

SIMPLEX METHOD

Contents

- [QUESTION-1](#)
- [QUESTION-2](#)
- [QUESTION-3](#)

QUESTION-1

Solve LPP using simplex using Simplex Algo

```
%MAx Z= x1+2x2
% s.t.  -x1+x2<=1
%        x1+x2<=2
%        xi>=0  i=1-2
% Phase-T: Input the Parameter
clc
clear all
Noofvariables=2;
variables={'x1','x2','s1','s2','sol'};
c=[1 2]; % cost of objective function
Abar=[-1 1;1 1];% const coeff
B=[1;2]; %RHS of constraints
s=eye(size(Abar,1));
A=[Abar s B];
Cost=zeros(1,size(A,2));
Cost(1:Noofvariables)=c;
% Constraints BV
BV=Noofvariables+1:1:size(A,2)-1;
% To calculate Zj-Cj
ZjCj=Cost(BV)*A-Cost;
% For printing 1st simplex table
ZCj=[ZjCj;A];
simplextable=array2table(ZCj);
simplextable.Properties.VariableNames(1:size(ZCj,2))=variables;
% Start simplex Algorithm
Run=true;
while Run
    if any(ZjCj<0) % to check if any negative value there
        fprintf('The current BFS is not optimal\n')
        fprintf('Next iteration required \n')
        disp('Old basic variable (BV)=')
        disp(BV)
        % For finding entering variable
        Zc=ZjCj(1:end-1);
        [Ent_col pvt_col]=min(Zc);
        fprintf('The most negative value in Zj-Cj row is %d and coresponding to column %d \n',Ent_col,pvt_col)
        fprintf('Entering variable is %d \n',pvt_col)
        %For finding the leaving variable
        sol=A(:,end);
        column=A(:,pvt_col);
        if all(column<=0)
            error('The LPP has unbounded solution \n since all enteries are <=0 in %d \n',pvt_col)
        else
            for i=1:size(column,1)
                if column(i)>0
```

```

        ratio(i)=sol(i)./column(i)
    else
        ratio(i)=inf
    end
end
% To finding minimum ratio
[minratio pvt_row]=min(ratio);
fprintf('The minimum ratio corresponding to pivot row %d \n ',pvt_row)
fprintf('leaving variable is %d \n ',BV(pvt_row))
BV(pvt_row)=pvt_col;
disp('New basic variable(BV)==')
disp(BV)
pvt_key=A(pvt_row,pvt_col)
% To update table for next iteration
A(pvt_row,:)=A(pvt_row,:)./pvt_key
for i=1:size(A,1)
    if i~=pvt_row
        A(i,:)=A(i,:)-A(i,pvt_col).*A(pvt_row,:);
    end
    ZjCj=ZjCj-ZjCj(pvt_col).*A(pvt_row,:);
end

end

else
    Run= false;
    ZCj=[ZjCj;A]
    FinalTable=array2table(ZCj);
    FinalTable.Properties.VariableNames(1:size(ZCj,2))=variables
    FinalTable.Properties.RowNames(1:size(ZCj,1))={'Zj-Cj','x1','x2'}
    BFS=zeros(1,size(A,2));
    BFS(BV)=A(:,end)
    BFS(end)=sum(BFS.*Cost);
    currentBFS=array2table(BFS);
    currentBFS.Properties.VariableNames(1:size(currentBFS,2))={'x1','x2','s1','s2','Opt.Val of Z'}
    disp('Optimal sol is reached')
end
end
end

```

The current BFS is not optimal

Next iteration required

Old basic variable (BV)=

3 4

The most negative value in Zj-Cj row is -2 and corresponding to column 2

Entering variable is 2

ratio =

1

ratio =

1 2

The minimum ratio corresponding to pivot row 1

leaving variable is 3

New basic variable(BV)=

2 4

pvt_key =

1

A =

-1	1	1	0	1
1	1	0	1	2

The current BFS is not optimal

Next iteration required

Old basic variable (BV)=

2 4

The most negative value in Zj-Cj row is -3 and corresponding to column 1

Entering variable is 1

ratio =

Inf 2

ratio =

Inf 0.5000

The minimum ratio corresponding to pivot row 2

leaving variable is 4

New basic variable(BV)=

2 1

pvt_key =

2

A =

-1.0000	1.0000	1.0000	0	1.0000
1.0000	0	-0.5000	0.5000	0.5000

ZCj =

0	0	0.5000	1.5000	3.5000
0	1.0000	0.5000	0.5000	1.5000
1.0000	0	-0.5000	0.5000	0.5000

