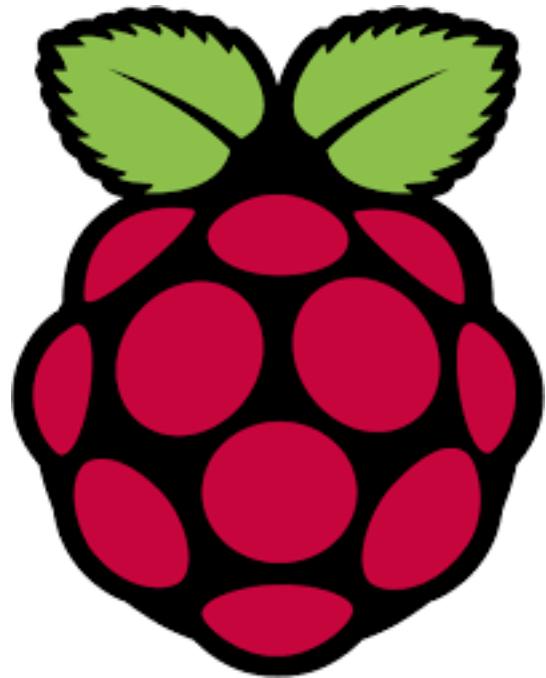


Raspberry Pi Training



Dr. Vinay Chamola, Assistant Professor, EEE Department, BITS-Pilani

Agenda

- Introduction
- Pin Diagram
- Setup
- SSH
- RealVNC
- Wireless remote access
- Running program on Pi
- LED blink
- LED PWM

What is Rpi

- The **Raspberry Pi** is a series of small single-board computers developed in the United Kingdom by the Raspberry Pi Foundation to promote the teaching of basic computer science in schools and in developing countries.
- The original model became far more popular than anticipated, selling outside its target market for uses such as robotics.
- It does not include peripherals (such as keyboards, mice and cases). However, some accessories have been included in several official and unofficial bundles.

History

- In 2006, early concepts of the Raspberry Pi were based on the Atmel ATmega644 microcontroller. Its schematics and PCB layout are publicly available. Foundation trustee Eben Upton assembled a group of teachers, academics and computer enthusiasts to devise a computer to inspire children.
- The Model A, Model B and Model B+ names are references to the original models of the British educational BBC Micro computer, developed by Acorn Computers.

Rpi Boards

Rpi 3 model B



Rpi 2 model B



Rpi 1 model B+



Rpi Zero W



Rpi Zero



Rpi Industrial Compute module 3

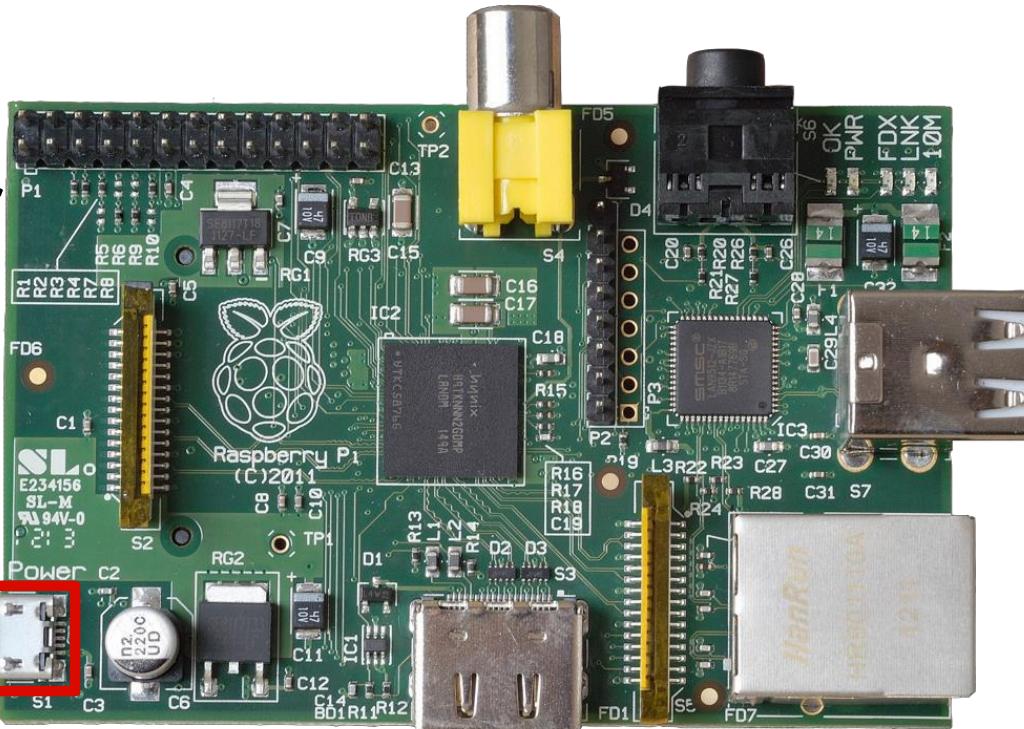
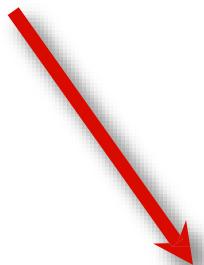


