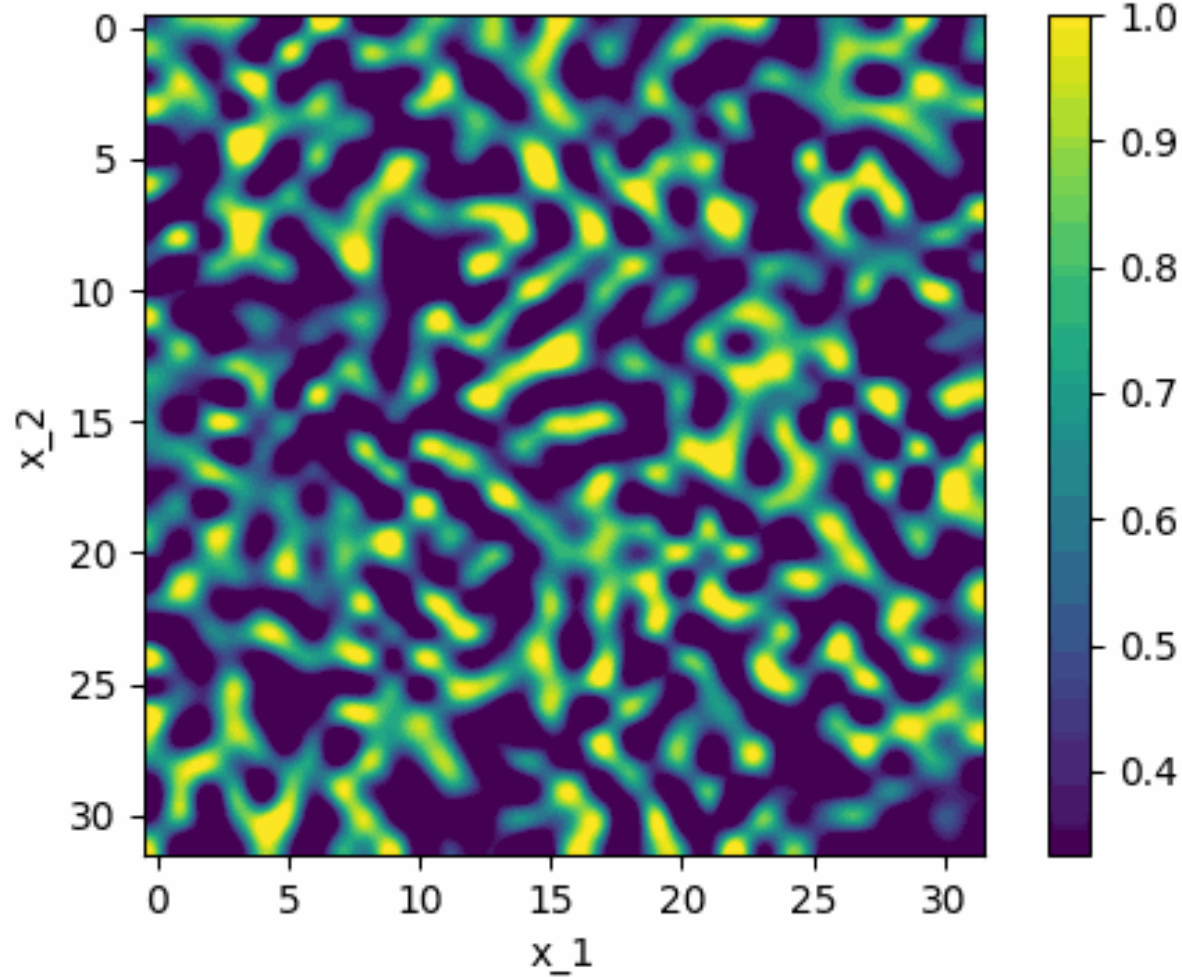
Activator Concentrations of Gierer-Meinhardt Model



