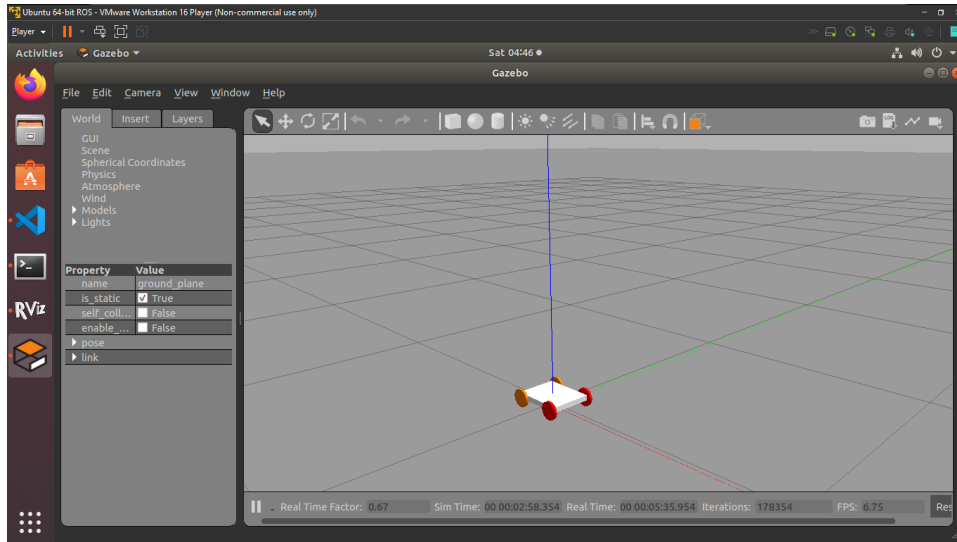


Assignment - 6

Name: Shree Varshan V

Build the 4 wheeled Robot using ROS URDF and Xacro methods.

Gazebo output:



Rviz output:

