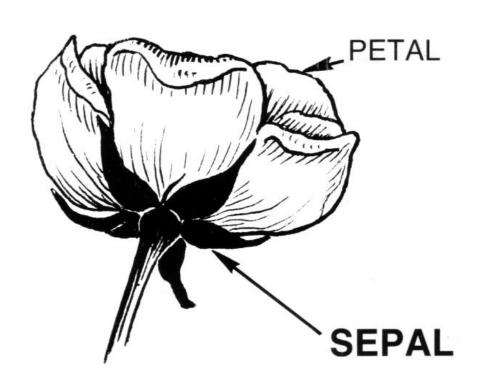
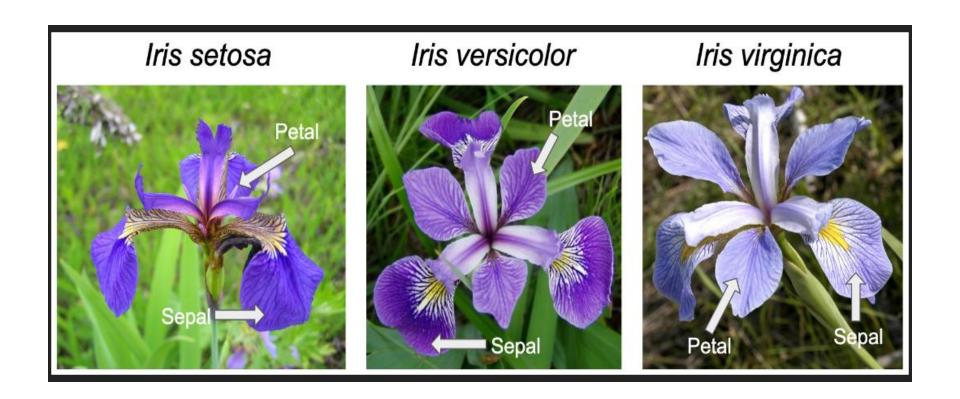
## **Example Iris Dataset**

The Iris dataset is a staple of machine learning. It contains a bunch of measurements for 150 flowers representing three species of iris. For each flower we have its petal length, petal width, sepal length, and sepal width, as well as its species. You can download it from https://archive.ics.uci.edu/ml/datasets/iris:





## **Example: The Iris Dataset**

```
import requests
data = requests.get( "https://archive.ics.uci.edu/ml/machine-
learningdatabases/ iris/iris.data")
with open('iris.dat', 'w') as f:
       f.write(data.txt)
   The data is comma-separated, with fields:
```

sepal\_length, sepal\_width, petal\_length, petal\_width, class

For example, the first row looks like:

5.1,3.5,1.4,0.2,Iris-setosa

### **Example: The Iris Dataset: Code Snippet**

Build a model that can predict the class (that is, the species) from the first four measurements. from typing import Dict import csv from collections import defaultdict def parse\_iris\_row(row: List[str]) -> LabeledPoint: sepal\_length, sepal\_width, petal\_length, petal\_width, class """ measurements = [float(value) for value in row[:-1]] # class is e.g. "Iris-virginica"; we just want "virginica" label = row[-1].split("-")[-1]return LabeledPoint(measurements, label) with open('iris.data') as f: reader = csv.reader(f) iris\_data = [parse\_iris\_row(row) for row in reader] # We'll also group just the points by species/label so we can plot them points\_by\_species: Dict[str, List[Vector]] = defaultdict(list) for iris in iris\_data:

points\_by\_species[iris.label].append(iris.point)