FinalTable =

3x5 table

x1	x2	s1	s2	sol
—	—	—	—	—

0	0	0.5	1.5	3.5
0	1	0.5	0.5	1.5
1	0	-0.5	0.5	0.5

FinalTable =

3×5 table

	x1	x2	s1	s2	sol
	—	—	—	—	—
Zj-Cj	0	0	0.5	1.5	3.5
x1	0	1	0.5	0.5	1.5
x2	1	0	-0.5	0.5	0.5

BFS =

0.5000	1.5000	0	0	0
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currentBFS =

1×5 table

x1	x2	s1	s2	Opt.Val of Z
—	—	—	—	—
0.5	1.5	0	0	3.5

Optimal sol is reached

QUESTION-2

```
%Solve LPP using simplex using Simplex Algo
% Min Z= x1-3x2+2x3
% s.t. 3x1-x2+2x3<=7
%      -2x1+4x2<=12
%      -4x1+3x2+8x3<=10
%      xi>=0 i=1-3
% Phase-T: Input the Parameter
clc
clear all
Noofvariables=3;
variables={'x1','x2','x3','s1','s2','s3','sol'};
c=[-1 3 -2]; % cost of objective func
Abar=[3 -1 2;-2 4 0;-4 3 8];% const coeff
B=[7;12;10]; %RHS of constraints
s=eye(size(Abar,1));
A=[Abar s B];
Cost=zeros(1,size(A,2));
Cost(1:Noofvariables)=c;
% Constraints BV
BV=Noofvariables+1:1:size(A,2)-1;
% To calculate Zj-Cj
ZjCj=Cost(BV)*A-Cost;
% For printing 1st simplex table
ZCj=[ZjCj;A];
```

```

simplextable=array2table(ZCj);
simplextable.Properties.VariableNames(1:size(ZCj,2))=variables;
% Start simplex Algorithm
Run=true;
while Run
    if any(ZjCj<0) % to check if any negative value there
        fprintf('The current BFS is not optimal\n')
        fprintf('Next iteration required \n')
        disp('Old basic variable (BV)=')
        disp(BV)
        % For finding entering variable
        Zc=ZjCj(1:end-1);
        [Ent_col pvt_col]=min(Zc);
        fprintf('The most negative value in Zj-Cj row is %d and corresponding to column %d \n',Ent_col,pvt_col)
        fprintf('Entering variable is %d \n',pvt_col)
        %For finding the leaving variable
        sol=A(:,end);
        column=A(:,pvt_col);
        if all(column<=0)
            error('The LPP has unbounded solution \n since all enteries are <=0 in %d \n',pvt_col)
        else
            for i=1:size(column,1)
                if column(i)>0
                    ratio(i)=sol(i)./column(i)
                else
                    ratio(i)=inf
                end
            end
            % To finding minimum ratio
            [minratio pvt_row]=min(ratio);
            fprintf('The minimum ratio corresponding to pivot row %d \n ',pvt_row)
            fprintf('leaving variable is %d \n ',BV(pvt_row))
            BV(pvt_row)=pvt_col;
            disp('New basic variable(BV)==')
            disp(BV)
            pvt_key=A(pvt_row,pvt_col)
            % To update table for next iteration
            A(pvt_row,:)=A(pvt_row,:)./pvt_key
            for i=1:size(A,1)
                if i~=pvt_row
                    A(i,:)=A(i,:)-A(i,pvt_col).*(A(pvt_row,:));
                end
                ZjCj=ZjCj-ZjCj(pvt_col).*(A(pvt_row,:));
            end

            end
        else
            Run= false;
            ZCj=[ZjCj;A]
            FinalTable=array2table(ZCj);
            FinalTable.Properties.VariableNames(1:size(ZCj,2))=variables
            FinalTable.Properties.RowNames(1:size(ZCj,1))={'Zj-Cj','x1','s2','x3'}
            BFS=zeros(1,size(A,2));
            BFS(BV)=A(:,end)
            BFS(end)=0-sum(BFS.*Cost);
            currentBFS=array2table(BFS);
            currentBFS.Properties.VariableNames(1:size(currentBFS,2))={'x1','x2','x3','s1','s2','s3','Opt.Val of Z'}
            disp('Optimal sol is reached')
        end
    end
end

