

1. Intro. We output an Eulerian trail of the (undirected) graph named on the command line. (Each edge is considered to be two directed arcs; thus it is traversed in both directions.)

If the graph isn't connected, we consider only the vertices that are reachable from the first one, $g\text{-vertices}$.

```
#include <stdio.h>
#include <stdlib.h>
#include "gb_graph.h"
#include "gb_save.h"
⟨Subroutine 3⟩
main(int argc, char *argv[])
{
    register int k;
    Graph *g;
    Vertex *u, *v;
    Arc *a;
    ⟨Input the graph 2⟩;
    ⟨Traverse depth first 4⟩;
    ⟨Output the trail 5⟩;
    printf("\n");
}
```

2. ⟨Input the graph 2⟩ \equiv

```
if (argc  $\neq$  2  $\vee$   $\neg$ ( $g = \text{restore\_graph}(argv[1])$ )) {
    fprintf(stderr, "Usage: %s foo.gb\n", argv[0]);
    exit(-1);
}
fprintf(stderr, "OK, I've input '%s'.\n", argv[1]);
gb_new_edge(g-vertices, g-vertices + g-n, 0);    /* dummy edge */
```

This code is used in section 1.

3. Subroutine $\text{dfs}(u, v)$ sets $v\text{-parent} = u$ and $v\text{-nav}$ to the vertex that follows u in v 's adjacency list. It also explores all vertices reachable from v that haven't already been seen.

```
#define parent v.V
#define nav w.A
⟨Subroutine 3⟩  $\equiv$ 
void dfs(register Vertex *u, register Vertex *v)
{
    register Vertex *w;
    register Arc *a;
    v-parent = u;
    for (a = v-arcs; a; a = a-next) {
        w = a-tip;
        if (w  $\equiv$  u) v-nav = a-next;
        else if (w-parent  $\equiv$   $\Lambda$ ) dfs(v, w);
    }
}
```

This code is used in section 1.

4. ⟨Traverse depth first 4⟩ \equiv

```
dfs(g-vertices + g-n, g-vertices);
```

This code is used in section 1.

$$\langle \text{Output the trail } 5 \rangle \equiv$$

This code is used in section 1.

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- ⟨Input the graph 2⟩ Used in section 1.
- ⟨Output the trail 5⟩ Used in section 1.
- ⟨Subroutine 3⟩ Used in section 1.
- ⟨Traverse depth first 4⟩ Used in section 1.

EULER-TRAIL

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