### **Example: The Iris Dataset Code Snippet**

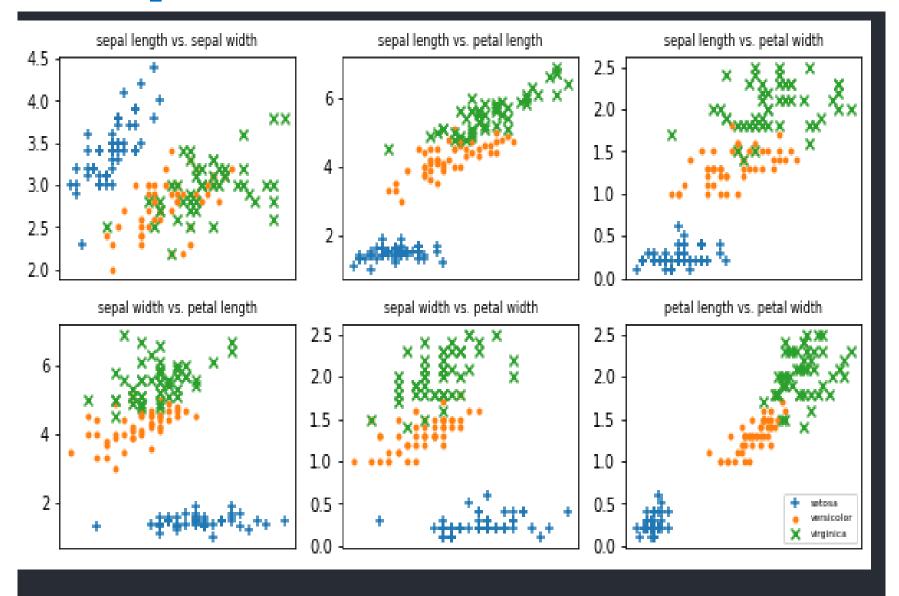
```
import random
from scratch.machine learning import split data
random.seed(12)
iris_train, iris_test = split_data(iris_data, 0.70)
assert len(iris_train) == 0.7 * 150
assert len(iris test) == 0.3 * 150
from typing import Tuple
# track how many times we see (predicted, actual)
confusion_matrix: Dict[Tuple[str, str], int] = defaultdict(int)
num correct = 0
for iris in iris test:
   predicted = knn_classify(5, iris_train, iris.point)
   actual = iris.label
   if predicted == actual:
           num correct += 1
   confusion_matrix[(predicted, actual)] += 1
pct correct = num correct / len(iris test)
print(pct correct, confusion matrix)
```

### **Example: The Iris Dataset: Code Snippet**

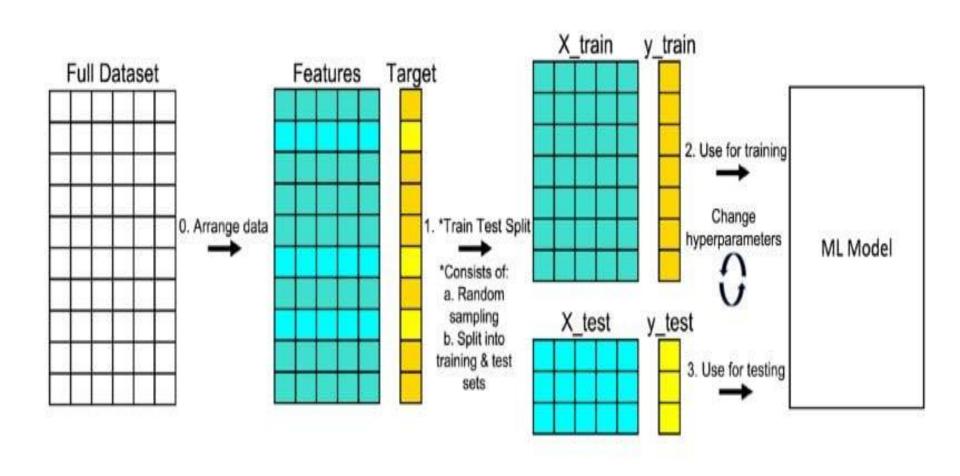
from matplotlib import pyplot as plt

```
metrics = ['sepal length', 'sepal width', 'petal length', 'petal width']
pairs = [(i, j) \text{ for } i \text{ in range}(4) \text{ for } j \text{ in range}(4) \text{ if } i < j]
marks = ['+', '.', 'x'] # we have 3 classes, so 3 markers
fig, ax = plt.subplots(2, 3)
for row in range(2):
   for col in range(3):
      i, j = pairs[3 * row + col]
       ax[row][col].set_title(f"{metrics[i]} vs {metrics[i]}", fontsize=8)
       ax[row][col].set_xticks([])
       ax[row][col].set vticks([])
      for mark, (species, points) in zip(marks,
       points_by_species.items()):
       xs = [point[i] for point in points]
       ys = [point[i] for point in points]
       ax[row][col].scatter(xs, ys, marker=mark, label=species)
ax[-1][-1].legend(loc='lower right', prop={'size': 6})
plt.show()
```

