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QUESTION 1

TO OBTAIN BFS USING ALGEBRAIC METHOD Question Max Z= 2x1+3x2+4x3+7x4 st: 2x1+3x2-x3+4x4=8 x1-2x2+6x3-7x4=-3 %xi>=0; i=1,2,3,4

```
clc
clear all
format short
% PHASE-1: Input the parameter
c=[2,3,4,7]; %Objective function
A=[2 3 -1 4; 1 -2 6 -7]; %Coefficient Matrix
B=[8;-3];%RHS of const
objective=1; %1 for max and -1 for minimization problem
%Number of possible solutions: nCm:nchoosek
% PHASE-2: Number of constraint and variable
m=size(A,1); %number of constraints
n=size(A,2); % number of variables
% PHASE-3: Compute the ncm Basic Solutions: The max number of basic
% solutions will always be nCm
nab=nchoosek(n,m); %total number of atmost basic solution
t=nchoosek(1:n,m); %from this we can extract our set of variables that we need to equate to zero
% PHASE-4:Construct the basic solution
% for this n>m must be satisfied
sol=[]; %default solution is zero (Empty Matrix)
if n>=m %if this is not statisfied then we can not have solutions
    for i=1:nab
    y=zeros(n,1);
    %selecting all rows for a specific column where for t we are taking all columns for a
    % specific row (which is basically the variables that are equated to zero)
    X=(A(:,t(i,:)))\setminus B;
    %fetching values from A matrix for the rows correspond
    %checking feasibility condition
    if all(X>=0 & X~=inf & X~=-inf)
        y(t(i,:))=X;
        sol=[sol y];
    end
    end
    disp("Solution: ");
    disp(sol);
else
    error('No. of variables is less than number of constraints')
if any(X == 0)
        fprintf("DEGENERATE SOLUTION");
else
    fprintf('NON-DEGENERATE SOLUTION\n');
%PHASE 5: To find optimal solution
```

```
Z=c*sol; %finding the values corresponding to each point
if(objective==1)
    [Zmax,Zindex]=max(Z);%storing the max value of Z and the col in which this max value resides
else
    [Zmax,Zindex]=min(Z);%storing the min value of Z and the col in which this min value resides
end
BFS=sol(:,Zindex);%basic feasible solution
[Optimal_Value]=[BFS' Zmax];
Optimal_bfs=array2table(Optimal_Value);
Optimal_bfs.Properties.VariableNames(1:size(Optimal_bfs,2))={'x1','x2','x3','x4','Optimal Value of Z'};
disp(Optimal_bfs);
```

```
Solution:
         2.4444
  1.0000
                  0
                             0
   2.0000
           0 2.8125
                             0
      0
            0 0.4375 2.5882
      0
          0.7778
                    0 2.6471
NON-DEGENERATE SOLUTION
                           Optimal Value of Z
   x1
     x2
                    x4
          x3
```

2.5882 2.6471

QUESTION 2

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0

TO OBTAIN BFS USING ALGEBRAIC METHOD Question 2 Max Z= -x1+2x2-x3 st: x1+s1=4 x2+s2=4 -x1+x2+s3=6 -x1+2x3+s4=4 x1,x2,x3>=0

