



COMPUTER ENGINEERING



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EMBEDDED SYSTEM DESIGN

MEMORY

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Objective and Content

- Overview of memory
- Memory Organization
- Example



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- Example



Role of memory in embedded systems

Traditional roles: Storage and Communication for Programs

In embedded systems:

- Communication with Sensors and Actuators
- Often much more constrained than in general-purpose computing: Size, power, reliability, etc.

→ *Can be important for programmers to understand these constraints?*



Practical Issues

- Types of memory
 - volatile vs. non-volatile, SRAM vs. DRAM
- Memory maps
 - Harvard architecture
 - Memory-mapped I/O
- Memory organization
 - statically allocated
 - stacks
 - heaps (allocation, fragmentation, garbage collection)
- The memory model of C
- Memory hierarchies
 - scratchpads, caches, virtual memory)
- Memory protection
 - segmented spaces



Memory mapping

Memory Map of an ARM Cortex™ - M3 architecture

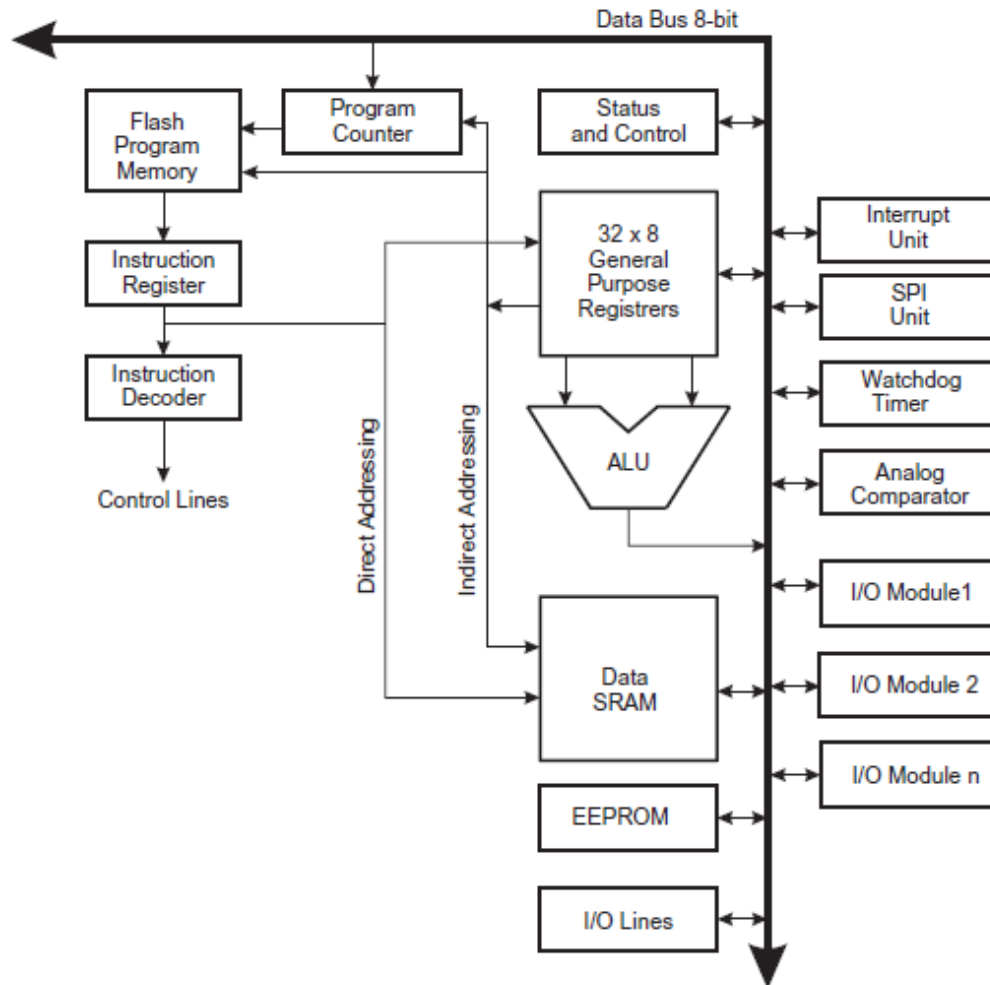
■ Defines the mapping of addresses to physical memory.