Why RPi

- Very Low Cost
- Great tool for **Learning Programming**, Computers & Concepts of **Embedded Linux**, etc
- Support for **all Age Groups** (School Children, College Undergraduates, Professional Developers, Programmers)
- Supports & runs **Free and Open Source Linux OS**
- Consumes **less than 5W** of Power
- Supports **Full HD Video Output (1080p)**, **Multiple USB Ports** ,etc
- Fun to learn & explore. You are limited by your imagination

Power

5v micro
USB connector

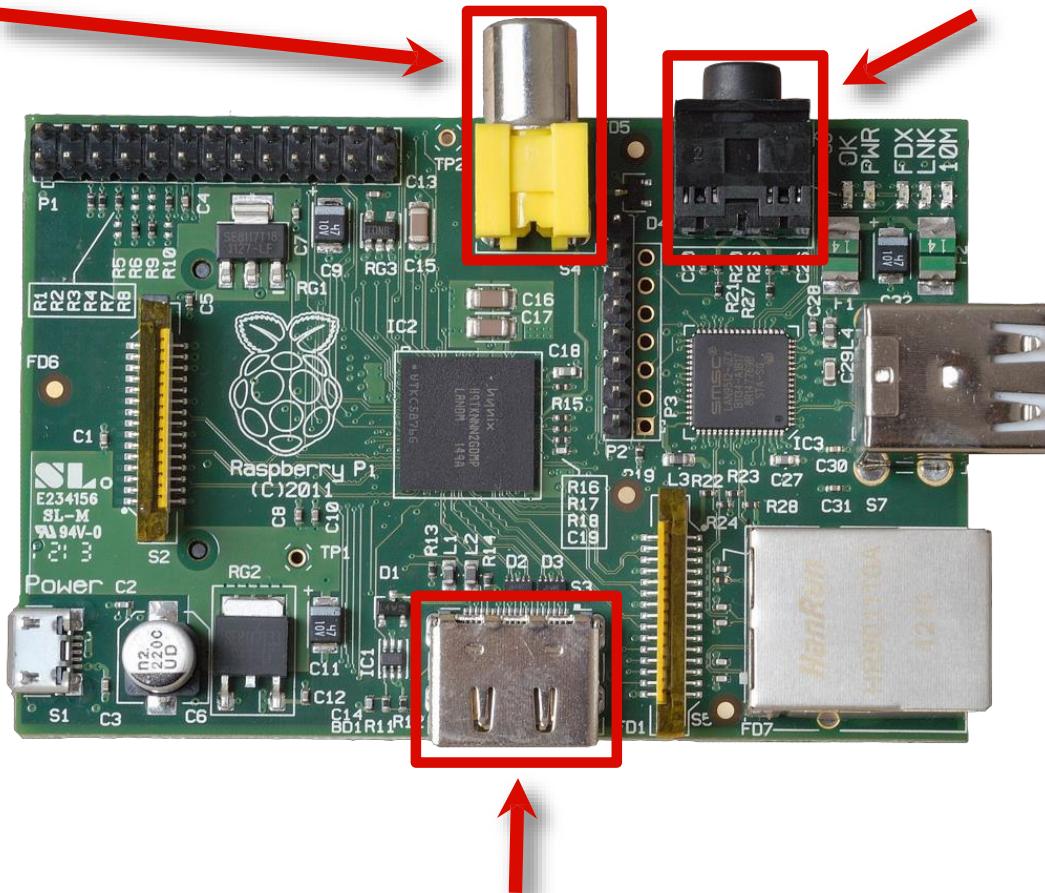


(Similar to the one on a lot of mobile phones!)