28.882

```
clc
clear all
format short
% PHASE-1: Input the parameter
c=[-1,2,-1,0,0,0,0]; %Objective function
A=[1,0,0,1,0,0,0;0,1,0,0,1,0,0;-1,1,0,0,0,1,0;-1,2,0,0,0,0,1]; %Coefficient Matrix
B=[4;4;6;4];%RHS of const
objective=1; %1 for max and -1 for minimization problem
%Number of possible solutions: nCm:nchoosek
% PHASE-2: Number of constraint and variable
m=size(A,1); %number of constraints
n=size(A,2); % number of variables
% PHASE-3: Compute the ncm Basic Solutions: The max number of basic
% solutions will always be nCm
nab=nchoosek(n,m); %total number of atmost basic solution
t=nchoosek(1:n,m); %from this we can extract our set of variables that we need to equate to zero
% PHASE-4:Construct the basic solution
% for this n>m must be satisfied
sol=[]; %default solution is zero (Empty Matrix)
if n>=m %if this is not statisfied then we can not have solutions
   for i=1:nab
    y=zeros(n,1);
    %selecting all rows for a specific column where for t we are taking all columns for a
    % specific row (which is basically the variables that are equated to zero)
    X=(A(:,t(i,:)))B;
    %fetching values from A matrix for the rows correspond
    %checking feasibility condition
    if all(X>=0 & X~=inf & X~=-inf)
```

```
y(t(i,:))=X;
        sol=[sol y];
    end
    end
    disp("Solution: ");
    disp(sol);
else
    error('No. of variables is less than number of constraints')
if any(X == 0)
        fprintf("DEGENERATE SOLUTION");
else
    fprintf('NON-DEGENERATE SOLUTION\n');
end
%PHASE 5: To find optimal solution
Z=c*sol; %finding the values corresponding to each point
if(objective==1)
    [Zmax,Zindex]=max(Z);%storing the max value of Z and the col in which this max value resides
else
    [Zmax,Zindex]=min(Z);%storing the min value of Z and the col in which this min value resides
end
BFS=sol(:,Zindex);%basic feasible solution
[Optimal Value]=[BFS' Zmax];
Optimal_bfs=array2table(Optimal_Value);
Optimal_bfs.Properties.VariableNames(1:size(Optimal_bfs,2))={'x1','x2','x3','s1','s2','s3','s4','Optimal Value of Z'};
disp(Optimal_bfs);
Warning: Matrix is singular to working precision.
Solution:
```

4 4 4 4 0 4 4 4 0 2 0 0 0 0 a 0 0 0 0 0 4 4 0 0 0 4 2 4 6 6 6 10 4 6 0 8

NON-DEGENERATE SOLUTION

x1 x2 x3 s1 s2 s3 s4 Optimal Value of Z

QUESTION 3

TO OBTAIN BFS USING ALGEBRAIC METHOD Question Max Z= 5x2-2x1 st; 2x1+5x2+s1=8 x1+x2+s2=2 %xi>=0

```
c1c
clear all
format short
% PHASE-1: Input the parameter
c=[-2,5,0,0]; %Objective function
A=[2,5,1,0;1,1,0,1]; %Coefficient Matrix
B=[8;2];%RHS of const
objective=-1; %1 for max and -1 for minimization problem
%Number of possible solutions: nCm:nchoosek
% PHASE-2: Number of constraint and variable
m=size(A,1); %number of constraints
n=size(A,2); % number of variables
% PHASE-3: Compute the ncm Basic Solutions: The max number of basic
% solutions will always be nCm
nab=nchoosek(n,m); %total number of atmost basic solution
t=nchoosek(1:n,m); %from this we can extract our set of variables that we need to equate to zero
% PHASE-4:Construct the basic solution
% for this n>m must be satisfied
sol=[]; %default solution is zero (Empty Matrix)
if n>=m %if this is not statisfied then we can not have solutions
    for i=1:nab
    y=zeros(n,1);
    %selecting all rows for a specific column where for t we are taking all columns for a
    % specific row (which is basically the variables that are equated to zero)
    X=(A(:,t(i,:)))
    %fetching values from A matrix for the rows correspond
    %checking feasibility condition
    if all(X>=0 & X~=inf & X~=-inf)
        y(t(i,:))=X;
        sol=[sol y];
    end
    end
    disp("Solution: ");
    disp(sol);
else
    error('No. of variables is less than number of constraints')
end
if any(X == 0)
        fprintf("DEGENERATE SOLUTION");
else
    fprintf('NON-DEGENERATE SOLUTION\n');
%PHASE 5: To find optimal solution
Z=c*sol; %finding the values corresponding to each point
if(objective==1)
    [Zmax,Zindex]=max(Z);%storing the max value of Z and the col in which this max value resides
else
    [Zmax,Zindex]=min(Z);%storing the min value of Z and the col in which this min value resides
end
%Optimal BFS
BFS=sol(:,Zindex);%basic feasible solution
```

```
[Optimal_Value]=[BFS' Zmax];
Optimal_bfs=array2table(Optimal_Value);
Optimal_bfs.Properties.VariableNames(1:size(Optimal_bfs,2))={'x1','x2','s1','s2','Optimal Value of Z'};
disp(Optimal_bfs);
```

```
Solution:
                   0
   0.6667
          2.0000
   1.3333
         0
                  1.6000
                              0
          4.0000 0
                          8.0000
       0
       0
           0
                  0.4000
                         2.0000
NON-DEGENERATE SOLUTION
   x1
       x2
                 52
                     Optimal Value of Z
   2
       0 4
                 0
                            -4
```

