SOFTWARE ENGINEERINGBUG WORLD SPECIFICATION AND DESIGN

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GENERAL INFORMATION

PURPOSE

The purpose of this document is to implement a Web environment for the simulation of a bug game to observe two swarms of bugs (e.g., red and black bugs) with their own instruction set in a hunting competition (for food) lasting a specific amount of time.

SCOPE

Bug World is an implementation of the above-mentioned Web game that attempts to subdivide the game into:

- GUI: screen and interaction management
- Assembler: generating an executable bug program from assembler input
- Simulator: the engine executing the bug codes and updating its world state

Additional functionality includes:

- **to_string():** method defined in every class, which outputs the current internal object state in human-readable format
- **rand(n)**: a pseudo-random nonnegative integer in the range [0, n-1]

The goal is to run an experiment, also called tournament, which consists of two runs where the two bugs compete. They switch starting positions on the second run. Two runs are made to alleviate the advantage of any particular landscape.

During the entire experiment, the state of the world will be constantly changed, and these changes need to be able to be viewed in the GUI and the logging ability must also be provided.

To conduct unique tournaments, an ability to define the environment and a specific amount of time along with additional options and functionality must also be implemented.

IMPLEMENTATION

TECHNOLOGIES

- *User-Interface*: for the user interface of Bug World the technologies used are
 - HTML: helps build structured web pages / documents and directly introduce content
 - o CSS: helps style and present the web page and its content
 - o JavaScript: helps add dynamic capabilities, further functionality, and interaction on the web page
- Application: for the application of Bug World the technologies used are:
 - o JavaScript

ARCHITECTURE

As mentioned above, Bug World will be subdivided into three main layers:

1. GUI

Manages the screen, accepts user input and displays responses by invoking assembler and simulator.

For **inputs** it will receive:

- a world map file (.world file),
- two bug assembler source code files (.buggy file). The bugs do not need to be called red and black.

Various additional options can also be inputted:

- the number of ticks / iterations / cycles (mandatory)
- various optional controls like log output, state information every *i*-th cycle, etc.
 (optional)

Every tick, it will **output** a visual representation of:

- the current tick
- remaining ticks
- world map
- log output (if enabled)
- a summary of current tournament status (amount of undetected food; for red and black bugs: food brought home, bugs killed / remaining, etc.)

There should also be a way to load just one bug assembler program and show the machine code generated otherwise the errors.

2. Simulator

Generated or created from three files: the world file (.world file), red bug file (.bug file), and black bug file (.bug file). It parses bug code, provides defaults, and holds everything together. It consists of two main modules:

- **Engine**: defines operational semantics of the bug machine language. The simulation lasts for n cycles; every cycle the simulator is logged if logging is activated. The simulation, at the end, responds with statistics about the state of the world.
- o **Tournament**: As mentioned above, it creates a two-game competition in each environment, called a tournament. The swarms will switch starting positions in the second game. Here, a bug will receive 2 points if it wins, a draw will result in 1 point and a loss gets 0 points.

The run function receives file names for the environment world and the bugs, characterized by their machine instructions. The result is the number of points each bug has won in the tournament.

3. Assembler

Reads assembler code (.buggy file) (for correct grammar see **Appendix**), translates to bug code / machine instruction (for correct syntax of instruction set see **Appendix**) for the simulator and emits it onto the GUI. Primarily, it provides a parser read for assembler instructions. It does two passes over the assembler code:

- **First pass:** assigns addresses to labels (*address resolution*)
- Second pass: translates assembler instruction to machine instruction. Notably, a *goto* that follows an instruction can be eliminated by making the target of *goto* the successor of the instruction. If *goto* is the first instruction, implement it using *flip*.

The *assemble()* method implements both passes.

The labels should have a symbol table; the labels are denoted by a state (integer). Parser reads line by line from input file until EOF in a loop – and pattern matches over the list of tokens. *Exception:* **cond**, which may have 1-2 tokens. As **cond** is last element of sense – the remaining tokens can just be passed to **cond**.

