

## Exercise 05: The quenched solution to randomised perceptron learning

In this exercise we basically follow the same procedures of the last exercise, but instead of having the **annealed** analytical solution we use the **quenched** one and compare it with the data we obtained from Exercise 03.

We hence have

$$\frac{R}{\sqrt{1-R}} = \frac{\alpha}{\pi} I(R) \quad (1)$$

where

$$I(R) = \int_{-\infty}^{+\infty} \frac{dv}{2\pi} \frac{\exp[-(1+R)v^2/2]}{H(-\sqrt{R}v)}$$

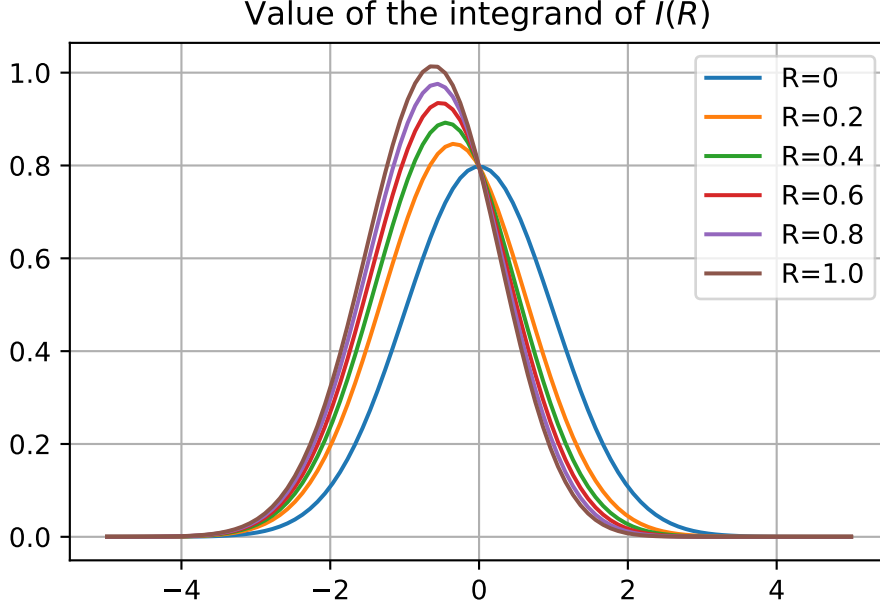
and

$$H(u) = \int_u^{+\infty} \frac{dx}{\sqrt{2\pi}} \exp(-x^2/2) = \frac{1}{2} \operatorname{erfc}\left(\frac{u}{\sqrt{2}}\right).$$

Recall that

$$\epsilon(R) = \frac{1}{\pi} \arccos(R).$$

We first make sure that the integrand that we chose can be effectively be integrated in a limited interval, such as  $[-10, +10]$ , without any heavy consequence over the computations. We can check that it has a bell-shape in the  $[-5, +5]$  interval and elsewhere it is almost zero, for our domain of interest  $R \in [0, 1.)$ . We choose anyways, just to be safe, to integrate the function between  $[-20, +20]$ .



**Step 1: Choose a parameter and represent  $\epsilon(\alpha)$  in a parametric plot**

Since it is present in both functions  $\epsilon$  and  $\alpha$ , I will choose  $R$  as my parameter of choice.

$$t \equiv R$$

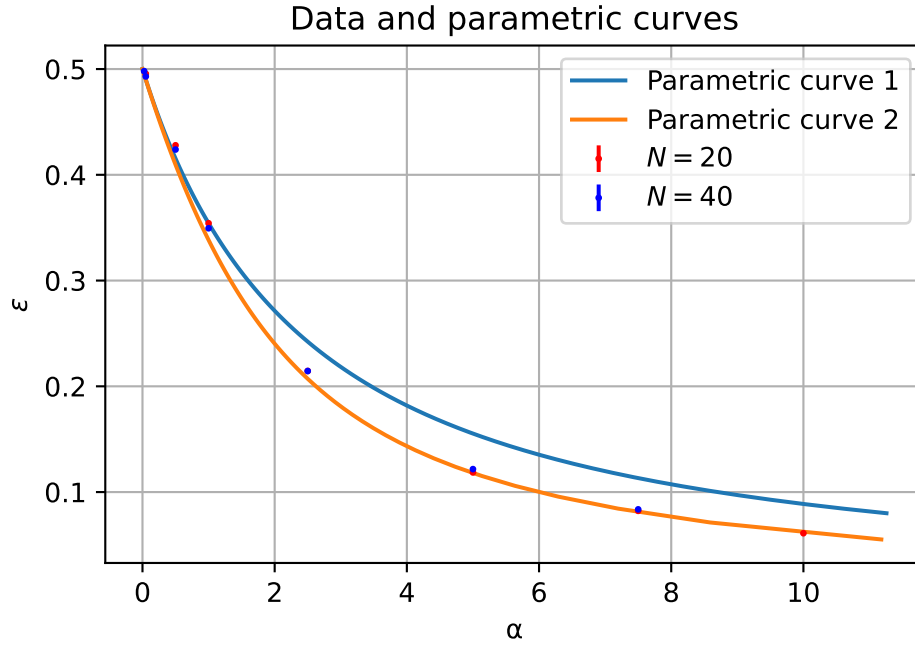
I will hence have the following parametric expressions:

$$\epsilon(t) = \frac{\arccos(t)}{\pi}$$

and

$$\alpha(t) = \frac{\pi t}{\sqrt{1-t} I(t)}.$$

The superimposition between data, parametric curve from the annealed computation (parametric curve 1) and parametric curve from the quenched computation (parametric curve 2) will look like this:



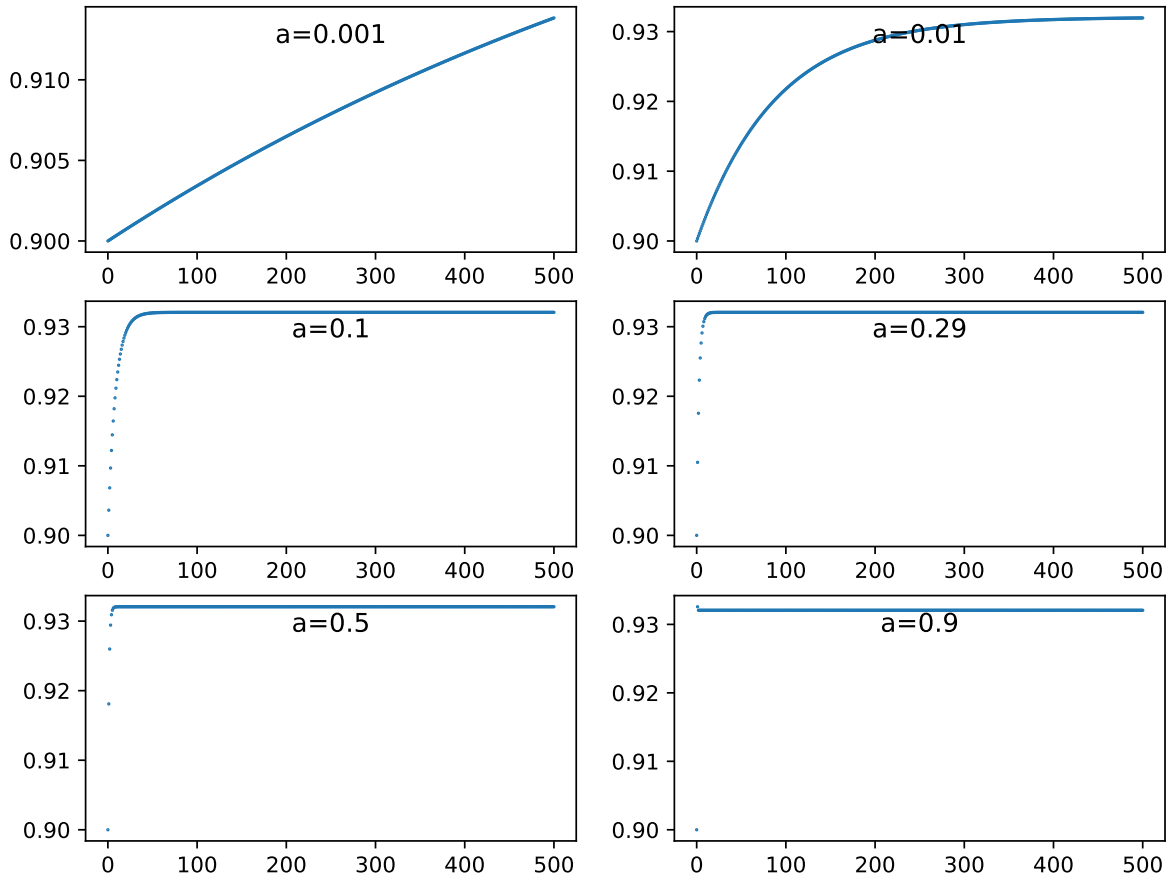
**Step 2: Devise a strategy to explicitly solve equation (1) for, say,  $\alpha = 5$**

We will, for example, rewrite the equation in an iterative form such as

$$R \equiv f(R, \alpha) = 1 - \left( \frac{\pi R}{\alpha I(R)} \right)^2$$

and see whether for different values of the  $a$ , we get a convergence. We can see in the following plots that the algorithm converges in all cases.