'D1', 0.0002, 'D2', 0.01, 'a', 2, 'b', 1, 'mu', 1, 'nu', 2, 'd', 2, 'delta', 1.5

# Simulation 3: eq2

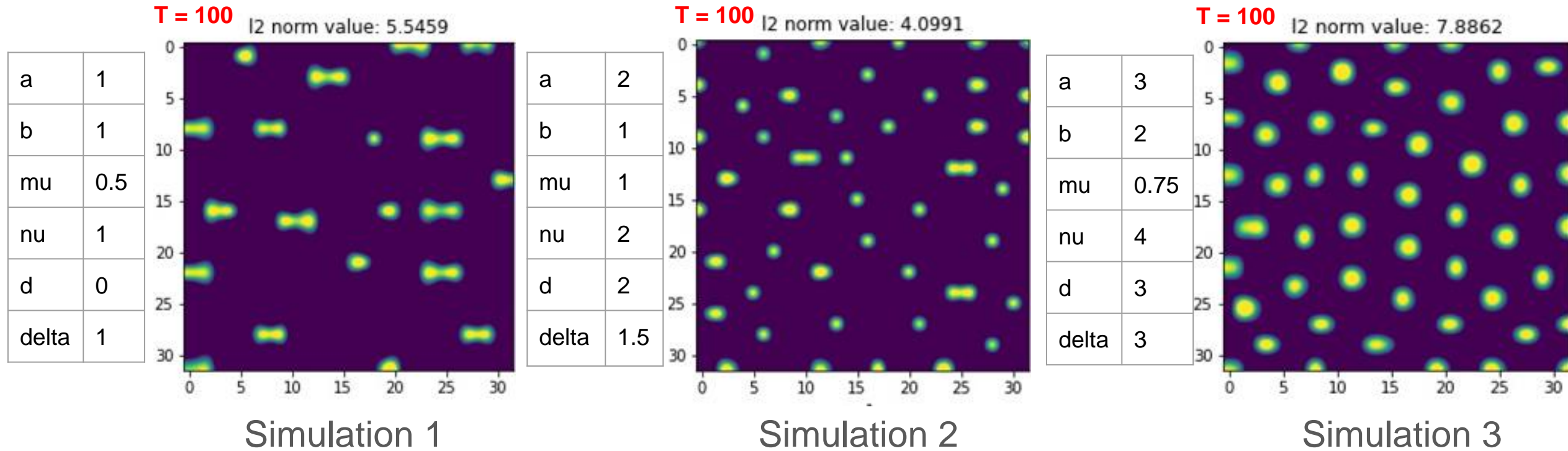
Activator Concentrations of Gierer-Meinhardt Model



'D1', 0.0002, 'D2', 0.01, 'a', 3, 'b', 2, 'mu', 0.75, 'nu', 4, 'd', 3, 'delta', 3



# Results 1: eq2



- Comparison of the systems at their final pattern
- **D1** and **D2** values were **0.0002** and **0.01** for all
- **L2 norm** tending to 0 indicates reaching the steady state
  - values did not go lower when increasing **tf** from **100** to **300**