DESCRIPTION

WORLD

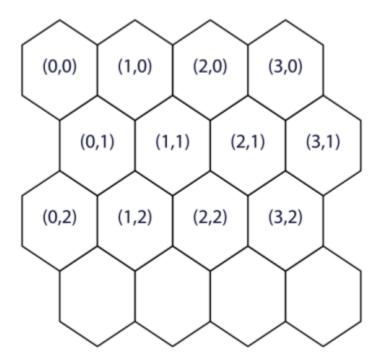
2D flat environment of contiguous hexagonal cells containing bases / nest of swarm for food depositing; bugs; food, and obstacles. The world simulation proceeds in ticks – which executes instructions for each bug and updates its and the world state accordingly.

BUGS

In this world, two types of bugs compete against each other to collect the most food at a specific time. Bugs can also leave traces (path bug has taken) and up to 6 markers. A marker has an *id*, *color*, and *position*. Both can be viewed by the enemy, but the enemy cannot view the marker id.

CELLS

Each cell is identified through its (x,y) position. The top-left corner cell has position (0,0), coordinates increase to bottom and right (see example below). A cell is either free or obstructed. A free cell can contain at most one bug, a non-negative number of food packages and markers from each swarm.



DEBUGGING

The state of the world can be written into log file (either icfp log or sopra log). A stats function returns a record of statistics per bug colony: the number of alive bugs, and the amount of food (e.g., bits) placed on the colony's base.

Requirement Analysis

USER REQUIRMENTS

- 1. User must provide valid .word file.
- 2. User must provide valid .buggy files.
- 3. User must be able to provide options for simulation.
- 4. User must be able to change number of ticks(cycles).

SYSTEM REQUIRMENTS

- 1. User must have JavaScript enabled.
- 2. User must have a Browser.
- 3. User must have an Internet connection.

FUNCTIONAL REQUIRMENTS

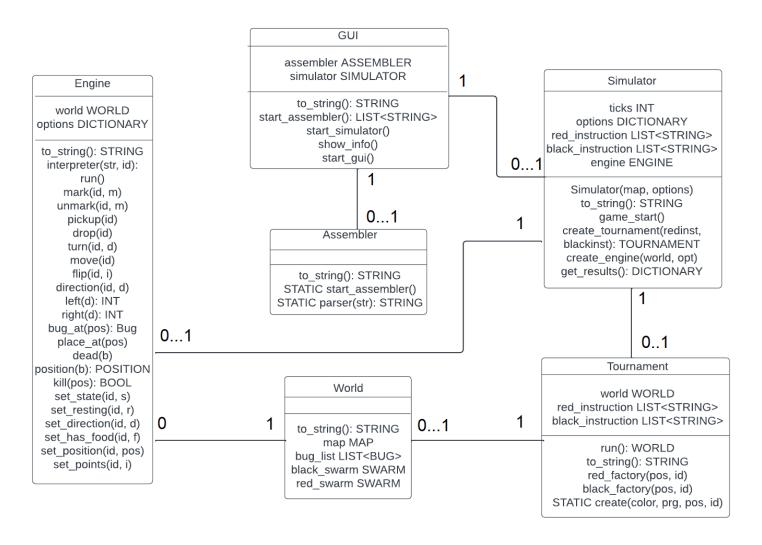
- 1. The simulation must have 2 bug's nests and two bug types.
- 2. The bug must be able to make actions: to move, turn, pick up and drop food, set and unset markers, kill other bugs and check cell or sense for one of these parameters: "Friend", "Foe", "FriendWithFood", "FoeWithFood", "Food", "Rock", "Marker" int, "FoeMarker", "Home", "FoeHome".
- 3. For every tick, instruction sets must be executed sequentially based on the Bugs' id (ascending).
- 4. The bug can make only one action per tick.
- 5. The bug must rest for 14 ticks after making an action.
- **6.** The simulation must provide logs if asked by options (see **Appendix**)
- 7. The simulation must show a leaderboard after the last tick.
- 8. By default, simulation will run for 1000 ticks.
- 9. The bug behavior must be described as finite automata.
- 10. The bug must be able to tell whether the cell is free.
- 11. The assembler must notify the user if .buggy file is not valid.
- 12. The assembler must notify the user if .world file is not valid.
- 13. The maximum value of markers for each nest must be 6.
- 14. The bug can carry at most one food package at a time.
- 15. Each cell can have only non-negative number of food packages.
- 16. Absolute direction in the world is encoded as an integer

- 17. Each position has up to six neighbours
- 18. The bug can only change its direction left or right relative to its current heading
- 19. The bug can cannot view the value of adversarial markers
- 20.On creation, the bug must face direction 0, carry no food, be in state 0 and need no resting (0).
- 21.All opcode and symbolic constants need to be mapped to single-byte numbers. State requires two bytes to allow for more than 255 states.

