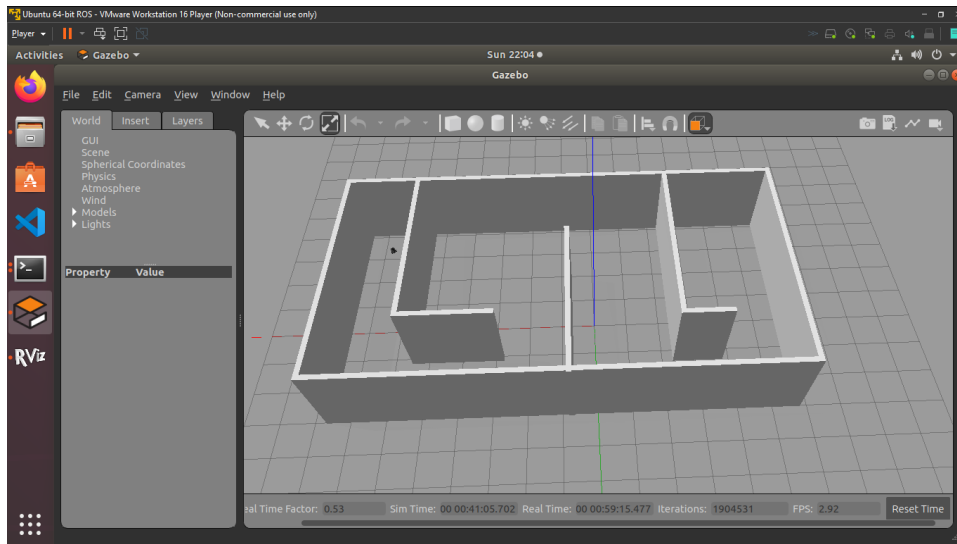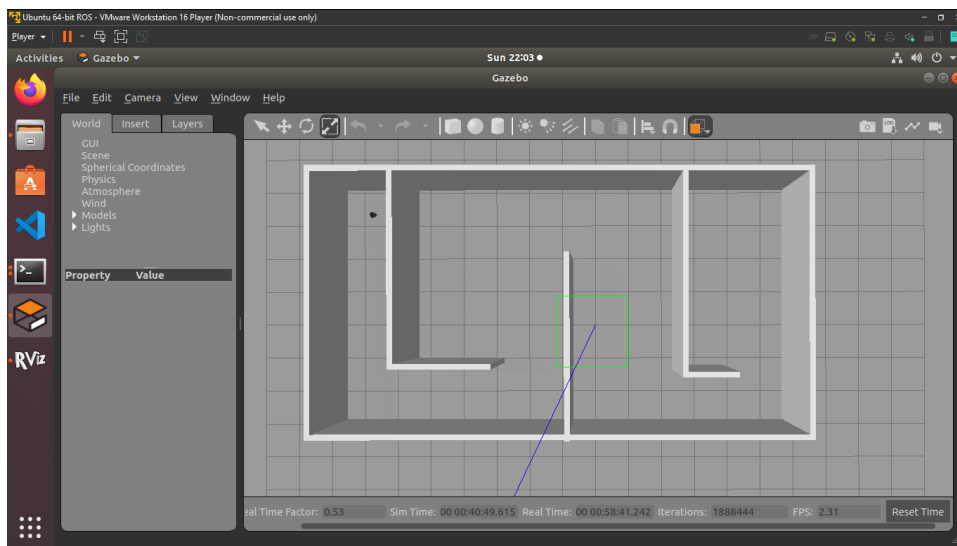