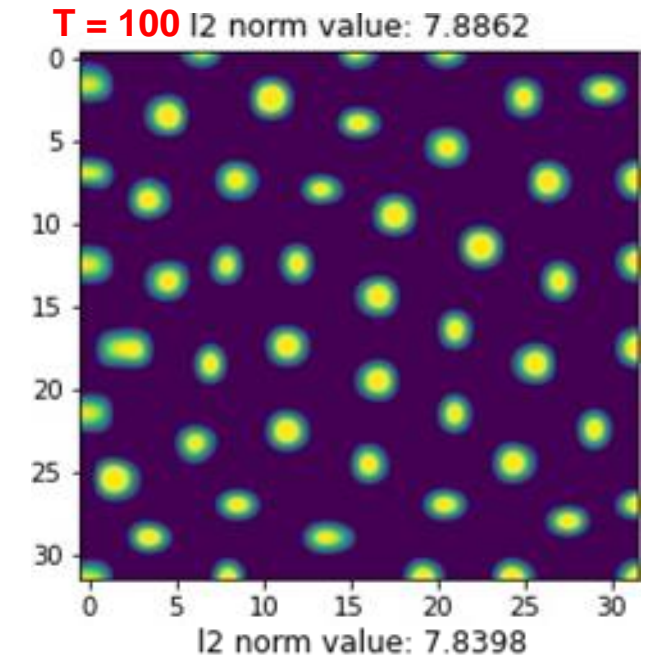
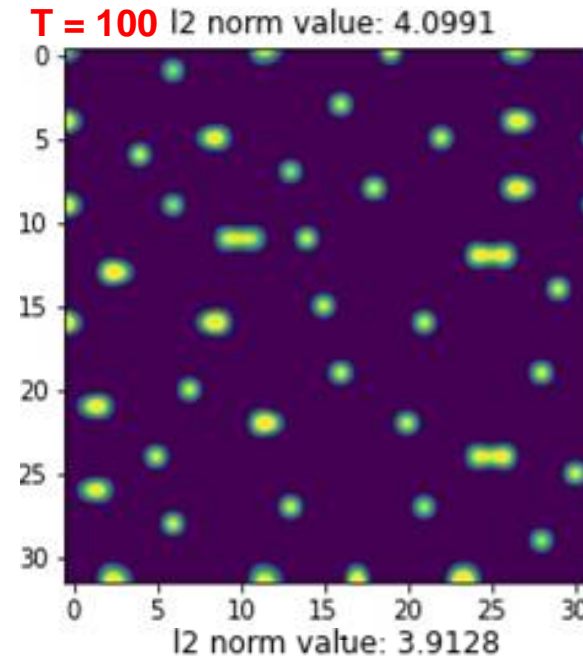
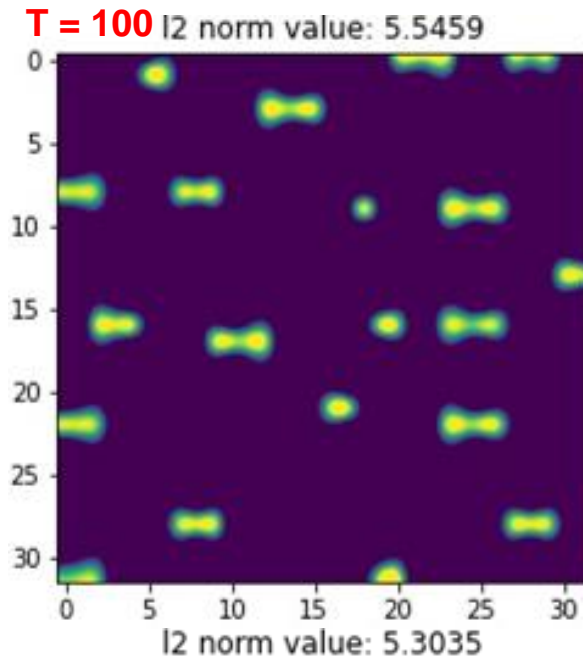
# Results 2: Comparison

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With source density  
(eq2)

Same parameters

No source density  
(eq1)





# Results 3: Slight changes

- Experimenting with slightly different equation:
  - Source density impact is higher
  - However the difference is not major
  - Compared to **eq1** and **eq2**

