

Creating Libraries – Class Notes

Executables can be categorized into two:

- **Static Executables:** They contain fully resolved library functions that are physically linked into executable image during built.
- **Dynamic Executable:** They contain symbolic references to library functions used and these references are fully resolved either during application load time or run time.

There are mainly two types of libraries:

- Static Libraries (.a)
- Dynamically linked libraries (.so)

Steps for creating Static Libraries:

- 1) Implement library sources

eg.:

one.c

two.c

```
veda@veda: ~/lib
#include<stdio.h>

test()
{
    printf("\ntest app\n");
}
~
~
~
~
~
```

```
veda@veda: ~/lib
#include<stdio.h>

test1()
{
    printf("\ntest1 app\n");
}
~
~
~
~
~
```

2) Compile sources into relocatables

```
$gcc -c one.c -o one.o
```

```
$gcc -c two.c -o two.o
```

3) Using Unix static library tool archive [ar] create static library

```
$ar rcs libtest.a one.o two.o
```

➤ To check the number of files in libtest.a and libtest.so, we use the commands

```
$ar -t libtest.a
```

- In our case it will show one.o and two.o.

```
$nm -s libtest.a
```

- It will list all object files also all the functions inside the object file.

Thus created a static library **libtest.a** and in order to check this library let's write a C program **test.c** which calls the two functions **test()** and **test1()** in **one.c** and **two.c**.

```
$vim test.c
```

```
#include<stdio.h>
```

```
int main()
```

```
{
```

```
test();
```

```
test1();
```

```
}
```

Then we need to compile **test.c** with the static library **libtest.a**. Generally linker checks the default path only, but our library is in our working directory therefore while compiling we have to specify the path of our library in order to avoid undefined reference error.

```
$gcc test.c -o teststat ./libtest.a
```

This will create an executable **teststat** which is statically linked

Steps for creating Dynamic libraries:

Generally relocatables are of two types

- **Position dependent:** Relocatables which cannot be shared.
- **Position independent:** Relocatables which can be shared.

- First create two **.c** files **one.c** and **two.c** as above.
- Compile the sources into position independent relocatables

```
$gcc -c -fpic one.c -o one.o
```

```
$gcc -c -fpic two.c -o two.o
```

-fpic is a flag which is used to tell the linker as it is position independent.

Using dynamic linker creating shared library

```
$gcc -shared -o libtest.so one.o two.o
```

- Then compile the above **test.c** using dynamic library **libtest.so**.

```
$gcc test.c -o testdyn ./libtest.so
```

In both the cases output will be same. In order to understand the major differences between static and dynamic linking, we will analyze the executables using **objdump** tool.

```
$ objdump -D teststat [static executable]
```

```

veda@veda: ~/lib
veda@veda: ~/lib
080483d4 <main>:
80483d4: 55                push    %ebp
80483d5: 89 e5             mov     %esp,%ebp
80483d7: 83 e4 f0          and     $0xfffffffff0,%esp
80483da: 83 ec 10          sub     $0x10,%esp
80483dd: c7 44 24 08 0a 00 00 movl    $0xa,0x8(%esp)
80483e4: 00
80483e5: c7 44 24 0c 14 00 00 movl    $0x14,0xc(%esp)
80483ec: 00
80483ed: e8 0a 00 00 00    call   80483fc <test>
80483f2: e8 19 00 00 00    call   8048410 <test1>
80483f7: c9               leave   %ebp
80483f8: c3               ret
80483f9: 90               nop
80483fa: 90               nop
80483fb: 90               nop

080483fc <test>:
80483fc: 55                push    %ebp
80483fd: 89 e5             mov     %esp,%ebp
80483ff: 83 ec 18          sub     $0x18,%esp
8048402: c7 04 24 00 85 04 08 movl    $0x8048500,(%esp)
8048409: e8 e2 fe ff ff    call   80482f0 <puts@plt>
804840e: c9               leave   %ebp
804840f: c3               ret

```

If we analyze the main function in objdump file we could see that test function base address is given and it is called directly.

\$ **objdump -D testdyn** [dynamic executable]

```

veda@veda: ~/lib
80484d3: 90               nop
080484d4 <main>:
80484d4: 55                push    %ebp
80484d5: 89 e5             mov     %esp,%ebp
80484d7: 83 e4 f0          and     $0xfffffffff0,%esp
80484da: 83 ec 10          sub     $0x10,%esp
80484dd: c7 44 24 08 0a 00 00 movl    $0xa,0x8(%esp)
80484e4: 00
80484e5: c7 44 24 0c 14 00 00 movl    $0x14,0xc(%esp)
80484ec: 00
80484ed: e8 1e ff ff ff    call   8048410 <test@plt>
80484f2: e8 e9 fe ff ff    call   80483e0 <test1@plt>
80484f7: c9               leave   %ebp
80484f8: c3               ret
80484f9: 90               nop
80484fa: 90               nop
80484fb: 90               nop
80484fc: 90               nop
80484fd: 90               nop
80484fe: 90               nop
80484ff: 90               nop

08048500 <__libc_csu_init>:
8048500: 55                push    %ebp
8048501: 57                push    %edi
8048502: 56                push    %esi
8048503: 53                push    %ebx
8048504: e8 69 00 00 00    call   8048572 <__i686.get_pc_thunk.bx>
8048509: 81 c3 eb 1a 00 00 add     $0x1aeb,%ebx
804850f: 83 ec 1c          sub     $0x1c,%esp
8048512: 8b 6c 24 30       mov     0x30(%esp),%ebp
8048516: 8d bb 18 ff ff ff lea     -0xe8(%ebx),%edi
804851c: e8 7f fe ff ff    call   80483a0 <init>

```

Here in dynamic executables main function, it is calling test@plt , (plt= procedure linkage table). Plt table is generated by linker and contains information about dynamic linking.

```

veda@veda: ~/lib
08048400 <__libc_start_main@plt>:
8048400: ff 25 08 a0 04 08 jmp *0x804a008
8048406: 68 10 00 00 00 push $0x10
804840b: e9 c0 ff ff ff jmp 80483d0 <_init+0x30>

08048410 <test@plt>:
8048410: ff 25 0c a0 04 08 jmp *0x804a00c
8048416: 68 18 00 00 00 push $0x18
804841b: e9 b0 ff ff ff jmp 80483d0 <_init+0x30>

Disassembly of section .text:

08048420 <_start>:
8048420: 31 ed xor %ebp,%ebp
8048422: 5e pop %esi
8048423: 89 e1 mov %esp,%ecx
8048425: 83 e4 f0 and $0xfffffffff0,%esp
8048428: 50 push %eax
8048429: 54 push %esp
804842a: 52 push %edx
804842b: 68 70 85 04 08 push $0x8048570

```

Above figure shows the plt table. In that table we could find a **function pointer**, which derefers to our particular function **test**.

USE CASES

- Static executables occupies more disk space but it has zero initialization time.
- Dynamic executables consumes less disk space but it consumes n amount of cpu cycles for initialization.
- Static builds are preferred if executables are being built for a specific use and will be used in a resource constrained environment where initialization delays are not tolerable.
- Dynamic builds are preferred for easier customization, maintenance and extensions for an application.