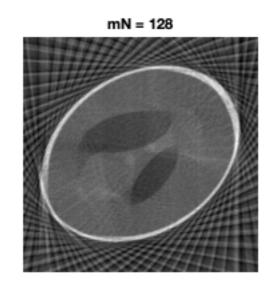
Tomography under unknown angles

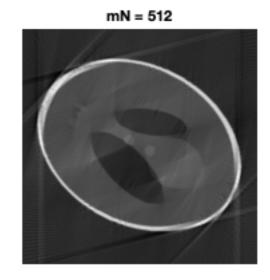
Shreyas Pimpalgaonkar 160050024

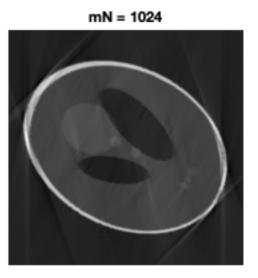
- Graph Laplacians
- SLLE different weight measurements
- Nearest Neighbour without dimensionality reduction
- Unknown Shifts with/without noise

Variation with number of angles







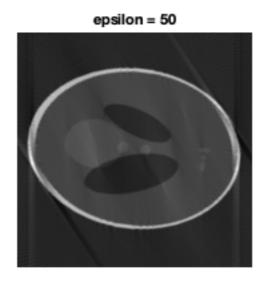


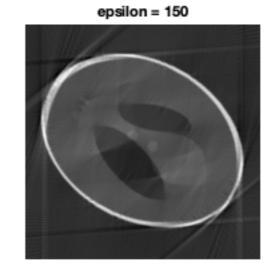
mN = projection angles, N = reconstruction angles, m = redundancy factor

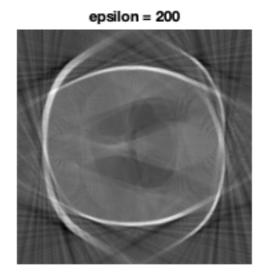
Better reconstruction with more angles

Variation with epsilon

epsilon = 1

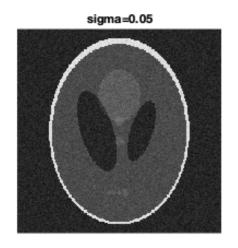


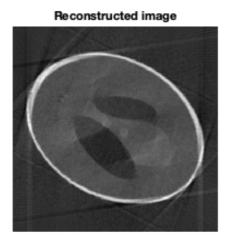


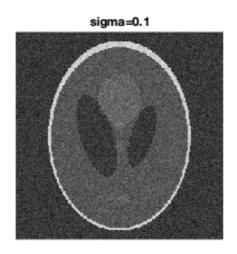


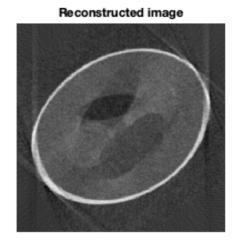
$$W_{ij} = k \left(\frac{\|\boldsymbol{x}_i - \boldsymbol{x}_j\|^2}{2\varepsilon} \right), \quad i, j = 1, \dots, N$$

