# **Threads Part 2**

#### **Thread Libraries**

- Thread library provides programmer with API for creating and managing threads
- Two primary ways of implementing
  - Library entirely in user space
  - Kernel-level library supported by the OS

#### **Pthreads**

- May be provided either as user-level or kernel-level
- A POSIX standard (IEEE 1003.1c) API for thread creation and synchronization
- Specification, not implementation
- API specifies behavior of the thread library, implementation is up to development of the library
- Common in UNIX operating systems (Solaris, Linux, Mac OS X)

#### **Pthreads Example**

```
#include <pthread.h>
#include <stdio.h>
int sum; /* this data is shared by the thread(s) */
void *runner(void *param); /* threads call this function */
int main(int argc, char *argv[])
  pthread_t tid; /* the thread identifier */
  pthread_attr_t attr; /* set of thread attributes */
  if (argc != 2) {
     fprintf(stderr, "usage: a.out <integer value>\n");
     return -1;
  if (atoi(argv[1]) < 0) {
     fprintf(stderr, "%d must be >= 0\n", atoi(argv[1]));
     return -1;
```

#### Pthreads Example (Cont.)

```
/* get the default attributes */
  pthread_attr_init(&attr);
  /* create the thread */
  pthread_create(&tid,&attr,runner,argv[1]);
  /* wait for the thread to exit */
  pthread_join(tid,NULL);
  printf("sum = %d\n",sum);
/* The thread will begin control in this function */
void *runner(void *param)
  int i, upper = atoi(param);
  sum = 0;
  for (i = 1; i <= upper; i++)
     sum += i;
  pthread_exit(0);
```

#### **Pthreads Code for Joining 10 Threads**

```
#define NUM_THREADS 10

/* an array of threads to be joined upon */
pthread_t workers[NUM_THREADS];

for (int i = 0; i < NUM_THREADS; i++)
   pthread_join(workers[i], NULL);</pre>
```

#### Windows Multithreaded C Program

```
#include <windows.h>
#include <stdio.h>
DWORD Sum; /* data is shared by the thread(s) */
/* the thread runs in this separate function */
DWORD WINAPI Summation(LPVOID Param)
  DWORD Upper = *(DWORD*)Param;
  for (DWORD i = 0; i <= Upper; i++)</pre>
     Sum += i;
  return 0;
int main(int argc, char *argv[])
  DWORD ThreadId;
  HANDLE ThreadHandle;
  int Param;
  if (argc != 2) {
     fprintf(stderr, "An integer parameter is required\n");
    return -1;
  Param = atoi(argv[1]);
  if (Param < 0) {
     fprintf(stderr, "An integer >= 0 is required\n");
     return -1;
```

#### Windows Multithreaded C Program (Cont.)

```
/* create the thread */
ThreadHandle = CreateThread(
  NULL, /* default security attributes */
  0, /* default stack size */
  Summation, /* thread function */
  &Param, /* parameter to thread function */
  0, /* default creation flags */
  &ThreadId); /* returns the thread identifier */
if (ThreadHandle != NULL) {
   /* now wait for the thread to finish */
  WaitForSingleObject(ThreadHandle,INFINITE);
  /* close the thread handle */
  CloseHandle (ThreadHandle);
  printf("sum = %d\n",Sum);
```

#### **Java Threads**

- Java threads are managed by the JVM
- Typically implemented using the threads model provided by underlying OS
- Java threads may be created by:

```
public interface Runnable
{
    public abstract void run();
}
```

- Extending Thread class
- Implementing the Runnable interface

### Java Multithreaded Program

```
class Sum
  private int sum;
  public int getSum() {
   return sum;
  public void setSum(int sum) {
   this.sum = sum;
class Summation implements Runnable
  private int upper;
  private Sum sumValue;
  public Summation(int upper, Sum sumValue) {
   this.upper = upper;
   this.sumValue = sumValue;
  public void run() {
   int sum = 0;
   for (int i = 0; i \le upper; i++)
      sum += i;
   sumValue.setSum(sum);
```

