

Exp No:1

8 bit arithmetic operations

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Date: 12/07/2021

AIM:

To perform 8 bit operations – addition, subtraction, multiplication, division

PROCEDURE FOR EXECUTING MASM:

1. Open DosBox, mount masm to d drive

```
Z:\>mount D D:/masm
Drive D is mounted as local directory D:/masm\
```

2. Navigate to d drive

```
Z:\>d:
```

3. Assemble code

```
D:\>masm 8BITADD.ASM
Microsoft (R) MASM Compatibility Driver
Copyright (C) Microsoft Corp 1993. All rights reserved.

Invoking: ML.EXE /I. /Zm /c /Ta 8BITADD.ASM

Microsoft (R) Macro Assembler Version 6.11
Copyright (C) Microsoft Corp 1981-1993. All rights reserved.

Assembling: 8BITADD.ASM
```

4. Link the object file to create .exe file(executable)

```
D:\>link 8BITADD.OBJ

Microsoft Object Linker V2.01 (Large)
(C) Copyright 1982, 1983 by Microsoft Inc.

Run File [8BITADD.EXE]:
List File [NUL.MAP]:
Libraries [.LIB]:
Warning: No STACK segment

There was 1 error detected.
```

5. Run the .exe file using debug mode

6. Use commands like

- a) -u (to view unassembled code)
 - b) -d segment:offset to display values of variables in memory
 - c) -e segment:offset to change values of variable
 - d) -g to execute code
7. -q to quit from debug mode
 8. Exit to quit dosbox

ALGORITHM:

Addition:

- a. Declare variables – 2 operands a and b, res(to store result), carry in data segment
- b. Move first operand to ah (half word accumulator) and second operand to bh
- c. Use add ah,bh to store the result in ah
- d. Store 1 in ch if carry exists, else branch to e (using branch)
- e. Move the contents from ah to res, and ch to carry
- f. Terminate the program

Subtraction:

- a. Declare variables – 2 operands a and b, res(to store result), carry in the data segment
- b. Move first operand to ah (half word accumulator) and second to bh
- c. Use sub ah,bh to store result in accumulator
- d. If there is a carry, store 1 in ch and perform neg ah (to obtain 2s complement). Else branch to e
- e. Move result from ah to res and ch to carry

Multiplication:

- a. Declare variables – 2 operands a and b, result (16 bit) in the data segment
- b. Move first operand to al and second to bl (16 bit accumulators)
- c. Use mul bl to perform multiplication and store result in ax accumulator
- d. Move result from ax to result

Division:

- a. Declare the variables – 2 operands a and b, res(to store result), remainder in data segment
- b. Move first operand a to al and second operand to bl. Initialize ah to 0

- c. Use div bl to store the result in al. (ax/bl is performed)
- d. Remainder is stored in ah
- e. Move contents of al to result, and ah to remainder

PROGRAM

Addition:

<u>PROGRAM</u>	<u>COMMENTS</u>
assume cs:code,ds:data	Declare code segment as code, data segment as data
data segment	Begin data segment
a db 11h	Initialize a to 11
b db 99h	Initialize b to 99
res db 00H	Initialize res to 0
carry db 00H	Initialize carry to 0
data ends	Data segment ends
code segment	Begin code segment
org 0100h	Set origin as 100
start: mov ax,data	Move contents from data to ax
mov ds,ax	Move contents from ax to ds
mov ah,a	Move a to ah
mov bh,b	Move b to bh
mov ch,00h	Initialize ch(to store carry) to 0
add ah,bh	Add ah+bh and store in ah
jnc here	If no carry, jump to label here
inc ch	Else, Increment carry
here: mov res,ah	Move contents from ah to res
mov carry,ch	Move contents from ch to carry
mov ah,4ch	Move 4ch to ah
int 21h	This step generates an interrupt for terminating the program
code ends	Code segment ends
end start	End of start

Subtraction:

<u>PROGRAM</u>	<u>COMMENTS</u>
assume cs:code,ds:data	Declare code segment as code, data segment as data
data segment	Begin data segment
a db 11h	Initialize a to 11
b db 99h	Initialize b to 99
res db 00H	Initialize res to 0
carry db 00H	Initialize carry to 0
data ends	Data segment ends
code segment	Begin code segment
org 0100h	Set origin as 100
start: mov ax,data	Move contents from data to ax
mov ds,ax	Move contents from ax to ds
mov ah,a	Move a to ah
mov bh,b	Move b to bh
mov ch,00h	Initialize ch(to store carry) to 0
sub ah,bh	Perform ah-bh and store in ah
jnc here	If no carry, jump to label here
inc ch	Else, Increment carry
neg ah	Find twos complement of ah
here: mov res,ah	Move contents from ah to res
mov carry,ch	Move carry from ch to carry
mov ah,4ch	Move 4ch to ah
int 21h	This step generates an interrupt for terminating the program
code ends	Code segment ends
end start	End of start

Multiplication:

<u>PROGRAM</u>	<u>COMMENTS</u>
assume cs:code,ds:data	Declare code segment as code, data segment as data
data segment	Begin data segment
a db 11h	Initialize a to 11
b db 99h	Initialize b to 99
res db 00H	Initialize res to 0
data ends	Data segment ends
code segment	Begin code segment
org 0100h	Set origin as 100
start: mov ax,data	Move contents from data to ax
mov ds,ax	Move contents from ax to ds

mov al,a	Move a to al
mov bl,b	Move b to bl
mov ch,00h	Initialize carry to 0
mul bl	Perform ax*bl and store in ax
here: mov res,ax	Move contents from ax to res
mov ah,4ch	Move 4ch to ah
int 21h	This step generates an interrupt for terminating the program
code ends	Code segment ends
end start	End of start

Addition:

PROGRAM	COMMENTS
assume cs:code,ds:data	Declare code segment as code, data segment as data
data segment	Begin data segment
a db 11h	Initialize a to 11
b db 99h	Initialize b to 99
res db 00H	Initialize res to 0
data ends	Data segment ends
code segment	Begin code segment
org 0100h	Set origin as 100
start: mov ax,data	Move contents from data to ax
mov ds,ax	Move contents from ax to ds
mov ah,00h	Initialize ah to 0
mov al,a	Move a to al
mov bl,b	Move b to bl
div bl	Perform al/bl and store quotient in al
here: mov res,al	Move contents from al to res
mov remainder,ah	Move carry from ah to remainder
mov ah,4ch	Move 4ch to ah
int 21h	This step generates an interrupt for terminating the program
code ends	Code segment ends
end start	End of start

OUTPUT SCREENSHOTS

1) Addition

```
D:\EX1>masm 8bitadd.asm
Microsoft (R) MASM Compatibility Driver
Copyright (C) Microsoft Corp 1993. All rights reserved.

Invoking: ML.EXE /I. /Zm /c /Ta 8bitadd.asm

Microsoft (R) Macro Assembler Version 6.11
Copyright (C) Microsoft Corp 1981-1993. All rights reserved.

Assembling: 8bitadd.asm

D:\EX1>link 8bitadd.obj

Microsoft Object Linker V2.01 (Large)
(C) Copyright 1982, 1983 by Microsoft Inc.

Run File [8BITADD.EXE]:
List File [NUL.MAP]:
Libraries [.LIB]:
Warning: No STACK segment

There was 1 error detected.
```

```
D:\>EX1>debug 8bitadd.exe
-u
076B:0100 B86A07      MOV     AX,076A
076B:0103 8ED8        MOV     DS,AX
076B:0105 8A260000    MOV     AH,[0000]
076B:0109 8A3E0100    MOV     BH,[0001]
076B:010D B500        MOV     CH,00
076B:010F 02E7        ADD     AH,BH
076B:0111 7302        JNB    0115
076B:0113 FEC5        INC     CH
076B:0115 88260200    MOV     [0002],AH
076B:0119 882E0300    MOV     [0003],CH
076B:011D B44C        MOV     AH,4C
076B:011F CD21        INT     21
-d 076A:0000
076A:0000 11 99 00 00 00 00 00 00-00 00 00 00 00 00 00 00 . .
076A:0010 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 . .
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 . .
076A:0030 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 . .
076A:0040 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 . .
076A:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 . .
076A:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 . .
076A:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 . .
```

```

-D 076A:0000
076A:0000 11 99 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0010 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0030 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0040 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
-E 076A:0000
076A:0000 11.23 99.47

-G

Program terminated normally
-D 076A:0000
076A:0000 23 47 6A 00 00 00 00 00-00 00 00 00 00 00 00 00 #Gj...
076A:0010 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0030 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0040 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00

```

2) Subtraction

```

D:\EX1>masm 8bitsub.asm
Microsoft (R) MASM Compatibility Driver
Copyright (C) Microsoft Corp 1993. All rights reserved.

Invoking: ML.EXE /I. /Zm /c /Ta 8bitsub.asm

Microsoft (R) Macro Assembler Version 6.11
Copyright (C) Microsoft Corp 1981-1993. All rights reserved.

Assembling: 8bitsub.asm

D:\EX1>link 8bitsub.obj

Microsoft Object Linker V2.01 (Large)
(C) Copyright 1982, 1983 by Microsoft Inc.

Run File [8BITSUB.EXE]:
List File [NUL.MAP]:
Libraries [.LIB]:
Warning: No STACK segment

There was 1 error detected.

```

```
D:\EX1>debug 8bitsub.exe
-U
076B:0100 B86A07      MOV     AX,076A
076B:0103 8ED8        MOV     DS,AX
076B:0105 8A260000    MOV     AH,[0000]
076B:0109 8A3E0100    MOV     BH,[0001]
076B:010D B500        MOV     CH,00
076B:010F ZAE7        SUB    AH,BH
076B:0111 7304        JNB    0117
076B:0113 FEC5        INC    CH
076B:0115 F6DC        NEG    AH
076B:0117 88260200    MOV    [0002],AH
076B:011B 882E0300    MOV    [0003],CH
076B:011F B44C        MOV    AH,4C
```

```
-e 076A:0000
076A:0000 11.45 99.29
```

```
-G
```

Program terminated normally

```
-d 076A:0000
```

```
076A:0000 45 29 1C 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 E).....
076A:0010 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0030 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0040 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
```

3) Multiplication

```
D:\EX1>masm 8bitmul.asm
Microsoft (R) MASM Compatibility Driver
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Invoking: ML.EXE /I. /Zm /c /Ta 8bitmul.asm
Microsoft (R) Macro Assembler Version 6.11
Copyright (C) Microsoft Corp 1981-1993. All rights reserved.

Assembling: 8bitmul.asm

D:\EX1>link 8bitmul.obj

Microsoft Object Linker V2.01 (Large)
(C) Copyright 1982, 1983 by Microsoft Inc.

Run File [8BITMUL.EXE]:
List File [NUL.MAP]:
Libraries [.LIB]:
Warning: No STACK segment

There was 1 error detected.
```

```
D:\EX1>debug 8bitmul.exe
-u
076B:0100 B86A07      MOV     AX,076A
076B:0103 8ED8      MOV     DS,AX
076B:0105 A00000      MOV     AL,[00000]
076B:0108 8A1E0100      MOV     BL,[00001]
076B:010C F6E3      MUL     BL
076B:010E A30200      MOV     [00002],AX
076B:0111 B44C      MOV     AH,4C
076B:0113 CD21      INT     21
076B:0115 0000      ADD     [BX+SI1],AL
076B:0117 8C7EFDD0      CMP     BYTE PTR [BP-031],00
076B:011B B0FF      MOV     AL,FF
076B:011D 7701      JA      0120
076B:011F 40      INC     AX
-d 076a:0000
076A:0000 11 99 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0010 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0030 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0040 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
-S
```

```
-e 076a:0000
076A:0000 11.34 99.56

-g

Program terminated normally
-d 076a:0000
076A:0000 34 56 78 11 00 00 00 00-00 00 00 00 00 00 00 00 4Ux.
076A:0010 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .
076A:0030 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .
076A:0040 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .
076A:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .
076A:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .
076A:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .

-ss
```

4) Division

```
D:\EX1>masm 8bitdiv.asm
Microsoft (R) MASM Compatibility Driver
Copyright (C) Microsoft Corp 1993. All rights reserved.

Invoking: ML.EXE /I. /Zm /c /Ta 8bitdiv.asm

Microsoft (R) Macro Assembler Version 6.11
Copyright (C) Microsoft Corp 1981-1993. All rights reserved.

Assembling: 8bitdiv.asm

D:\EX1>link 8bitdiv.obj

Microsoft Object Linker V2.01 (Large)
(C) Copyright 1982, 1983 by Microsoft Inc.

Run File [8BITDIV.EXE]:
List File [NUL.MAP]:
Libraries [.LIB]:
Warning: No STACK segment
```

```

D:\EX1>debug 8bitdiv.exe
-u
076B:0100 B86A07      MOV     AX,076A
076B:0103 8ED8        MOV     DS,AX
076B:0105 B400        MOV     AH,00
076B:0107 A00000      MOV     AL,[00000]
076B:010A 8A1E0100    MOV     BL,[0001]
076B:010E F6F3        DIV     BL
076B:0110 A20200      MOV     [0002],AL
076B:0113 88260300    MOV     [0003],AH
076B:0117 B44C        MOV     AH,4C
076B:0119 CD21        INT     Z1
076B:011B B0FF        MOV     AL,FF
076B:011D 7701        JA     0120
076B:011F 40          INC     AX
                                     . . .
-E 076A:0000
076A:0000 11.34 99.3

-G

Program terminated normally
-D 076A:0000
076A:0000 34 03 11 01 00 00 00 00-00 00 00 00 00 00 00 00 4. .....
076A:0010 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 ..... .
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 ..... .
076A:0030 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 ..... .
076A:0040 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 ..... .
076A:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 ..... .
076A:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 ..... .
076A:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 ..... .
-S

```

Result:

The arithmetic operations have been performed and executed correctly using masm

Exp No:2

16 bit arithmetic operations

Name: Shreya Sriram
Register Number: 195001106
Date: 19/07/2021

AIM:

To perform 16 bit operations – addition, subtraction, multiplication, division

ALGORITHM:

Addition:

- a. Declare variables – 2 operands a and b, res(to store result), carry in data segment
- b. Move first operand to ax(word accumulator) and second operand to bx
- c. Use add ax,bx to store the result in ax
- d. Store 1 in ch if carry exists, else branch to e (using branch)
- e. Move the contents from ax to res, and ch to carry
- f. Terminate the program

Subtraction:

- a. Declare variables – 2 operands a and b, res(to store result), carry in the data segment
- b. Move first operand to ax(word accumulator) and second to bx
- c. Use sub ax,bx to store result in accumulator
- d. If there is a carry, store 1 in ch and perform neg ax (to obtain 2s complement). Else branch to e
- e. Move result from ax to res and ch to carry

Multiplication:

- a. Declare variables – 2 operands a and b, res1,res2 (16 bit) in the data segment
- b. Move first operand to ax and second to bx
- c. Use mul bx to perform multiplication and store result in dxax accumulator
- d. Move result from dxax to result

Division:

- a. Declare the variables – 2 operands a and b, res1,res2(to store result), remainder in data segment
- b. Move first operand a to ax and second operand to bx. Initialize ah to 0

- c. Use div bx to store the result in dxax. (dxax/bx is performed)
- d. Remainder is stored in ah
- e. Move contents of ax to res1 and bx to res2, and ah to remainder

PROGRAM

Addition:

<u>PROGRAM</u>	<u>COMMENTS</u>
assume cs:code,ds:data	Declare code segment as code, data segment as data
data segment	Begin data segment
a dw 0011h	Initialize a to 0011
b dw 0099h	Initialize b to 0099
res dw 0000H	Initialize res to 0000
carry db 00H	Initialize carry to 0
data ends	Data segment ends
code segment	Begin code segment
org 0100h	Set origin as 100
start: mov ax,data	Move contents from data to ax
mov ds,ax	Move contents from ax to ds
mov ax,a	Move a to ax
mov bx,b	Move b to bx
mov ch,00h	Initialize ch(to store carry) to 0
add ax,bx	Add ax+bx and store in ax
jnc here	If no carry, jump to label here
inc ch	Else, Increment carry
here: mov res,ax	Move contents from ax to res
mov carry,ch	Move contents from ch to carry
mov ah,4ch	Move 4ch to ah
int 21h	This step generates an interrupt for terminating the program
code ends	Code segment ends
end start	End of start

