# CS 2200 Systems and Networking

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Homework 2 - Calling Convention

Due: February  $1^{st}$  2023

# 1 Problem 1: Getting Started with the LC-5500

In this homework, you will be using the LC-5500 ISA to complete a Tower of Hanoi move-counting function. Before you begin, you should familiarize yourself with the available instructions, the register conventions and the calling convention of LC-5500. Details can be found in the section, Appendix A: LC-5500 Instruction Set Architecture, at the end of this document.

The assembly folder contains several tools for you to use:

- assembler.py: a basic assembler that can take your assembly code and convert it into binary instructions for the LC-5500.
- 1c5500.py: the ISA definition file for the assembler, which tells assembler.py the instructions supported by the LC-5500 and their formats.
- lc5500-sim.py: A simulator of the LC-5500 machine. The simulator reads binary instructions and emulates the LC-5500 machine, letting you single-step through instructions and check their results.

To learn how to run these tools, see the README.md file in the assembly directory.

Before you begin work on the second problem of the homework, try writing a simple program for the LC-5500 architecture. This should help you familiarize yourself with the available instructions.

We have provided a template, mod.s, for you to use for this purpose. Try writing a program that performs the mod operation on the two provided arguments. A correct implementation will result in a value of 2.

You can use the following C code snippet as a guide to implement this function:

```
int mod(int a, int b) {
  int x = a;
  while (x >= b) {
    x = x - b;
  }
  return x;
}
```

There is no turn-in for this portion of the assignment, but it is **recommended** that you attempt it in order to familiarize yourself with the ISA.

## 2 Problem 2: Tower of Hanoi

For this problem, you will be implementing the missing portions of the program that calculates the minimum number of moves to solve the Tower of Hanoi problem for n disks.

Tower of Hanoi involves three vertical rods and a set of varying sized disks, which can slide onto any rod. The disks are initially stacked on one of the rods in ascending order of size, with the largest disk on the bottom and the smallest on top, thus making a conical shape. The objective of this puzzle is to migrate the tower of disks completely to another rod, under the rule that only individual disks may be moved at once, and no disks may be placed on smaller disks.

You will be finishing a **recursive** implementation of the Tower of Hanoi minimal moves calculator program that follows the LC-5500 calling convention. Recursive functions always obtain a return address through the function call and return to the callee using the return address.

You must use the stack pointer (\$sp) and frame pointer (\$fp) registers as described in the textbook and lecture slides. Use the PUSH and POP instructions to manipulate the stack.

Here is the C code for the Tower of Hanoi minimal moves calculator you have been provided:

```
int minimumHanoi(int n) {
  if (n == 1)
    return 1;
  else
    return (2 * minimumHanoi(n - 1)) + 1;
}
```

Note that this C code is just to help your understanding and does not need to be exactly followed. However, your assembly code implementation should meet all of the given conditions in the description.

Open hanoi.s file in the assembly directory. This file contains an implementation of the Tower of Hanoi minimal moves calculator program that is missing significant portions of the calling convention. Near the bottom of the hanoi.s we have provided multiple numbers that you can use to test your homework. They are located at labels testNumDisks1, testNumDisks2, testNumDisks3. Be sure to use these provided integers by loading them from the labels into registers. None of the numbers provided and tested will be lower than 1.

Complete the program by implementing the various missing portions of the LC-5500 calling convention. Each location where you need to implement a portion of the calling convention is marked with a TODO label as well as a short hint describing the portion of the calling convention you should be implementing.

Please note that we will be testing your implementation for multiple different instances, so please do not attempt to hardcode your solutions.

#### 3 Problem 3: Short Answer

Please answer the following question in the file named answers.txt:

1. The LC-5500 instruction set contains an instruction called jalr that is used to jump to a location while saving a return address. However, this functionality could be emulated using a combination of other instructions available in the ISA. Describe a sequence of other instructions in the LC-5500 ISA that you may use to accomplish the functionality of jalr.

For the purpose of this question, you may assume the target address is represented with the label <target> which can be accessed using the 20 bits reserved for an offset or immediate value in the LC-5500 ISA.

# 4 Deliverables

- hanoi.s: your assembly code from Section 2
- answers.txt: your answer to the problem from Section 3

Submit these files to **Gradescope** before the assignment deadline.

The TAs should be able to type python assembler.py -i 1c5500 --sym hanoi.s and then python 1c5500-sim.py hanoi.bin to run your code. If you cannot do this with your submission, then you have done something wrong.

#### Appendix A: LC-5500 Instruction Set Architecture 5

The LC-5500 is a simple, yet capable computer architecture. The LC-5500 combines attributes of both ARM and the LC-2200 ISA defined in the Ramachandran & Leahy textbook for CS 2200.

