ASSIGNMENT 3

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PARTICLE SWARM OPTIMIZATION

Evolutionary Computation - CSCI 547

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ABSTRACT

The assignments implements Particle Swarm Optimization. Using PSO it stimulates behaviour of swarm and is useful in order to optimize numeric problems iteratively. We observe nature and try to learn how biological phenomenon can be implemented in a computer system in order to optimize the problems. In PSO our main focus is how behaviour of group of birds and their interaction with environment

INTRODUCTION

Particle Swarm Optimization:

Particle Swarm intelligence is inspired by a swarm of birds. The overall concept of PSO is on what biological phenomena, the working is based upon.PSO is a population based algorithm Each particles is attracted to some degree to the best location it has so far, found by any member. After some steps, the population can unite around one location, or can join together around a few locations, or can continue to move.Particle Swarm Optimization has some similarities with genetic programming. A collection of individuals called particles moves in steps through a region.At each step, the algorithm evaluates the objective function at each particle After evaluation, the algorithm decides on the new velocity of each particle. The particles move, then the algorithm reevaluates

PSO versus GA

The have common procedure: randomly generate initial population, estimate fitness value, reproduction based on the fitness value. In genetic algorithm we have operators like crossover and mutation whereas, we don't have such operators in particle swarm optimization. Particles in update with internal velocity. They also have memory. Information Sharing in different in PSO when compared with GA. In GA chromosomes share information with each other and the whole group of population moves towards optimum result. Whereas, in PSO only gBest can give information to others. It is a one-way mechanism and it looks for only the best result.

TEST FUNCTION FOR OPTIMIZATION

1 Beale Function

$$f(x,y)=(1.5-x+xy)2+(2.25-x+xy)2+(2.625-x+xy)32$$

2 Three Hump Camel Function

$$f(x,y)=2x^2-1.05x^4+(x^6)/6+xy+y^2$$

PsuedoCode

- \bullet w = inertia
- c1 = x velocity coeff
- c2 = velocity coeff
- $rand_{1,2} = 0_{i} = rand_{i} = 1$

Random allocation algorithm

for each particle in system

fordimensionxandy

initialize positions x—y (p) within the range given

initialize velocity of each particle within permissible range

Fitness value calculation

for each particle

calculate dimension z as fitness value

if fitness value is better than p_best value in history $-\xi$ set current value as pbest

choose the particle having best among the whole group as g_best particle

Update position and calculate velocity

for each particle

for each dimension

calculate velocity according to below

v(k+1)=w.v(k)+c1.rand1.(pbest-x)+c2.rand2.(gbest-x)

update position as x(k+1) = x(k) + v(k+1)

VISUALIZATION

For Visualization I have used gnuplot. Started with downloading gnuplot from https://sourceforge.net/projects/gnuplot/ After it is downloaded and installed start the execution file(wgnuplot.exe).

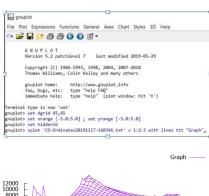
Now type the below code:

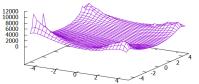
- \bullet set dgrid 45,45
- set xrange [-5.0:5.0]; set yrange [-5.0:5.0]
- \bullet set hidden3d
- splot '¡coordinate file generated by py script¿' u 1:2:3 with lines tit "Graph"

Co-ordinates file will be generated on every run I have done visualization for the following code: Run python script with 10000 elements. with 10 iteration each

VISUALIZATION FOR BEALE FUNC-TION

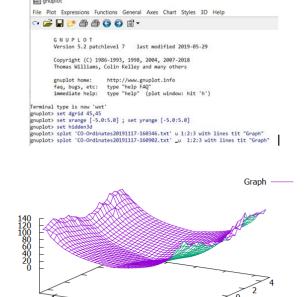
- python PSOTest.py 10000 10 0.5 0.8 0.9 4.5 4.5 -4.5 -4.5
- files are generated in the folder. Co-Ordinate file: CO-Ordinates 20191117-160346





VISUALIZATION

- VISUALIZATION FOR Three Hump Camel FUNCTION
- python PSOTest.py 10000 10 0.5 0.8 0.9 4.5 4.5 -4.5 -4.5
- For second function do following code changes: Comment line no.91 i.e $(mat[2]=(1.5-x+x^*y)^{**2}+(2.25-x+x^*y^{**2})^{**2}+(2.625-x+x^*y^{**3})^{**2}$ (Beale function) and uncomment no. 92 i.e $(mat[2]=2^*(x^{**2})-1.05^*(x^{**4})+(x^{**6.0})/6.0+x^*y+(y^{**2})$ (three hump camel function)
- \bullet CO-Ordinate file : CO-Ordinates 20191117-160902 is generated



visualization for two function is obtained.

Output

when we run this program three files are generated in the folder (AssignPSO) namely AllRunStats,IndividualRun and CO-Ordinates file.

Stats

Statistics of all the runs made is in file AllRunStats.csv



References

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Citation

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- [2] https://sourceforge.net/projects/gnuplot/
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