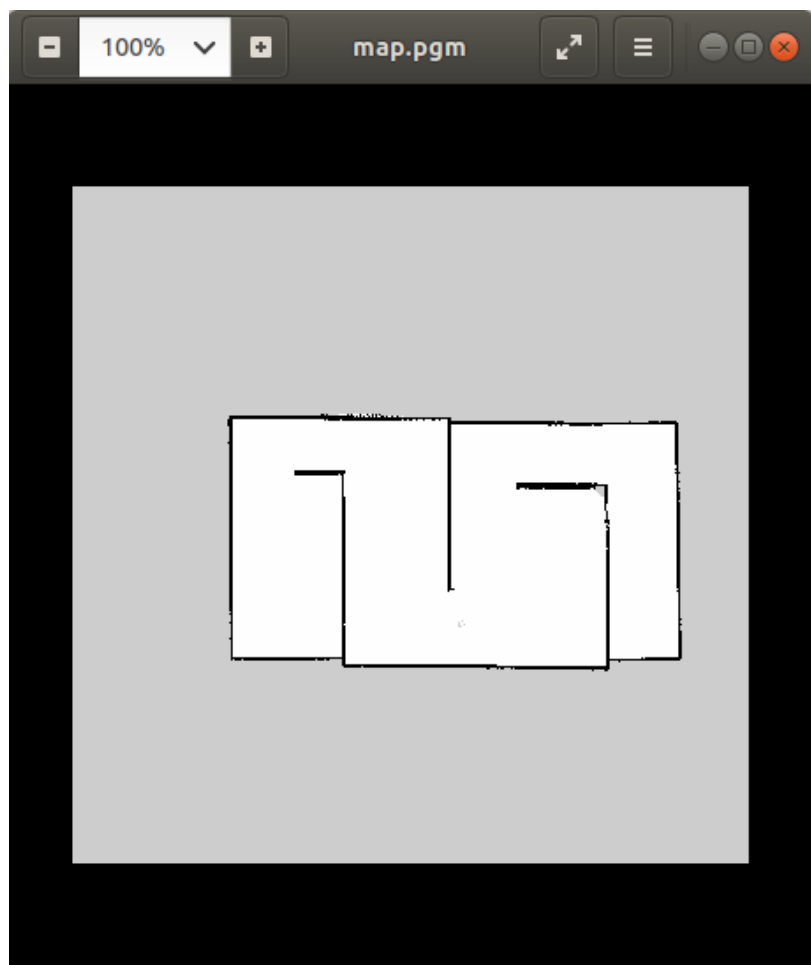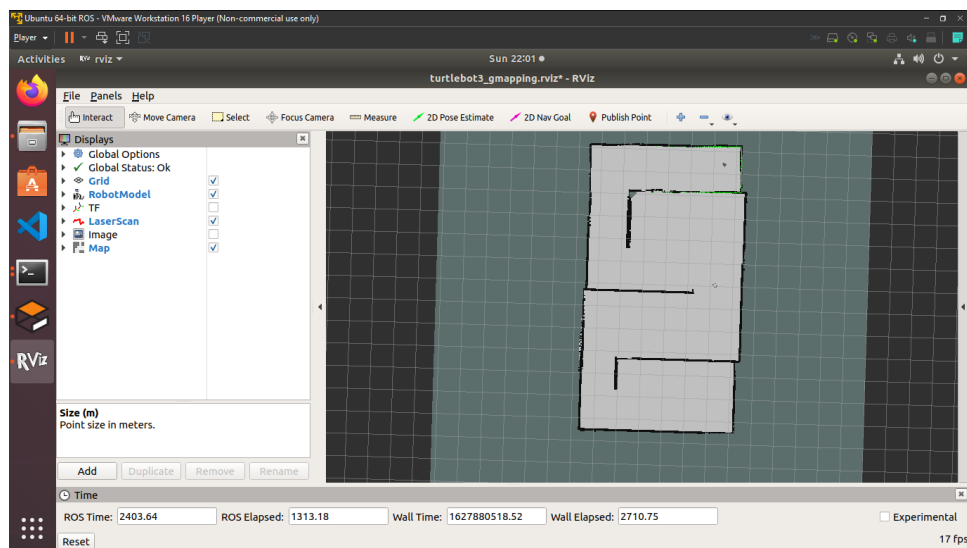# Assignment - 8

