Work Origination Certification

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- The content of this report reflects my personal work and, in cases it is not, the source(s) of the relevant material has/have been appropriately acknowledged after it has been first approved by the courses instructor.
- 3. In preparing and compiling all this report material, I have not collaborated with anyone and I have not received any type of help from anyone but from the courses instructor.

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11/03/2016

Signature

Date

- of r(0) is referred to as penalty term as increase / decrease in it's value, directly affects how the classifier classifier tlp data samples r(0) in general helps to reduce over-fitting by helping the model achieve a good trade off b/w bios and variance.
 - The term getting penalised here is the log likelihood function that is wed to classify data Increase in Pk, decreases model classification ability and vice-versa.

b) We know that

$$lr(\theta) = \sum_{n=1}^{N} \sum_{j=1}^{c} y_{nj} log T_{i} + \sum_{n=1}^{N} \sum_{j=1}^{c} y_{nj} log \left[g(x_{n})\right]$$

$$\frac{\delta I_{r}(\theta)}{\delta \hat{\pi}_{k}} = 0 \Rightarrow \hat{\pi}_{k}^{r} = \frac{\sum_{y=1}^{N} y_{nk}}{\sum_{y=1}^{N} \sum_{i=1}^{N} y_{ni}} = \frac{N_{k}}{N_{i}}$$

$$\frac{\partial I_r(\theta)}{\partial A_k} = 0 \Rightarrow \hat{\mathcal{A}}_k^* = \frac{1}{N_k} + \frac{\sum_{|(x_n)=k}^n x_n|}{N_k}$$

The class priors The & doss means the do not change since regularisation term does not depend on The & Mr. Hence, dass privis The & doss means of for k=1,2... (Mot maximise Ir rainade with maximum likelihood estimates utilised in DDA.

c) Differnitating 1) with it, we get

 $\frac{\partial I_{r}(\hat{\delta})}{\partial \hat{c}_{k}} = \frac{\partial I(\hat{\theta})}{\partial \hat{c}_{k}} - \frac{1}{2} N_{k} P_{k} C_{k}^{\dagger} R_{k} C_{k}^{\dagger}$

=(1) \(\sum_{n=1}^{N} \) \(\

+ @ > YMk " 1/2 . fk (Rk () = 0

> \(\frac{1}{2} \left \

 $\Rightarrow C_k^* = \hat{C}_k + P_k R_k \qquad k=1,2....$

d> Wk. + Ck = Ck + PkRk

> VT (Ĉk + PkRk) V > VT Ĉk V + Pk VTRK V

here, v = dunny motrix

here,

V^TĈ_k V ≥0 , only when Ĉ_k is definite Pu 30 positive > VTRKY is the defnite VIR, V >0 Thus, when we all the Rk ; we ensure that cit is always positive lefnite e) - We use RADA instead of ADA, when data sample size is less than # of limensions i.e, features of data set. Here, we get a singular covariance matrix. - In order to choose Pk, we can use Cross validation techniques like Look /K-fold. Task 4 a) We know that, P((i|x) = P(x|Ci) P(Ci)E P(XICk) P(Ch) = g(n;) h(x) exp(n; x) + p(c;) $\sum_{k} g(n_k) h(x) exp(n_k x) * P(Ci)$

$$P((i/x) = P(t_i) \exp[\log(P(G_i)g(n_i))] \exp(n_i x) = x$$

$$= \exp[\log(P(G_i)g(n_i))] \exp(n_i x)$$

$$= \exp[\log(P(G_i)g(n_i))] \exp(n_i x)$$

$$= exp \left\{ log \left[P(C_i) g(n_i) \right] + n_i^T x \right\}$$

$$= exp \left\{ log \left[P(C_k) g(n_i) \right] + n_k^T x \right\}$$

$$= exp \left\{ log \left[P(C_k) g(n_i) \right] + n_k^T x \right\}$$

$$= exp \left\{ 1 + \frac{n_i x}{\log \{r(c_i) g(n_i)\}} \right\}$$

$$\sum_{k=1}^{6} \left(\frac{e^{x} p}{\log \left(\frac{P(\omega_{k}) q(\eta_{k})}{\log \left(\frac{P(\omega_{k})$$

1ed,
$$\frac{h_{i}^{T}x}{\log \left(r(\omega_{k})g(n_{k})\right)} = \omega_{k}^{T}$$
; $\frac{n_{i}^{T}x}{\log \left(r(\omega_{i})g(n_{i})\right)} = \omega_{i}^{T}$

$$= P((i/x)) = \underbrace{e^{1} \cdot e^{\omega_{i}^{T}x}}_{e^{1}, \sum_{k=1}^{c} e^{\omega_{k}^{T}x}} = \underbrace{e^{\omega_{i}^{T}x}}_{k=1}$$

PDM arising from MNR

(given)

b) (ross Entropy function is given as:

-Fr = E + r(w) = -\(\int \int \int \int \frac{1}{k=1} \rightarrow \fr

 $\Rightarrow \frac{\partial E_r}{\partial \omega_i} = \sum_{n=1}^{\infty} (y_{in} - t_{in}) x_n + 2 t^n \omega_i$

 $\Rightarrow \omega_{i}^{kil} = \omega_{i}^{k} - \lambda \left(\sum_{n=1}^{p} (Y_{in} - t_{in}) X_{n} + 2 \Omega_{i}^{k} \right)$

→ GD uplate equation

here, $\lambda = learning rate$ t = regularisation parameter

- Adding regulariser term to weight update equation, ensures that the new weight obtained is not very much different from the old weight values, - Thus, it prevents over-fitting. Resulting decision boundary will have a smooth curve.

Task 1
Run Task1.m to observe Graphs

Model	Classifier	Avg LOOC Error	Test Set Error
General Case	LDA	0.02	0.06
Naive Bayes	LDA	0.00	0.05
Isotropic	LDA	0.00	0.04
General Case	QDA	0.02	0.04
Naive Bayes	QDA	0.00	0.04
Isotropic	QDA	0.00	0.04

Table: LOOC and Test Set Error for Various Classifier Models

- b) From the table, we realize that Isotropic LDA Classifier is the champion Model. LOOC is used to find the average validation set error. It helps us to ensure that during training phase, we use all combinations of input samples and thus we end up realizing the best classifier model.
- c) From the table, we realize that QDA model is better than LDA model by observing the test set errors. Results are as expected as decision boundaries for QDA are non-linear in shape when compared to LDA model. This is the reason why we get a lower test error for QDA models.
- d) Decision boundaries for QDA are non-linear in shape when compared to LDA model. This is the reason why we get a lower test error for QDA models as they are able to classify data better than LDA that generate linear decision boundaries. The curve or non-linear boundaries is obtained for QDA as we add the prior weighted covariance matrices of all class together to form the log likelihood function.

Task 3

Run Task3.m to observe Graphs

a)		
a)	Average LOOC Error	Test Set Error
	0.02	0.08

b) Decision boundary obtained classifies the data with above accuracy. When compared to LDA and QDA models, the decision boundary of MNR is much more precise i.e., it's not well spread as in case of LDA and QDA. This because they are not constrained by decision boundaries that is based on prior weighted covariance matrices. As a result, MNR have more freedom to generate precise decision boundaries.

Note:

Convergence of MNR model is seen post 100 iterations as mean / gradient found is not divided by total # of Data Samples i.e. it's not normalized.