# Java Multithreaded Program (Cont.)

```
public class Driver
  public static void main(String[] args) {
   if (args.length > 0) {
     if (Integer.parseInt(args[0]) < 0)</pre>
      System.err.println(args[0] + " must be >= 0.");
     else {
      Sum sumObject = new Sum();
      int upper = Integer.parseInt(args[0]);
      Thread thrd = new Thread(new Summation(upper, sumObject));
      thrd.start();
      try {
         thrd.join();
         System.out.println
                  ("The sum of "+upper+" is "+sumObject.getSum());
       catch (InterruptedException ie) { }
   else
     System.err.println("Usage: Summation <integer value>"); }
```

# Implicit Threading

- Growing in popularity as numbers of threads increase, program correctness more difficult with explicit threads
- Creation and management of threads done by compilers and run-time libraries rather than programmers
- Three methods explored
  - Thread Pools
  - OpenMP
  - Grand Central Dispatch
- Other methods include Microsoft Threading Building Blocks (TBB), java.util.concurrent package

#### **Thread Pools**

- Create a number of threads in a pool where they await work
- Advantages:
  - Usually slightly faster to service a request with an existing thread than create a new thread
  - Allows the number of threads in the application(s) to be bound to the size of the pool
  - Separating task to be performed from mechanics of creating task allows different strategies for running task
    - i.e.Tasks could be scheduled to run periodically
- Windows API supports thread pools:

```
DWORD WINAPI PoolFunction(AVOID Param) {
    /*
    * this function runs as a separate thread.
    */
}
```

### **OpenMP**

- Set of compiler directives and an API for C, C++, FORTRAN
- Provides support for parallel programming in shared-memory environments
- Identifies parallel regions blocks of code that can run in parallel

```
#pragma omp parallel
```

Create as many threads as there are cores

```
#pragma omp parallel for
   for(i=0;i<N;i++) {
      c[i] = a[i] + b[i];
}</pre>
```

Run for loop in parallel

```
#include <omp.h>
#include <stdio.h>
int main(int argc, char *argv[])
  /* sequential code */
  #pragma omp parallel
     printf("I am a parallel region.");
  /* sequential code */
  return 0;
```

# **Grand Central Dispatch**

- Apple technology for Mac OS X and iOS operating systems
- □ Extensions to C, C++ languages, API, and run-time library
- Allows identification of parallel sections
- Manages most of the details of threading
- Block is in "^{ }" ^{ printf("I am a block"); }
- Blocks placed in dispatch queue
  - Assigned to available thread in thread pool when removed from queue

# **Grand Central Dispatch**

- Two types of dispatch queues:
  - serial blocks removed in FIFO order, queue is per process, called main queue
    - Programmers can create additional serial queues within program
  - concurrent removed in FIFO order but several may be removed at a time
    - ▶ Three system wide queues with priorities low, default, high

```
dispatch_queue_t queue = dispatch_get_global_queue
    (DISPATCH_QUEUE_PRIORITY_DEFAULT, 0);
dispatch_async(queue, ^{ printf("I am a block."); });
```

### Threading Issues

- Semantics of fork() and exec() system calls
- Signal handling
  - Synchronous and asynchronous
- Thread cancellation of target thread
  - Asynchronous or deferred
- Thread-local storage
- Scheduler Activations

# Semantics of fork() and exec()

- Does fork() duplicate only the calling thread or all threads?
  - Some UNIXes have two versions of fork
- exec() usually works as normal replace the running process including all threads

# **Signal Handling**

- Signals are used in UNIX systems to notify a process that a particular event has occurred.
- n A signal handler is used to process signals
  - 1. Signal is generated by particular event
  - 2. Signal is delivered to a process
  - 3. Signal is handled by one of two signal handlers:
    - 1. default
    - user-defined
- n Every signal has default handler that kernel runs when handling signal
  - User-defined signal handler can override default
  - For single-threaded, signal delivered to process

# **Signal Handling (Cont.)**

- where should a signal be delivered for multi-threaded?
  - Deliver the signal to the thread to which the signal applies
  - Deliver the signal to every thread in the process
  - Deliver the signal to certain threads in the process
  - Assign a specific thread to receive all signals for the process