A/V (Audio/Video)

RCAVideo
(works with most
older TVs)

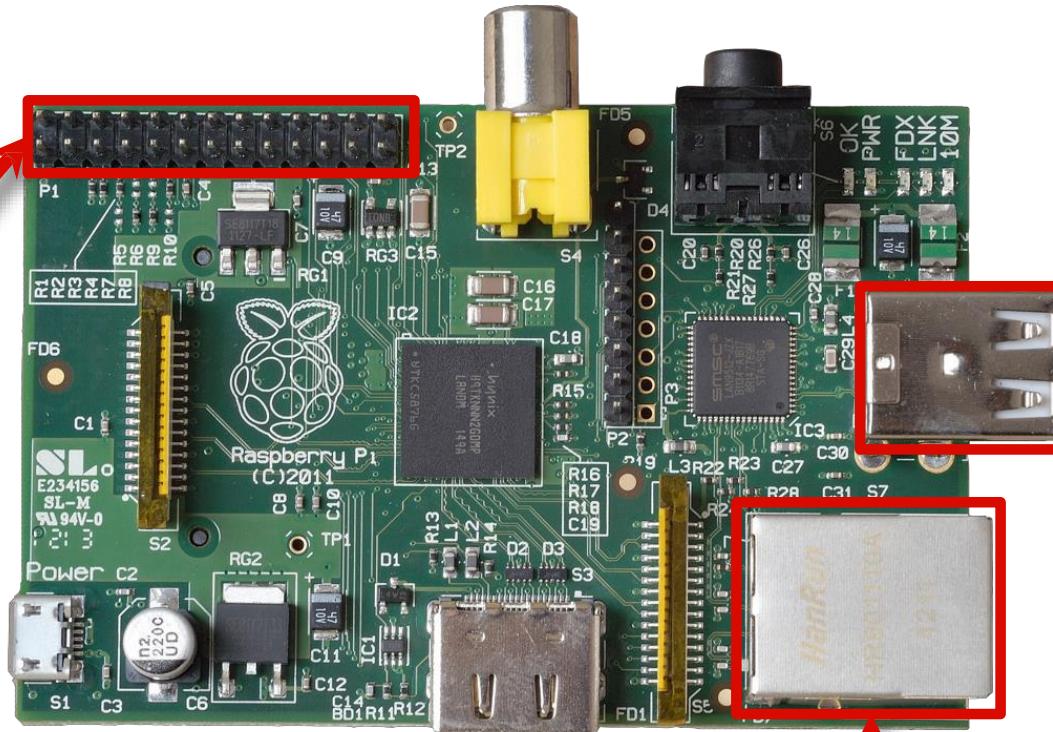
3.5mm Audio
Standard
headphone
socket



HDMI Audio & Video

Connectivity

GPIO
(General
Purpose
Input &
Output)