■ Note that this does not define how much physical memory there is!

G	peripherals	0xFFFFFFFF	}	0.5 GB
F	private peripheral bus	0xE0000000		
E	external devices (memory mapped)	0xDFFFFFFF	}	1.0 GB
		0xA0000000		
D	data memory (DRAM)	0x9FFFFFFF	}	1.0 GB
		0x60000000		
C	peripherals (memory-mapped registers)	0x5FFFFFFF	}	0.5 GB
B	data memory (SRAM)	0x40000000	}	0.5 GB
		0x3FFFFFFF		
A	program memory (flash)	0x20000000	}	0.5 GB
		0x1FFFFFFF		
		0x00000000	}	0.5 GB



Questions for understanding



- Why is it called an 8-bit microcontroller?
- What is the difference between an 8-bit microcontroller and a 32-bit microcontroller?
- Why use volatile memory? Why not always use non-volatile memory?



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Memory organization for Programs

☐ Statically-allocated memory

- Compiler chooses the address at which to store a variable.

☐ Stack

- Dynamically allocated memory with a Last-in, First-out (LIFO) strategy

☐ Heap

- Dynamically allocated memory



Memory allocation (1)

■ What is meant by the following C code:

```
char x;  
void foo(void) {  
    x = 0x20;  
    ...  
}
```

An 8-bit quantity (hex 0x20) is stored at an address in statically allocated memory in internal RAM determined by the compiler.



Memory allocation (2)

■ What is meant by the following C code:

```
char *x;  
void foo(void) {  
    x = 0x20;  
  
    ...  
}
```

An 16-bit quantity (hex 0x0020) is stored at an address in statically allocated memory in internal RAM determined by the compiler.



Memory allocation (3)

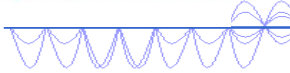
■ What is meant by the following C code:

```
char *x, y;  
void foo(void) {  
    x = 0x20;  
    y = *x;  
    ...  
}
```

The 8-bit quantity in the I/O register at location 0x20 is loaded into y, which is at a location in internal SRAM determined by the compiler.



Memory allocation (4)



Where are x, y, z in memory?

```
char foo() {  
    char *x, y;  
    x = 0x20;  
    y = *x;  
    return y;  
}  
  
char z;  
  
int main(void) {  
    z = foo();  
  
    ...  
}
```

x occupies 2 bytes on the stack, y occupies 1 byte on the stack, and z occupies 1 byte in static memory.



Memory allocation (5)

■ What is meant by the following C code:

```
void foo(void) {  
    char *x, y;  
    x = &y;  
    *x = 0x20;  
    ...  
}
```

16 bits for x and 8 bits for y are allocated on the stack, then x is loaded with the address of y, and then y is loaded with the 8-bit quantity 0x20.



Memory allocation (6)

What goes into z in the following program:

```
char foo() {  
    char y;  
    uint16_t x;  
    x = 0x20;  
    y = *x;  
    return y;  
}  
char z;  
int main(void) {  
    z = foo();  
    ...  
}
```

z is loaded with the 8-bit quantity in the I/O register at location 0x20.

Dynamically-Allocated Memory

The Heap

- An operating system typically offers a way to dynamically allocate memory on a “heap”.
- Memory management (`malloc()` and `free()`) can lead to many problems with embedded systems:
 - Memory leaks (allocated memory is never freed)
 - Memory fragmentation (allocatable pieces get smaller)
- Automatic techniques (“ garbage collection ”) often require stopping everything and reorganizing the allocated memory. This is deadly for real-time programs.