$$\partial_t u = D_1 \Delta u + \left\{ \frac{au^2}{v} - \mu u \right\} S$$

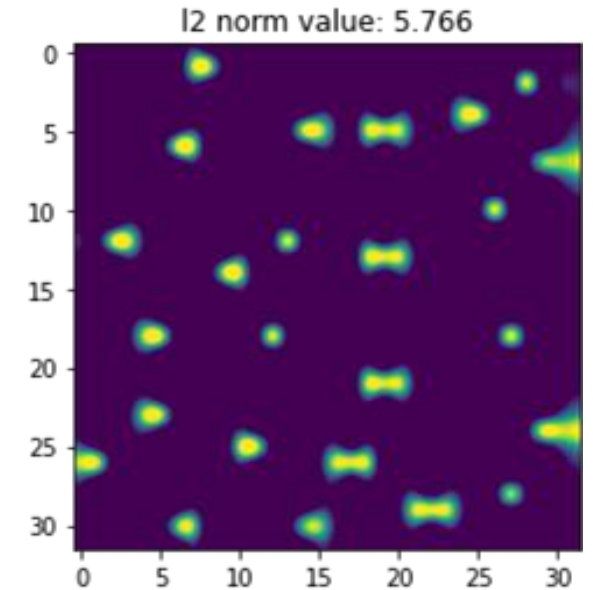
$$\partial_t v = D_2 \Delta v + \left\{ bu^2 - \nu v \right\} S$$

$$\partial_t S = d \Delta S + u - \delta S$$

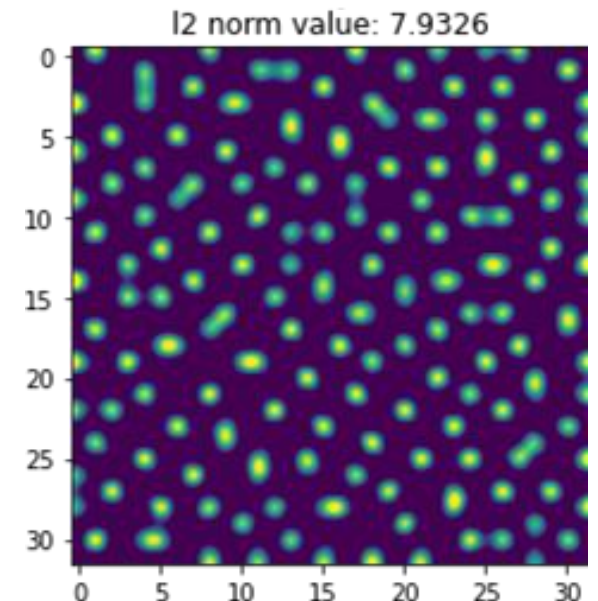
activator (**u**), inhibitor (**v**), source density (**S**) **eq3**

**T = 100**

a	1
b	1
mu	0.5
nu	1
d	0
delta	1



a	3
b	2
mu	0.75
nu	4
d	3
delta	3



# Results 4: Saturation

- For the case of saturation of the activator [1]:
  - Replacing  $u^2$  with  $u^2/(1+ku^2)$
  - $K = 0.002$
  - Gives rise to striped and checkered patterns
  - Steady state not reached within  $T=200$

$$\partial_t u = D_1 \Delta u + \left\{ \frac{au^2}{v(1+ku^2)} - \mu u \right\} S$$

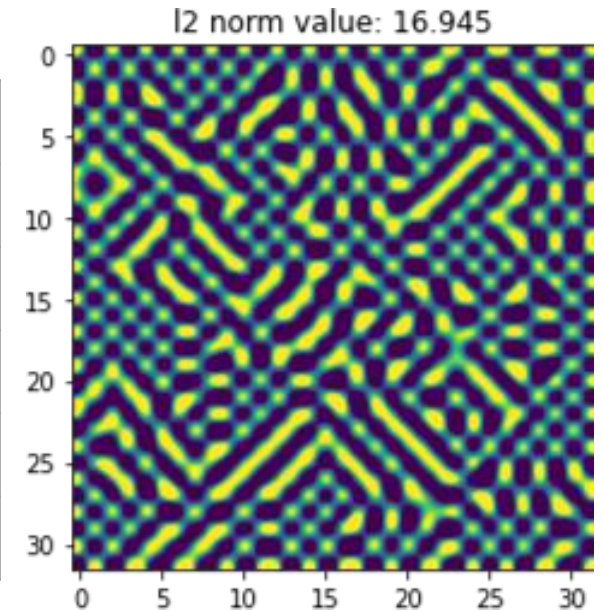
$$\partial_t v = D_2 \Delta v + \left\{ bu^2 - \nu v \right\} S$$