### Convergence of iterative solution ( $\alpha=5$ , $R_0 = 0.9$ )



### Step 3: Check the possible choices of $f$ and verify if they converge

Two possibilities are proposed:

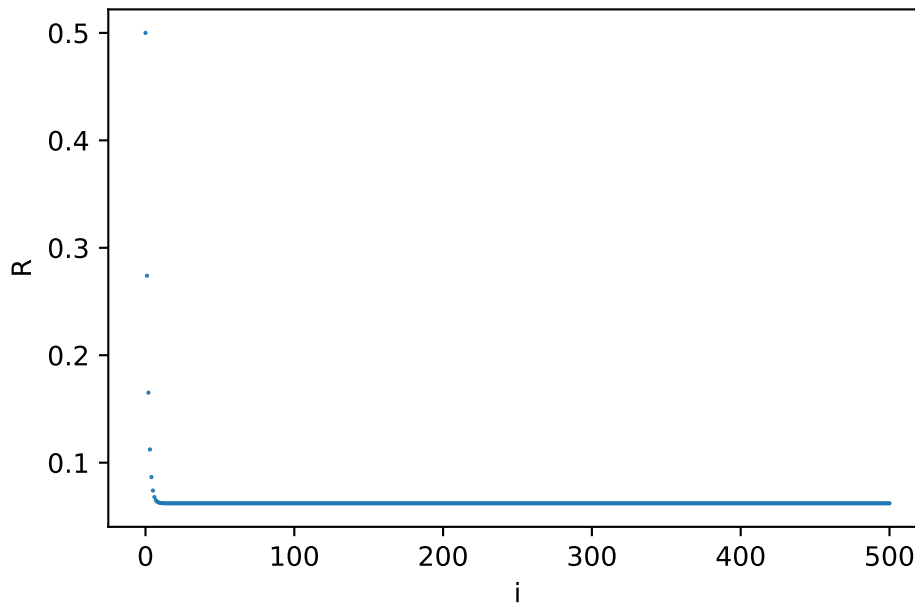
$$f_1(R, \alpha) = \frac{\alpha}{\pi} \sqrt{1-R} I(R)$$

and

$$f_2(R, \alpha) = 1 - \left( \frac{\pi R}{\alpha I(R)} \right)^2$$

which is, by the way, the function that we used in step 2.

Convergence of iterative solution ( $\alpha=0.1$ ,  $R_0 = 0.5$ ,  $a = 0.5$ )



Instead if we try to do the same with  $\alpha = 5$  we get:

Error of numerical integral is higher than 0.001: nan

```
/tmp/ipykernel_38261/2132753670.py:2: RuntimeWarning: invalid value encountered in sqrt
  return alpha * np.sqrt(1-R) * vI_func(R) / np.pi
/tmp/ipykernel_38261/514324215.py:5: IntegrationWarning: The occurrence of roundoff error is
the requested tolerance from being achieved. The error may be
underestimated.
  integrate_result = integrate.quad(lambda x: I_integrand(R, x), -lim, +lim)
```

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As we can see the integration in this case explodes and yields to an error. This is probably due to convergence properties not being satisfied by  $f_1$ . Instead  $f_2$ , as we can see in the following, converges for high values of  $\alpha$  but not for low ones.