# **Example: The Iris Dataset**



# **Example: The Iris Dataset**



# KNN Implementation using Libraries

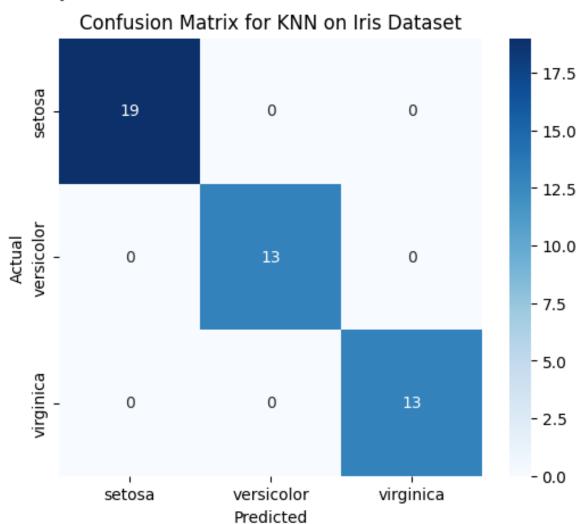
```
from sklearn.datasets import load iris
from sklearn.model selection import train test split
from sklearn.neighbors import KNeighborsClassifier
from sklearn.metrics import accuracy score, confusion matrix
import matplotlib.pyplot as plt
import seaborn as sns
# Step 1: Load the Iris dataset
iris = load iris()
X = iris.data # Features: sepal length, sepal width, etc.
y = iris.target  # Labels: 0=setosa, 1=versicolor, 2=virginica
target names = iris.target names
# Step 2: Split into train and test sets
X_train, X_test, y_train, y_test = train_test_split(X, y,
test size=0.3, random state=42)
```

# **KNN Implementation using Libraries**

```
# Step 3: Create and train KNN model
knn = KNeighborsClassifier(n neighbors=3)
knn.fit(X train, y train)
# Step 4: Predict
y pred = knn.predict(X test)
# Step 5: Accuracy and confusion matrix
acc = accuracy score(y test, y pred)
print(f"Accuracy: {acc:.2f}")
# Confusion Matrix
cm = confusion matrix(y test, y pred)
# Step 6: Visualize confusion matrix
plt.figure(figsize=(6, 5))
sns.heatmap(cm, annot=True, cmap="Blues", fmt='d',
            xticklabels=target names, yticklabels=target names)
plt.xlabel("Predicted")
plt.ylabel("Actual")
plt.title("Confusion Matrix for KNN on Iris Dataset")
plt.show()
```

# **Example: The Iris Dataset**

Accuracy: 1.00



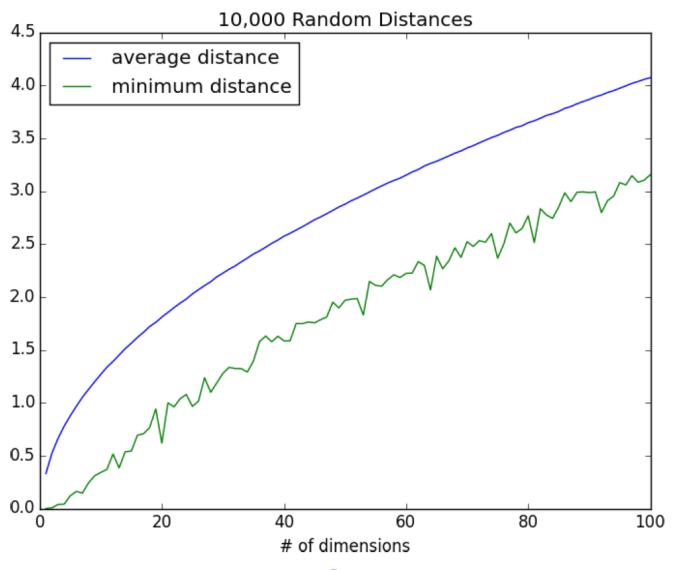
- The **curse of dimensionality** refers to a set of problems and challenges that arise when working with **high-dimensional data** (i.e., data with many features or variables)
- The k-nearest neighbors algorithm runs into trouble in higher dimensions.
  - ❖ Data Sparsity: In high-dimensional space, data points are very far apart. Models struggle to find patterns, and overfitting becomes likely.
  - **❖ Distance Metrics** Become Useless Algorithms
  - **❖ Computational Cost**: More features = more computations. High-dimensional data increases time complexity and memory usage for many algorithms.
  - **Overfitting** Risk Models can easily find patterns in high dimensions that are just noise.

