# **OT LAB ASSIGNMENT 5**

# **Question 1**

Maximize 
$$Z = 2x_1 + 3x_2 + 4x_3 + 7x_4$$
  
s.t.  $2x_1 + 3x_2 - x_3 + 4x_4 = 8$ ,  
 $x_1 - 2x_2 + 6x_3 - 7x_4 = -3$ ,  
 $x_i \ge 0 \ \forall \ i = 1 - 4$ .

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%% QUESTION 1
% TO OBTAIN BFS USING ALGEBRAIC METHOD
% Ouestion
\% Max Z= 2x1+3x2+4x3+7x4
% st: 2x1+3x2-x3+4x4=8
% x1-2x2+6x3-7x4=-3
% \text{ %xi} = 0; i = 1, 2, 3, 4
clc
clear all
format short
% PHASE-1: Input the parameter
c=[2,3,4,7]; %Objective function
A=[2 3 -1 4; -1 2 -6 7]; %Coefficient Matrix
B=[8;3];%RHS of const
objective=1; %1 for max and -1 for minimization problem
%Number of possible solutions: nCm:nchoosek
% PHASE-2: Number of constraint and variable
m=size(A,1); %number of constraints
n=size(A,2); % number of variables
% PHASE-3: Compute the ncm Basic Solutions: The max number of basic
% solutions will always be nCm
nab=nchoosek(n,m); %total number of atmost basic solution
t=nchoosek(1:n,m); %from this we can extract our set of variables that we need to
equate to zero
% PHASE-4:Construct the basic solution
% for this n>m must be satisfied
sol=[]; %default solution is zero (Empty Matrix)
if n>=m %if this is not statisfied then we can not have solutions
    for i=1:nab
    y=zeros(n,1);
    %selecting all rows for a specific column where for t we are taking all
columns for a
    % specific row (which is basically the variables that are equated to zero)
    X=(A(:,t(i,:)))
    %fetching values from A matrix for the rows correspond
    %checking feasibility condition
    if all(X>=0 & X~=inf & X~=-inf)
        y(t(i,:))=X;
        sol=[sol y];
    end
```

```
end
    disp("Solution: ");
    disp(sol);
else
    error('No. of variables is less than number of constraints')
end
if any(X == 0)
        fprintf("DEGENERATE SOLUTION");
else
    fprintf('NON-DEGENERATE SOLUTION\n');
end
%PHASE 5: To find optimal solution
Z=c*sol; %finding the values corresponding to each point
if(objective==1)
    [Zmax,Zindex]=max(Z); %storing the max value of Z and the col in which this max
value resides
else
    [Zmax,Zindex]=min(Z); %storing the min value of Z and the col in which this min
value resides
end
BFS=sol(:,Zindex);%basic feasible solution
[Optimal_Value]=[BFS' Zmax];
Optimal_bfs=array2table(Optimal_Value);
Optimal bfs.Properties.VariableNames(1:size(Optimal bfs,2))={'x1','x2','x3','x4','
Optimal Value of Z'};
disp(Optimal_bfs);
```

#### **Output:**

Solution	1:			
1.00	000	2.4444	0	0
2.00	000	0	2.8125	0
	0	0	0.4375	2.5882
	0	0.7778	0	2.6471
NON-DEGE	NERATE	SOLUTION	I	
x1	x2	<b>x</b> 3	x4	Optimal Value of Z
	_			
0	0	2.5882	2.6471	28.882

#### Question 2

Maximize 
$$Z = -x_1 + 2x_2 - x_3$$
  
s.t.  $x_1 \le 4$ ,  
 $x_2 \le 4$ ,  
 $-x_1 + x_2 \le 6$ ,  
 $-x_1 + 2x_3 \le 4$ ,  
 $x_1, x_2, x_3 \ge 0$ 