#### **Thread Cancellation**

- Terminating a thread before it has finished
- Thread to be canceled is target thread
- Two general approaches:
  - Asynchronous cancellation terminates the target thread immediately
  - Deferred cancellation allows the target thread to periodically check if it should be cancelled
- Pthread code to create and cancel a thread:

```
pthread_t tid;

/* create the thread */
pthread_create(&tid, 0, worker, NULL);

. . .

/* cancel the thread */
pthread_cancel(tid);
```

# **Thread Cancellation (Cont.)**

 Invoking thread cancellation requests cancellation, but actual cancellation depends on thread state

Mode	State	Type
Off	Disabled	_
Deferred	Enabled	Deferred
Asynchronous	Enabled	Asynchronous

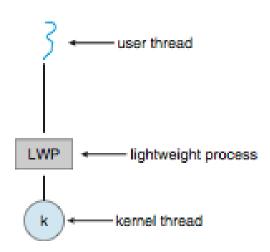
- If thread has cancellation disabled, cancellation remains pending until thread enables it
- Default type is deferred
  - Cancellation only occurs when thread reaches cancellation point
    - | l.e. pthread\_testcancel()
    - Then cleanup handler is invoked
- On Linux systems, thread cancellation is handled through signals

# **Thread-Local Storage**

- Thread-local storage (TLS) allows each thread to have its own copy of data
- Useful when you do not have control over the thread creation process (i.e., when using a thread pool)
- Different from local variables
  - Local variables visible only during single function invocation
  - TLS visible across function invocations
- ☐ Similar to static data
  - TLS is unique to each thread

#### **Scheduler Activations**

- Both M:M and Two-level models require communication to maintain the appropriate number of kernel threads allocated to the application
- Typically use an intermediate data structure between user and kernel threads – lightweight process (LWP)
  - Appears to be a virtual processor on which process can schedule user thread to run
  - Each LWP attached to kernel thread
  - How many LWPs to create?
- Scheduler activations provide upcalls a communication mechanism from the kernel to the upcall handler in the thread library
- This communication allows an application to maintain the correct number kernel threads



# **Operating System Examples**

- Windows Threads
- Linux Threads

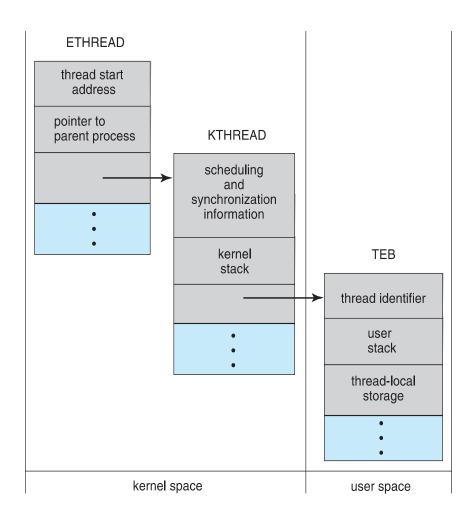
#### **Windows Threads**

- Windows implements the Windows API primary API for Win 98, Win NT, Win 2000, Win XP, and Win 7
- Implements the one-to-one mapping, kernel-level
- Each thread contains
  - A thread id
  - Register set representing state of processor
  - Separate user and kernel stacks for when thread runs in user mode or kernel mode
  - Private data storage area used by run-time libraries and dynamic link libraries (DLLs)
- The register set, stacks, and private storage area are known as the context of the thread

### Windows Threads (Cont.)

- ☐ The primary data structures of a thread include:
  - ETHREAD (executive thread block) includes pointer to process to which thread belongs and to KTHREAD, in kernel space
  - KTHREAD (kernel thread block) scheduling and synchronization info, kernel-mode stack, pointer to TEB, in kernel space
  - □ TEB (thread environment block) thread id, user-mode stack, thread-local storage, in user space

#### **Windows Threads Data Structures**



#### **Linux Threads**

- ☐ Linux refers to them as *tasks* rather than *threads*
- Thread creation is done through clone () system call
- clone() allows a child task to share the address space of the parent task (process)
  - Flags control behavior

flag	meaning	
CLONE_FS	File-system information is shared.	
CLONE_VM	The same memory space is shared.	
CLONE_SIGHAND	Signal handlers are shared.	
CLONE_FILES	The set of open files is shared.	

struct task\_struct points to process data structures (shared or unique)