Memory Hierarchies

□ Cache:

- A subset of memory addresses is mapped to SRAM
- Accessing an address not in SRAM results in *cache miss*
- A miss is handled by copying contents of DRAM to SRAM

□ Scratchpad:

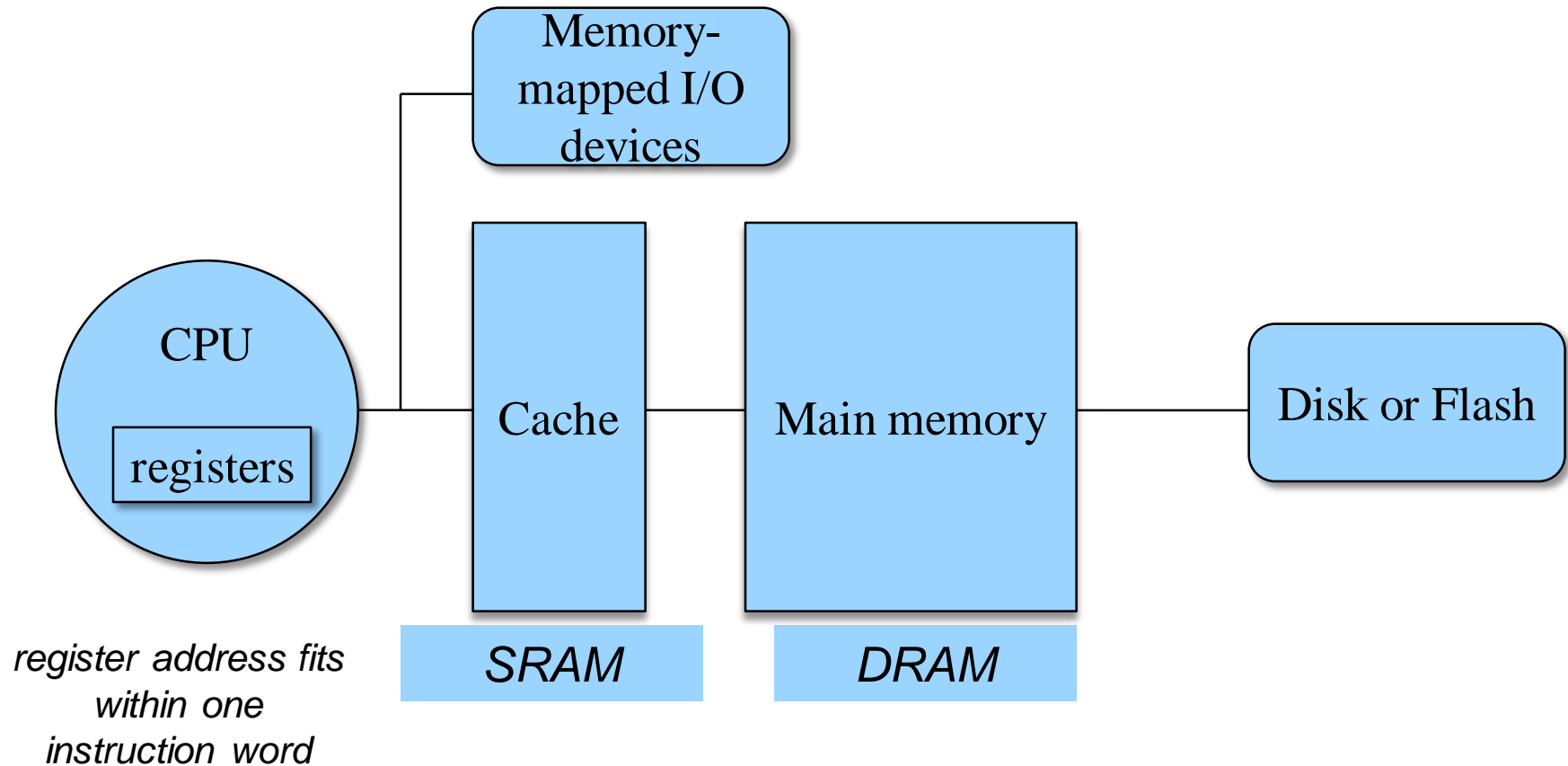
- SRAM and DRAM occupy disjoint regions of memory space
- Software manages what is stored where

□ Segmentation

- Logical addresses are mapped to a subset of physical addresses
- Permissions regulate which tasks can access which memory