```
%% QUESTION 2
% TO OBTAIN BFS USING ALGEBRAIC METHOD
% Question 2
% Max Z = -x1+2x2-x3
% st: x1+s1=4
% x2+s2=4
% -x1+x2+s3=6
% -x1+2x3+s4=4
% x1,x2,x3>=0
clc
clear all
format short
% PHASE-1: Input the parameter
c=[-1,2,-1,0,0,0,0]; %Objective function
A=[1,0,0,1,0,0,0;0,1,0,0,1,0,0;-1,1,0,0,0,1,0;-1,0,2,0,0,0,1]; %Coefficient Matrix
B=[4;4;6;4];%RHS of const
objective=1; %1 for max and -1 for minimization problem
%Number of possible solutions: nCm:nchoosek
% PHASE-2: Number of constraint and variable
m=size(A,1); %number of constraints
n=size(A,2); % number of variables
% PHASE-3: Compute the ncm Basic Solutions: The max number of basic
% solutions will always be nCm
nab=nchoosek(n,m); %total number of atmost basic solution
t=nchoosek(1:n,m); %from this we can extract our set of variables that we need to
equate to zero
% PHASE-4:Construct the basic solution
% for this n>m must be satisfied
sol=[]; %default solution is zero (Empty Matrix)
if n>=m %if this is not statisfied then we can not have solutions
    for i = 1:nab
        y = zeros(n, 1);
        % Check if the selected variables form a singular matrix
        if rank(A(:, t(i, :))) == m
            X = A(:, t(i, :)) \setminus B; % Solve for basic variables
            if all(X >= 0)
                y(t(i, :)) = X;
                sol = [sol y];
            end
        end
    end
    disp("Solution: ");
    disp(sol);
else
    error('No. of variables is less than number of constraints')
end
if any(X == 0)
        fprintf("DEGENERATE SOLUTION");
else
    fprintf('NON-DEGENERATE SOLUTION\n');
end
%PHASE 5: To find optimal solution
Z=c*sol; %finding the values corresponding to each point
if(objective==1)
```

```
[Zmax,Zindex]=max(Z);%storing the max value of Z and the col in which this max
value resides
else
    [Zmax,Zindex]=min(Z);%storing the min value of Z and the col in which this min
value resides
end
BFS=sol(:,Zindex);%basic feasible solution
[Optimal_Value]=[BFS' Zmax];
Optimal_bfs=array2table(Optimal_Value);
Optimal_bfs.Properties.VariableNames(1:size(Optimal_bfs,2))={'x1','x2','x3','s1','
s2','s3','s4','Optimal Value of Z'};
disp(Optimal_bfs);
```

#### **Output:**

Solution	:							
4	4	4	4	0	0	0	0	
4	4	0	0	4	4	0	0	
4	0	4	0	2	0	2	0	
0	0	0	0	4	4	4	4	
0	0	4	4	0	0	4	4	
6	6	10	10	2	2	6	6	
0	8	0	8	0	4	0	4	
NON-DEGENERATE SOLUTION								
x1	<b>x</b> 2	x3	s1	s2	s3	s4	Optimal Value of Z	
_	_	_	_	_	_	_		
0	4	0	4	0	2	4	8	

#### Question 3:

Minimize 
$$Z = 5x_2 - 2x_1$$
  
s.t.  $2x_1 + 5x_2 \le 8$ ,  
 $x_1 + x_2 \le 2$ ,  
 $x_1, x_2 \ge 0$ 

```
%% QUESTION 3
% TO OBTAIN BFS USING ALGEBRAIC METHOD
% Question
% Min Z= 5x2-2x1
% st: 2x1+5x2+s1=8
% x1+x2+s2=2
% %xi>=0
clc
clear all
format short
% PHASE-1: Input the parameter
c=[-2,5,0,0]; %Objective function
A=[2,5,1,0;1,1,0,1]; %Coefficient Matrix
B=[8;2];%RHS of const
objective=-1; %1 for max and -1 for minimization problem
```