$$\partial_t S = d\Delta S + u - \delta S$$

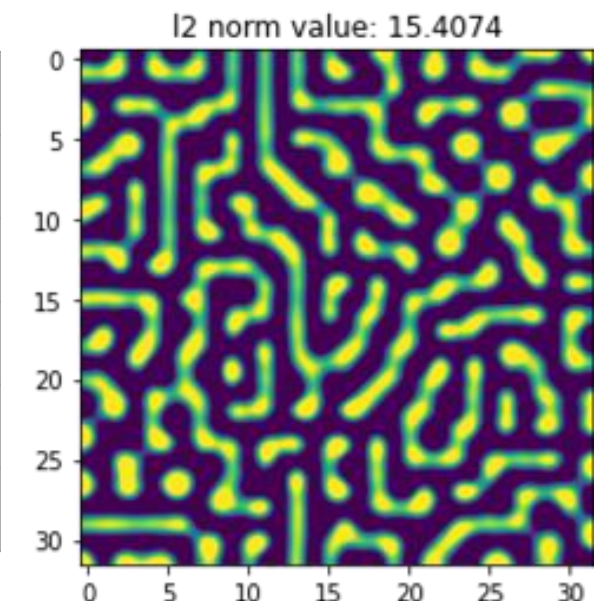
activator (**u**), inhibitor (**v**), source density (**S**) **eq4**

**T = 200**

a	2
b	1
mu	1
nu	4
d	2
delta	1.5



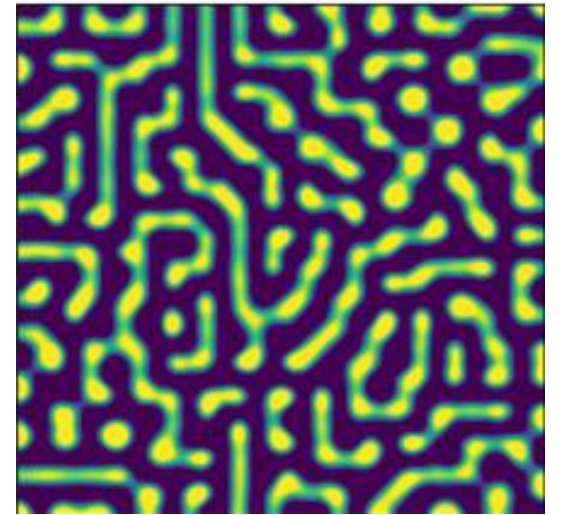
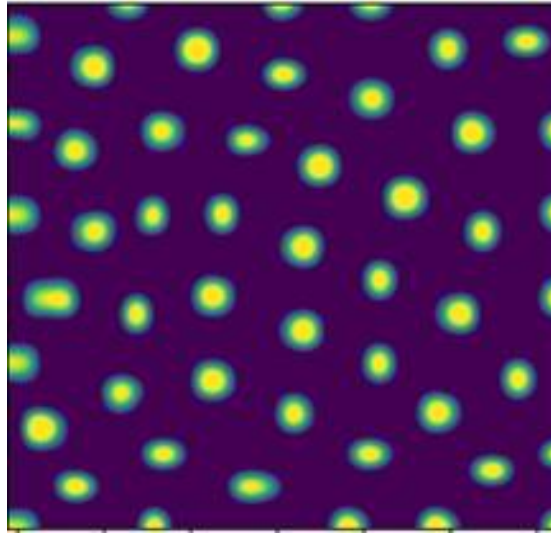
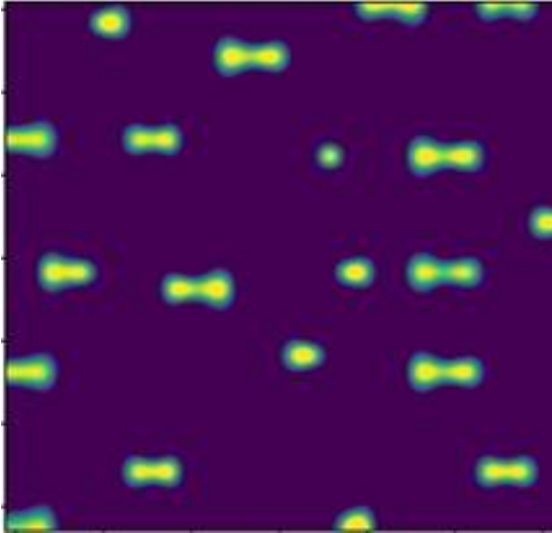
a	2
b	1
mu	1
nu	4
d	3
delta	3