Subtraction:

<u>PROGRAM</u>	<u>COMMENTS</u>
assume cs:code,ds:data	Declare code segment as code, data segment as data
data segment	Begin data segment
a dw 0011h	Initialize a to 0011
b dw 0099h	Initialize b to 0099
res dw 0000H	Initialize res to 0000h
carry db 00H	Initialize carry to 0
data ends	Data segment ends
code segment	Begin code segment
org 0100h	Set origin as 100
start: mov ax,data	Move contents from data to ax
mov ds,ax	Move contents from ax to ds
mov ax,a	Move a to ax
mov bx,b	Move b to bx
mov ch,00h	Initialize ch(to store carry) to 0
sub ax,bx	Perform ax-bx and store in ax
jnc here	If no carry, jump to label here
inc ch	Else, Increment carry
neg ax	Find twos complement of ax
here: mov res,ax	Move contents from ax to res
mov carry,ch	Move carry from ch to carry
mov ah,4ch	Move 4ch to ah
int 21h	This step generates an interrupt for terminating the program
code ends	Code segment ends
end start	End of start

Multiplication:

<u>PROGRAM</u>	<u>COMMENTS</u>
assume cs:code,ds:data	Declare code segment as code, data segment as data
data segment	Begin data segment
a dw 0011h	Initialize a to 11
b dw 0099h	Initialize b to 99
res1 db 00H	Initialize res1 to 0(to store last 16bits)
res2 db 00H	Initialize res2 to 0(to store first 16bits)
data ends	Data segment ends
code segment	Begin code segment

org 0100h	Set origin as 100
start: mov ax,data	Move contents from data to ax
mov ds,ax	Move contents from ax to ds
mov ax,a	Move a to ax
mov bx,b	Move b to bx
mov ch,00h	Initialize carry to 0
mul bx	Perform ax*bx and store in dxax
here: mov res1,ax	Move contents from ax to res1
mov res2,dx	Move contents from dx to res2
mov ah,4ch	Move 4ch to ah
int 21h	This step generates an interrupt for terminating the program
code ends	Code segment ends
end start	End of start

Division

<u>PROGRAM</u>	<u>COMMENTS</u>
assume cs:code,ds:data	Declare code segment as code, data segment as data
data segment	Begin data segment
a dw 0011h	Initialize a to 0011
b dw 0099h	Initialize b to 0099
res1 dw 0000H	Initialize res1 to 0
res2 dw 0000H	Initialize res2 to 0
remainder db 00H	Initialize remainder to 0
data ends	Data segment ends
code segment	Begin code segment
org 0100h	Set origin as 100
start: mov ax,data	Move contents from data to ax
mov ds,ax	Move contents from ax to ds
mov ah,00h	Initialize ah to 0
mov ax,a	Move a to ax
mov bx,b	Move b to bx
div bx	Perform ax/bx and store quotient in ax
here: mov res1,ax	Move contents from ax to res1
mov res2,bx	Move contents of bx to res2
mov remainder,ah	Move carry from ah to remainder
mov ah,4ch	Move 4ch to ah
int 21h	This step generates an interrupt for terminating the program
code ends	Code segment ends
end start	End of start

OUTPUT SCREENSHOTS

1) Addition

```
D:\EX2>masm 16bitadd.asm
Microsoft (R) MASM Compatibility Driver
Copyright (C) Microsoft Corp 1993. All rights reserved.

Invoking: ML.EXE /I. /Zm /c /Ta 16bitadd.asm

Microsoft (R) Macro Assembler Version 6.11
Copyright (C) Microsoft Corp 1981-1993. All rights reserved.

Assembling: 16bitadd.asm

D:\EX2>link 16bitadd.obj

Microsoft Object Linker V2.01 (Large)
(C) Copyright 1982, 1983 by Microsoft Inc.

Run File [16BITADD.EXE]:
List File [NUL.MAP]:
Libraries [.LIB]:
Warning: No STACK segment

There was 1 error detected.
```

```
D:\EX2>debug 16bitadd.exe
-u
076B:0100 B86A07      MOV     AX,076A
076B:0103 8ED8      MOV     DS,AX
076B:0105 A10000      MOV     AX,[0000]
076B:0108 8B1E0200      MOV     BX,[0002]
076B:010C B500      MOV     CH,00
076B:010E 03C3      ADD     AX,BX
076B:0110 7302      JNB    0114
076B:0112 FEC5      INC     CH
076B:0114 A30400      MOV     [0004],AX
076B:0117 882E0600      MOV     [0006],CH
076B:011B B84C00      MOV     AX,004C
076B:011E CD21      INT    21
-d 076a:0000
076A:0000 11 00 99 00 00 00 00 00-00 00 00 00 00 00 00 00 . . .
076A:0010 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 . . .
076A:0020 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 . . .
076A:0030 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 . . .
076A:0040 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 . . .
076A:0050 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 . . .
076A:0060 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 . . .
076A:0070 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 . . .
.
```

```
-u
076A:0020 0000      ADD     [BX+SI],AL
076A:0022 0000      ADD     [BX+SI],AL
076A:0024 0000      ADD     [BX+SI],AL
076A:0026 0000      ADD     [BX+SI],AL
076A:0028 0000      ADD     [BX+SI],AL
076A:002A 0000      ADD     [BX+SI],AL
076A:002C 0000      ADD     [BX+SI],AL
076A:002E 0000      ADD     [BX+SI],AL
076A:0030 0000      ADD     [BX+SI],AL
076A:0032 0000      ADD     [BX+SI],AL
076A:0034 0000      ADD     [BX+SI],AL
076A:0036 0000      ADD     [BX+SI],AL
076A:0038 0000      ADD     [BX+SI],AL
076A:003A 0000      ADD     [BX+SI],AL
076A:003C 0000      ADD     [BX+SI],AL
076A:003E 0000      ADD     [BX+SI],AL
```

```

-d 076a:0000
076A:0000 11 00 99 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0010 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0030 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0040 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
-e 076a:0000
076A:0000 11.BA 00.AA 99.AC 00.00

-g

Program terminated normally
-d 076a:0000
076A:0000 BA AA AC 00 66 AB 00 00-00 00 00 00 00 00 00 00
076A:0010 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0030 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0040 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
.....f.....

```

2) Subtraction

```

D:\EX2>masm 16bitsub.asm
Microsoft (R) MASM Compatibility Driver
Copyright (C) Microsoft Corp 1993. All rights reserved.

Invoking: ML.EXE /I. /Zm /c /Ta 16bitsub.asm

Microsoft (R) Macro Assembler Version 6.11
Copyright (C) Microsoft Corp 1981-1993. All rights reserved.

Assembling: 16bitsub.asm

D:\EX2>link 16bitsub.obj

Microsoft Object Linker V2.01 (Large)
(C) Copyright 1982, 1983 by Microsoft Inc.

Run File [16BITSUB.EXE]:
List File [NUL.MAP]:
Libraries [.LIB]:
Warning: No STACK segment

There was 1 error detected.

```

```

D:\EX2>debug 16bitsub.exe
-u
076B:0100 B86A07      MOV    AX,076A
076B:0103 8ED8      MOV    DS,AX
076B:0105 A10000      MOV    AX,[0000]
076B:0108 8B1E0200      MOV    BX,[0002]
076B:010C B500      MOV    CH,00
076B:010E 2BC3      SUB    AX,BX
076B:0110 7304      JNB    0116
076B:0112 FEC5      INC    CH
076B:0114 F7D8      NEG    AX
076B:0116 A30400      MOV    [0004],AX
076B:0119 882E0600      MOV    [0006],CH
076B:011D B44C      MOV    AH,4C
076B:011F CD21      INT    21
-d 076a:0000
076A:0000 11 00 99 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0010 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0030 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0040 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
076A:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00
.....s.....

```

```
-e 076a:0000
076A:0000 11.BA 00.AA 99.AC 00.00

-g

Program terminated normally
-d 076a:0000
076A:0000 BA AA AC 00 0E AA 00 00-00 00 00 00 00 00 00 00 00
076A:0010 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00
076A:0030 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00
076A:0040 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00
076A:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00
076A:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00
076A:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00
```

3) Multiplication

```
D:\EX2>masm 16bitmul.asm
Microsoft (R) MASM Compatibility Driver
Copyright (C) Microsoft Corp 1993. All rights reserved.

Invoking: ML.EXE /I. /Zm /c /Ta 16bitmul.asm

Microsoft (R) Macro Assembler Version 6.11
Copyright (C) Microsoft Corp 1981-1993. All rights reserved.

Assembling: 16bitmul.asm

D:\EX2>link 16bitmul.obj

Microsoft Object Linker V2.01 (Large)
(C) Copyright 1982, 1983 by Microsoft Inc.

Run File [16BITMUL.EXE]:
List File [NUL.MAP]:
Libraries [.LIB]:
Warning: No STACK segment

There was 1 error detected.
```

```
D:\EX2>debug 16bitmul.exe
-U
076B:0100 B86A07      MOV     AX,076A
076B:0103 8ED8      MOV     DS,AX
076B:0105 A10000      MOV     AX,[0000]
076B:0108 8B1E0200      MOV     BX,[0002]
076B:010C F7E3      MUL     BX
076B:010E A30400      MOV     [0004],AX
076B:0111 89160600      MOV     [0006],DX
076B:0115 B44C      MOV     AH,4C
076B:0117 CD21      INT     21
076B:0119 FD      STD
076B:011A 00B0FF??      ADD     [BX+SI+??FF],DH
076B:011E 01408B      ADD     [BX+SI-?5],AX
-E 076A:0000
076A:0000 11.BA 00.BA 99.AA 00.AA

-G

Program terminated normally
```

4) Division

```
D:\EX2>masm 16bitdiv.asm
Microsoft (R) MASM Compatibility Driver
Copyright (C) Microsoft Corp 1993. All rights reserved.

Invoking: ML.EXE /I. /Zm /c /Ta 16bitdiv.asm

Microsoft (R) Macro Assembler Version 6.11
Copyright (C) Microsoft Corp 1981-1993. All rights reserved.

Assembling: 16bitdiv.asm

D:\EX2>link 16bitdiv.obj

Microsoft Object Linker V2.01 (Large)
(C) Copyright 1982, 1983 by Microsoft Inc.

Run File [16BITDIV.EXE]:
List File [NUL.MAP]:
Libraries [.LIB]:
Warning: No STACK segment

There was 1 error detected.
```

```
D:\EX2>debug 16bitdiv.exe
-u
076B:0100 B86A07      MOV      AX, 076A
076B:0103 8ED8        MOV      DS, AX
076B:0105 B400        MOV      AH, 00
076B:0107 A10000      MOV      AX, [0000]
076B:010A 8B1E0200    MOV      BX, [0002]
076B:010E F7F3        DIV      BX
076B:0110 A30400      MOV      [0004], AX
076B:0113 89160600    MOV      [0006], DX
076B:0117 8B260800    MOV      [0008], AX
076B:011B B44C        MOV      AH, 4C
076B:011D CD21        INT      21
076B:011F 40          INC      AX
-e 076a:0000
076A:0000 11.FA      00.FA      99.78      00.03

-g

Program terminated normally
```

```
Program terminated normally
-d 076a:0000
076A:0000  FA FA 78 03 48 00 3A 01-00 00 00 00 00 00 00 00 00 00 00 00 ..x.H.:.....
076A:0010  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 00 .....
076A:0020  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 00 .....
076A:0030  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 00 .....
076A:0040  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 00 .....
076A:0050  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 00 .....
076A:0060  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 00 .....
076A:0070  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 00 .....
S
```

Result:

The arithmetic operations have been performed and executed correctly using MASM

Exp No:3

String Operations

Name: Shreya Sriram

Register Number:195001106

Date: 06/07/2021

AIM:

To perform the following string manipulation operations using MASM

1. Moving a string of bytes
2. Comparing 2 strings of bytes
3. Searching a byte in a string
4. Moving a string of bytes without using string instructions

a. Moving a string of bytes

Algorithm:

- Declare the source string and string length in the data segment
- Declare the location of destination string in the extra segment
- Move the offset of source string into SI
- Move the offset of destination string into DI
- Move the string length value into CX count register
- Use **REP MOVSB** instruction to move the data at SI to DI

PROGRAM CODE	COMMENTS
assume cs:code,ds:data,es:extra data segment source db 'abcd' strlen dw 0004h data ends extra segment dest db 4 dup(0) extra ends code segment org 0100h start : mov ax,data	Declare the code,data,extra segments Start the data segment Initialise the source string in bytes Initialise the source string length End the data segment Start the extra segment Declare the destination string End the extra segment Start the code segment Enter starting address of the code segment Label start: Move the data segment to DS through the AX register

mov ds,ax

Move the extra segment to ES through the AX register

SI = [source]

DI = [dest]

CX = strlen

Clear the direction flag

Move the string from DI to SI until CX =0

Terminate the program

End code segment

End start label

OUTPUT:

b. Comparing 2 strings of bytes

Algorithm:

- Declare and initialise string1, length of string1, memory location to store the result in the data segment
 - Declare and initialise string2 in the extra segment
 - Move the offset of string1 into SI
 - Move the offset of string2 into DI
 - Store the length of string1 in both BX and CX registers
 - Use the REPE CMPSB instruction to compare the two strings. After the end of loop if ZF is not set, go to not equal label, else go to equal label
 - not equal label : Subtract CX from BX ($BX=BX-CX$) to get the index of the first mismatch and store the value in result
 - equal label: Implies the strings are equal. Hence store the value 0000 in result

PROGRAM:

PROGRAM CODE	COMMENTS
--------------	----------

<pre> assume cs:code,ds:data,es:extra data segment str1 db 'abcde' strlen dw 0005h result dw 0000h data ends extra segment str2 db 'abcbe' extra ends code segment org 0200h start: mov ax,data </pre>	<p>Declare the code,data,extra segments Start the data segment Initialise the string1 of bytes Initialise the source string length Declare result to store the output</p> <p>End the data segment</p> <p>Start the extra segment</p> <p>Declare the string2 of bytes</p> <p>End the extra segment</p> <p>Start the code segment</p> <p>Enter starting address of the code segment</p> <p>Label start:</p> <p>Move the data segment to DS through the AX register</p>
---	--

<pre> mov ds,ax mov ax,extra mov es,ax mov cx,strlen mov si,offset str1 mov di,offset str2 mov bx,strlen cld repe cmpsb jne notequal jmp equal notequal: sub bx,cx mov result,bx jmp exit equal: mov result,0000h exit: mov ah,4ch </pre>	<p>Move the extra segment to ES through the AX register</p> <p>CX = strlen</p> <p>SI = [str1]</p> <p>DI = [str2]</p> <p>BX = strlen</p> <p>Clear the direction flag</p> <p>Compare Strings at SI and DI</p> <p>If ZF is not set go to notequal label Jump to equal label</p> <p>Notequal label</p> <p>BX = BX - CX</p> <p>result = BX</p> <p>Jump to Exit label</p> <p>Equal label</p> <p>result = 0000h</p> <p>Exit label</p> <p>Terminate the program</p> <p>End code segment</p>
---	---

<pre>int 21h code ends end start</pre>	End start label
--	-----------------

OUTPUT:

```
-u
076C:0200 B86A07      MOV     AX,076A
076C:0203 8ED8      MOV     DS,AX
076C:0205 B86B07      MOV     AX,076B
076C:0208 8EC0      MOV     ES,AX
076C:020A BB0E0500    MOV     CX,[0005]
076C:020E BE0000    MOV     SI,0000
076C:0211 BF0000    MOV     DI,0000
076C:0214 8B1E0500    MOV     BX,[0005]
076C:0218 FC      CLD
076C:0219 F3      REPZ
076C:021A A6      CMPSB
076C:021B 7502    JNZ     021F
076C:021D EB08    JMP     0227
076C:021F 2BD9    SUB    BX,CX
```

```
D:\EX4>debug strcmp.exe
-d 076a:0000
076A:0000  68 65 6C 6C 6F 05 00 00-00 00 00 00 00 00 00 00  hello.....
076A:0010  68 65 6C 6C 6F 00 00 00-00 00 00 00 00 00 00 00  hello.....
076A:0020  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00  .....
076A:0030  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00  .....
076A:0040  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00  .....
076A:0050  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00  .....
076A:0060  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00  .....
076A:0070  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00  .....
-
-g
Program terminated normally
-d 076a:0000
076A:0000  68 65 6C 6C 6F 05 00 00-00 00 00 00 00 00 00 00  hello.....
076A:0010  68 65 6C 6C 6F 00 00 00-00 00 00 00 00 00 00 00  hello.....
076A:0020  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00  .....
076A:0030  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00  .....
076A:0040  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00  .....
076A:0050  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00  .....
076A:0060  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00  .....
076A:0070  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00  .....
-S
```

c. Searching a byte in a string

Algorithm:

- Declare and initialize the string in the extra segment
- Declare and initialize the string length, memory to store index of occurrence of substring (indexval), and the substring itself in the data segment
- Move the substring into the AL register
- Move the string length into the BX and CX registers
- Move offset of string into DI
- Compare the byte (substring) stored in AL register to the byte pointed to by the DI using REPNE SCASB instruction, the instruction terminates when the substring is found and the number of comparisons is found in the CX register
- If the ZF is not set, go to absent label, else go to present label
- present label : store the value 0000h in indexval and go to exit label
- absent label : subtract CX from BX (BX=BX-CX) to get the index of the first occurrence and then move it to indexval

PROGRAM:

PROGRAM CODE	COMMENTS
assume cs:code,ds:data,es:extra data segment subst db 'd' strlen dw 0004h indexval dw 0000h data ends extra segment str db 'abcde' extra ends code segment org 0300h start: mov ax,data mov ds,ax mov ax,extra mov es,ax mov al,subst mov bx,strlen	Declare the code,data,extra segments Start the data segment Initialise the substring Initialise the length of the string Declare indexval to store the index of occurrence End the data segment Start the extra segment Declare and initialize the string of bytes End the extra segment Start the code segment Enter starting address of the code segment Label start: Move the data segment to DS through the AX register Move the extra segment to ES through the AX register AL =substring BX = strlen

<pre> mov cx,strlen mov di,offset str cld repne scasb jne absent jmp present absent: mov indexval,0000h jmp exit present: sub bx,cx </pre>	<p>CX = strlen DI =[dest] Clear the direction flag</p> <p>Search for substring stored in AL in the string at DI until found or CX=0</p> <p>If Zero flag is not set go to absent label Jump to present label absent label indexval = 0000h(substring not present)</p> <p>Jump to Exit label Present label BX = BX - CX indexval = BX</p>
---	---

<pre> mov indexval,bx exit: mov ah,4ch int 21h code ends end start </pre>	<p>Exit label Terminate the program</p> <p>End code segment End start label</p>
---	---

SNAPSHOTS:

OUTPUT:

```
D:\EX4>debug search.exe
-u
076C:0300 B86A07      MOV      AX,076A
076C:0303 8ED8        MOV      DS,AX
076C:0305 B86B07      MOV      AX,076B
076C:0308 BEC0        MOV      ES,AX
076C:030A A00000      MOV      AL,[0000]
076C:030D 8B1E0100    MOV      BX,[0001]
076C:0311 8B0E0100    MOV      CX,[0001]
076C:0315 BF0000      MOV      DI,0000
076C:0318 FC          CLD
076C:0319 F2          REPNZ
076C:031A AE          SCASB
076C:031B 7502        JNZ      031F
076C:031D EB08        JMP      0327
076C:031F C70603000000  MOV     WORD PTR [0003],0000
.
```

```
-d 076a:0000
076A:0000 64 04 00 00 00 00 00 00-00 00 00 00 00 00 00 00 d.....
076A:0010 61 62 63 64 65 00 00 00-00 00 00 00 00 00 00 00 abcde.....
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....
076A:0030 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....
076A:0040 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....
076A:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....
076A:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....
076A:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....
-g

Program terminated normally
-d 076a:0000
076A:0000 64 04 00 04 00 00 00 00-00 00 00 00 00 00 00 00 d.....
076A:0010 61 62 63 64 65 00 00 00-00 00 00 00 00 00 00 00 abcde.....
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....
076A:0030 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....
076A:0040 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....
076A:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....
076A:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....
076A:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....
```

d.Moving a string without using string instructions

Algorithm:

- Declare and initialize the source string in the data segment
- Declare string length and destination string location also in data segment
- Move the offset of source string into SI
- Move the offset of destination string into DI
- Move the string length value into CX count register
- Repeat the following statements until CX register value becomes 0 (Loop start)
 - Move the value at [SI] into AL register
 - Move the value in AL register to the memory location [DI]

- Increment SI and DI
- Decrement CX
- (Loop end)
- Terminate the program

PROGRAM:

PROGRAM CODE	COMMENTS
<pre> assume cs:code,ds:data data segment source db 'abcde' strlen dw 0005h dest db 5 dup(0) data ends code segment org 0500h </pre>	<p>Declare the code, data segments Start the data segment</p> <p>Initialise the source string</p> <p>Initialise the length of the string</p> <p>Declare destination location</p> <p>End the data segment</p> <p>Start the code segment</p> <p>Enter starting address of the code segment</p>

<pre> start: mov ax,data mov ds,ax mov si,offset source mov di,offset dest mov cx,strlen looper: mov al,[si] mov [di],al inc si inc di dec cx jnz looper mov ah,4ch int 21h code ends end start </pre>	<p>Label start:</p> <p>Move the data segment to DS through the AX register</p> <p>SI = [source]</p> <p>DI = [dest]</p> <p>CX = strlen</p> <p>Loop label</p> <p>AL = [SI]</p> <p>[DI] = AL</p> <p>SI = SI + 1</p> <p>DI = DI +1</p> <p>CX = CX - 1</p> <p>Jump to loop label if ZF is not set Terminate the program</p> <p>End code segment</p> <p>End start label</p>
--	---

OUTPUT:

```

-u
076B:0522 50      PUSH   AX
076B:0523 B8C200  MOV     AX,00C2
076B:0526 50      PUSH   AX
076B:0527 9AA701FD02 CALL   02FD:01A7
076B:052C 8A5E0A  MOV     BL,[BP+0A]
076B:052F B700  MOV     BH,00
076B:0531 D1E3  SHL     BX,1
076B:0533 8B87AA2A MOV     AX,[BX+2AAA]
076B:0537 8946F8  MOV     [BP-08],AX
076B:053A 83F8FF  CMP     AX,-01
076B:053D 7509  JNZ    0548
076B:053F B8C300  MOV     AX,00C3
-s

```

```
-d 076a:0000
076A:0000  61 62 63 64 65 05 00 00-00 00 00 00 00 00 00 00 00 00 abcde.....
076A:0010  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0020  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0030  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0040  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0050  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0060  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0070  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
-g

Program terminated normally
-d 076a:0000
076A:0000  61 62 63 64 65 05 00 61-62 63 64 65 00 00 00 00 00 abcde..abcde....
076A:0010  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0020  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0030  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0040  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0050  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0060  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0070  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
```

RESULT:

The above mentioned 4 string manipulation operations using the mentioned instructions has been performed and the result is verified.

Exp No:4

Code Conversion

Name: Shreya Sriram

Register Number:195001106

Date: 02/08/2021

AIM:

To convert BCD to hexadecimal and vice versa

ALGORITHM:

BCD to Hexadecimal

- Declare the variables bcd, first, second and hex to store the bcd number, first digit, second digit and hexadecimal number
- Move bcd number to the al register
- Move 0FH to bl register
- Perform al and bl and store the result in al
- This fetches the second digit and it is moved to second
- Move the bcd number to the al register
- Left shift 0FH four times to bl
- Perform al and bl and move result to first
- Initialize bl to 0Ah
- Multiply al and bl
- Add second to al
- Move the result to hex
- Terminate the program

Hexadecimal to BCD

- Declare the variables bcd and hex to store the bcd number and hexadecimal number
- Move hexadecimal to al
- Move 64h to cl
- Divide al/cl
- Move al to bl
- Move 00h to ah
- Move 00Ah to cl
- Divide al/cl
- Move al to dh and ah to dl
- Move 04h to cl and right rotate by 4 positions
- Add dh and dl
- Move dx to bcd number
- Terminate

CODE:**BCD to Hexadecimal**

<u>CODE</u>	<u>REMARKS</u>
<pre> assume cs:code,ds:data data segment bcd db 34h first db 00H second db 00H hex db 00H data ends code segment org 0100h start: mov ax, data mov ds,ax mov al,bcd mov bl,0FH and al,bl mov second,al mov al,bcd mov cl, 4 shl bl,cl and al,bl shr al,cl mov first,al mov al,first mov bl,0Ah mov ch,00h mul bl add al,second mov hex,al mov ah,4ch int 21h code ends end start </pre>	<p>Data segment starts Initialise bcd to 34h Initialise first to 0 Initialise second to 0 Initialise hex to 0 Data segment ends Code segment starts</p> <p>Mov data to ax Move ax to ds Move bcd to al Move 0Fh to bl Perform al and bl Move al to second Move bcd to al Initialize cl to 4 Left shift bl 4 times Perform al and bl Right shift al 4 times Move al to first(first digit) Move first to al Move 0Ah to bl Move 00h to ch Multiply al*bl and store in al Add second and al Move al to hex Move 4ch to ah Terminate the code Code ends</p>

Hexadecimal to BCD

<u>CODE</u>	<u>REMARKS</u>
<pre> assume cs:code, ds:data data segment hex db 0FFh bcd dw 00h data ends </pre>	<p>Data segment starts Initialise bcd to 0FFh Initialise hex to 0 Data segment ends</p>

code segment	Code segment starts
org 0100h	
start:	
mov ax, data	Mov data to ax
mov ds, ax	Move ax to ds
mov ch, 00h	Move 00h to ch
mov ah, 00h	Move ooh to ah
mov al, hex	Move hex to al
mov cl, 64h	Move 64h to cl
div cl	Divide al/cl
mov bl, al	Move al to bl
mov al, ah	Move ah to al
mov ah, 00h	Move 00h to ah
mov cl, 00Ah	Move 00Ah to cl
div cl	Divide al/cl
mov dh, al	Move al to dh
mov dl, ah	Move ah to dl
mov cl, 04h	Move 04h to cl
ror dh, cl	Right rotate dh 4 times
add dh, dl	Add dh and dl and store in dh
mov dl, bl	Move bl to dl
mov bcd, dx	Move dx to bcd
mov ah, 4ch	Move 4ch to ah
int 21h	Terminate the code
code ends	Code ends
end start	

OUTPUT:

BCD TO HEXADECIMAL

```
D:\EX5>debug bcddhex.exe
-u
076B:0100 B86A07      MOV     AX,076A
076B:0103 8ED8        MOV     DS,AX
076B:0105 A00000      MOV     AL,[0000]
076B:0108 B30F        MOV     BL,OF
076B:010A 22C3        AND    AL,BL
076B:010C A20200      MOV    [0002],AL
076B:010F A00000      MOV    AL,[0000]
076B:0112 B104        MOV    CL,04
076B:0114 D2E3        SHL    BL,CL
076B:0116 22C3        AND    AL,BL
076B:0118 D2E8        SHR    AL,CL
076B:011A A20100      MOV    [0001],AL
076B:011D A00100      MOV    AL,[0001]
-d 076a:0000
076A:0000 34 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 4. .....
076A:0010 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0020 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0030 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0040 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0050 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0060 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
076A:0070 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .....
```

HEXADECIMAL TO BCD

```
-u
076B:0120 D2CE        ROR      DH,CL
076B:0122 02F2        ADD      DH,DL
076B:0124 8AD3        MOV      DL,BL
076B:0126 89160100    MOV      [0001],DX
076B:012A B44C        MOV      AH,4C
076B:012C CD21        INT      21
076B:012E BOFF        MOV      AL,FF
076B:0130 7201        JB       0133
076B:0132 40          INC      AX
076B:0133 59          POP     CX
076B:0134 22C1        AND      AL,CL
076B:0136 D0D8        RCR      AL,1
076B:0138 7203        JB       013D
076B:013A E98300    JMP      01C0
076B:013D 8A46FD    MOV      AL,[BP-03]
```

```
-g  
Program terminated normally  
-d 076A:0000  
076A:0000 FF 02 55 00 00 00 00 00-00 00 00 00 00 00 00 00 00 ..U.....  
076A:0010 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 .....  
076A:0020 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 .....  
076A:0030 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 .....  
076A:0040 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 .....  
076A:0050 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 .....  
076A:0060 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 .....  
076A:0070 00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 ..
```

RESULT:

Code conversion from BCD to Hexadecimal and vice versa is coded and tested.

Exp No:5

Matrix Operations

Name: Shreya Sriram

Register Number:195001106

Date: 09/08/2021

AIM:

To perform sum and difference of two matrices

ALGORITHM:

Addition:

- Declare and initialize row1 and col1
- Declare and initialize mat_a and mat_b
- Move data to ax, ax to ds, ax to es
- Move row1 to al and row2 to bl
- Compare al and bl, if they are not equal, go to finish
- Move col1 to al and col2 to bl
- Compare al and bl, if they are not equal, go to finish
- Move row1 to al and col1 to cl
- Move offset of mat_a to SI and mat_b to DI and offset of mat_res to bx
- Move ax to cx
- Move address of SI to al, add this to the address of DI
- Move al to the address of BX
- Increment SI, DI, BL
- Terminate the program

Subtraction:

- Declare and initialize row1 and col1
- Declare and initialize mat_a and mat_b
- Move data to ax, ax to ds, ax to es
- Move row1 to al and row2 to bl
- Compare al and bl, if they are not equal, go to finish
- Move col1 to al and col2 to bl
- Compare al and bl, if they are not equal, go to finish
- Move row1 to al and col1 to cl
- Move offset of mat_a to SI and mat_b to DI and offset of mat_res to bx
- Move ax to cx
- Move address of SI to al, subtract this from the address of DI
- Move al to the address of BX

- Increment SI, DI, BL
- Terminate the program

CODE:

Addition:

CODE	REMARKS
assume cs:code,ds:data data segment row1 db 02h col1 db 02h mat_a db 01H,02H,03H,04H org 0010h row2 db 02h col2 db 02h mat_b db 05H,06H,07H,08H org 0020h mat_res db ? data ends code segment start: mov ax, data mov ds, ax mov es, ax	Data segment starts Initialize row1 to 02h Initialize col1 to 02h Initialize matrix a Initialise row2 to 02h Initialize col2 to 02h Initialize matrix b Store result matrix Data segment ends Code segment begins
CHK: MOV AL, ROW1 MOV BL, ROW2 CMP AL,BL JNZ FINISH MOV AL, COL1 MOV BL, COL2 CMP AL,BL JNZ FINISH mov al, row1 mov cl, col1 mul cl mov SI, offset mat_a mov DI, offset mat_b mov bx,offset mat_res mov cx,ax	Move row1 to al Move row2 to bl Compare al and bl If they are not equal, move to end Move col1 to al Move col2 to bl Compare al and bl If not equal, move to end Move row1 to al Move col1 to cl Multiply al*cl Move the offset of matrix a to SI Move the offset of matrix b to DI Move the offset of matrix res to bx Move ax to cx
WRK: MOV AL,[SI] ADD AL,[DI] MOV [BX],AL INC SI INC DI	Move SI address to al Add DI address to al Move the address of bx to al Increment SI Increment DI

INC BL LOOP WRK	Increment bl
FINISH: mov ah, 4ch int 21h code ends	Terminate the program
end start	Code ends

Subtraction:

<u>CODE</u>	<u>REMARKS</u>
assume cs:code,ds:data	
data segment	Data segment starts
row1 db 02h	Initialize row1 to 02h
col1 db 02h	Initialize col1 to 02h
mat_a db 01H,02H,03H,04H	Initialize matrix a
org 0010h	
row2 db 02h	Initialise row2 to 02h
col2 db 02h	Initialize col2 to 02h
mat_b db 05H,06H,07H,08H	Initialize matrix b
org 0020h	
mat_res db ?	Store result matrix
data ends	Data segment ends
code segment	Code segment begins
start:	
mov ax, data	Move data to ax
mov ds, ax	Move ax to ds
mov es, ax	Move ax to es
CHK: MOV AL, ROW1	Move row1 to al
MOV BL, ROW2	Move row2 to bl
CMP AL,BL	Compare al and bl
JNZ FINISH	If they are not equal, move to end
MOV AL, COL1	Move col1 to al
MOV BL, COL2	Move col2 to bl
CMP AL,BL	Compare al and bl
JNZ FINISH	If not equal, move to end
mov al, row1	Move row1 to al
mov cl, col1	Move col1 to cl
mul cl	Multiply al*cl
mov SI, offset mat_a	Move the offset of matrix a to SI
mov DI, offset mat_b	Move the offset of matrix b to DI
mov bx,offset mat_res	Move the offset of matrix res to bx
mov cx,ax	Move ax to cx
WRK: MOV AL,[SI]	Move SI address to al