QUESTION 4

TO OBTAIN BFS USING ALGEBRAIC METHOD Question Max Z= x1+x2+x3+0s1+0s2 st: x1+x2+s1=1 -x2+x3+s2=0 %xi>=0

```
clc
clear all
format short
% PHASE-1: Input the parameter
c=[1,1,1,0,0]; %Objective function
A=[1,1,0,1,0;0,-1,1,0,1]; %Coefficient Matrix
B=[1;0];%RHS of const
objective=1; %1 for max and -1 for minimization problem
%Number of possible solutions: nCm:nchoosek
% PHASE-2: Number of constraint and variable
m=size(A,1); %number of constraints
n=size(A,2); % number of variables
% PHASE-3: Compute the ncm Basic Solutions: The max number of basic
% solutions will always be nCm
nab=nchoosek(n,m); %total number of atmost basic solution
t=nchoosek(1:n,m); %from this we can extract our set of variables that we need to equate to zero
% PHASE-4:Construct the basic solution
% for this n>m must be satisfied
sol=[]; %default solution is zero (Empty Matrix)
if n>=m %if this is not statisfied then we can not have solutions
    for i=1:nab
       y=zeros(n,1);
        %selecting all rows for a specific column where for t we are taking all columns for a
        % specific row (which is basically the variables that are equated to zero)
        X=(A(:,t(i,:)))\B;
        %fetching values from A matrix for the rows correspond
        %checking feasibility condition
        if all(X>=0 & X~=inf & X~=-inf)
            y(t(i,:))=X;
            sol=[sol y];
        end
    end
    disp("Solution: ");
    disp(sol);
else
```

```
error('No. of variables is less than number of constraints')
end
if any(X == 0)
        fprintf("DEGENERATE SOLUTION\n");
else
    fprintf('NON-DEGENERATE SOLUTION\n');
end
%PHASE 5: To find optimal solution
Z=c*sol; %finding the values corresponding to each point
if(objective==1)
    [Zmax,Zindex]=max(Z); %storing the max value of Z and the col in which this max value resides
else
    [Zmax,Zindex]=min(Z);%storing the min value of Z and the col in which this min value resides
end
BFS=sol(:,Zindex);%basic feasible solution
[Optimal_Value]=[BFS' Zmax];
Optimal_bfs=array2table(Optimal_Value);
Optimal_bfs.Properties.VariableNames(1:size(Optimal_bfs,2))={'x1','x2','x3','s1','s2','Optimal Value of Z'};
disp(Optimal_bfs);
```

```
Warning: Matrix is singular to working precision.
Warning: Matrix is singular to working precision.
Solution:
    1
         1
              1
                    0
                         0
    0
         0
              0
                   1
                         0
                              1
                                         0
            0
    0
         0
                 1
                         0
                            0
                                   0
                                         0
    0
                       1 0
                                 1
                                         1
    0
                         0
                              1
                                   0
                                         0
DEGENERATE SOLUTION
        x2
                             Optimal Value of Z
   x1
              х3
                        s2
                   s1
                                    2
```

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