## Mathematical Morphology - Gray Scaled Morphology

## 1. Dilation



```
template<typename T, size_t M, size_t N>
Mat Dilation(Mat img, T(&kernel)[M][N], int widthLimit, int heightLimit) {
     //創建新圖準備處理
     Mat result(heightLimit, widthLimit, CV_8U, Scalar(0));
     for (int height = 0; height < heightLimit; height++) {</pre>
          for (int width = 0; width < widthLimit; width++) {</pre>
               if (img.at<uchar>(height, width) > 0) {
                    uchar max = 0;
                     for (int i = 0; i < M; i += 1) {
                          if (kernel[i][0] + height >= 0 && kernel[i][0] + height < heightLimit</pre>
                               && kernel[i][1] + width >= 0 && kernel[i][1] + width < widthLimit)
                               \max = img.at < uchar > (kernel[i][0] + height, kernel[i][1] + width) > max ?
img.at<uchar>(kernel[i][0] + height, kernel[i][1] + width) : max;
                     }
                     for (int i = 0; i < M; i += 1) {
                          if (kernel[i][0] + height >= 0 && kernel[i][0] + height < heightLimit
```

在Main function中:

Mat dilation = Dilation(img, kernel, widthLimit, heightLimit);

解釋:利用octonal 3-5-5-5-3 kernel with value = 0,偵測其最大值max,在不超出整張圖的範圍內,將kernel所遮罩的點的identity替換成max值

## 2. Erosion



```
template<typename T, size_t M, size_t N>

Mat Erosion(Mat img, T(&kernel)[M][N], int widthLimit, int heightLimit) {
    //創建新圖準備處理
    Mat result(heightLimit, widthLimit, CV_8U, Scalar(0));

for (int height = 0; height < heightLimit; height++) {
    for (int width = 0; width < widthLimit; width++) {
```

```
bool exist;
               if (img.at<uchar>(height, width) > 0) {
                    exist = true;
                   uchar min = 255;
                    for (int i = 0; i < M; i += 1) {
                         if (kernel[i][0] + height < 0 | | kernel[i][0] + height >= heightLimit
                              II kernel[i][1] + width < 0 II kernel[i][1] + width >= widthLimit
                             II img.at<uchar>(kernel[i][0] + height, kernel[i][1] + width) = 0) {
                             exist = false;
                             break;
                         }
                        min = img.at < uchar > (kernel[i][0] + height, kernel[i][1] + width) < min?
img.at<uchar>(kernel[i][0] + height, kernel[i][1] + width) : min;
                    }
                    for (int i = 0; i < M; i += 1) {
                         if (exist)
                             result.at<uchar>(kernel[i][0] + height, kernel[i][1] + width) = min;
                   }
              }
          }
     }
     return result;
在Main function中:
Mat erosion = Erosion(img, kernel, widthLimit, heightLimit);
解釋:利用octonal 3-5-5-5-3 kernel with value = 0, 偵測其最小值min,若圓心所對到的位置無法容納下整個kernel,
```

則exist為false,反之則為true,並進行接下來的像素處理,在不超出整張圖的範圍內,將kernel所遮罩的點的identity替

3. Opening

換成min值



```
template<typename T, size_t M, size_t N>

Mat Opening(Mat img, T(&kernel)[M][N], int widthLimit, int heightLimit) {
    return Dilation(Erosion(img, kernel, widthLimit, heightLimit), kernel, widthLimit, heightLimit);
}
在 Main function 中:
```

Mat opening = Opening(img, kernel, widthLimit, heightLimit);

解釋:依照定義,相當於先做 Erosion 後再做 Dilation

## 4. Closing



template<typename T, size\_t M, size\_t N>

```
Mat Closing(Mat img, T(&kernel)[M][N], int widthLimit, int heightLimit) {
    return Erosion(Dilation(img, kernel, widthLimit, heightLimit), kernel, widthLimit, heightLimit);
}

在 Main function 中:
Mat closing = Closing(img, kernel, widthLimit, heightLimit);

解釋:依照定義,相當於先做 Dilation 後再做 Erosion
```