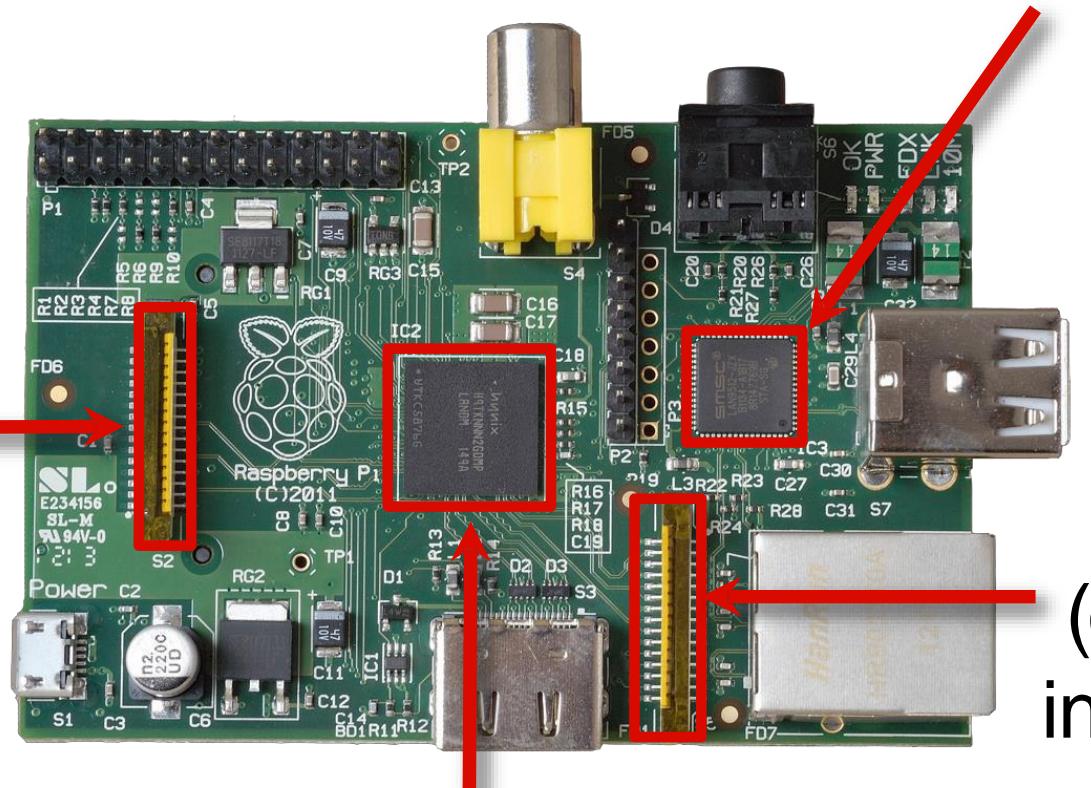


4 x USB 2.0
ports

Internals

LAN Controller

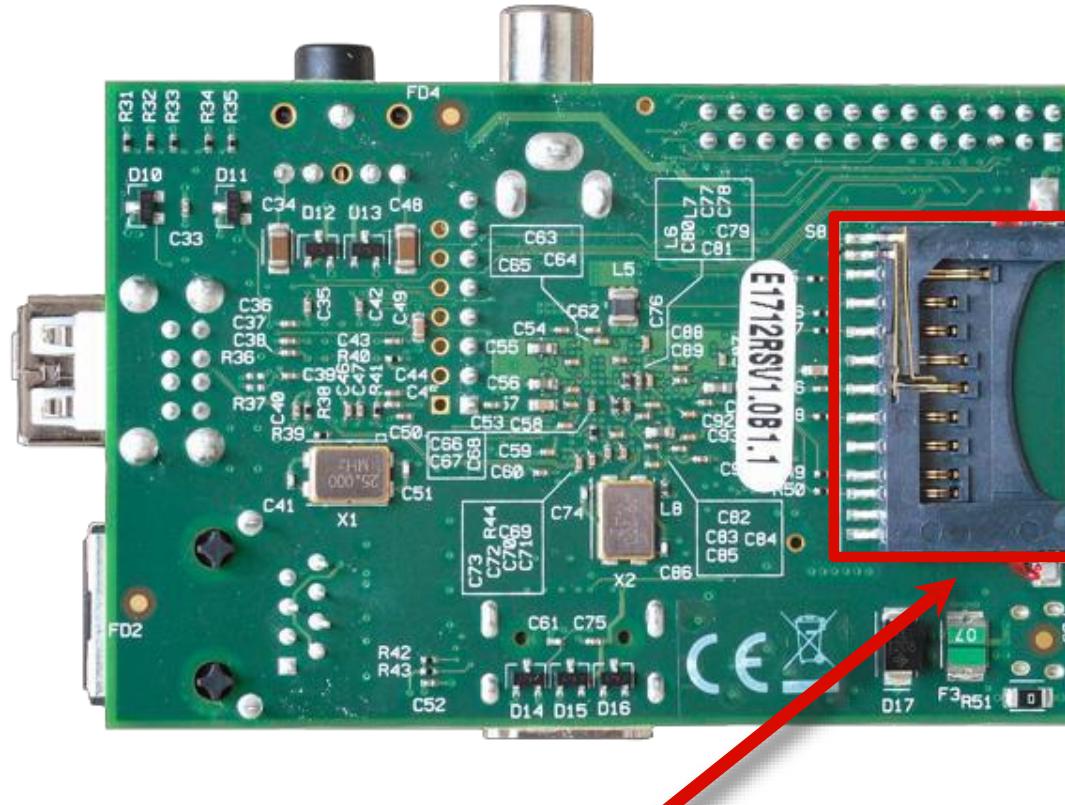
DSI
(display
interface)