- The **curse of dimensionality** refers to a set of problems and challenges that arise when working with **high-dimensional data** (i.e., data with many features or variables)
- The k-nearest neighbors algorithm runs into trouble in higher dimensions.
  - ❖ Data Sparsity: In high-dimensional space, data points are very far apart. Models struggle to find patterns, and overfitting becomes likely.
  - **❖ Distance Metrics** Become Useless Algorithms
  - **❖ Computational Cost**: More features = more computations. High-dimensional data increases time complexity and memory usage for many algorithms.
  - **Overfitting** Risk Models can easily find patterns in high dimensions that are just noise.

- One way to see this is by randomly generating pairs of points in the d-dimensional "unit cube" in a variety of dimensions, and calculating the distances between them.
- For every dimension from 1 to 100, we'll compute 10,000 distances and use those to compute the average distance between points and the minimum distance between points in each dimension.

 Generating random points should be second nature by now:

```
def random_point(dim: int) -> Vector:
          return [random.random() for _ in range(dim)]
def random_distances(dim: int, num_pairs: int) -> List[float]:
          return [distance(random_point(dim), random_point(dim)) for _ in
range(num_pairs)]
import tqdm
dimensions = range(1, 101)
avg_distances = []
min distances = []
random.seed(0)
for dim in tqdm.tqdm(dimensions, desc="Curse of Dimensionality"):
   distances = random_distances(dim, 10000) # 10,000 random pairs
   avg_distances.append(sum(distances) / 10000) # track the average
   min_distances.append(min(distances)) # track the minimum
```



- In low-dimensional datasets, the closest points tend to be much closer than average.
- But two points are close only if they're close in every dimension, and every extra dimension—even if just noise—is another opportunity for each point to be farther away from every other point.
- When you have a lot of dimensions, it's likely that the closest points aren't much closer than average, so two points being close doesn't mean very much.

- Naive Bayes is a family of simple probabilistic classifiers based on Bayes' Theorem, with a strong (naive) assumption of independence between features.
- Supervised Machine Learning

Bayes' Theorem:

$$P(A|B) = \frac{P(B|A) \cdot P(A)}{P(B)}$$

In the context of classification:

- P(A|B): Posterior probability of class A given features B
- P(B|A): Likelihood of features B given class A
- P(A): Prior probability of class A
- P(B): Evidence (overall probability of features B)

The "naive" assumption is that features are conditionally independent given the class.

- Types of Naive Bayes Classifiers
- **1. Gaussian Naive Bayes**: Assumes features follow a normal distribution. Used for continuous data.
- **2. Multinomial Naive Bayes**: Best for document classification, especially for discrete features (like word counts).
- **3. Bernoulli Naive Bayes**: Assumes binary features (e.g., whether a word exists in a document).

Domain	Use Case	
Marketing	Customer segmentation, email campaign response prediction	
Healthcare	Disease diagnosis based on symptoms	
Finance	Credit scoring, fraud detection	
E-commerce	Predicting customer churn, product recommendation	
Natural Language Processing (NLP)	Spam detection, sentiment analysis, topic categorization	

#### **Advanages**

- Fast and efficient, even on large datasets
- Works well with high-dimensional data (e.g., text)
- Performs well with small datasets and requires less training data
- Easy to interpret and implement

#### Limitations

- Assumes independence of features, which is rarely true in real data
- Struggles with correlated features (can lead to misleading probabilities)
- Poor performance with continuous variables unless assumptions are met (e.g., Gaussian distribution)

import math

```
data = [
  ([1, 1, 1], 'yes'),
  ([1, 1, 0], 'yes'),
  ([0, 1, 1], 'no'),
  ([1,0,0],'no')
def train_naive_bayes(data):
  class_counts = {'yes': 0, 'no': 0}
  feature_counts = {'yes': [0]*3, 'no': [0]*3}
  total\_docs = len(data)
  for features, label in data:
    class_counts[label] += 1
    for i, val in enumerate(features):
      feature_counts[label][i] += val
  return feature_counts, class_counts, total_docs
```