SUB AL,[DI]	Subtract DI address to al
MOV [BX],AL	Move the address of bx to al
INC SI	Increment SI
INC DI	Increment DI
INC BL	Increment bl
LOOP WRK	
FINISH:	
mov ah, 4ch	Terminate the program
int 21h	
code ends	Code ends
end start	

OUTPUT:

Addition:

```
D:\EX6>debug matadd.exe  
-u  
076D:0000 B86A07        MOV     AX,076A  
076D:0003 8ED8          MOV     DS,AX  
076D:0005 8EC0          MOV     ES,AX  
076D:0007 A00000        MOV     AL,[0000]  
076D:000A 8A1E1000      MOV     BL,[0010]  
076D:000E 38D8          CMP     AL,BL  
076D:0010 752B          JNZ     003D  
076D:0012 A00100        MOV     AL,[0001]  
076D:0015 8A1E1100      MOV     BL,[0011]  
076D:0019 38D8          CMP     AL,BL  
076D:001B 7520          JNZ     003D  
076D:001D A00000        MOV     AL,[0000]
```

```
D:\EX6>debug matadd.exe  
-d 076a:0000  
076A:0000 02 02 01 02 03 04 00 00-00 00 00 00 00 00 00 00 00 00 .  
076A:0010 02 02 05 06 07 08 00 00-00 00 00 00 00 00 00 00 00 00 .  
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .  
076A:0030 B8 6A 07 8E D8 8E C0 A0-00 00 8A 1E 10 00 38 D8 .j .8  
076A:0040 75 2B A0 01 00 8A 1E 11-00 38 D8 75 20 A0 00 00 u+ .8.u  
076A:0050 8A 0E 01 00 F6 E1 BE 02-00 BF 12 00 BB 20 00 8B .  
076A:0060 C8 8A 04 02 05 88 07 46-47 FE C3 E2 F4 B4 4C CD . . . .FG .L  
076A:0070 21 B6 2C 3A 46 F8 74 7E-C7 46 FA 00 00 8A 46 F8 !.,:F.t~.F...F.  
-g  
  
Program terminated normally  
-d 076a:0000  
076A:0000 02 02 01 02 03 04 00 00-00 00 00 00 00 00 00 00 00 00 .  
076A:0010 02 02 05 06 07 08 00 00-00 00 00 00 00 00 00 00 00 00 .  
076A:0020 06 08 0A 0C 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .  
076A:0030 B8 6A 07 8E D8 8E C0 A0-00 00 8A 1E 10 00 38 D8 .j .8  
076A:0040 75 2B A0 01 00 8A 1E 11-00 38 D8 75 20 A0 00 00 u+ .8.u  
076A:0050 8A 0E 01 00 F6 E1 BE 02-00 BF 12 00 BB 20 00 8B .  
076A:0060 C8 8A 04 02 05 88 07 46-47 FE C3 E2 F4 B4 4C CD . . . .FG .L  
076A:0070 21 B6 2C 3A 46 F8 74 7E-C7 46 FA 00 00 8A 46 F8 !.,:F.t~.F...F.
```

Subtraction:

```
-u
076D:0000 B86A07      MOV     AX,076A
076D:0003 8ED8        MOV     DS,AX
076D:0005 8EC0        MOV     ES,AX
076D:0007 A00000      MOV     AL,[0000]
076D:000A 8A1E1000    MOV     BL,[0010]
076D:000E 38D8        CMP     AL,BL
076D:0010 752B        JNZ     003D
076D:0012 A00100      MOV     AL,[0001]
076D:0015 8A1E1100    MOV     BL,[0011]
076D:0019 38D8        CMP     AL,BL
076D:001B 7520        JNZ     003D
076D:001D A00000      MOV     AL,[0000]
```

RESULT:

Addition and subtraction of matrices is implemented and tested

Exp No:6

Sorting Operations

Name: Shreya Sriram

Register Number:195001106

Date: 16/08/2021

AIM:

To perform sorting of 8-bit numbers in ascending and descending order

ALGORITHM:

Ascending order:

- Initialize list1
- Move data to ax
- Move ax to ds
- Move 04h to ch
- Move 04h to cl
- Move the address of the lis1 to si
- Move content of si to al and si+1 to bl
- Compare al and bl, if al>bl, jump to down
- Move contents of si+1 to dl, exchange contents of si and dl
- Move si+1 to dl
- Increment si
- Decrement cl, if cl is not zero,move to up2
- Terminate the program

Descending order:

- Initialize list1
- Move data to ax
- Move ax to ds
- Move 04h to ch
- Move 04h to cl
- Move the address of the lis1 to si
- Move content of si to al and si+1 to bl
- Compare al and bl, if al<bl, jump to down
- Move contents of si+1 to dl, exchange contents of si and dl
- Move si+1 to dl
- Increment si
- Decrement cl, if cl is not zero,move to up2
- Terminate the program

CODE:

Ascending order:

<u>CODE</u>	<u>REMARKS</u>
<pre> assume cs:code, ds:data data segment list1 db 96h, 12h, 30h, 80h, 22h data ends code segment org 0100h start: mov ax,data mov ds,ax mov ch,04h up2: mov cl,04h lea si,list1 up1: mov al,[si] mov bl,[si+1] cmp al,bl jc down mov dl,[si+1] xchg [si],dl mov [si+1],dl down: inc si dec cl jnz up1 dec ch jnz up2 mov ah,4ch int 21h code ends end start </pre>	<p>Data segment starts Declare the list of elements Data segment ends</p> <p>Code segment starts</p> <p>Start the program Move data to ax Move ax to ds Move ch to 04h</p> <p>Move 04h to cl Move address of list1 to si</p> <p>Move the content of si to al Move the content of si+1 to bl Compare al and bl If al<bl, move to down Move the content of si+1 to dl Exchange [si] to dl Move the contents of [si+1] to dl</p> <p>Increment si Decrement cl If cl is not 0, move to up1 Decrement ch If not zero, jump to up2 Move 4ch to ah Terminate program</p> <p>Code segment ends End start</p>

Descending order:

<u>CODE</u>	<u>REMARKS</u>
<pre> assume cs:code, ds:data data segment list1 db 96h, 12h, 30h, 80h, 22h data ends code segment org 0100h start: mov ax,data mov ds,ax </pre>	<p>Data segment starts Declare the list of elements Data segment ends</p> <p>Code segment starts</p> <p>Start the program Move data to ax Move ax to ds</p>

mov ch,04h	Move ch to 04h
up2:	
mov cl,04h	Move 04h to cl
lea si,list1	Move address of list1 to si
up1:	
mov al,[si]	Move the content of si to al
mov bl,[si+1]	Move the content of si+1 to bl
cmp al,bl	Compare al and bl
jnc down	If al>bl, move to down
mov dl,[si+1]	Move the content of si+1 to dl
xchg [si],dl	Exchange [si] to dl
mov [si+1],dl	Move the contents of [si+1] to dl
down:	
inc si	Increment si
dec cl	Decrement cl
jnz up1	If cl is not 0, move to up1
dec ch	Decrement ch
jnz up2	If not zero, jump to up2
mov ah,4ch	Move 4ch to ah
int 21h	Terminate program
code ends	Code segment ends
end start	End start

OUTPUT:

Ascending order:

```
-u
076B:0100 B86A07      MOV     AX,076A
076B:0103 8ED8        MOV     DS,AX
076B:0105 B504        MOV     CH,04
076B:0107 B104        MOV     CL,04
076B:0109 8D360000    LEA     SI,[0000]
076B:010D 8A04        MOV     AL,[SI]
076B:010F 8A5C01      MOV     BL,[SI+01]
076B:0112 3B88        CMP     AL,BL
076B:0114 7208        JB      011E
076B:0116 8A5401      MOV     DL,[SI+01]
076B:0119 8614        XCHG   DL,[SI]
076B:011B 885401      MOV     [SI+01],DL
076B:011E 46          INC     SI
076B:011F FEC9        DEC     CL
-d 076a:0000
076A:0000 96 12 30 80 22 00 00 00-00 00 00 00 00 00 00 00 .0.".....
076A:0010 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .
076A:0030 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .
076A:0040 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .
076A:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .
076A:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .
076A:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .
l2
```

```
-g  
Program terminated normally  
-d 076A:0000  
076A:0000 12 22 30 80 96 00 00 00-00 00 00 00 00 00 00 00 . "0.....  
076A:0010 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....  
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....  
076A:0030 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....  
076A:0040 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....  
076A:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....  
076A:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....  
076A:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 .....
```

Descending order:

```
-g
Program terminated normally
-d 076A:0000
076A:0000  96 80 30 22 12 00 00 00-00 00 00 00 00 00 00 00 00 00 ..0"...
076A:0010  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .
076A:0020  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .
076A:0030  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .
076A:0040  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .
076A:0050  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .
076A:0060  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .
076A:0070  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 .
.
```

RESULT

Sorting operations are performed and tested

AIM:

To perform BCD addition and subtraction using 8086 microprocessor instructions in masm

ALGORITHM:**a)Addition**

- Initialize the 2 numbers,sum and carry both as 0 in the data segment
- Load data from num1 to register AL (first number).
- Load data from num2 to register BL (second number).
- Initialize carry to 0.
- Add these two numbers (contents of register AL and register BL).
- Store the result in packed BCD form using DAA instruction.
- Jump to final steps if there is no carry. Else do the following steps,
- Increment carry.
- Store additional values to sum.
- Terminate the program.

b)Subtraction

- Initialize the 2 numbers, diff and carry both as 0 in the data segment
- Load data from num1 to register AL (first number)
- Load data from num2 to register BL (second number)
- Subtract these two numbers (contents of register AL and register BL)
- Store the result in packed BCD form using DAS instruction
- Jump to final steps if there is no carry. Else do the following steps
- Increment carry.
- Find 10's complement of the result and store it in packed BCD form using DAS instruction
- Store answer to result.
- Terminate the program.

Program Code:**a) Addition :**

Code	Comments
assume cs:code,ds:data	Declare the code and data segments
data segment	Data segment starts
num1 db 27h	Initialize num1
num2 db 35h	Initialize num2
sum db 00h	Initialize sum as 0
carry db 00h	Initialize carry as 0
data ends	End of data segment
code segment	Code segment starts
org 0100h	Set starting address of code segment
start: mov ax,data	Start label
mov ds,ax	Move the data segment to DS through the AX register
mov cl,00h	Set CL register as 0
mov al,num1	Move num1 into AL register
mov bl,num2	Move num2 into BL register
add al,bl	AL=AL+BL
DAA	Store the result in packed BCD form
jnc noCarry	If there is no carry, jump to 'here' label
inc cl	Increment CL
noCarry:mov sum,al	
mov carry,cl	Nocarry label
mov ah,4ch	Move value at AL into sum
INT 21h	Move value at CL into carry
code ends	Terminate the program
end start	
	End of code segment
	End of start label

b) Subtraction :

CODE	Comments
<pre> assume cs:code,ds:data data segment num1 db 35h num2 db 27h diff db 00h carry db 00h data ends code segment org 0100h start: mov ax,data mov ds,ax mov cl,00h mov al,num1 mov bl,num2 sub al,bl DAS jnc here mov dl,99h sub dl,al inc dl inc cl mov al,dl DAS here: mov diff,al mov carry,cl mov ah,4ch INT 21h code ends end start </pre>	<p>Declare the code and data segments</p> <p>Data segment starts</p> <p>Initialize num1</p> <p>Initialize num2</p> <p>Initialize sum as 0</p> <p>Initialize diff as 0</p> <p>End of data segment</p> <p>Code segment starts</p> <p>Set starting address of code segment</p> <p>Move the data segment to DS through the AX register</p> <p>Set CL register as 0</p> <p>Move num1 into AL register</p> <p>Move num2 into BL register</p> <p>AL=AL-BL</p> <p>Store the result in packed BCD form</p> <p>If no carry, jump to here label</p> <p>Set DL as 99</p> <p>Increment CL register</p> <p>DL=DL-AL</p> <p>Increment DL</p> <p>Move contents of DL into AL</p> <p>Store the result in packed BCD form</p> <p>Label 'here'</p> <p>Move value at AL into diff</p> <p>Move value at CL into carry</p> <p>Terminate the program</p> <p>End of code segment</p> <p>End of start segment</p>

Unassembled Code:

a)Addition

```
D:\>debug bcdADD.exe:  
-u  
076B:0100 B86A07      MOV    AX,076A  
076B:0103 8ED8        MOV    DS,AX  
076B:0105 B100        MOV    CL,00  
076B:0107 A00000      MOV    AL,[0000]  
076B:010A 8A1E0100    MOV    BL,[0001]  
076B:010E 02C3        ADD    AL,BL  
076B:0110 27          DAA  
076B:0111 7302        JNB    0115  
076B:0113 FEC1        INC    CL  
076B:0115 A20200      MOV    [0002],AL  
076B:0118 880E0300    MOV    [0003],CL  
076B:011C B44C        MOV    AH,4C  
076B:011E CD21        INT    21
```

b) Subtraction

```
D:\>debug bcdSUB.exe:  
-u  
076B:0100 B86A07      MOV    AX,076A  
076B:0103 8ED8        MOV    DS,AX  
076B:0105 B100        MOV    CL,00  
076B:0107 A00000      MOV    AL,[0000]  
076B:010A 8A1E0100    MOV    BL,[0001]  
076B:010E 2AC3        SUB    AL,BL  
076B:0110 2F          DAS  
076B:0111 730B        JNB    011E  
076B:0113 B299        MOV    DL,99  
076B:0115 2AD0        SUB    DL,AL  
076B:0117 FEC2        INC    DL  
076B:0119 FEC1        INC    CL  
076B:011B 8AC2        MOV    AL,DL  
076B:011D 2F          DAS  
076B:011E A20200      MOV    [0002],AL
```

OUTPUT :

a)


```
D:\>debug bcdSUB.exe:  
-e 076A:0000  
076A:0000 35.22 27.44 00.  
  
-g  
  
Program terminated normally  
-d 076A:0000  
076A:0000 22 44 22 01 00 00 00 00-00 00 00 00 00 00 00 00 00  
076A:0010 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00  
076A:0020 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00  
076A:0030 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00  
076A:0040 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00  
076A:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00  
076A:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00  
076A:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00  
-
```

RESULT :

BCD addition and subtraction operations are performed using 8086 instructions in masm and the output is verified.