```

The current BFS is not optimal
Next iteration required
Old basic variable (BV)=
4 5 6

The most negative value in Zj-Cj row is -3 and corresponding to column 2
Entering variable is 2

ratio =

Inf

ratio =

Inf 3

ratio =

Inf 3.0000 3.3333

The minimum ratio corresponding to pivot row 2
leaving variable is 5
New basic variable(BV)==
4 2 6

pvt_key =

4

A =

3.0000	-1.0000	2.0000	1.0000	0	0	7.0000
-0.5000	1.0000	0	0	0.2500	0	3.0000
-4.0000	3.0000	8.0000	0	0	1.0000	10.0000

The current BFS is not optimal
Next iteration required
Old basic variable (BV)=
4 2 6

The most negative value in Zj-Cj row is -5.000000e-01 and corresponding to column 1
Entering variable is 1

ratio =

4.0000 3.0000 3.3333

ratio =

4.0000 Inf 3.3333

ratio =

4 Inf Inf

The minimum ratio corresponding to pivot row 1
leaving variable is 4
New basic variable(BV)==
1 2 6

pvt_key =

2.5000

A =

1.0000 0 0.8000 0.4000 0.1000 0 4.0000
-0.5000 1.0000 0 0 0.2500 0 3.0000
-2.5000 0 8.0000 0 -0.7500 1.0000 1.0000

ZCj =

0 0 2.4000 0.2000 0.8000 0 11.0000
1.0000 0 0.8000 0.4000 0.1000 0 4.0000
0 1.0000 0.4000 0.2000 0.3000 0 5.0000
0 0 10.0000 1.0000 -0.5000 1.0000 11.0000

FinalTable =

4x7 table

x1 x2 x3 s1 s2 s3 sol
— — — — — — —

0 0 2.4 0.2 0.8 0 11
1 0 0.8 0.4 0.1 0 4
0 1 0.4 0.2 0.3 0 5
0 0 10 1 -0.5 1 11

FinalTable =

4x7 table

x1 x2 x3 s1 s2 s3 sol
— — — — — — —

Zj-Cj 0 0 2.4 0.2 0.8 0 11
x1 1 0 0.8 0.4 0.1 0 4
s2 0 1 0.4 0.2 0.3 0 5
x3 0 0 10 1 -0.5 1 11