Naive Bayes def predict(features, feature\_counts, class\_counts, total\_docs): **results** = {} for c in class\_counts: log\_prob = math.log(class\_counts[c] / total\_docs) total\_in\_class = class\_counts[c] for i, val in enumerate(features):  $p = (feature\_counts[c][i] + 1) / (total\_in\_class + 2)$ if val == 1:  $\log_{prob} += math.log(p)$ else:  $\log_{prob} += math.log(1 - p)$ results[c] = log\_prob return results, max(results, key=results.get) **#Train and predict** feature\_counts, class\_counts, total\_docs = train\_naive\_bayes(data) probs, prediction = predict([1, 1, 0], feature\_counts, class\_counts, total\_docs) print("Log probabilities:", probs)

print("Prediction:", prediction)

```
from sklearn.naive_bayes import BernoulliNB
from sklearn.model_selection import train_test_split
from sklearn.metrics import accuracy_score, classification_report
# Sample dataset: [Fever, Cough, Fatigue], Label
data = [
 [1, 1, 1], # yes
  [1, 1, 0], # yes
  [0, 1, 1], # no
  [1,0,0] # no
labels = ['yes', 'yes', 'no', 'no']
# Split into training and test data (optional, here we'll just train and test on all)
X_{train} = data
y_train = labels
# Initialize and train the Naive Bayes classifier
model = BernoulliNB()
model.fit(X_train, y_train)
# Predict on the same data (for demonstration)
predictions = model.predict(X_train)
# Output results
print("Predictions:", predictions)
print("Accuracy:", accuracy_score(y_train, predictions))
print("Classification Report:\n", classification report(v train, predictions))
```

## Simple Linear Regression

- We have used the correlation function to measure the strength of the linear relationship between two variables.
- For most applications, knowing that such a linear relationship exists isn't enough.
- We'll want to understand the nature of the relationship.
- This is where we'll use simple linear regression.

$$correlation(x, y) = \frac{1}{n-1} \sum \left( \frac{x_i - \bar{x}}{s_x} \cdot \frac{y_i - \bar{y}}{s_y} \right)$$

- Recall that we were investigating the relationship between a DataSciencester user's number of friends and the amount of time the user spends on the site each day.
- Let's assume that you've considered that having more friends causes people to spend more time on the site.
- The VP of Engagement asks you to build a model describing this relationship.

$$y_i = \beta x_i + \alpha + \varepsilon_i$$

#### Where:

- y<sub>i</sub>: Minutes user i spends on the site per day.
- x<sub>i</sub>: Number of friends user i has.
- ε<sub>i</sub>: Error term.
- α: Intercept base time spent when number of friends is 0.
- β: Slope additional time spent for each new friend.

User	x = Friends	y = Minutes on Site
1	0	23
2	1	24
3	2	26
4	3	28
5	4	30

You can already see there's a clear linear trend.

### The Model: Program/Code Snippet

alpha = mean(y) - beta \* mean(x)

return alpha, beta

```
from typing import Tuple
from statistics import mean, stdev
                            correlation(x, y) = \frac{1}{n-1} \sum_{i=1}^{n} \left( \frac{x_i - \bar{x}}{s_x} \cdot \frac{y_i - \bar{y}}{s_y} \right)
from math import sqrt
def correlation(x, y):
    n = len(x)
    mean x, mean y = mean(x), mean(y)
    std x, std y = stdev(x), stdev(y)
     return sum((x_i - mean_x) * (y_i - mean_y) for x_i, y_i in zip(x, y)) / ((n -
1) * std x * std y)
least squares fit function calculates the best-fit line parameters, alpha
and beta.
beta (slope): How much y increases for every 1-unit increase in x.
alpha (intercept): The value of y when x = 0.
def least squares fit(x, y) -> Tuple[float, float]:
    beta = correlation(x, y) * stdev(y) / stdev(x)
```

