STUDENT'S NAME CLASS SUBJECT ROLL NO. DATE Derive a stepper motor Interface to notate the motor in Anti- clockwise direction by N steps thenclude & sldio h > # include < reg51 h} char sidata porta at 0x803 char idata au at 0x800; int j; for(j=0; j<800; j++) while (1) acc = 0XII; forta = au; delay(); PRINCE

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STUDENT'S NAME

TOTAL MARKS OBTAINED

STUDENT'S NAME SUBJECT CLASS ACLL NO. Design the slepper motor to rotate the # molude < sldie by #molude regs 1 h) char ratala fort at DX e803. char xdata forta at Oxe800; char idata au at 0x.30, void delay lor (int i=0; i<800; i+t) port - 0x 860, ace = 0x 88) posta = acc; delay (); au = 0x 44; porta = acc delay(); acc = OX 22° porta - acc; delay (); ace = 0x11, porta = aci; & delay (): PRINCE