The LC-5500 is a word-addressable, 32-bit computer. All addresses refer to words, i.e. the first word (four bytes) in memory occupies address 0x0, the second word, 0x1, etc.

All memory addresses are truncated to 16 bits on access, discarding the 16 most significant bits if the address was stored in a 32-bit register. This provides roughly 64 KB of addressable memory.

#### 5.1 Registers

The LC-5500 has 16 general-purpose registers. While there are no hardware-enforced restraints on the uses of these registers, your code is expected to follow the conventions outlined below.

> Callee Save? Register Number Name Use 0 \$zero Always Zero NA 1 \$at Assembler/Target Address NA 2 \$v0 Return Value No 3 \$a0 Argument 1 No 4 \$a1 Argument 2 No 5 \$a2 Argument 3 No 6 \$t0 Temporary Variable No 7 \$t1 Temporary Variable No 8 \$t2 Temporary Variable No Saved Register 9 \$s0Yes 10 \$s1Saved Register Yes 11 s2Saved Register Yes \$k0 Reserved for OS and Traps 12 NA Stack Pointer No 13 \$sp 14 \$fp Frame Pointer Yes 15 \$ra Return Address No

Table 1: Registers and their Uses

- 1. Register 0 is always read as zero. Any values written to it are discarded. Note: for the purposes of this project, you must implement the zero register. Regardless of what is written to this register, it should always output zero.
- 2. Register 1 is used to hold the target address of a jump. It may also be used by pseudo-instructions generated by the assembler.
- 3. **Register 2** is where you should store any returned value from a subroutine call.
- 4. Registers 3 5 are used to store function/subroutine arguments. Note: registers 2 through 8 should be placed on the stack if the caller wants to retain those values. These registers are fair game for the callee (subroutine) to trash.
- 5. Registers 6 8 are designated for temporary variables. The caller must save these registers if they want these values to be retained.
- 6. Registers 9 11 are saved registers. The caller may assume that these registers are never tampered with by the subroutine. If the subroutine needs these registers, then it should place them on the stack and restore them before they jump back to the caller.
- 7. Register 12 is reserved for handling interrupts. While it should be implemented, it otherwise will not have any special use on this assignment.

- 8. **Register 13** is the everchanging top of the stack stack; it keeps track of the top of the activation record for a subroutine.
- 9. **Register 14** is the anchor point of the activation frame. It is used to point to the first address on the activation record for the currently executing process.
- 10. Register 15 is used to store the address a subroutine should return to when it is finished executing.

#### 5.2 Instruction Overview

The LC-5500 supports a variety of instruction forms, only a few of which we will use for this project. The instructions we will implement in this project are summarized below.

Table 2: LC-5500 Instruction Set

	$31\ 30\ 29\ 28\ 27\ 26\ 25\ 24\ 23\ 22\ 21\ 20\ 19\ 18\ 17\ 16\ 15\ 14\ 13\ 12\ 11\ 10\ 9\ 8\ 7\ 6\ 5\ 4\ 3\ 2\ 1\ 0$					
ADD	0000	DR	SR1	unused	SR2	
NAND	0001	DR	SR1	unused	SR2	
ADDI	0010	DR	SR	immval20		
LW	0011	DR	BaseR	offset20		
SW	0100	SR	BaseR	offset20		
BR	0101	unu	ısed	offset20		
JALR	0110	RA	AT	unused		
HALT	0111			unused		
BLT	1000	SR1	SR2	PCoffset20		
LEA	1001	DR	unused	PCoffset20		
PUSH	1010	SR	\$SP	offset20 (-1)		
POP	1011	DR	\$SP	offset $20 (+1)$		

#### 5.3 Detailed Instruction Reference

#### 5.3.1 ADD

#### **Assembler Syntax**

ADD DR, SR1, SR2

#### **Encoding**

31 30 29 28	27 26 25 24	23 22 21 20	19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4	3	2 1	0
0000	DR	SR1	unused		SR:	2

#### Operation

DR = SR1 + SR2;

#### Description

The ADD instruction obtains the first source operand from the SR1 register. The second source operand is obtained from the SR2 register. The second operand is added to the first source operand, and the result is stored in DR.

#### 5.3.2 NAND

#### **Assembler Syntax**

NAND DR, SR1, SR2

#### **Encoding**

31 30 29 28	27 26 25 24	$23\ 22\ 21\ 20$	19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4	3 2	1 (	C
0001	DR	SR1	unused	S	R2	

#### Operation

DR = (SR1 & SR2);

#### Description

The NAND instruction performs a logical NAND (AND NOT) on the source operands obtained from SR1 and SR2. The result is stored in DR.

**HINT:** A logical NOT can be achieved by performing a NAND with both source operands the same. For instance,

NAND DR, SR1, SR1

...achieves the following logical operation:  $DR \leftarrow \overline{SR1}$ .