Name: Shree Varshan V

Create the Robot Simulation Environment and Perform Build navigation applications using Turtlebot3 Burger.
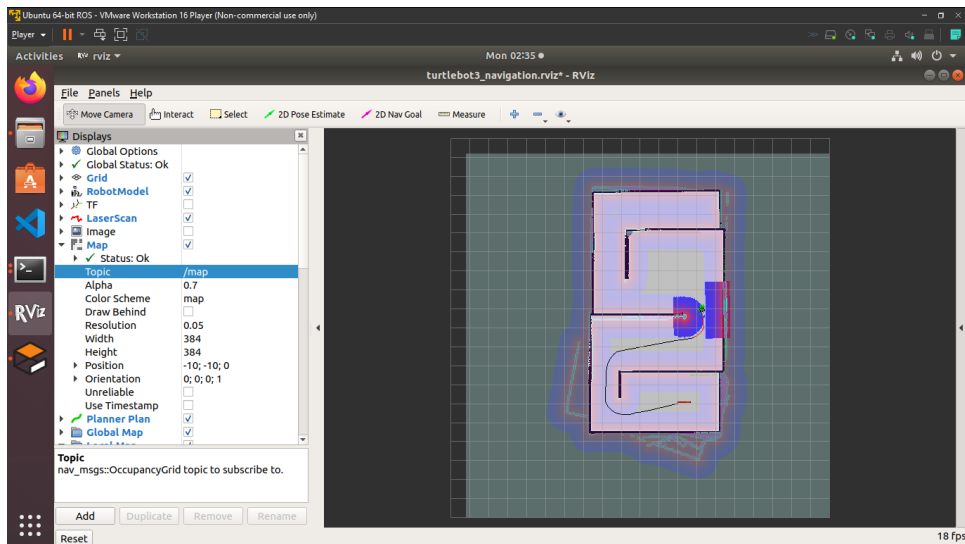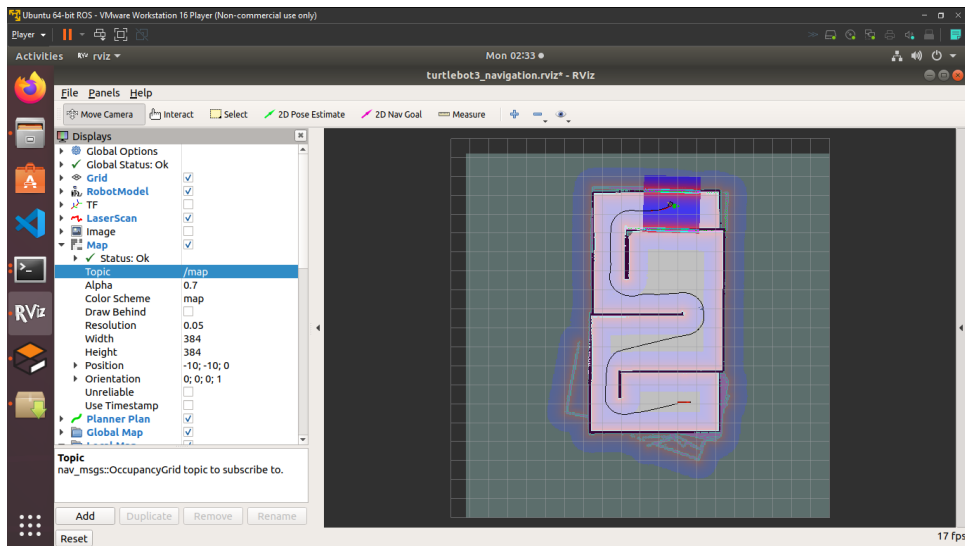
Robot Simulation Environment : Gazebo

Map

Navigation

Starting point :

Final point :