```
┌─────────────────────────────────────┐
│          view_frames Result          │
│                                      │
│   Recorded at time: 1772041558.023734│
└─────────────────────────────────────┘
```


odom

Broadcaster: default_authority
Average rate: 50.397
Buffer length: 2.52
Most recent transform: 66.019
Oldest transform: 63.499

base_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

diff_bar_1

hull_mid_1

bracket_left_1

bracket_right_1

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

pushrod_left_1

pushrod_right_1

hull_top_1

pushrod_left_rocker_1

rocker_left_1

rocker_right_1

pushrod_right_rocker_1

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

lidar_link

motor_left_front_1

motor_left_rear_1

motor_right_front_1

motor_right_rear_1

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

coupling_left_front_1

coupling_left_rear_1

coupling_right_front_1

coupling_right_rear_1

Broadcaster: default_authority
Average rate: 10.404
Buffer length: 2.499
Most recent transform: 66.0
Oldest transform: 63.501

Broadcaster: default_authority
Average rate: 10.404
Buffer length: 2.499
Most recent transform: 66.0
Oldest transform: 63.501

Broadcaster: default_authority
Average rate: 10.404
Buffer length: 2.499
Most recent transform: 66.0
Oldest transform: 63.501

Broadcaster: default_authority
Average rate: 10.404
Buffer length: 2.499
Most recent transform: 66.0
Oldest transform: 63.501

wheel_left_front_1

wheel_left_rear_1

wheel_right_front_1

wheel_right_rear_1