Exp No:8 Floating Point Operations

Name: Shreya Sriram

Register Number:195001106

Date: 30/08/2021

AIM:

To implement floating point operations- addition and subtraction using masm

ALGORITHM:

a) Addition

1. Move the starting address of data segment to AX register and move the data from AX register to DS register.
2. Initialize the 8087-stack using FINIT command. This stack will be used for floating point operations.
3. Load the floating-point number from variable X to the top of the stack i.e. ST (0) using FLD command.
4. Now again load the floating-point number from variable Y to the top of the stack i.e. ST (0) using FLD command. The previous stack top contents will be pushed into the stack.
5. Using FADD add ST(0) and ST(1) which stores the result in ST(0).
6. Using FST store the resulting floating-point number from the top of the stack to the variable SUM.
7. Move the hexadecimal value 4C into AH register. INT 21H means invoke the interrupt identified by the hexadecimal number 21. In MS-DOS, invoking interrupt 21h while AH = 4Ch causes the current process to terminate and uses the value of register AL as the exit code of the process.

b) Subtraction:

1. Initialize 8087 stack using FINIT command. This stack is used for floating point operations
2. Load the floating point number from variable X to the top of stack(ST(0)) using FLD command
3. Load the floating point number from variable Y to the top of stack(ST(0)) using FLD command

4. Use FSUB to subtract ST(0) from ST(1) and store the result in ST(0)
5. Use FST to store the resulting floating point number from top of stack to variable DIFF
6. Terminate the program

PROGRAM:

a) Addition

CODE	COMMENTS
assume cs:code, ds:data	Assign code segment to variable code and data segment to variable data
	Start of data segment
data segment	Directive to assign offset address
org 00h	Initialize 2 floating point values
x dd 20.4375	
org 10h	
y dd 20.4375	
org 20h	Declare address space for result
sum dd ?	Data segment ends
data ends	Start of code segment
code segment	

start:	Start label
mov ax,data	Move the data segment to DS through the AX register
mov ds,ax	initialize 8087 stack
finit	load X into ST(0)
fld x	load Y into ST(0)
fld y	$ST(0) = X+Y$
fadd	
st(0),st(1)	store ST(0) in sum
fst sum	setup function-4C of the int21
mov ah,4ch	call BIOS int21 to return to DOS
int 21h	end of code segment
code ends	End of start label
end start	

b) Subtraction

Code	Comments

assume cs:code, ds:data	Assign code segment to variable code and data segment to variable data
	Start of data segment
data segment	Directive to assign offset address
org 00h	Initialize 2 floating point values
x dd 20.4375	
org 10h	
y dd 0.125	
org 20h	Declare address space for result
sum dd ?	Data segment ends
data ends	Start of code segment
code segment	

start:	Start label
mov ax,data	Move the data segment to DS through the AX register
mov ds,ax	initialize 8087 stack
finit	load X into ST(0)
fld x	load Y into ST(0)
fld y	ST(0) = X-Y
fsub st(0),st(1)	store ST(0) in diff
fst diff	setup function
mov ah,4ch	4C of the int21
int 21h	call BIOS int21 to return to DOS
code ends	end of code segment
end start	End of start label

Unassembled code :

a)**addition**

```
D:\>debug floatADD.exe:  
-u  
076D:0000 BB6A07      MOV     AX,076A  
076D:0003 8ED8      MOV     DS,AX  
076D:0005 9B      WAIT  
076D:0006 DBE3      FINIT  
076D:0008 9B      WAIT  
076D:0009 D9060000      FLD     DWORD PTR [0000]  
076D:000D 9B      WAIT  
076D:000E D9061000      FLD     DWORD PTR [0010]  
076D:0012 9B      WAIT  
076D:0013 D8C1      FADD    ST,ST(1)  
076D:0015 9B      WAIT  
076D:0016 D9162000      FST     DWORD PTR [0020]  
076D:001A B44C      MOV     AH,4C  
076D:001C CD21      INT     21  
076D:001E F8      CLC  
076D:001F B700      MOV     BH,00  
-S
```

B) subtraction

```
D:\>debug flosub.exe  
-u  
076D:0000 BB6A07      MOV     AX,076A  
076D:0003 8ED8      MOV     DS,AX  
076D:0005 9B      WAIT  
076D:0006 DBE3      FINIT  
076D:0008 9B      WAIT  
076D:0009 D9060000      FLD     DWORD PTR [0000]  
076D:000D 9B      WAIT  
076D:000E D9061000      FLD     DWORD PTR [0010]  
076D:0012 9B      WAIT  
076D:0013 D8E1      FSUB    ST,ST(1)  
076D:0015 9B      WAIT  
076D:0016 D9162000      FST     DWORD PTR [0020]  
076D:001A B44C      MOV     AH,4C  
076D:001C CD21      INT     21
```

Snapshots:

a) Addition

```
-d 076a:0000
076A:0000  00 80 A3 41 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0010  00 80 A3 41 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0020  00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00
076A:0030  B8 6A 07 BE D8 9B DB E3-9B D9 06 00 00 9B D9 06
076A:0040  10 00 9B D8 C1 9B D9 16-20 00 B4 4C CD 21 F8 B7
076A:0050  00 8A 87 48 2F D0 D8 73-17 E8 B6 00 8A 5E F8 B7
076A:0060  00 8A 87 48 2F D0 D8 73-07 53 B0 01 50 E8 73 01
076A:0070  A0 B6 2C 3A 46 F8 74 7E-C7 46 FA 00 00 8A 46 F8
-g
```

Program terminated normally

```
-d 076a:0000
076A:0000  00 80 A3 41 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0010  00 80 A3 41 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0020  00 80 23 42 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0030  B8 6A 07 BE D8 9B DB E3-9B D9 06 00 00 9B D9 06
076A:0040  10 00 9B D8 C1 9B D9 16-20 00 B4 4C CD 21 F8 B7
076A:0050  00 8A 87 48 2F D0 D8 73-17 E8 B6 00 8A 5E F8 B7
076A:0060  00 8A 87 48 2F D0 D8 73-07 53 B0 01 50 E8 73 01
076A:0070  A0 B6 2C 3A 46 F8 74 7E-C7 46 FA 00 00 8A 46 F8
```

b) Subtraction

```
-d 076a:0000
076A:0000  00 80 A3 41 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0010  00 00 00 3E 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0020  00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0030  B8 6A 07 BE D8 9B DB E3-9B D9 06 00 00 9B D9 06
076A:0040  10 00 9B D8 E1 9B D9 16-20 00 B4 4C CD 21 F8 B7
076A:0050  00 8A 87 48 2F D0 D8 73-17 E8 B6 00 8A 5E F8 B7
076A:0060  00 8A 87 48 2F D0 D8 73-07 53 B0 01 50 E8 73 01
076A:0070  A0 B6 2C 3A 46 F8 74 7E-C7 46 FA 00 00 8A 46 F8
-g
```

Program terminated normally

```
-d 076a:0000
076A:0000  00 80 A3 41 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0010  00 00 00 3E 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0020  00 80 A2 C1 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0030  B8 6A 07 BE D8 9B DB E3-9B D9 06 00 00 9B D9 06
076A:0040  10 00 9B D8 E1 9B D9 16-20 00 B4 4C CD 21 F8 B7
076A:0050  00 8A 87 48 2F D0 D8 73-17 E8 B6 00 8A 5E F8 B7
076A:0060  00 8A 87 48 2F D0 D8 73-07 53 B0 01 50 E8 73 01
076A:0070  A0 B6 2C 3A 46 F8 74 7E-C7 46 FA 00 00 8A 46 F8
```

Result:

Hence, floating point operations – addition and subtraction were implemented using masm

Exp No:9

Case Conversions

Name: Shreya Sriram

Register Number:195001106

Date: 7/09/2021

AIM:

To perform case conversion using 8086 instructions in masm

ALGORITHM:

- Use dos interrupt 21H with AH=01 to read the letters with echo
 - Compare the input letter with 60h
 - If result is greater, subtract 20h from the input letter
 - Else , add 20h to the input letter
- Use AH=2 to display the letters to standard output device
- Move character from AL to DL
- Use AH=2 to display the letters to standard output device
- Terminate the program

Program :

PROGRAM CODE	COMMENTS
ASSUME CS:CODE,DS:data data SEGMENT COUNT equ 10h data ends CODE SEGMENT START: MOV AX,data MOV DS,AX	Declare the code and data segments Data segment starts Assign value 10 to COUNT End of Data segment Code segment starts Start label Move the data segment to DS through the AX register

<pre> MOV CX,COUNT L1: MOV AH,1 ; INPUT CHARACTER, INT 21H ; AL = CHARACTER, ASCII(hex) :A-Z=41-5A, a- z=61-7A CMP AL,60H JNC UPPER ADD AL,20H JMP SKIP UPPER: SUB AL,20H ; CONVERT TO UPPER CASE SKIP: MOV AH,2 ; CHARACTER OUTPUT FUNCTION MOV DL,AL ; CHARACTER MUST BE IN DL INT 21H ; DISPLAY THE CHARACTER LOOP L1 ; REPEAT LOOP MOV Ah,4CH INT 21H CODE ENDS end start </pre>	<p>Move count value into CX register Label ‘L1’ Use dos interrupt 21H with AH=01 to read the letters with echo</p> <p>Compare AL with 60H If carry flag is unset,jump to upper label AL=AL+20 Jump to skip label Label ‘Upper’ AL=AL-20</p> <p>Label ‘skip’ Use AH=2 to display the letters to standard output device</p> <p>Move the character into DL register Display to output device using int 21h</p> <p>Loop back to label L1 Terminate the program</p> <p>End of code segment End of start label</p>
---	--

UNASSEMBLED CODE

```

D:\>debug casecon.exe
-u
076A:0000 BB6A07      MOV    AX,076A
076A:0003 8ED8      MOV    DS,AX
076A:0005 B91000      MOV    CX,0010
076A:0008 B401      MOV    AH,01
076A:000A CD21      INT    21
076A:000C 3C60      CMP    AL,60
076A:000E 7304      JNB    0014
076A:0010 0420      ADD    AL,20
076A:0012 EB02      JMP    0016
076A:0014 2C20      SUB    AL,20
076A:0016 B402      MOV    AH,02
076A:0018 B8D0      MOV    DL,AL
076A:001A CD21      INT    21
076A:001C E2EA      LOOP   0008
076A:001E B44C      MOV    AH,4C

```

```

D:\>caseCon.exe
Hi IaOkKaNyY

```

Exp No:10

Display a string

Name: Shreya Sriram

Register Number:195001106

Date: 14/09/2021

AIM:

To write and execute 8086 programs for displaying a string.

PROCEDURE:

- Firstly, write the 8086 program using editor(like notepad) and save it with .asm(filename.asm) extension and move to the MASM folder.
 - Now mount the MASM folder in DOSBOX("mount d e:/masm") and then enter into the mounted drive("d:")
 - Now using "edit filename.asm", we can edit or create a asm file for execution and then save and exit.
 - Assemble the code using "masm filename.asm" to generate the "filename.obj" file.
 - Link the file using "link filename.obj;" to generate the executable "filename.exe" file.
 - Now enter the debug mode using "debug filename.exe" to execute and analyse memory contents. The various commands used in debug mode are as follows:-
 - U :- To display unassembled code
 - D :- Used as 'D segment:offset' to see the content of memory locations starting from segment:offset address.
 - E:- To change the value in memory
 - G:- To execute
 - Q:- To quit

ALGORITHM:

1. START: Move the starting address of data segment to AX register and move the data from AX register to DS register.
2. Move 9H to AH register.
3. Calling int 21H with AH == 9 will display the contents from the offset stored in DX register.
4. Move the hexadecimal value 4C into AH register. INT 21H means invoke the interrupt identified by the hexadecimal number 21. In MS-DOS, invoking interrupt 21h while AH = 4Ch causes the current process to terminate and uses the value of register AL as the exit code of the process.

	Program	Comments
START:	MOV AX, DATA MOV DS, AX	Transferring the data from DATA to AX register and from AX register to DS register.
	MOV AH,9	DOS FUNCTION #9
	MOV DX, OFFSET MESSAGE	OFFSET OF THE STRING.
	MOV AH,4CH	Setup function-4C of the int21.
	INT 21H	Call BIOS int21 to return to DOS.

SNAPSHOT:

UNASSEMBLED CODE:

```
-u
076C:0000 B86A07      MOV     AX,076A
076C:0003 8ED8      MOV     DS,AX
076C:0005 B409      MOV     AH,09
076C:0007 BA0000      MOV     DX,0000
076C:000A CD21      INT     21
076C:000C B44C      MOV     AH,4C
076C:000E CD21      INT     21
076C:0010 F9      STC
076C:0011 B700      MOV     BH,00
076C:0013 D1E3      SHL     BX,1
076C:0015 BB87AE16    MOV     AX,[BX+16AE]
076C:0019 3B46FE      CMP     AX,[BP-02]
076C:001C 7709      JA     0027
076C:001E 8946FE      MOV     [BP-02],AX
```

SAMPLE I/O:

```
-g
Hey hello there!
Program terminated normally
```

Result:

Thus the 8086 programs for displaying string is executed successfully using DOS-BOX.

Exp No:11

Display system date and time

Name: Shreya Sriram
Register Number: 195001106
Date: 14/09/2021

AIM:

To write and execute 8086 programs for displaying system date and time.

PROCEDURE:

- Firstly, write the 8086 program using editor (like notepad) and save it with .asm(filename.asm) extension and move to the MASM folder.
 - Now mount the MASM folder in DOSBOX ("mount d e:/masm") and then enter into the mounted drive ("d:")
 - Now using "edit filename.asm", we can edit or create a asm file for execution and then save and exit.
 - Assemble the code using "masm filename.asm" to generate the "filename.obj" file.
 - Link the file using "link filename.obj;" to generate the executable "filename.exe" file.
 - Now enter the debug mode using "debug filename.exe" to execute and analyse memory contents. The various commands used in debug mode are as follows:-
 - U :- To display unassembled code
 - D :- Used as 'D segment:offset' to see the content of memory locations starting from segment:offset address.
 - E:- To change the value in memory
 - G:- To execute
 - Q:- To quit

ALGORITHM:

A) System date

1. START: Move the starting address of data segment to AX register and move the data from AX register to DS register.
2. Move 2ah to AH register.
3. Calling int 21H with 2a in AH register will return year in CX register, month in DH register, day in DL register and day of the week in AL register.
4. Move the offset of the variable DAY in SI register.
5. Move the contents stored in DL register to the location in SI register.
6. Move the offset of the variable MONTH in SI register.

7. Move the contents stored in DH register to the location in SI register.
8. Move the offset of the variable YEAR in SI register.
9. Move the contents stored in CX register to the location in SI register.
10. Move the hexadecimal value 4C into AH register. INT 21H means invoke the interrupt identified by the hexadecimal number 21. In MS-DOS, invoking interrupt 21h while AH = 4Ch causes the current process to terminate and uses the value of register AL as the exit code of the process.

	Program	Comments
START:	MOV AX, DATA MOV DS, AX	Transferring the data from DATA to AX register and from AX register to DS register.
	MOV AH, 2AH	AH <- 2AH
	INT 21H	INT 21h /AH=2Ah - get system date
	MOV SI, OFFSET DAY	SI <- DAY
	MOV [SI], DL	[SI] <- DL
	MOV SI, OFFSET MONTH	SI <- MONTH
	MOV [SI], DH	[SI] <- DH
	MOV SI, OFFSET YEAR	SI <- YEAR
	MOV [SI], CX	[SI] <- CX
	MOV AH,4CH	Setup function-4C of the int21.
	INT 21H	Call BIOS int21 to return to DOS.

SNAPSHOT:

UNASSEMBLED CODE:

```

-H
073F:0100 800D00    OR     BYTE PTR [DI],00
073F:0103 0B7379    OR     SI,[BP+DI+79]
073F:0106 7364      JNB    016C
073F:0108 61        DB     61
073F:0109 7465      JZ    0170
073F:010B 2E        CS:
073F:010C 61        DB     61
073F:010D 736D      JMB    017C
073F:010F FC        CLD
073F:0110 96        XCHG   SI,AX
073F:0111 0C00      OR     AL,00
073F:0113 0004      ADD    [SI],AL
073F:0115 44        INC    SP
073F:0116 41        INC    CX
073F:0117 54        PUSH   SP
073F:0118 41        INC    CX
073F:0119 0443      ADD    AL,43
073F:011B 4F        DEC    DI
073F:011C 44        INC    SP
073F:011D 45        INC    BP
073F:011E 21980700  AND    [BX+SI+0007],BX

```

SAMPLE I/O:

```

-d 076a:0000
076A:0000  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0010  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0020  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0030  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0040  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0050  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0060  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0070  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00
-g

Program terminated normally
-d 076a:0000
076A:0000  14 0A E4 07 00 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0010  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0020  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0030  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0040  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0050  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0060  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00
076A:0070  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00

```

B) System time

- START: Move the starting address of data segment to AX register and move the data from AX register to DS register.
- Move 2ch to AH register.
- Calling int 21H with 2c in AH register will return hour in CH register, minute in CL register and second in DH register.
- Move the offset of the variable HOUR in SI register.

- e. Move the contents stored in CH register to the location in SI register.
- f. Move the offset of the variable MINUTE in SI register.
- g. Move the contents stored in CL register to the location in SI register.
- h. Move the offset of the variable SECOND in SI register.
- i. Move the contents stored in DH register to the location in SI register.
- j. Move the hexadecimal value 4C into AH register. INT 21H means invoke the interrupt identified by the hexadecimal number 21. In MS-DOS, invoking interrupt 21h while AH = 4Ch causes the current process to terminate and uses the value of register AL as the exit code of the process.

	Program	Comments
START:	MOV AX, DATA MOV DS, AX	Transferring the data from DATA to AX register and from AX register to DS register.
	MOV AH, 2CH	AH <- 2CH
	INT 21H	INT 21h /AH=2Ch - get system date
	MOV SI, OFFSET HOUR	SI <- HOUR
	MOV [SI], DL	[SI] <- CH
	MOV SI, OFFSET MINUTE	SI <- MINUTE
	MOV [SI], DH	[SI] <- CL
	MOV SI, OFFSET SECOND	SI <- SECOND

MOV [SI], CX	[SI] <- DH
MOV AH,4CH	Setup function-4C of the int21.
INT 21H	Call BIOS int21 to return to DOS.

Unassembled code:

```
-u
076B:0100 B86A07      MOV     AX,076A
076B:0103 8ED8        MOV     DS,AX
076B:0105 B42C        MOV     AH,2C
076B:0107 CD21        INT     21
076B:0109 BE0000        MOV    SI,0000
076B:010C 882C        MOV    [SI],CH
076B:010E BE0100        MOV    SI,0001
076B:0111 880C        MOV    [SI],CL
076B:0113 BE0200        MOV    SI,0002
076B:0116 8834        MOV    [SI],DH
076B:0118 B44C        MOV    AH,4C
076B:011A CD21        INT     21
076B:011C FF7701        PUSH   [BX+01]
076B:011F 40          INC    AX
```

Sample I/O:

```
-d 076a:0000
076a:0000  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 ..... .
076a:0010  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 ..... .
076a:0020  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 ..... .
076a:0030  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 ..... .
076a:0040  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 ..... .
076a:0050  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 ..... .
076a:0060  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 ..... .
076a:0070  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 ..... .
-g

Program terminated normally
-d 076a:0000
076a:0000  14 0A 32 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 ..2..
076a:0010  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 ..... .
076a:0020  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 ..... .
076a:0030  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 ..... .
076a:0040  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 ..... .
076a:0050  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 ..... .
076a:0060  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 ..... .
076a:0070  00 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00 00 00 00 00 ..... .
```

Result:

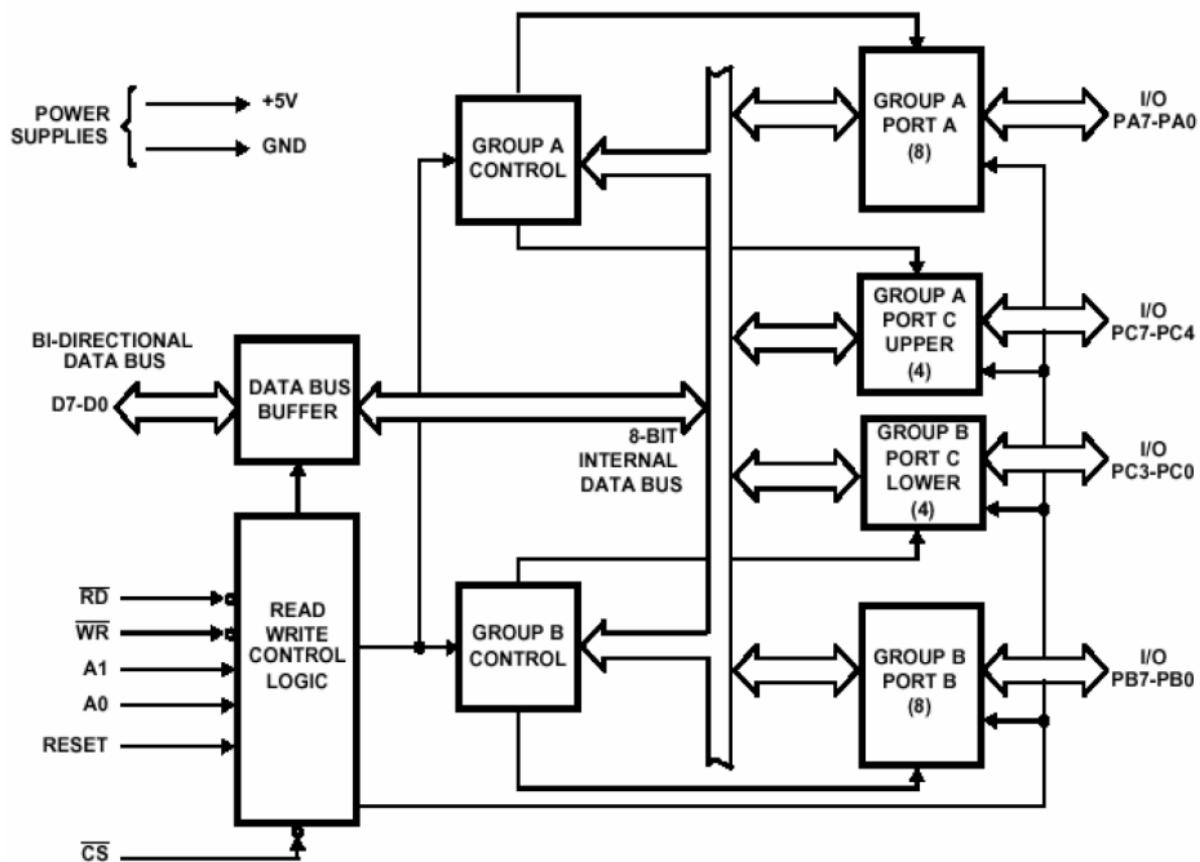
Thus the 8086 programs for displaying system date and time are executed successfully using DOS BOX.

Exp No:12

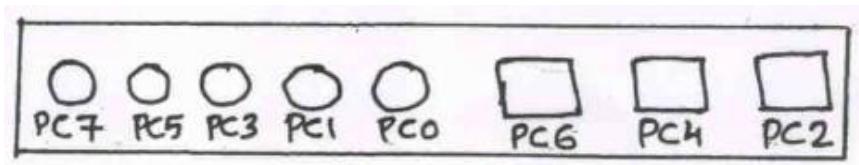
8255 Parallel Interface (PPI)

Name: Shreya Sriram
Register Number: 195001106
Date: 30/09/21

ARCHITECTURE DIAGRAM:



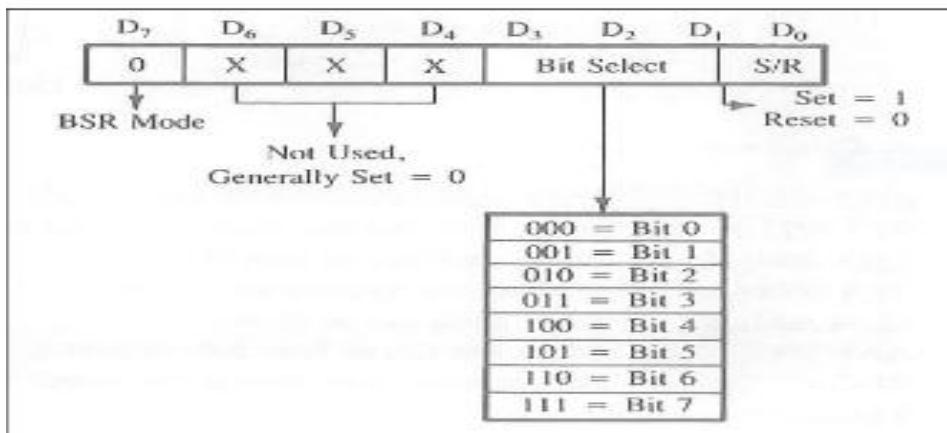
PORT C PATTERN IN BOARD:



PORT ADDRESSES:

PORT ADDRESS	
CONTROL REGISTER	C6
PORT A	C0
PORT B	C2
PORT C	C4

BSR mode control word



INPUT CONFIGURATION

D ₇	D ₆	D ₅	D ₄	D ₃	D ₂	D ₁	D ₀
I/O	I/O	IBFA	INTEA	INTR _A	INTEB	IBFB	INTR _B
GROUP A				GROUP B			

OUTPUT CONFIGURATIONS

D ₇	D ₆	D ₅	D ₄	D ₃	D ₂	D ₁	D ₀
OBF _A	INTE _A	I/O	I/O	INTR _A	INTE _B	OBF _B	INTR _B
GROUP A				GROUP B			

1. AIM:

To initialize Port A as an input port in mode-0

ALGORITHM:

- a) Move 1500 to SI
 - b) Move 90 to AL

- c) Move AL to C6(output)
- d) Move AL to C0 (input)
- e) Move AL to [SI]
- f) End code

PROGRAM:

<u>CODE</u>	<u>COMMENTS</u>
MOV SI,1500H MOV AL,90 OUT C6,AL IN AL,C0 MOV [SI],AL HLT	; Move 1500 to SI ; Move 90 to AL ; Move AL to C6(output) ; Move AL to C0 (input) ; Move AL to [SI] ; End code

2. AIM:

To initialize Port A as input port and Port B as output port in mode-0

ALGORITHM:

- a) Move 90 to AL
- b) Move AL to output port C6(control register)
- c) Move C0 to AL(Port A)
- d) Move AL to C2 (Port B)
- e) End code

PROGRAM:

<u>CODE</u>	<u>COMMENTS</u>
MOV AL,90H OUT C6,AL IN AL,C0 OUT C2,AL HLT	; Move 90 to AL ; Move AL to output port C6(control register) ; Move C0 to AL(Port A) ; Move AL to C2 (Port B) ; End code

3. AIM:

To initialize port C as output port in mode-0

ALGORITHM:

- a) Move 90 to AL
- b) Move AL to output port C6(control register)
- c) Move 80 to AL(Port A)
- d) Move AL to C2 (Port C)

e) End code

PROGRAM:

<u>CODE</u>	<u>COMMENTS</u>
MOV AL,90H	; Move 90 to AL
OUT C6,AL	; Move AL to output port C6(control register)
IN AL,80	; Move 80 to AL(Port A)
OUT C4,AL	; Move AL to C2 (Port C)
HLT	; End code

4. AIM:

To initialize Port C as an output port in mode-0 and to explain the bit set and reset feature of Port C

ALGORITHM:

- a) Move 80 to AL
- b) Move AL to output port C6(control register)
- c) Move 01 to AL
- d) Move AL to C4 (Port C)
- e) Move 07 to AL
- f) Move AL to Port C
- g) End code

PROGRAM:

<u>CODE</u>	<u>COMMENTS</u>
MOV AL,80H	; Move 80 to AL
OUT C6,AL	; Move AL to output port C6(control register)
MOV AL,01	; Move 01 to AL
OUT C4,AL	; Move AL to C4 (Port C)
MOV AL,07	; Move 07 to AL
OUT C4,AL	; Move AL to Port C
HLT	; End code

5. AIM:

To initialize Port C as an input port in Mode-0

ALGORITHM:

- a) Move 1200 to SI

- b) Move 99 to AL
- c) Move AL to C6(control register)
- d) Move AL to C4 (Port C)
- e) Move AL to [SI]
- f) End code**

PROGRAM:

<u>CODE</u>	<u>COMMENTS</u>
MOV SI,1200H MOV AL,99 OUT C6,AL IN AL,C4 MOV [SI],AL HLT	; Move 1200 to SI ; Move 99 to AL ; Move AL to C6(control register) ; Move AL to C4 (Port C) ; Move AL to [SI] ; End code

6. AIM:

To verify the working of 8255 in mode 1

ALGORITHM:

- a) Move 80 to AL
- b) Move AL to output port C6(control register)
- c) Move 01 to AL
- d) Move AL to C4 (Port C)
- e) Move 07 to AL
- f) Move AL to Port C
- g) End code**

PROGRAM:

<u>CODE</u>	<u>COMMENTS</u>
MOV AL,B4 OUT C6,AL READ: IN AL,C4 AND AL,20 JZ READ IN AL,C0 OUT C2,AL HLT	; Move 80 to AL ; Move AL to output port C6(control register) ; Move 01 to AL ; Move AL to C4 (Port C) ; Move 07 to AL ; Move AL to Port C ; End code

RESULT:

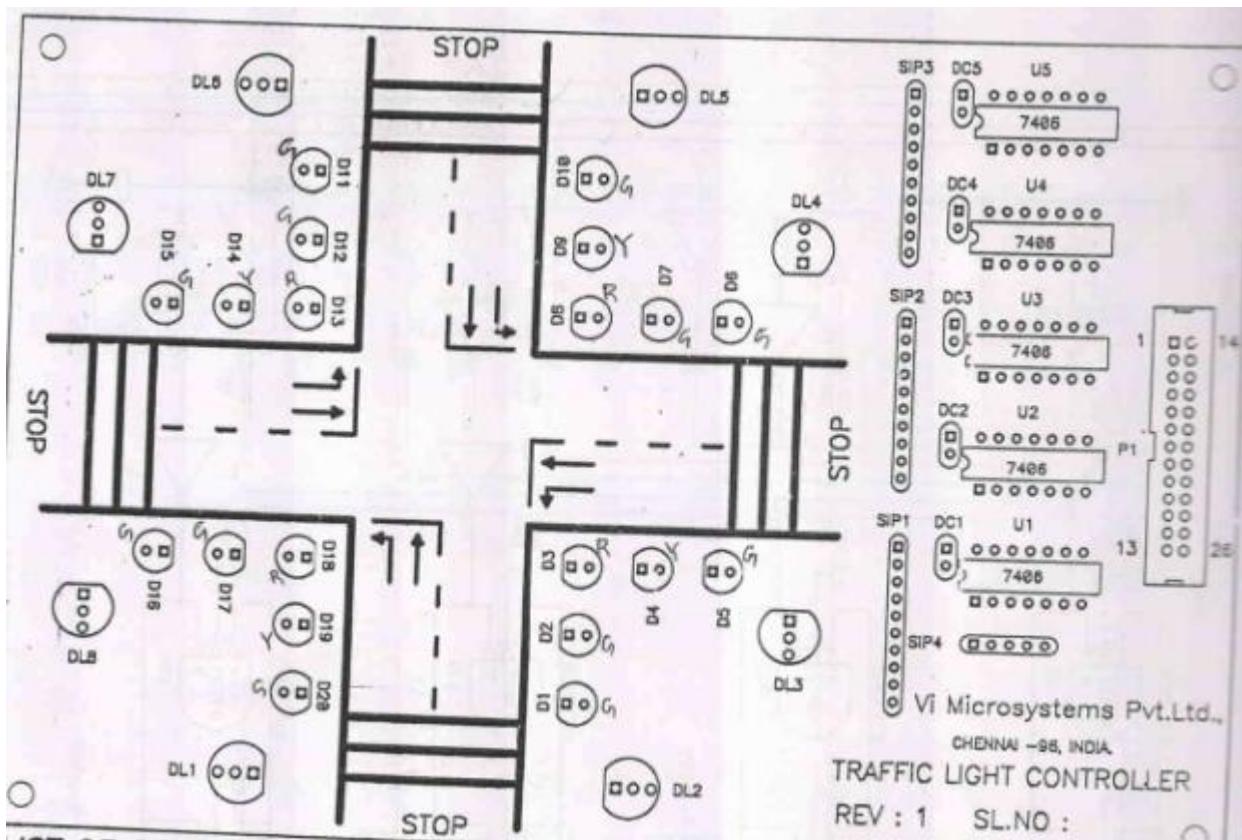
Parallel interface experiments are successfully implemented using 8255 interface

Exp No:13

Traffic Light Controller

Name: Shreya Sriram
Register Number: 195001106
Date: 30/09/21

BLOCK DIAGRAM:



POR TS:

PORT A

BITS	A7	A6	A5	A4	A3	A2	A1	A0
LEDS	D8	D7	D6	D5	D4	D3	D2	D1

PORT B

BITS	B7	B6	B5	B4	B3	B2	B1	B0
LEDS	D20	D19	D18	D17	DL7 DL8	DL5 DL6	DL3 DL4	DL1 DL2

PORt C:

BITS	C7	C6	C5	C4	C3	C2	C1	C0
LEDS	D16	D15	D14	D13	D12	D11	D10	D9

CONTROL WORD LOOKUP TABLE

12 > Port C 27 > Port B 44 > Port A Call Delay	Fig 1
48 > Port A Call Delay1	Fig 2
10 > Port C 2B > Port B 92 > Port A Call Delay	Fig 3
4B > Port B Call Delay1	Fig 4
10 > Port C 9D > Port B 84 > Port A Call Delay	Fig 5
20 > Port C Call Delay1	Fig 6
48 > Port C 2E > Port B 84 > Port A Call Delay	Fig 7
49 > Port C 04 > Port A Call Delay1	Fig 8

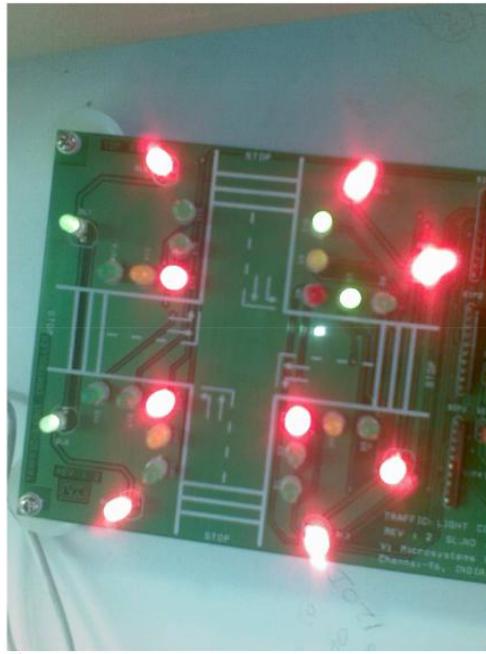


Fig 1

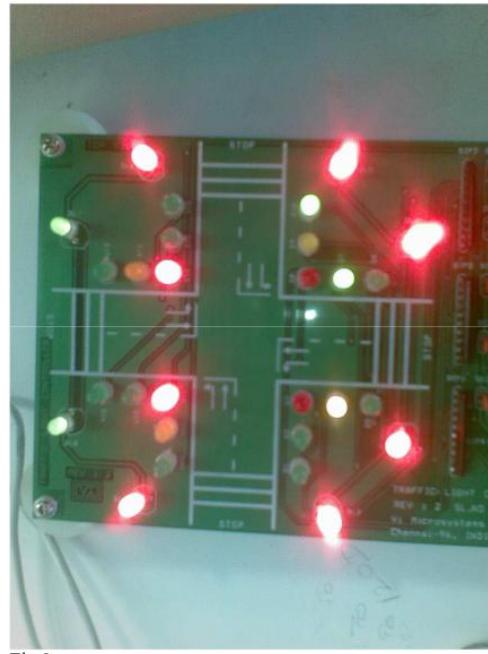


Fig 2

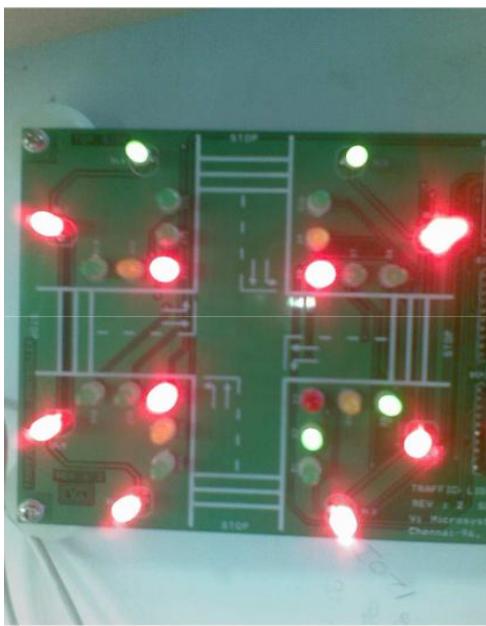


Fig 3

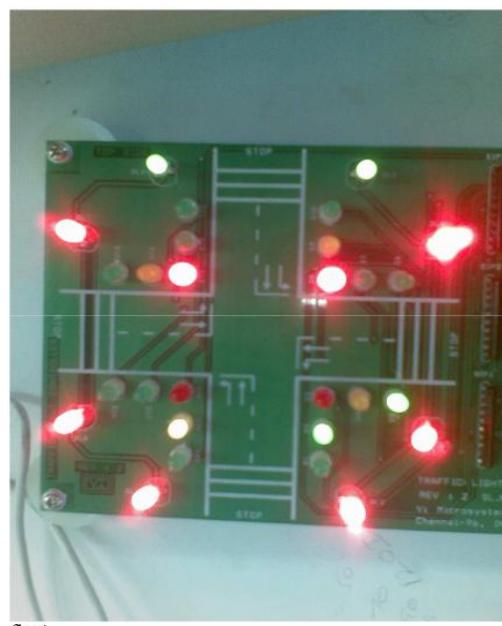


fig 4



fig 5

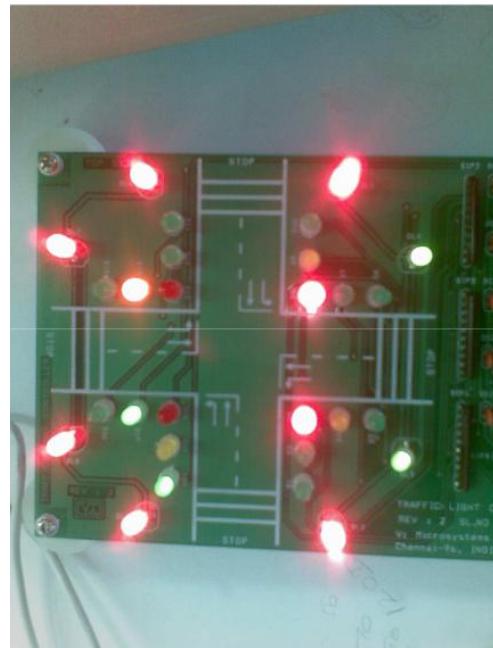


fig 6

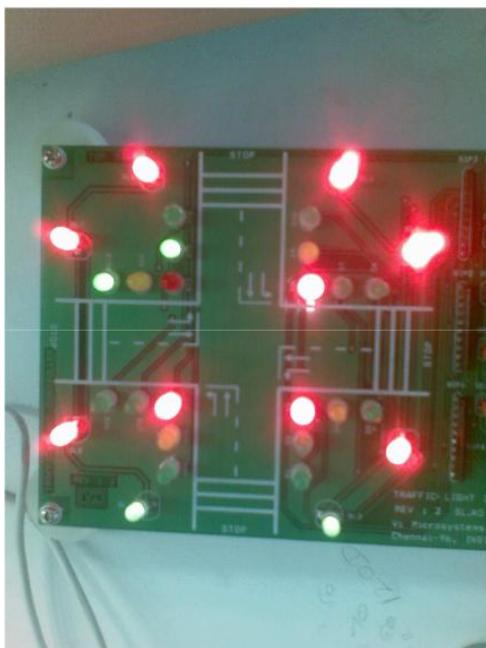


fig 7

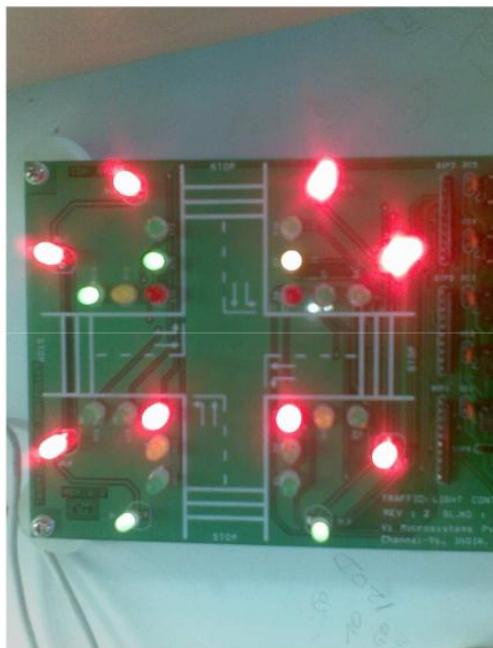


Fig 8

AIM:

To implement a traffic light controller by interfacing with an 8086 microprocessor.

ALGORITHM:

- 1) EQU Directive used to assign values to CNTL ,PORT A ,PORT B and PORT C
- 2) Move control word into AL
- 3) Output the content of AL into CNTL
- 4) Load the lookup table with values into BX
- 5) Move Label into SI
- 6) Jump to 13
- 7) Move SI ro AL
- 8) Output AL contents to PORT A
- 9) Call DELAY 1 routine
- 10) Increment SI and BX values
- 11) Repeat 7-10 for PORT B AND PORT C
- 12) Jump to 6
- 13) Output AL content to PORT C and increment BX
- 14) Move BX to AL
- 15) Output AL content to PORT B and increment BX
- 16) Move BX to AL
- 17) Output AL content to PORT A and increment BX
- 18) Return to after calling routine
- 19) Delay and Delay 1 defined
- 20) 40H move to DI
- 21) Move FFFFH to DX
- 22) Decrement DX till DX=0
- 23) Decrement till DI =0
- 24) Return to after calling routine
- 25) Load lookup table with the required values
- 26) STOP

PROGRAM:

ORG 1000H			
CNTRL	EQU	26H	
PORTA	EQU	20H	
PORTB	EQU	22H	
PORTC	EQU	24H	
1000 C6 C0 80	START:	MOV	AL,80H
1003 E6 26		OUT	CNTRL,AL
1005 C7 C3 73 10	REPEAT:	MOV	BX,LOOK UP
1009 C7 C6 7F 10		MOV	SI,LABEL
100D E8 33 00		CALL	OUT
1010 8A 04		MOV	AL,[SI]
1012 E6 20		OUT	PORTA,AL
1014 E8 4D 00		CALL	DELAY1
1017 46		INC	SI
1018 43		INC	BX
1019 E8 27 00		CALL	OUT
101C 8A 04		MOV	AL,[SI]
101E E6 22		OUT	PORTB,AL
1020 E8 41 00		CALL	DELAY1
1023 46		INC	SI
1024 43		INC	BX
1025 E8 1B 00		CALL	OUT
1028 8A 04		MOV	AL,[SI]
102A E6 24		OUT	PORTC,AL
102C E8 35 00		CALL	DELAY1
102F 46		INC	SI
1030 43		INC	BX
1031 E8 0F 00		CALL	OUT
1034 8A 04		MOV	AL,[SI]
1036 E6 24		OUT	PORTC,AL
1038 46		INC	SI
1039 8A 04		MOV	AL,[SI]
103B E6 20		OUT	PORTA,AL
103D E8 24 00		CALL	DELAY1
1040 E9 C2 FF		JMP	REPEAT
1043 8A 07	OUT:	MOV	AL,[BX]
1045 E6 24		OUT	PORTC,AL →
1047 43		INC	BX
1048 8A 07		MOV	AL,[BX]

104A	E6 22		OUT	PORTB,AL
104C	43		INC	BX
104D	8A 07		MOV	AL,[BX]
104F	E6 20		OUT	POR TA,AL
1051	E8 01 00		CALL	DELAY
1054	C3		RET	
1055	C7 C7 40 00	DELAY:	MOV	DI,00040H
1059	C7 C2 FF FF	A:	MOV	DX,0FFFFH
105D	4A	A1:	DEC	DX
105E	75 FD		JNZ	A1
1060	4F		DEC	DI
1061	75 F6		JNZ	A
1063	C3		RET	
1064	C7 C7 15 00	DELAY1:	MOV	DI,00015H
1068	C7 C2 FF FF	B:	MOV	DX,0FFFFH
106C	4A	B1:	DEC	DX
106D	75 FD		JNZ	B1
106F	4F		DEC	DI
1070	75 F6		JNZ	B
1072	C3		RET	
1073	12 27 44 10	LOOK UP:	DB	12H,27H,44H,10H
1077	2B 92 10 9D			2BH,92H,10H,9DH
107B	84 48 2E 84			84H,48H,2EH,84H
107F	48 4B 20 49	LABEL :	DB	48H,4BH,20H,49H
1083	04			04H
107C			END	

RESULT:

Traffic light controller has been successfully implemented

Exp No:14

Stepper Motor Interfacing

Name: Shreya Sriram
Register Number:195001106
Date: 07/10/21

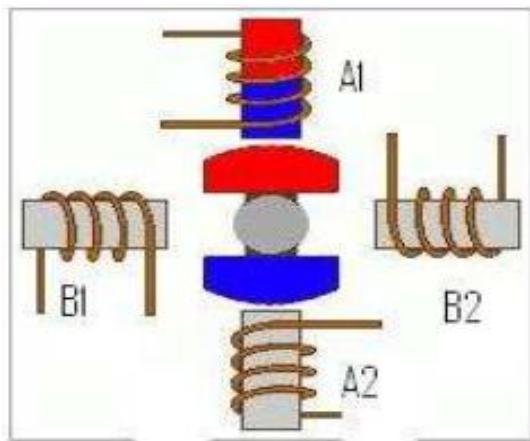
AIM:

To interface the stepper motor with 8086 and run in clockwise and anticlockwise directions

ALGORITHM:

- a) Move 1018 to D1
- b) Move 04 to CL
- c) Move address of DI to AL
- d) Move AL to C0
- e) Move 1010 to DX
- f) Decrement DX
- g) Jump to 100F if DX not zero
- h) Increment DI
- i) Loop to 1007
- j) Jump to start

DIAGRAM:



LOOKUP TABLE:

Address	For Clockwise Rotation	For Anticlockwise Rotation
1018	08	08
1019	01	02
101A	04	04
101B	02	01

Clock wise						Anticlock wise					
Step	A1	A2	B1	B2		Step	A1	A2	B1	B2	
1	1	0	0	0	8	1	1	0	0	0	8
2	0	0	0	1	1	2	0	0	1	0	2
3	0	1	0	0	4	3	0	1	0	0	4
4	0	0	1	0	2	4	0	0	0	1	1

PROGRAM:

CODE	COMMENTS
MOV DI,1018	; Move 1018 to D1
MOV CL,04	; Move 04 to CL
MOV AL,[DI]	; Move address of DI to AL
OUT C0,AL	; Move AL to C0
MOV DX,1010	; Move 1010 to DX
DEC DX	; Decrement DX
JNZ 100F	; Jump to 100F if DX not zero
INC DI	; Increment DI
LOOP 1007	; Loop to 1007
JMP 1000	; Jump to start

RESULT:

The stepper motor has been successfully interfaced with 8086 and made to run in clockwise and anticlockwise directions

Exp No:15

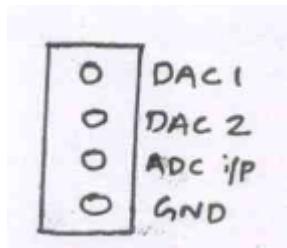
Wave Generation using DAC interface

Name: Shreya Sriram
Register Number: 195001106
Date: 07/10/21

INPUT OUTPUT TABLE

INPUT DATA IN HEX	O/P VOLTAGE(V)
00	-5
01	-4.96
.	.
.	.
7F	0
.	.
.	.
.	.
FE	4.96
FF	5

PIN CONNECTION IN BOARD



DATA ADDRESS REGISTER

DAC 1	CO
DAC 2	C8

a) AIM:

To generate a square wave at the output of DAC 2

ALGORITHM:

- Move 0 to AL
- Move AL to C8 (DAC2)

- c) Call line stored at 1010
- d) Move FF to AL
- e) Move AL to C8
- f) Call mov cx,05ff
- g) Jump to start
- h) Move 05FF to CX
- i) Loop statement 1013
- j) Return to main

PROGRAM:

<u>CODE</u>	<u>COMMENTS</u>
MOV AL,00	; Move 0 to AL
OUT C8,AL	; Move AL to C8 (DAC2)
CALL 1010	; Call line stored at 1010
MOV AL,FF	; Move FF to AL
OUT C8,AL	; Move AL to C8
CALL 1010	; Call mov cx,05ff
JMP 1000	; Jump to start
MOV CX,05FF	; Move 05FF to CX
LOOP 1013	; Loop statement 1013
RET	; Return

OUTPUT:



b) AIM:

To create a saw-tooth wave at the output of DAC 2

ALGORITHM:

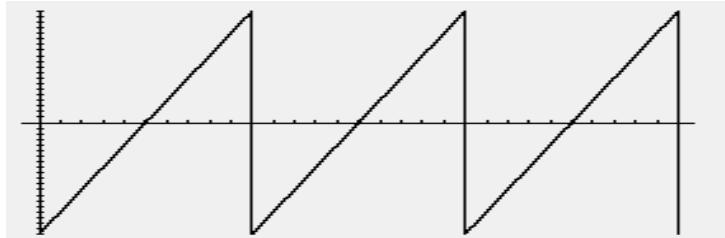
- a) Move 0 to AL
- b) Move AL to C8 (DAC2)
- c) Increment AL
- d) Jump to 1002 if not 0
- e) Jump to location 1000

PROGRAM:

<u>CODE</u>	<u>COMMENTS</u>
MOV AL,00	; Move 0 to AL
OUT C8,AL	; Move AL to C8 (DAC2)

INC AL	; Increment AL
JNZ 1002	; Jump to 1002 if not 0
JMP 1000	; Jump to location 1000

OUTPUT:



c) **AIM:**

To generate triangular waveform at DAC 2 output

ALGORITHM:

- a) Move 0 to BL
- b) Move BL to AL (DAC2)
- c) Move AL to C8
- d) Increment BL
- e) Jump to location 1002 from BL
- f) Move FF to BL
- g) Move BL to AL
- h) Move AL to C8
- i) Decrement BL
- j) Jump to 100C if BL is not zero
- k) Jump to location 1000

PROGRAM:

<u>CODE</u>	<u>COMMENTS</u>
MOV BL,00	; Move 0 to BL
MOV AL,BL	; Move BL to AL (DAC2)
OUT C8,AL	; Move AL to C8
INC BL	; Increment BL
JNZ 1002	; Jump to location 1002 from BL
MOV BL,FF	; Move FF to BL
MOV AL,BL	; Move BL to AL
OUT C8,AL	; Move AL to C8
DEC BL	; Decrement BL
JNZ 100C	; Jump to 100C if BL is not zero
JMP 1000	; Jump to location 1000

OUTPUT:



RESULT:

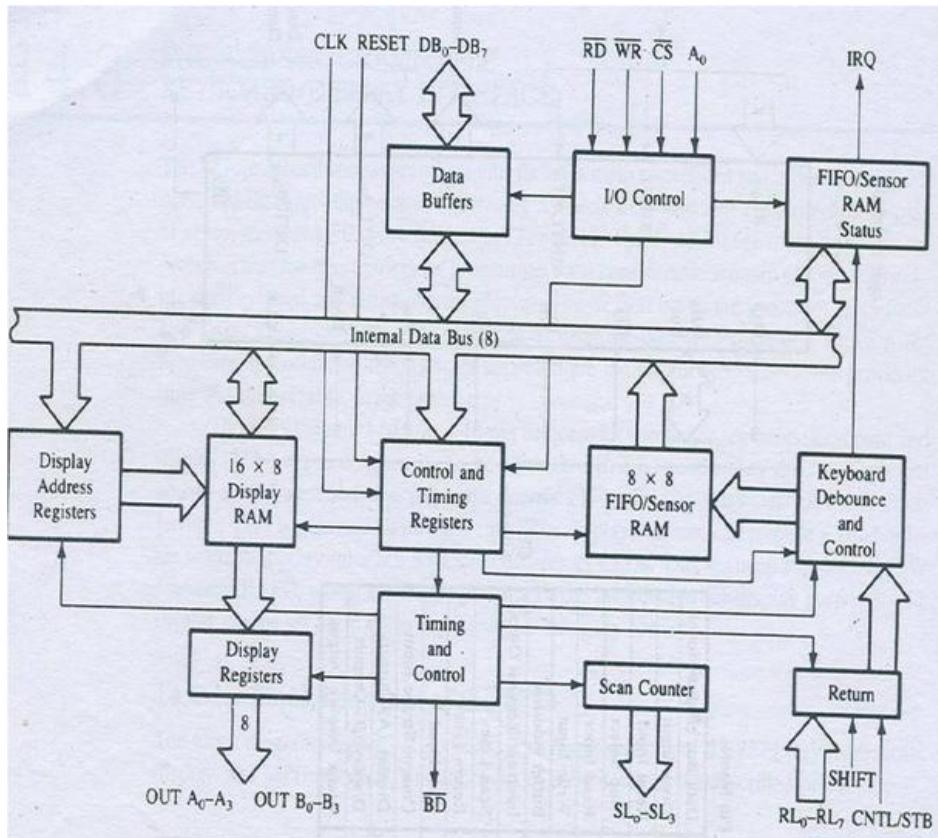
The waves are successfully generated using DAC interface

Exp No:16

Keyboard and Display Interface - 8279

Name: Shreya Sriram
Register Number:195001106
Date: 07/10/21

ARCHITECTURE DIAGRAM OF 8279:



KEYBOARD/DISPLAY MODE SET

	MSB		LSB					
Code:	0	0	0	D	D	K	K	K

DISPLAY MODE

DD

- 0 0 8 8-bit character display—Left entry
- 0 1 16 8-bit character display—Left entry*
- 1 0 8 8-bit character display—Right entry
- 1 1 16 8-bit character display—Right entry

KEYBOARD MODE

KKK

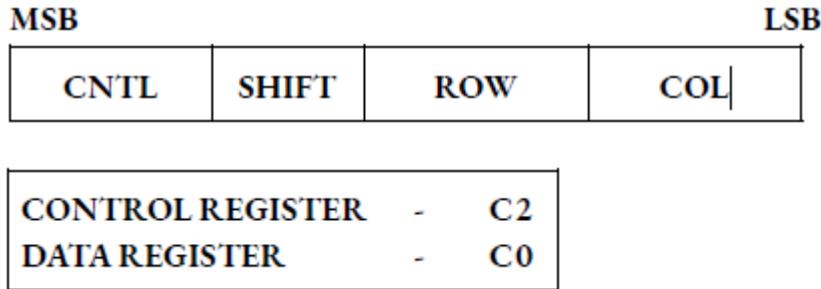
- 0 0 0 Encoded Scan Keyboard—2 Key Lock-out*
- 0 0 1 Decoded Scan Keyboard—2-Key Lock-out
- 0 1 0 Encoded Scan Keyboard—N-Key Roll-over
- 0 1 1 Decoded Scan Keyboard—N-Key Roll-over
- 1 0 0 Encoded Scan Sensor Matrix
- 1 0 1 Decoded Scan Sensor Matrix
- 1 1 0 Strobed Input, Encoded Display Scan
- 1 1 1 Strobed Input, Decoded Display Scan

KEYBOARD CONNECTION IN THE BOARD

Keyboard connection in the board								
	C ₀	C ₁	C ₂	C ₃	C ₄	C ₅	C ₆	C ₇
R ₀	0	1	2	3	4	5	6	7
R ₁	8	9	A	B	C	D	E	F

● CNTL ● SHIFT

KEYBOARD DATA FORMAT



AIM:

- a) Read a key from the keyboard and store in a memory location

ALGORITHM:

- a) Move 1100 to BX
 - b) Move control register contents to AL
 - c) Check if AL is equal to 7
 - d) Unless it is 7, goto loop
 - e) Move 40 to AL
 - f) Move AL to control register
 - g) Move contents of data register to AL
 - h) Move AL to address of BX
 - i) End

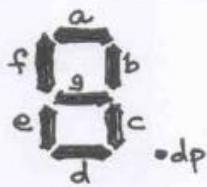
PROGRAM:

<u>CODE</u>	<u>COMMENTS</u>
MOV BX,1100 LOOP: IN AL,C2 TEST AL,07 JZ LOOP MOV AL,40 OUT C2,AL IN AL,C0 MOV [BX],AL HLT	; Move 1100 to BX ; Move control register contents to AL ; Check if AL is equal to 7 ; Unless it is 7, goto loop ; Move 40 to AL ; Move AL to control register ; Move contents of data register to AL ; Move AL to address of BX ; End

AIM:

- b) Roll the message “HELP US” in the display

Segment Definitions



DATA FORMAT:

D7	D6	D5	D4	D3	D2	D1	D0
d	c	b	a	dp	g	f	e

H	1001 1000	98
E	0110 1000	68
L	0111 1100	7C
P	1100 1000	C8
U	0001 1100	1C
S	0110 1001	29

ALGORITHM:

MAIN CODE:

- a) Set origin to 1000
- b) Move 1200 to SI
- c) Move 0F to CX
- d) Move AL to C2 port
- e) Move CC to AL
- f) Move AL to C2
- g) Move 90 to AL
- h) Move AL to C2
- i) Move SI to AL
- j) Move AL to C0
- k) Call delay function
- l) Increment SI
- m) Loop statement

DELAY FUNCTION:

- a) Move 03 to D1
- b) Move FFFF to DX
- c) Decrement DX
- d) If DX to not zero, jump to B1
- e) Decrement DI
- f) Jump to B if not zero
- g) Return to main

PROGRAM:

<u>CODE</u>	<u>COMMENTS</u>
ORG 1000H START: MOV SI,1200 MOV CX,000F OUT C2,AL MOV AL,CC OUT C2,AL MOV AL,90 OUT C2,AL NEXT: MOV AL,[SI] OUT C0,AL CALL DELAY INC SI LOOP NEXT JMP DELAY: MOV D1,0003 B: MOV DX,FFFF B1: DEC DX JNZ B1 DEC DI JNZ B RET	; Set origin to 1000 ; Move 1200 to SI ; Move 0F to CX ; Move AL to C2 port ; Move CC to AL ; Move AL to C2 ; Move 90 to AL ; Move AL to C2 ; Move SI to AL ; Move AL to C0 ; Call delay function ; Increment SI ; Loop statement Move 03 to D1 Move FFFF to DX Decrement DX If DX to not zero, jump to B1 Decrement DI Jump to B if not zero Return to main

RESULT:

The keyboard and display operations have been implemented successfully using 8279

Exp No:17

8 bit arithmetic operations using 8051

Name: Shreya Sriram
Register Number:195001106
Date: 19/10/21

AIM:

To perform 8 bit operations – addition, subtraction, multiplication, division using 8051

1) Addition

ALGORITHM:

- a) Move 0 to R0(represents carry)
- b) Move num1 to a
- c) Add num2 to a
- d) If no carry, move to label
- e) Else, increment carry
- f) Move a to dptr
- g) Mov R0 to a
- h) Increment dptr and move a to dptr

CODE:

MOV R0, #00	Move 0 to R0
MOV A, #FE	Move num1 to A
ADD A, #01	Move num2+num1 to A
JNC LABEL	Move to label if no carry
INC R0	Increment R0
LABEL: MOV DPTR, #4150	Move a location to dptr
MOVX @DPTR, A	Move a to the location
MOV A, R0	Move R0 to a
INC DPTR	Increment dptr
MOVX @DPTR, A	Move a to dptr
HERE: SJMP HERE	Jump here

OUTPUT:

A = FE

DPTR = 4150

[4150] = FF

[4151] = 0

2) Subtraction

ALGORITHM:

- a) Move 0 to R0(represents carry)
- b) Move num1 to a
- c) Subtract num2 from a and store in a
- d) If no carry, move to label
- e) Else, increment carry
- f) Complement a and increment a
- g) Move a to dptr
- h) Move R0 to a
- i) Increment dptr and move a to dptr

CODE:

MOV R0, #00	Move 0 to R0
MOV A, #FE	Move num1 to A
SUBB A, #01	Move num2-num1 to A
JNC LABEL	Move to label if no carry
INC R0	Increment R0
CPL A	Complement A
INC A	Increment A
LABEL: MOV DPTR, #4150	Move a location to dptr
MOVX @DPTR, A	Move a to the location
MOV A, R0	Move R0 to a
INC DPTR	Increment dptr
MOVX @DPTR, A	Move a to dptr
HERE: SJMP HERE	Jump here

OUTPUT:

A = FE

DPTR = 4150

[4150] = FD

[4151] = 0

3) Multiplication

ALGORITHM:

- a) Move num1 to a
- b) Move num2 to b
- c) Multiply ab
- d) Move a to dptr
- e) Increment dptr
- f) Move b to a
- g) Move a to dptr

CODE:

MOV R0, #00	Move 0 to R0
MOV A, #FE	Move num1 to A
MUL AB	Move num2*num1 to A
MOV DPTR, #4150	Move a location to dptr
MOVX @DPTR, A	Move a to the location
MOV A, R0	Move R0 to a
INC DPTR	Increment dptr
MOV A,B	Move b to a
MOVX @DPTR, A	Move a to dptr
HERE: SJMP HERE	Jump here

OUTPUT:

A = 03

B = 05

DPTR = 4150

[4150] = 0F

[4151] = 00

4) Division

ALGORITHM:

- a) Move num1 to a
- b) Move num2 to b
- c) Divide a and b and store in a
- d) Move a to dptr

- e) Increment dptr
- f) Move b to a
- g) Move a to dptr

CODE:

MOV R0, #00	Move 0 to R0
MOV A, #FE	Move num1 to A
DIV AB	Move num2/num1 to A
MOV DPTR, #4150	Move a location to dptr
MOVX @DPTR, A	Move a to the location
MOV A, R0	Move R0 to a
INC DPTR	Increment dptr
MOV A,B	Move b to a
MOVX @DPTR, A	Move a to dptr
HERE: SJMP HERE	Jump here

OUTPUT:

A = 0F

B = 07

DPTR = 4150

[4150] = 01

[4151] = 08

RESULT:

The 8 bit arithmetic operations are successfully implemented in 8051

Exp No:18

Cube of a number using 8051

Name: Shreya Sriram
Register Number:195001106
Date: 26/10/21

AIM:

To perform cube of a 8 bit number

ALGORITHM:

- a) Move num to A
- b) Move num to B
- c) Move the number to R0 (three copies of the number)
- d) Multiply A*B and store in A
- e) Clear B
- f) Move R0 to B
- g) Multiply A*B and store in A
- h) Move A to a location in external memory using DPTR
- i) Increment DPTR
- j) Move B to A (higher bits)
- k) Move A to DPTR

CODE:

MOV A, #03	Move num to A
MOV B, #03	Move num to B
MOV R0, #3	Move num to R0
MUL AB	Multiply A*B and store in A
CLR B	Clear B(higher bits)
MOV B, R0	Move R0 to B
MUL AB	Multiply A*B and store in A
MOV DPTR, #4150	Move a location to dptr
MOVX @DPTR, A	Move A to the location
INC DPTR	Increment dptr
MOV A,B	Move B to A
MOVX @DPTR, A	Move A to dptr
HERE: SJMP HERE	Jump here

OUTPUT:

```
A = 03
DPTR = 4150
[4150] = 1B
[4151] = 00
```

RESULT:

The cube of a number is performed and evaluated in 8051

Exp No:19

BCD to ASCII conversion using 8051

Name: Shreya Sriram
Register Number:195001106
Date: 26/10/21

AIM:

Perform 8 bit BCD to ASCII conversion using 8051

ALGORITHM:

- a) Move BCD number to A
- b) Move A to R0
- c) Perform A and F0, swap A to obtain lower nibble
- d) Move A to R1
- e) Move R0 to A
- f) Move 0 to R0
- g) Perform A and 0F to obtain the lower nibble
- h) Add 30 to A
- i) Move A to a external location using DPTR
- j) Move R1 to A
- k) Add 30 to A
- l) Increment DPTR
- m) Move A to DPTR
- n) Move A to DPTR

CODE:

MOV A,#23	Move bcd to A
MOV R0,A	Move the contents of A to R0
ANL A, #F0	Perform A and F0
SWAP A	Swap the upper and lower bits of A
MOV R1, A	Move A to R1
MOV A, R0	Move R0 to A
MOV R0, #00	Move 0 to R0
ANL A, #0F	Perform A and 0F
MOV R0, A	Move A to R0
MOV A, R0	Move R0 to A
ADD A,#30	Add 30 to A
MOV DPTR, #4150	Move a location to dptr
MOVX @DPTR, A	Move A to the location
MOV A, R1	Move R1 to A
ADD A,#30	Move 30 to A
INC DPTR	Increment dptr
MOVX @DPTR, A	Move A to dptr
HERE: SJMP HERE	Jump here

OUTPUT:

BCD = 23

DPTR = 4150

[4150] = 33

[4151] = 32

RESULT:

8 bit BCD to ASCII conversion is performed using 8051