#### 5.3.3 ADDI

#### **Assembler Syntax**

ADDI DR, SR, immval20

#### Encoding

31 30 29 28	27 26 25 24	23 22 21 20	19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
0010	DR	SR	immval20

#### Operation

```
DR = SR + SEXT(immval20);
```

#### Description

The ADDI instruction obtains the first source operand from the SR register. The second source operand is obtained by sign-extending the immval20 field to 32 bits. The resulting operand is added to the first source operand, and the result is stored in DR.

#### 5.3.4 LW

#### Assembler Syntax

LW DR, offset20(BaseR)

#### Encoding

31 30 29 28	27 26 25 24	23 22 21 20	19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0	
0011	DR	BaseR	offset20	

#### Operation

```
DR = MEM[BaseR + SEXT(offset20)];
```

#### Description

An address is computed by sign-extending bits [19:0] to 32 bits and then adding this result to the contents of the register specified by bits [23:20]. The 32-bit word at this address is loaded into DR.

#### 5.3.5 SW

#### Assembler Syntax

SW SR, offset20(BaseR)

#### Encoding

31 30 29 28	27 26 25 24	23 22 21 20	19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1	0
0100	$\operatorname{SR}$	BaseR	offset20	

#### Operation

MEM[BaseR + SEXT(offset20)] = SR;

#### Description

An address is computed by sign-extending bits [19:0] to 32 bits and then adding this result to the contents of the register specified by bits [23:20]. The 32-bit word obtained from register SR is then stored at this address.

#### 5.3.6 BR

#### **Assembler Syntax**

BR offset20

#### **Encoding**

31 30 29 28	27 26 25 24 23 22 21 20	19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0	
0101	unused	offset20	

#### Operation

PC = incrementedPC + offset20

#### Description

A branch is unconditionally taken. The PC will be set to the sum of the incremented PC (since we have already undergone fetch) and the sign-extended offset[19:0].

#### 5.3.7 JALR

#### **Assembler Syntax**

JALR RA, AT

#### **Encoding**

31 30	29 28	27 26 25 2	4 23 22 21 20	19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
01	10	RA	AT	unused

#### Operation

```
RA = PC;
PC = AT;
```

#### Description

First, the incremented PC (address of the instruction + 1) is stored into register RA. Next, the PC is loaded with the value of register AT, and the computer resumes execution at the new PC.

#### 5.3.8 HALT

#### Assembler Syntax

HALT

#### **Encoding**

#### Description

The machine is brought to a halt and executes no further instructions.

#### 5.3.9 BLT

#### Assembler Syntax

```
BLT SR1, SR2
```

## **Encoding**

```
31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

1000 SR1 SR2 PCoffset 20
```

#### Operation

```
if (SR1 < SR2) {
    PC = incrementedPC + SEXT(PCoffset20)
}</pre>
```

### Description

This is a conditional branch that will be taken only if the value of the register SR1 is less that then value of the SR2 register. The PC will be set to the sum of the incremented PC (since we have already undergone fetch) and the sign-extended offset [19:0].

#### 5.3.10 LEA

#### **Assembler Syntax**

LEA DR, label

#### **Encoding**

31 30 29 28	27 26 25 24	23 22 21 20	19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
1001	DR	unused	PCoffset20

#### Operation

```
DR = PC + SEXT(PCoffset20);
```

#### Description

An address is computed by sign-extending bits [19:0] to 32 bits and adding this result to the incremented PC (address of instruction + 1). It then stores the computed address into register DR.

#### 5.3.11 PUSH

#### Assembler Syntax

PUSH SR

#### **Encoding**

$31\ 30\ 29\ 28$	$27\ 26\ 25\ 24$	$23\ 22\ 21\ 20$	$19\ 18\ 17\ 16\ 15\ 14\ 13\ 12\ 11\ 10\ 9\ 8\ 7\ 6\ 5\ 4\ 3\ 2\ 1\ 0$
1010	$\operatorname{SR}$	\$SP	offset20 (-1)

## Operation

```
X = SR

SP = SP - 1

MEM[SP] = X
```

### Description

Decrements the stack pointer and stores the value of the source register SR at the memory location of the stack pointer. Note: the operation of the decrement must happen before the store in order to ensure that the stack pointer always points to the top of the stack, but be sure to take special care when pushing the stack pointer itself.

#### 5.3.12 POP

#### **Assembler Syntax**

POP DR

#### Encoding

31 30 29 28	27 26 25 24	23 22 21 20	19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
1010	DR	\$SP	offset $20 (+1)$

#### Operation

#### Description

Loads the value from memory pointed to by the stack pointer into DR and increments the value of the stack pointer. Note: the operation of the increment must happen after the load in order to ensure that the stack pointer always points to the top of the stack.