BFS =

4 5 0 0 0 11 0

currentBFS =

1×7 table

x1	x2	x3	s1	s2	s3	Opt.Val of Z
—	—	—	—	—	—	—
4	5	0	0	0	11	-11

Optimal sol is reached

QUESTION-3

Solve LPP using simplex using Simplex Algo Max $Z = 5x_1 + 3x_2$ s.t. $3x_1 + 5x_2 \leq 15$ $5x_1 + 2x_2 \leq 10$ $x_i \geq 0$ $i=1-2$ Phase-T: Input the Parameter

```
clc
clear all
Noofvariables=2;
variables={'x1','x2','s1','s2','sol'};
c=[5 3]; % cost of objective func
Abar=[3 5;5 2];% const coeff
B=[15;10]; %RHS of constraints
s=eye(size(Abar,1));
A=[Abar s B];
Cost=zeros(1,size(A,2));
Cost(1:Noofvariables)=c;
% Constraints BV
BV=Noofvariables+1:1:size(A,2)-1;
% To calculate Zj-Cj
ZjCj=Cost(BV)*A-Cost;
% For printing 1st simplex table
ZCj=[ZjCj;A];
simplextable=array2table(ZCj);
simplextable.Properties.VariableNames(1:size(ZCj,2))=variables;
% Start simplex Algorithm
Run=true;
while Run
    if any(ZjCj<0) % to check if any negative value there
        fprintf('The current BFS is not optimal\n')
        fprintf('Next iteration required \n')
        disp('Old basic variable (BV)=')
        disp(BV)
        % For finding entering variable
        Zc=ZjCj(1:end-1);
        [Ent_col pvt_col]=min(Zc);
        fprintf('The most negative value in Zj-Cj row is %d and coresponding to column %d \n',Ent_col,pvt_col)
        fprintf('Entering variable is %d \n',pvt_col)
        %For finding the leaving variable
        sol=A(:,end);
        column=A(:,pvt_col);
        if all(column<=0)
            error('The LPP has unbounded solution \n since all enteries are <=0 in %d \n',pvt_col)
        else
            for i=1:size(column,1)
                if column(i)>0
                    ratio(i)=sol(i)./column(i)
                else
                    ratio(i)=inf
                end
            end
            % To finding minimmum ratio
```



```

[minratio pvt_row]=min(ratio);
fprintf('The minimum ratio corresponding to pivot row %d \n ',pvt_row)
fprintf('leaving variable is %d \n ',BV(pvt_row))
BV(pvt_row)=pvt_col;
disp('New basic variable(BV)==')
disp(BV)
pvt_key=A(pvt_row,pvt_col)
% To update table for next iteration
A(pvt_row,:)=A(pvt_row,:)./pvt_key
for i=1:size(A,1)
    if i~=pvt_row
        A(i,:)=A(i,:)-A(i,pvt_col).*A(pvt_row,:);
    end
    ZjCj=ZjCj-ZjCj(pvt_col).*A(pvt_row,:);
end

    end
else
    Run= false;
    ZCj=[ZjCj;A]
    FinalTable=array2table(ZCj);
    FinalTable.Properties.VariableNames(1:size(ZCj,2))=variables
    FinalTable.Properties.RowNames(1:size(ZCj,1))={'Zj-Cj','x1','x2'}
    BFS=zeros(1,size(A,2));
    BFS(BV)=A(:,end)
    BFS(end)=sum(BFS.*Cost);
    currentBFS=array2table(BFS);
    currentBFS.Properties.VariableNames(1:size(currentBFS,2))={'x1','x2','s1','s2','Opt.Val of Z'}
    disp('Optimal sol is reached')
end
end
end

```

The current BFS is not optimal

Next iteration required

Old basic variable (BV)=

3 4

The most negative value in Zj-Cj row is -5 and corresponding to column 1

Entering variable is 1

ratio =

5

ratio =

5 2

The minimum ratio corresponding to pivot row 2

leaving variable is 4

New basic variable(BV)=

3 1

pvt_key =

5

A =

3.0000	5.0000	1.0000	0	15.0000
1.0000	0.4000	0	0.2000	2.0000

The current BFS is not optimal

Next iteration required

Old basic variable (BV)=

3 1

The most negative value in Zj-Cj row is -1 and corresponding to column 2

Entering variable is 2

ratio =

2.3684	2.0000
--------	--------

ratio =

2.3684	5.0000
--------	--------

The minimum ratio corresponding to pivot row 1

leaving variable is 3

New basic variable(BV)=

2 1

pvt_key =

3.8000

A =

0	1.0000	0.2632	-0.1579	2.3684
1.0000	0.4000	0	0.2000	2.0000

ZCj =

0	0	0.2632	0.8421	12.3684
0	1.0000	0.2632	-0.1579	2.3684
1.0000	0	-0.1053	0.2632	1.0526

FinalTable =

3x5 table

x1	x2	s1	s2	sol
—	—	—	—	—
0	0	0.26316	0.84211	12.368
0	1	0.26316	-0.15789	2.3684
1	0	-0.10526	0.26316	1.0526

FinalTable =

3×5 table

	x1	x2	s1	s2	sol
	—	—	—	—	—
Zj-Cj	0	0	0.26316	0.84211	12.368
x1	0	1	0.26316	-0.15789	2.3684
x2	1	0	-0.10526	0.26316	1.0526

BFS =

1.0526	2.3684	0	0	0
--------	--------	---	---	---

currentBFS =

1×5 table

x1	x2	s1	s2	Opt.Val of Z
—	—	—	—	—
1.0526	2.3684	0	0	12.368

Optimal sol is reached