# Patterns in Nature

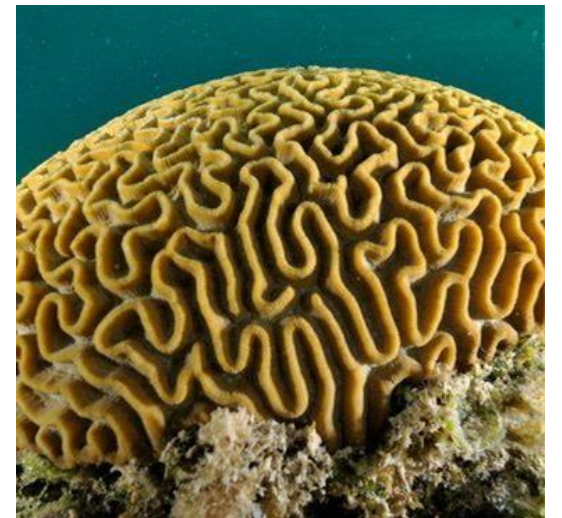
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<https://www.pinterest.com/pin/red-eyes--10062799137806377/>



<https://wildlifesafari.info/cheetah.html>



<https://nl.pinterest.com/pin/418553359100200002/>

- Time overhead (google colab):
  - Simulations took between 30 to 60 seconds when  $T=100$
  - Animation took approximately 30 seconds
- Not much noticeable difference between **eq1** and **eq2**
- Some difference was noticed in **eq3**
- Major difference in **eq4** when activator saturated
- Source density in simulations:
  - Seems not very effective for **eq1**, **eq2**
  - However very effective in case of **eq3**, **eq4**
  - Systems were most affected by  $\mu$  and  $\nu$

# Thank you for your time!

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Questions?



Github: link to code

# Appendix: delta2d function and params

```
N=32
dim = N**2
dx = 1/(N-1)

D1 = 0.0002
D2 = 0.01

a = 3
b = 2
mu = 0.75
nu = 4

d = 3
delta = 3
```

params

```
def delta2d(y,dx):
    y = y.reshape(-1,1)
    N = int(np.sqrt(len(y)))
    U = np.reshape(y,(N,N))

    Ur = np.hstack([U[:,1:],U[:, -1].reshape(-1,1)])
    Ul = np.hstack([U[:,0].reshape(-1,1), U[:, :-1]])
    Ut = np.vstack([U[0,:].reshape(-1,1).T, U[:-1,:]])
    Ub = np.vstack([U[1:,:], U[-1,:].reshape(-1,1).T])

    dU = (Ur+Ul+Ut+Ub - np.multiply(4,U))/dx**2
    dy = dU.ravel().reshape(-1,1)
    return(dy)
```

delta2D computes the finite difference approximation of the Laplace operator with Neumann boundary conditions in the 2D squared domain.