

Class	Responsibilities	Collaborators
Wizard	Drives Robot to the exit using MazeController.getNeighborCloserToExit() Method.	MazeController BasicRobot
WallFollower	Drives Robot to the exit using WallFollower algorithm, following the left wall.	MazeController BasicRobot
Pledge	Drives Robot to the exit using the Pledge algorithm.	MazeController BasicRobot
Explorer	Drives Robot to the exit using the Explorer algorithm.	MazeController BasicRobot