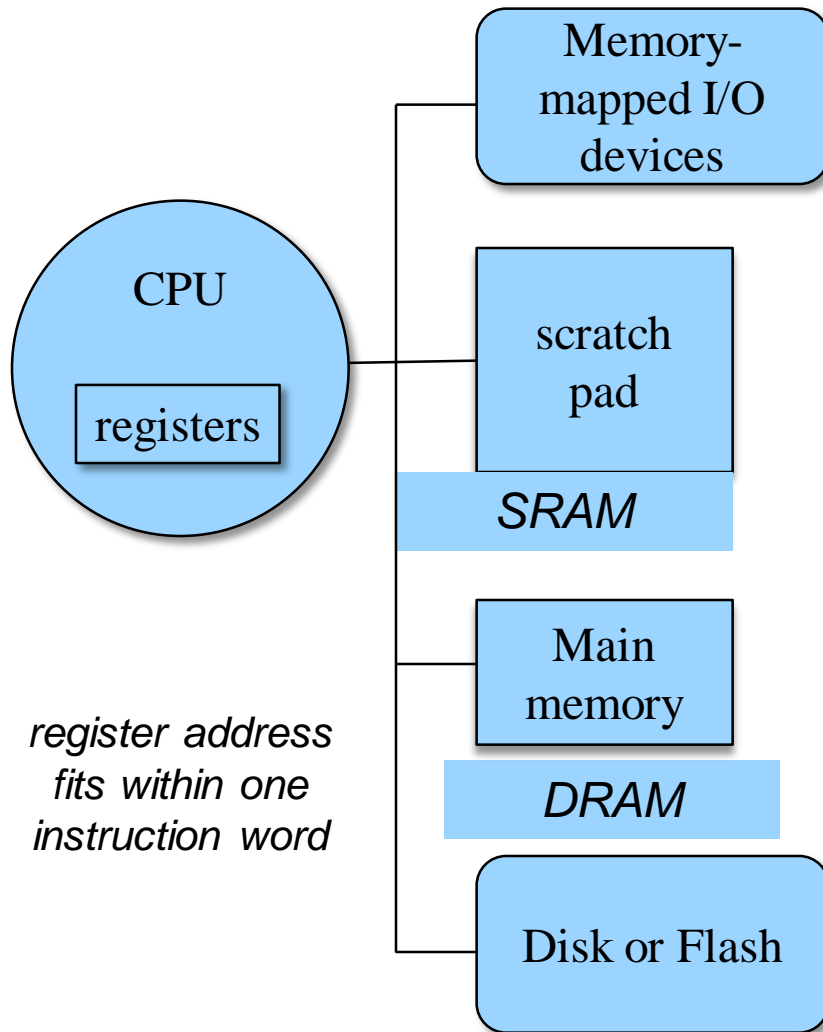
Memory Hierarchies



Here, the cache or scratchpad, main memory, and disk or flash share the same address space.



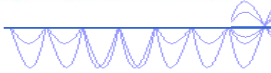
Memory Hierarchies



- Here, each distinct piece of memory hardware has its own segment of the address space.
- This requires more careful software design, but gives more direct control over timing.