Error of numerical integral is higher than 0.001: nan

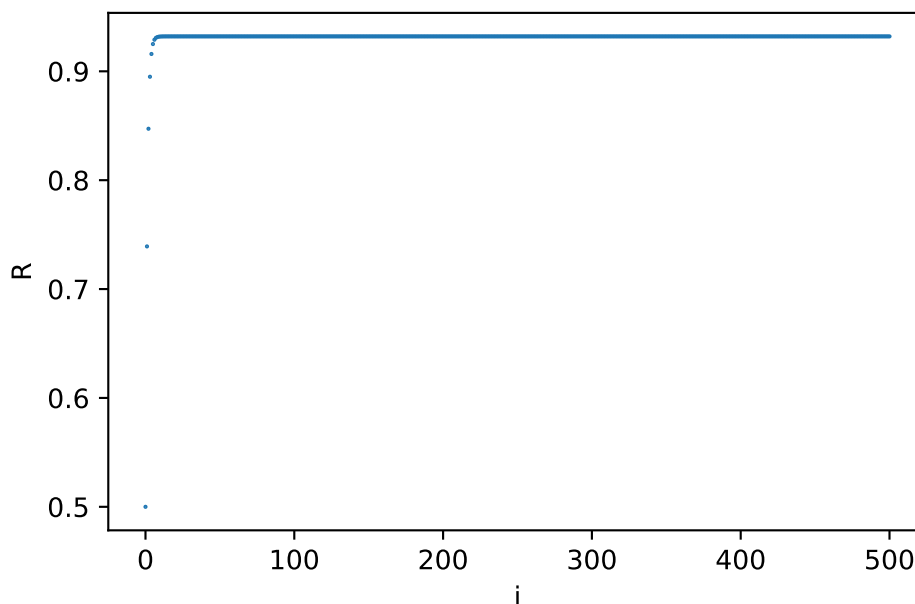
```

/tmp/ipykernel_38261/514324215.py:2: RuntimeWarning: invalid value encountered in sqrt
    return 2. * np.exp(-(1.+R) * v*v / 2.) / (np.sqrt(2.*np.pi) * erfc(-np.sqrt(R/2.) * v))
/tmp/ipykernel_38261/514324215.py:2: RuntimeWarning: overflow encountered in exp
    return 2. * np.exp(-(1.+R) * v*v / 2.) / (np.sqrt(2.*np.pi) * erfc(-np.sqrt(R/2.) * v))
/tmp/ipykernel_38261/514324215.py:5: IntegrationWarning: The occurrence of roundoff error is
the requested tolerance from being achieved. The error may be
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    integrate_result = integrate.quad(lambda x: I_integrand(R, x), -lim, +lim)

```

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Convergence of iterative solution ( $\alpha=5$ ,  $R_0 = 0.5$ ,  $a = 0.5$ )

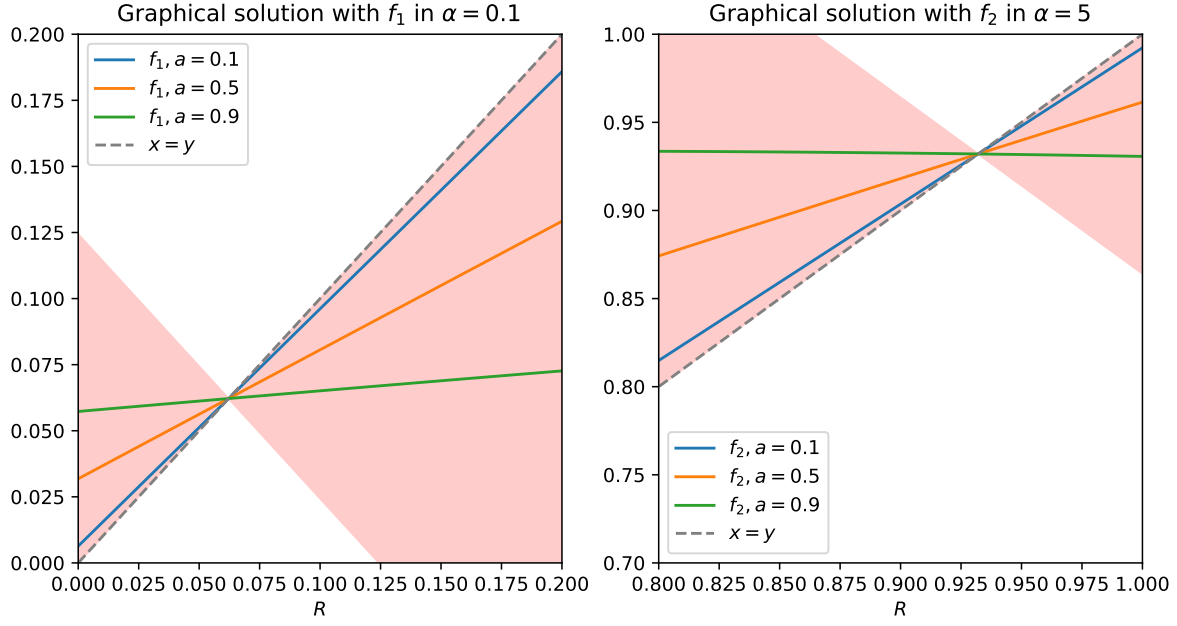


**Step 4: Is any of the two choices suitable over the entire range?**

No, both have limitations over the range where they yield to convergent results.