NON-FUNCTIONAL REQUIRMENTS

1. The Website must support N users at the same time.

CLASS DIAGRAMS

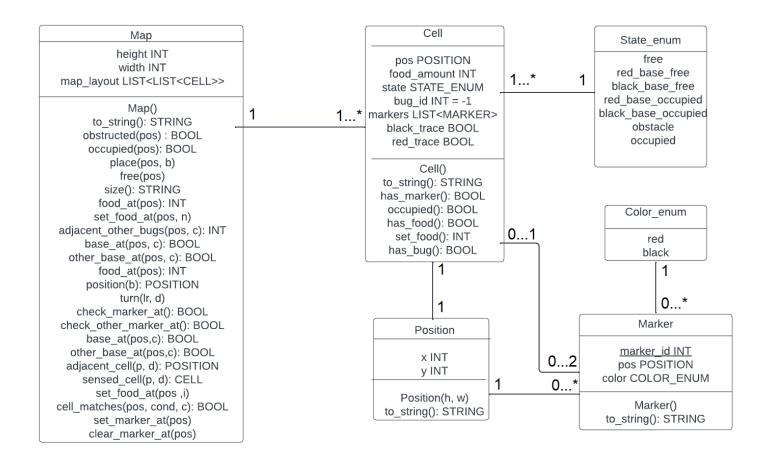


The GUI is the main class which will essentially start everything. First, the assembler and the simulator get created by the GUI. The former actually starts the assembler, while the latter commences the game creation, and creates the engine and the tournament. Then, the tournament creates the world which then gets passed on to the engine, which allows it to proceed further

Swarm marker_ids LIST<INT> instructions LIST<STRING> color COLOR_ENUM marker limit INT = 6 base_cells LIST<POSITION> Swarm() to_string(): STRING 2 1...* 0 World Мар map MAP id INT height INT bug_list LIST<BUG> 1 2...* points INT width INT black_swarm SWARM position POSITION map layout LIST<LIST<CELL>> red_swarm SWARM color COLOR_ENUM state INT = 0 Map() to string(): STRING instruction STRING to string(): STRING resting INT = 0 obstructed(pos) : BOOL direction INT = 0 occupied(pos): BOOL has_food BOOL = false place(pos, b) free(pos) Bug(color, prg, pos, id) size(): STRÍNG to_string(): STRING Color_enum food_at(pos): INT 0 1 2...* other_color(c): COLOR_ENUM set_food_at(pos, n) color(): COLOR_ENUM red adjacent_other_bugs(pos, c): INT state(): INT black base_at(pos, c): BOOL resting(): INT other_base_at(pos, c): BOOL direction(): INT food_at(pos): INT has_food(): INT position(b): POSITION position(): POSITION turn(lr, d) 2...* id(): INT check_marker_at(): BOOL inst(): STRING 1...* check_other_marker_at(): BOOL Position get_points(): INT base_at(pos,c): BOOL other_base_at(pos,c): BOOL x INT y INT adjacent_cell(p, d): POSITION sensed_cell(p, d): CELL Position(h, w) set_food_at(pos ,i) to_string(): STRING cell_matches(pos, cond, c): BOOL set_marker_at(pos) clear_marker_at(pos)

The World class from the previous diagram is shown here as well. It contains two swarms, many bugs, and just one map. A color enumeration is displayed also – it was a better choice than, say, a string containing the color, since only two colors can be given: red and black. The Position class is contained within the map, bug and swarm.