# The Model: Program/Code Snippet

```
x = [0, 1, 2, 3, 4]
y = [23, 24, 26, 28, 30]
alpha, beta = least_squares_fit(x, y)
print(f"alpha = {alpha:.2f}, beta = {beta:.2f}")
```

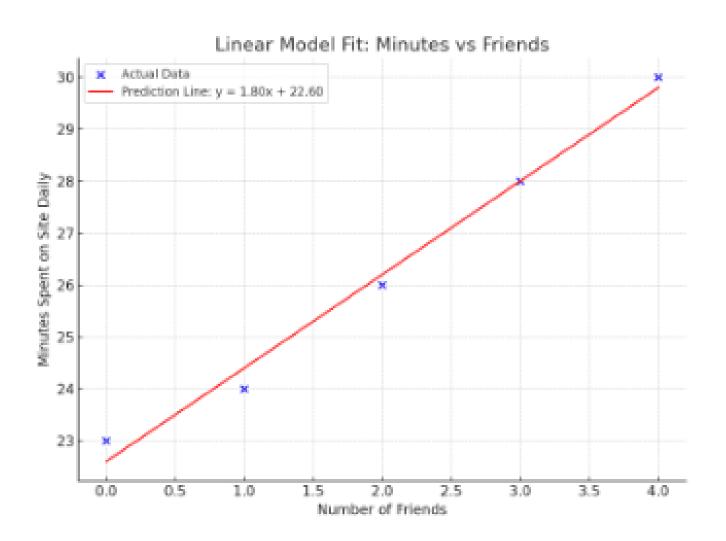
- alpha = 22.60, beta = 1.80
- What the Model Means
  - This gives us the model:
  - $\Rightarrow$  y=1.80x+22.60
  - ❖ A user with **0 friends** is predicted to spend **22 .60minutes/day**.
  - ❖ For **each additional friend**, they spend **1.80 more minutes/day**.

## The Model: Program/Code Snippet

Predicting how many minutes a user with **2 friends** will spend on the site

```
def predict(alpha, beta, x i):
    return beta * x_i + alpha
prediction = predict(22.60, 1., 2)
print(f"Predicted minutes: {prediction:.2f}")
error = prediction -26 \# = 0.5
sum of sqerrors function calculates the total squared error between your
model's predictions and the actual values in your dataset — also known as the sum
of squared errors (SSE).
def sum of sqerrors(alpha, beta, x, y):
    return sum((predict(alpha, beta, x_i) - y_i) ** 2 for x_i, y_i in zip(x, y))
sse = sum of sqerrors(alpha, beta, x, y)
```

print(f"Total Squared Error: {sse:.2f}")



**SE (Sum of Squared Errors)** and **R-squared (R<sup>2</sup>)** — two fundamental metrics in linear regression — to understand what each tells us about the quality of a model.

#### What is SSE (Sum of Squared Errors)?

#### Definition:

SSE measures the total squared difference between the actual values ( $y_i$ ) and the predicted values ( $\hat{y}_i$ ) from the model.

#### Formula:

$$SSE = \sum_{i=1}^{n} (y_i - \hat{y}_i)^2$$

#### Where:

- y<sub>i</sub> = actual value
- $\hat{y}_i$  = predicted value from the model
- n = number of data points

#### What it tells us:

- Lower SSE → Better model fit (smaller errors).
- Higher SSE → Worse model fit (larger prediction errors).

#### Definition:

R-squared measures the proportion of the variance in the dependent variable that is explained by the model. It's a relative measure.

#### Formula:

$$R^2 = 1 - \frac{\text{SSE}}{\text{TSS}}$$

#### Where:

- SSE = Sum of Squared Errors
- TSS = Total Sum of Squares

$$\mathrm{TSS} = \sum_{i=1}^n (y_i - \bar{y})^2$$

 $\bar{y}$  = mean of all  $y_i$ 

#### What it tells us:

- R<sup>2</sup> = 1 → Perfect fit: model explains 100% of the variance.
- R<sup>2</sup> = 0 → Model explains none of the variance (as good as just predicting the mean).
- Can be negative if the model is worse than predicting the mean.