```
%Number of possible solutions: nCm:nchoosek
% PHASE-2: Number of constraint and variable
m=size(A,1); %number of constraints
n=size(A,2); % number of variables
% PHASE-3: Compute the ncm Basic Solutions: The max number of basic
% solutions will always be nCm
nab=nchoosek(n,m); %total number of atmost basic solution
t=nchoosek(1:n,m); %from this we can extract our set of variables that we need to
equate to zero
% PHASE-4:Construct the basic solution
% for this n>m must be satisfied
sol=[]; %default solution is zero (Empty Matrix)
if n>=m %if this is not statisfied then we can not have solutions
    for i=1:nab
    y=zeros(n,1);
    %selecting all rows for a specific column where for t we are taking all
columns for a
    % specific row (which is basically the variables that are equated to zero)
    X=(A(:,t(i,:)))\setminus B;
    %fetching values from A matrix for the rows correspond
    %checking feasibility condition
    if all(X>=0 & X~=inf & X~=-inf)
        y(t(i,:))=X;
        sol=[sol y];
    end
    end
    disp("Solution: ");
    disp(sol);
else
    error('No. of variables is less than number of constraints')
end
if any(X == 0)
        fprintf("DEGENERATE SOLUTION\n");
else
    fprintf('NON-DEGENERATE SOLUTION\n');
end
%PHASE 5: To find optimal solution
Z=c*sol; %finding the values corresponding to each point
if(objective==1)
    [Zmax,Zindex]=max(Z); %storing the max value of Z and the col in which this max
value resides
else
    [Zmax,Zindex]=min(Z); %storing the min value of Z and the col in which this min
value resides
end
%Optimal BFS
BFS=sol(:,Zindex);%basic feasible solution
[Optimal_Value]=[BFS' Zmax];
Optimal bfs=array2table(Optimal Value);
Optimal bfs.Properties.VariableNames(1:size(Optimal bfs,2))={'x1','x2','s1','s2','
Optimal Value of Z'};
disp(Optimal_bfs);
```

## **Output:**

Solution	:			
0.66	67	2.0000	0	0
1.33	33	0	1.6000	0
	0	4.0000	0	8.0000
	0	0	0.4000	2.0000
NON-DEGE	NERATE <b>x2</b>	SOLUTI		imal Value of Z
				imal Value of Z

## **Question 4:**

Maximize 
$$Z = x_1 + x_2 + x_3$$
  
s.t.  $x_1 + x_2 \le 1$ ,  
 $-x_2 + x_3 \le 0$ ,  
 $x_1, x_2, x_3 \ge 0$ 

```
%% QUESTION 4
% TO OBTAIN BFS USING ALGEBRAIC METHOD
% Question
% Max Z= x1+x2+x3+0s1+0s2
% st: x1+x2+s1=1
% -x2+x3+s2=0
% xi >= 0
clc
clear all
format short
% PHASE-1: Input the parameter
c=[1,1,1,0,0]; %Objective function
A=[1,1,0,1,0;0,-1,1,0,1]; %Coefficient Matrix
B=[1;0];%RHS of const
objective=1; %1 for max and -1 for minimization problem
%Number of possible solutions: nCm:nchoosek
% PHASE-2: Number of constraint and variable
m=size(A,1); %number of constraints
n=size(A,2); % number of variables
% PHASE-3: Compute the ncm Basic Solutions: The max number of basic
% solutions will always be nCm
nab=nchoosek(n,m); %total number of atmost basic solution
t=nchoosek(1:n,m); %from this we can extract our set of variables that we need to
equate to zero
% PHASE-4:Construct the basic solution
% for this n>m must be satisfied
```

```
sol=[]; %default solution is zero (Empty Matrix)
if n>=m %if this is not statisfied then we can not have solutions
    for i = 1:nab
        y = zeros(n, 1);
        % Check if the selected variables form a singular matrix
        if rank(A(:, t(i, :))) == m
            X = A(:, t(i, :)) \setminus B; % Solve for basic variables
            if all(X >= 0)
                y(t(i, :)) = X;
                sol = [sol y];
            end
        end
    end
    disp("Solution: ");
    disp(sol);
else
    error('No. of variables is less than number of constraints')
end
if any(X == 0)
        fprintf("DEGENERATE SOLUTION\n");
else
    fprintf('NON-DEGENERATE SOLUTION\n');
end
%PHASE 5: To find optimal solution
Z=c*sol; %finding the values corresponding to each point
if(objective==1)
    [Zmax,Zindex]=max(Z); %storing the max value of Z and the col in which this max
value resides
else
    [Zmax,Zindex]=min(Z); %storing the min value of Z and the col in which this min
value resides
end
BFS=sol(:,Zindex);%basic feasible solution
[Optimal_Value]=[BFS' Zmax];
Optimal bfs=array2table(Optimal Value);
Optimal bfs.Properties.VariableNames(1:size(Optimal bfs,2))={'x1','x2','x3','s1','
s2','Optimal Value of Z'};
disp(Optimal bfs);
```

## Output:

Solution	:									
1	1	1	0	0	0	0	0			
0	0	0	1	0	1	0	0			
0	0	0	1	0	0	0	0			
0	0	0	0	1	0	1	1			
0	0	0	0	0	1	0	0			
DEGENERATE SOLUTION										
<b>x1</b>	<b>x</b> 2	<b>x</b> 3	s1	s2	Optimal Value of Z					
_	_	_	_	_						
0	1	1	0	0		2				