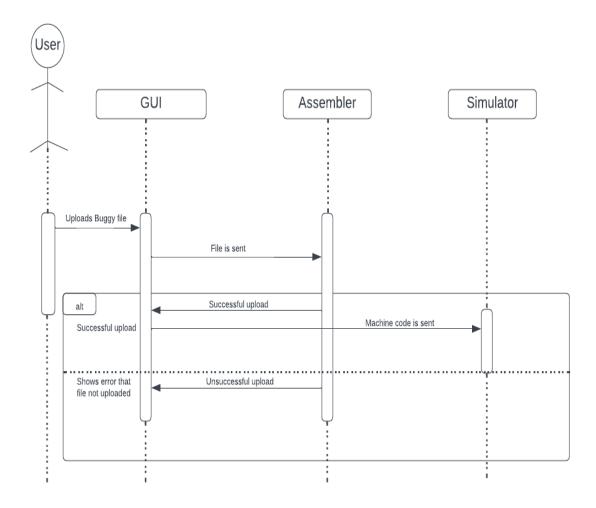
.



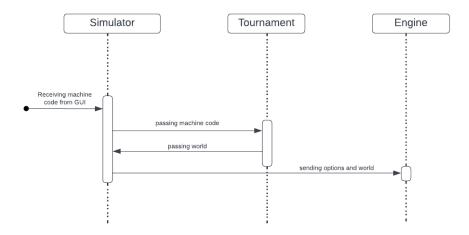
Similarly to the aforementioned diagram, the Map class shows up once again in this diagram. It contains a 2D List made up of cells. Cells have a state enum, a list of markers, and a position. A marker also has a position and color enum.

SEQUENCE DIAGRAM

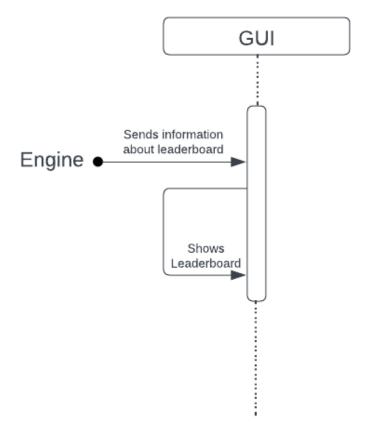
Sequence diagrams display the flow of order which is when and how the objects interact with each other



The user first uploads .buggy files in the GUI. Then the GUI sends the file to assembler which converts the .buggy files into the bug instructions (assembler code to machine code), if the conversion was successful then the user gets a message on the GUI saying that the upload was successful and the machine code is sent to the simulator, however if the conversion was not successful then the user sees an error message on the GUI.



The GUI sends the machine code (the instructions for bugs, and .world file) to the simulator, which then passes it to the tournament to create a world. Then this world is passed to the engine class, which then will start a simulation.



After the simulation has ended, the engine sends the score of the bugs to the GUI, which then displays it to the user in the form of a scoreboard/leaderboard.

APPENDIX

INSTRUCTION SET

sense sensedir s1 s2 cond check if condition cond is fulfilled in direction sensedir; if yes, go to s1,

otherwise s2.

mark m s set marker m in current cell, then go to s.

unmark i s delete marker I, then go to s.

pickup s1 s2 take food from current cell, then go to s1; if no food is available or bug

already carries food then go to s2.

drop s put food into current cell and go to s.
turn lr s turn in direction Ir (left or right), then go to s.

move s1 s2 advance by once cell in current direction, then go to s1; if cell ahead is

blocked go to s2.

flip p s1 s2 obtain a random number between 0 and p -1; if zero then go to s1,

otherwise go to s2.

direction d s1 s2 if current heading is d then go to s1, otherwise go to s2.

