## Vivekananda College of Engineering & Technology, Puttur [A Unit of Vivekananda Vidyavardhaka Sangha Puttur ®] Affiliated to VTU, Belagavi & Approved by AICTE New Delhi

CRMOS	Rev 1.16	ΑI		07/04/25			
CON	TINUOUS INT	ERNAL EVALUATI	ION	- 1	., _		
Dept: Al	Sem / Div: 4	Sub: Artificial Intelligence		Code: BAD402			2
Date:15/04/25	Time: 3:00-4:30	Max Marks: 50	Elec	ctive:N			
Note: Answer a	ny 2 full questions,	choosing one full ques	stion	from	eacl	n pa	rt.
QN	Questio	ns	M	larks	RBT	СО	)'s
	I	PART A					
into 4 categ		ial Intelligence organize the multiple disciplinate ial Intelligence.		8	L2	СО	1
(i) An A (ii) PEA	S Description						
Draw the ble environmen	t through Sensors a	ne agent interacts with and Actuators.		7	13	3 C	· O 3
Draw the ble environment of the agent is	ock diagram how the through Sensors and sinterested in when and [3,1] contain p	ne agent interacts with and Actuators. Ther the adjacent squa- oits. Illustrate the cond	ares	7	L3	3 C	О3
Draw the bloenvironment of the agent is [1,2], [2,2], of Logic by	ock diagram how the through Sensors are sinterested in wheth and [3,1] contain putaking 8 possible m	ther the adjacent squarets. Illustrate the conducted of t	ares	7	L3	3 C	О3
Draw the ble environment of the agent is [1,2], [2,2], of Logic by a Write a fundamental of the differences by	ock diagram how the through Sensors are sinterested in where and [3,1] contain putaking 8 possible must be tween:	ther the adjacent squarets. Illustrate the conducted of t	ares cept at is the	8		3 C	
Draw the ble environment of The agent is [1,2], [2,2], of Logic by  a Write a fundamental of the second of the worked of the second of the sec	ock diagram how the through Sensors are sinterested in where and [3,1] contain putaking 8 possible must between:  between:  ased reflex agents are peak description of the properties of the pro	ther the adjacent squarets. Illustrate the conducted of t	ares cept  at is the  nts. obot	8	L		CO

-		using the truth table.			
		PART B			
3	8	Compare the General Tree Search and Graph Search Algorithms.	8	L2	CO2
	b	Discuss the differences between Breadth First Search, Depth First Search and Depth-Limited Search along with an example.	10	L2	CO2
	c	Illustrate the A* search algorithm by taking the goal state as Bucharest with an example.	7	L3	CO3
		OR			
4	a	Explain Goal Formulation and Problem Formulation with examples.	8	L2	CO2
		Discuss briefly the example problems that uses Problem Solving Methods.	10	L2	CO2
		Show the sequence of a Knowlege Based Agent, given a percept and the agent adds it to the Knowledge Base. Make use of TELL, ASK and TELL mechanism.		L3	СО

Prepared by: Prof. Akshaya D. Shetty