**Step 5: Set up an automatic procedure to determine  $\epsilon(\alpha)$  over  $\alpha \in [0, 10]$**

Let's see the recursive functions plotted in order to understand the situation better.



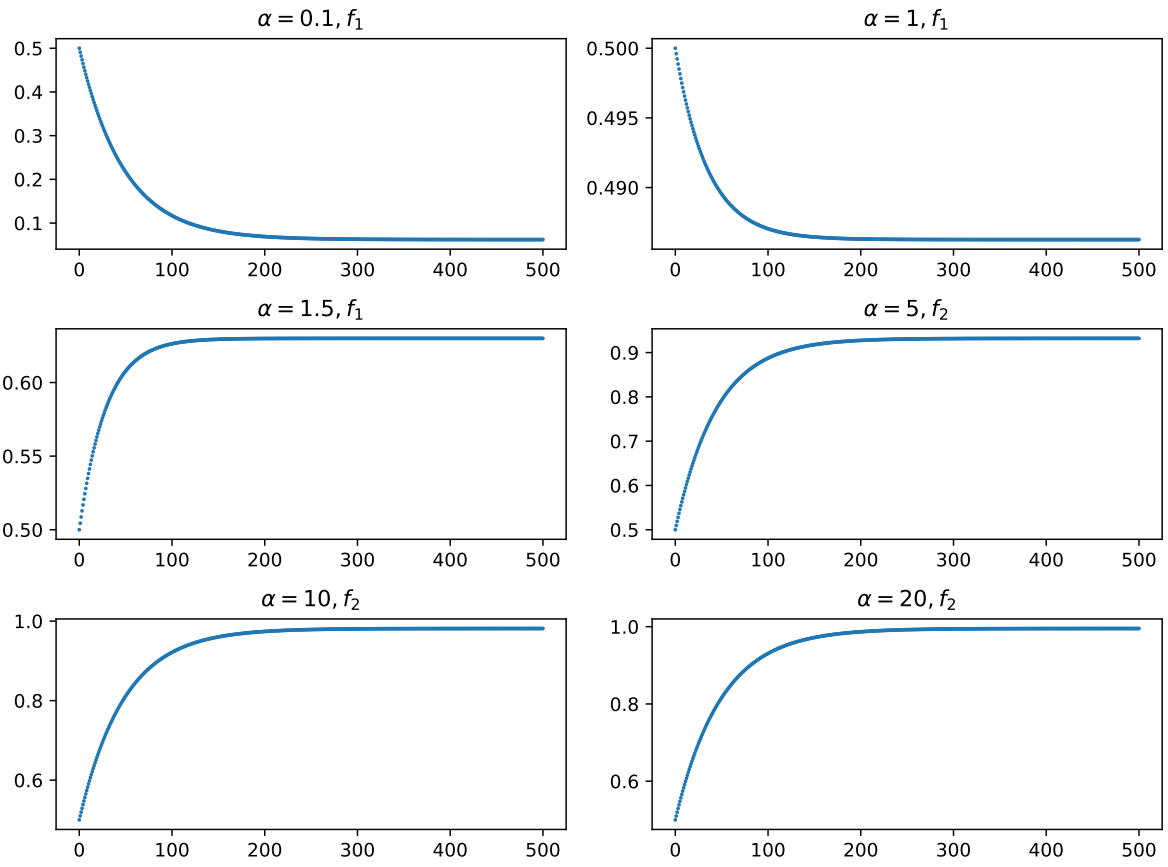
The choice of the function over the  $\alpha$ 's seems to give us some problems. Analytical computation of the absolute value of the parametric function seems to be a little bit too cumbersome, but we can see by tweaking the parameters which values do bring to convergence with which function. For example, it seems that choosing  $f_1$  for  $\alpha < 5$  and  $f_2$  for values of  $\alpha \geq 5$  is a good criterion for reaching convergence over the entire domain of  $\alpha$ .

We will hence (arbitrarily) choose to use the following rule

$$f = \begin{cases} \frac{\alpha}{\pi} \sqrt{1-R} I(R) & \alpha < 5 \\ 1 - \left( \frac{\pi R}{\alpha I(R)} \right)^2 & \alpha \geq 5 \end{cases}$$

with  $a = 0.02$  (found good value by trial and error).

Convergence of algorithm for mixed strategy ( $R_0 = 0.5, a = 0.02$ )





**Step 6: Plot the obtained curve on top of the parametric plot and the numerical results**