ASSEMBLER GRAMMAR

```
program ::= instruction+
instruction ::=
     | "Sense" dir cond "then" label "else" label
     | "Mark" int "then" label
     | "Unmark" int "then" label
     | "PickUp" "then" label "else" label
     | "Drop" next
     | "Turn" leftright
     | "Move" "then" label "else" label
     | "Flip" int "then" label "else" label
     | "Direction" int "then" label "else" label
     | string ":"
label ::= string | number
dir ::= "Here" | "LeftAhead" | "RightAhead" | "Ahead"
leftright ::= "Left" | "Right"
cond ::=
   | "Friend"
    l "Foe"
| "FriendWithFood"
     | "FoeWithFood"
     | "Food"
     | "Rock"
     | "Marker" int
     | "FoeMarker"
     | "Home"
     | "FoeHome"
```

SYMBOL CLASSES

```
number = ['0'-'9']+
ws = [''\t'\t'\'\n'\'\r']+
id = ['A'-'Z'\'a'-'z']+
comment = ';' [^'\n''\r']*
misc = [':']
nl = '\n''\r'?
```

TEST CASES

Val	Valid .world file									Invalid .world file
1	С									10
1	10									-10
#	#	#	#	#	#	#	#	#	#	########
#	9	9			•	•	3	3	#	* 989
#	9	#		_	_	-	_	-	#	+ + \$ \$ \$
#		#	_	_	_	_	_	-	#	########
#			5	_	_	_	_	_	#	
#	+	+	+	+	+	5			#	Expected reaction from system:
#	+	+	+	+	+	+	#		#	Invalid world file! Please make sure to use
#	+	+	+	+	+		#	9	#	valid dimensions, characters and properties.
#	3	3					9	9	#	
#	#	#	#	#	#	#	#	#	#	
Exp	ect	ed r	eac	tio	n fr	om	sys	ten	า:	
Acc	ept	ed ı	vor	ld f	ile.					

Valid .buggy file	Invalid .buggy file
search: sense ahead food else walk move else search pickup else search goto home	search: sense ahead food else run move else search jump else search goto albania
walk: flip 3 else searchright turn left goto search	walk: flip 3 else 3 turn behind goto tokyo
searchright: flip 2 else searchstraight turn right goto search	Ulqin: move up 3 turn left
searchstraight: move else walk goto search	searchstraight: demarcus cousins the 3rd goto search
home: sense ahead home else walkhome move else home drop goto search	home: sense ahead school else walkschool move else home drop goto search
<pre>walkhome: flip 3 else walkhomeright turn left goto home</pre>	walkhome: bababooey Flip 3 else bababooey Turn righeft
<pre>walkhomeright: flip 2 else walkhomestraight turn right goto home</pre>	<pre>walkhomeright: dab 3 else home walkhomestraight: turn back goto homie</pre>
<pre>walkhomestraight: move else walkhome goto home</pre>	walkhomestr8: move else walk to Dhangadhi Goto Kathmandu

```
Expected output by system:
                                       Expected output by system:
Machine code (passed onto simulator):
                                       ERROR! Invalid goto. Invalid grammar.
sense ahead 1 3 food; [0]
                                       Please fix.
move 2 0 ; [1]
pickup 8 0 ; [2]
flip 3 4 5 ;[3]
turn left 0 ;[4]
flip 2 6 7 ; [5]
turn right 0 ; [6]
move 0 3 ; [7]
sense ahead 9 11 home ;[8]
move 10 8 ; [9]
drop 0 ; [10]
flip 3 12 13 ;[11]
turn left 8 ; [12]
flip 2 14 15 ;[13]
turn right 8 ; [14]
move 8 11 ; [15]
```

LOG FILE FORMAT

```
After cycle 0...
====== cell ======= bug =====
        b b
        аi
                                  cbd
pos pos s t red black
                                  oii
 x y e s marks marks id ltr state rest
___ __ _ _ __ ____ _________________
001 007 r 02 543 0 5 3
002 007 r 03 5 1 5 3210
003 007 r 00 3 0 3210 010 r 4 00033 0000
004 007 r 00 \overline{4} \overline{10} \overline{54} 210 005 r\overline{x}3 00002 0000 005 007 r 00 \underline{321} 5 \underline{1}
006 007 <u>02 42</u> 54 1 012 r 4 00019 0000
007 007
008 007 09 5 2 5 2 0
. . .
```

BIBLIOGRAPHY

https://peter-baumann.org//Courses/SoftwareEngineering/index.php https://lucid.app/

Bug World Description – Peter Baumann

Bug World Assembler Manual - Peter Baumann

Bug World Simulator Manual – Peter Baumann