#### from scratch.statistics import de\_mean

```
def de mean(data: Vector) -> Vector:
     x bar = mean(data)
     return [x i - x bar for x i in data]
def total_sum_of_squares(y: Vector) -> float:
    """the total squared variation of y_i's from their mean"""
    return sum(v ** 2 for v in de_mean(y))
def r_squared(alpha: float, beta: float, x: Vector, y: Vector) -> float:
    the fraction of variation in y captured by the model, which equals
    1 - the fraction of variation in y not captured by the model
    11 11 11
    return 1.0 - (sum_of_sqerrors(alpha, beta, x, y) /
    total_sum_of_squares(y))
rsq = r_squared(alpha, beta, num_friends_good, daily_minutes_good)
assert 0.328 < rsq < 0.330
```

Metric	SSE (Sum of Squared Errors)	R-squared
Туре	Absolute measure of error	Relative measure of fit
Goal	Minimize	Maximize
Range	$0$ to $+\infty$	$-\infty$ to $1$
Interpretability	Harder (depends on scale of data)	Easier (percentage of variance explained)
Use	Model tuning, optimization	Model evaluation and comparison

- SSE tells you how wrong your model's predictions are (in total squared units).
- R-squared tells you how well your model explains the variability in the data (as a percentage).

You typically minimize SSE during model training and report R-squared to evaluate or compare models.

### Maximum Likelihood Estimation (MLE).

#### Linear regression model:

$$y_i = \alpha + \beta x_i + \varepsilon_i$$
, where  $\varepsilon_i \sim \mathcal{N}(0, \sigma^2)$ 

That is, the errors (differences between actual and predicted values) are normally distributed with mean 0 and constant variance  $\sigma^2$ .

#### Goal:

Estimate  $\alpha$  and  $\beta$  based on observed data  $(x_1, y_1), \ldots, (x_n, y_n)$ .

Maximum Likelihood Estimation (MLE) is used in linear regression to estimate the model parameters (like the intercept  $\alpha$ , slope  $\beta$ , and possibly error variance  $\sigma^2$ ) because it provides a principled, probabilistic way to find the values that make the observed data most likely under the assumed model.

## Maximum Likelihood Estimation (MLE).

#### 1. Likelihood Function for One Data Point

Given one data point  $(x_i, y_i)$ , the probability of observing  $y_i$  given  $x_i$ ,  $\alpha$ , and  $\beta$ , under the assumption of normally distributed errors, is:

$$L(lpha,eta\mid x_i,y_i,\sigma)=rac{1}{\sqrt{2\pi\sigma^2}}\exp\left(-rac{(y_i-lpha-eta x_i)^2}{2\sigma^2}
ight)$$

This expression tells us how *likely* the observed  $y_i$  is, given a predicted value  $\alpha + \beta x_i$  and a known error variance  $\sigma^2$ .

- $L(\alpha, \beta \mid x_i, y_i, \sigma)$ : This is the **likelihood function** — the probability (density) of observing the data point  $(x_i, y_i)$  given the parameters  $\alpha$ ,  $\beta$ , and  $\sigma$ .
- α:
   The intercept of the linear regression model. It represents the expected value of y when x = 0.
- $\beta$ : The **slope** of the regression line. It measures the change in y for a unit change in x.
- ullet  $x_i$ : The **input (independent variable)** value for the  $i^{
  m th}$  observation.
- y<sub>i</sub>:
   The output (dependent variable) value for the i<sup>th</sup> observation.
- σ:
   The standard deviation of the normally distributed errors. It reflects the variability of the observations around the regression line.

### Maximum Likelihood Estimation (MLE).

•  $\frac{1}{\sqrt{2\pi\sigma^2}}$ :

This is the **normalization constant** of the normal distribution. It ensures that the total area under the probability density function equals 1.

•  $\exp\left(-\frac{(y_i-\alpha-\beta x_i)^2}{2\sigma^2}\right)$ :

This is the **exponential part** of the normal distribution. It decreases as the squared difference between the observed value  $y_i$  and the predicted value  $\alpha + \beta x_i$  increases.

#### 2. Likelihood of the Whole Dataset

Assuming the data points are independent, the likelihood for the entire dataset is the **product** of the individual likelihoods:

$$L(\alpha, \beta) = \prod_{i=1}^{n} \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(y_i - \alpha - \beta x_i)^2}{2\sigma^2}\right)$$