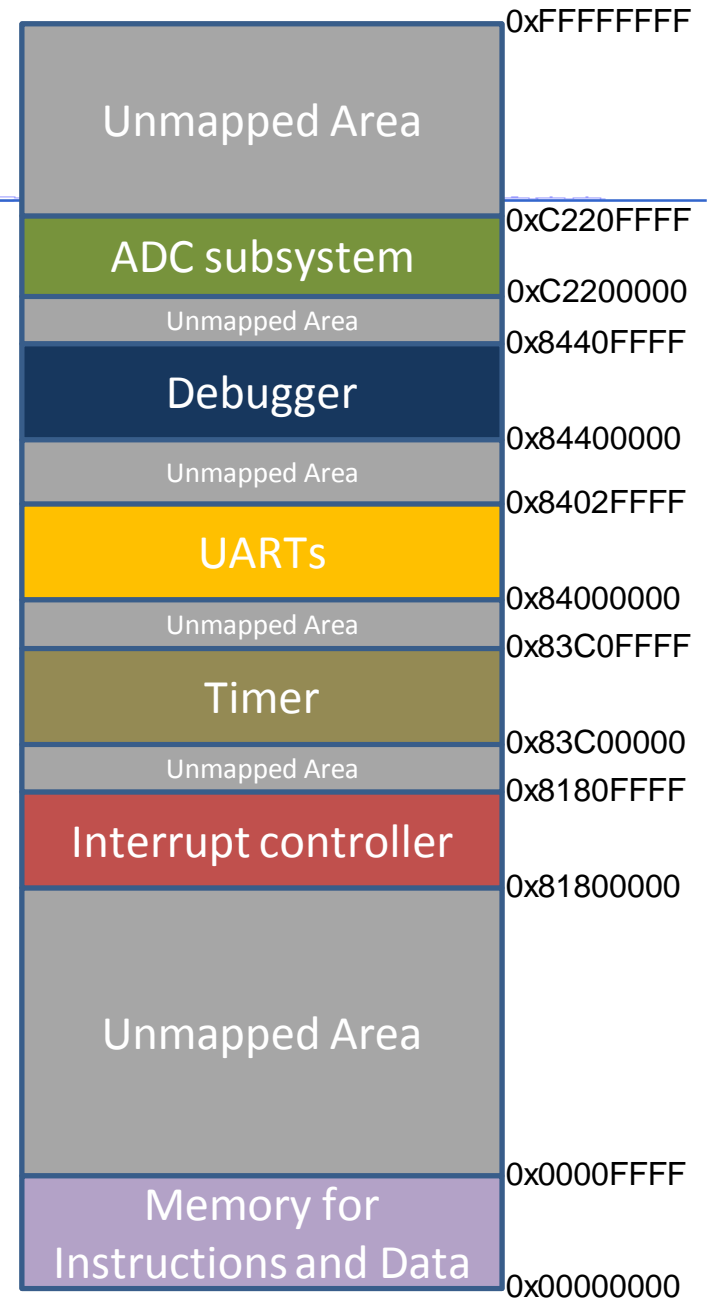
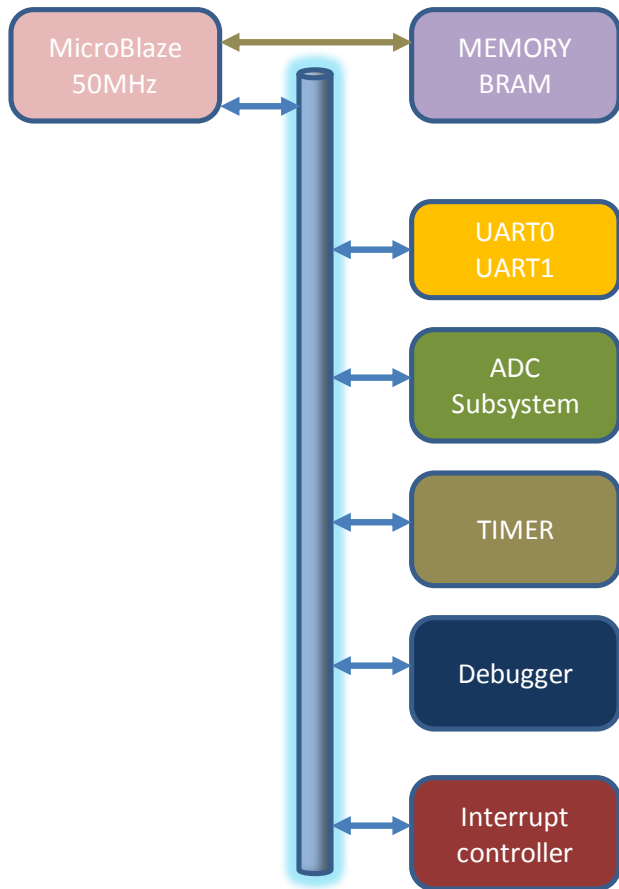


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Berkeley Microblaze Personality Memory Map





Conclusion

Understanding memory architectures is essential to programming embedded systems!



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Q&A