Variation with noise level

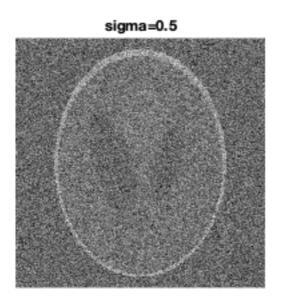


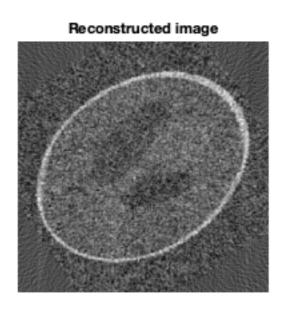






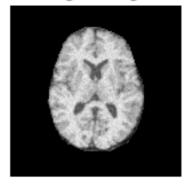
Able to reconstruct with large noise



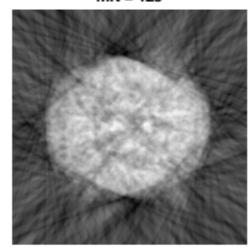


Testing on Brain image

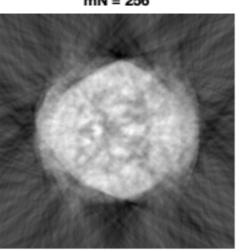
Original image



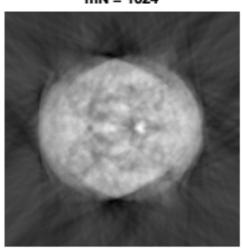
mN = 128



mN = 256

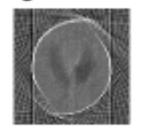


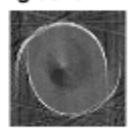
mN = 1024

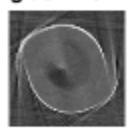


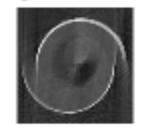
Variation with K and Angles

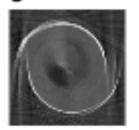
angles=32 K=1 angles=64 K=1 angles=128 K=1 angles=256 K=1 angles=512 K=1





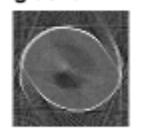


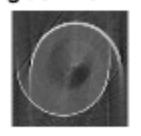


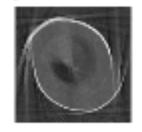


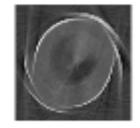
angles=32 K=10 angles=64 K=10 angles=128 K=10 angles=256 K=10 angles=512 K=10



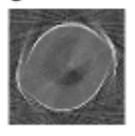


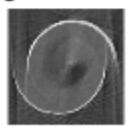


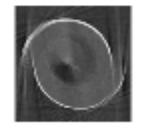


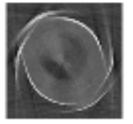


angles=64 K=50 angles=128 K=50 angles=256 K=50 angles=512 K=50

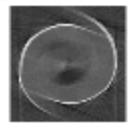


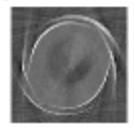


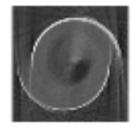




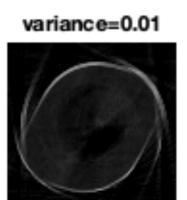
angles=128 K=100angles=256 K=100angles=512 K=100

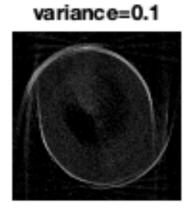


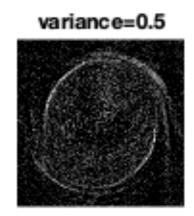


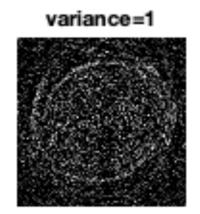


Variation with noise

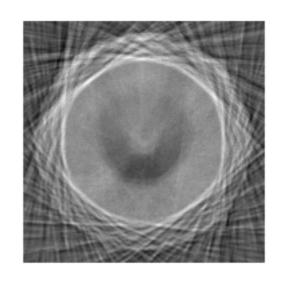








Ordering based approach



Unknown shifts

Sinogram with random shifts per angle for some range



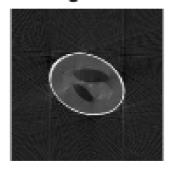


Normalised sinogram





range = 10



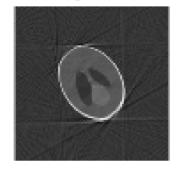


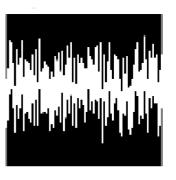
Normalised sinogram





range = 50



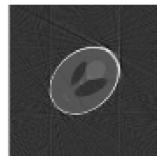


Normalised sinogram





range = 100



Under noise

Sinogram of moving image, variance = 0.1

Normalised sinogram

range = 20

Reduce noise in projections
Patch based PCA on every projection