CSI
(camera
interface)

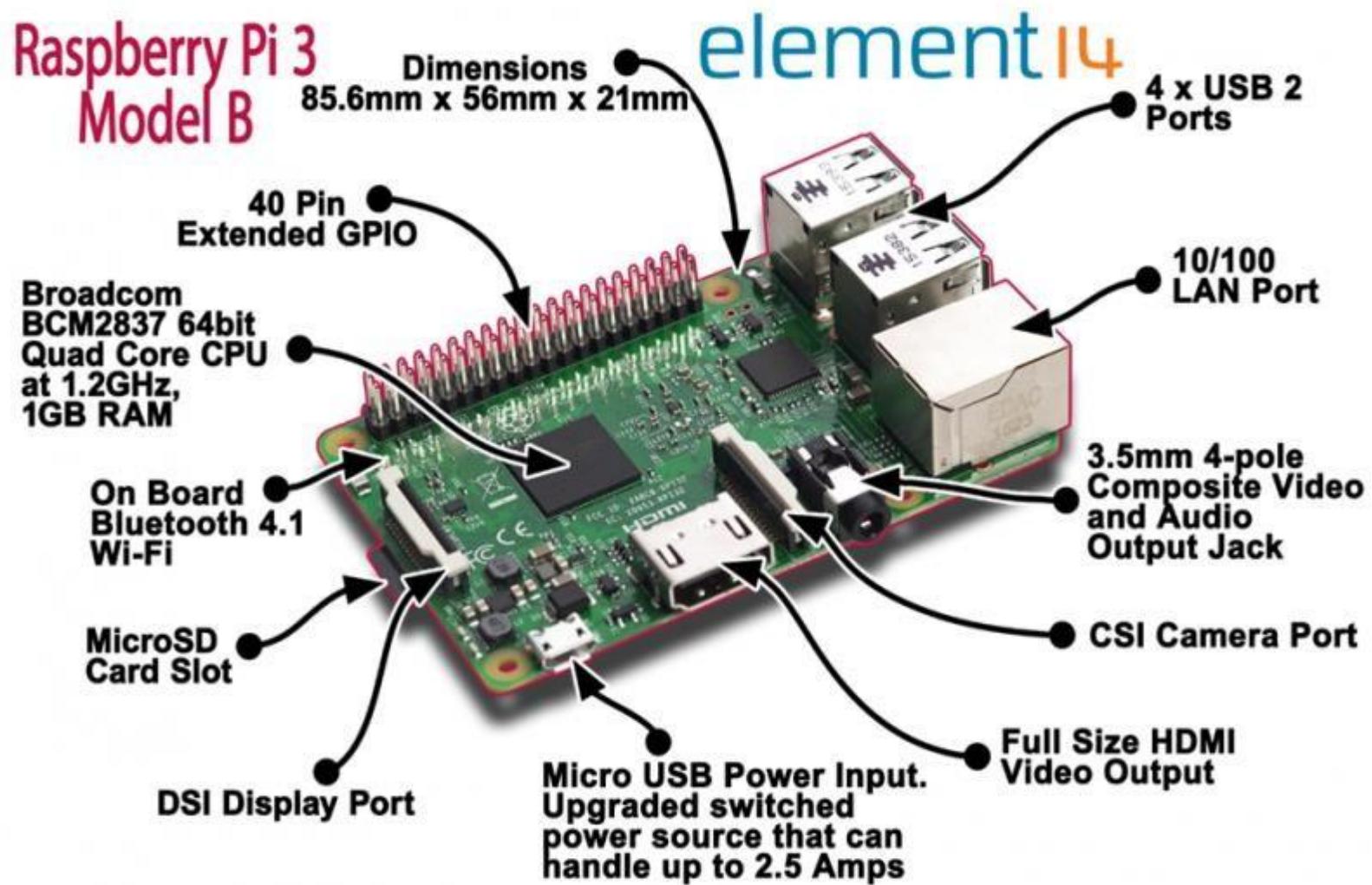
SOC(System On a Chip)
Broadcom BCM2835 700Mhz

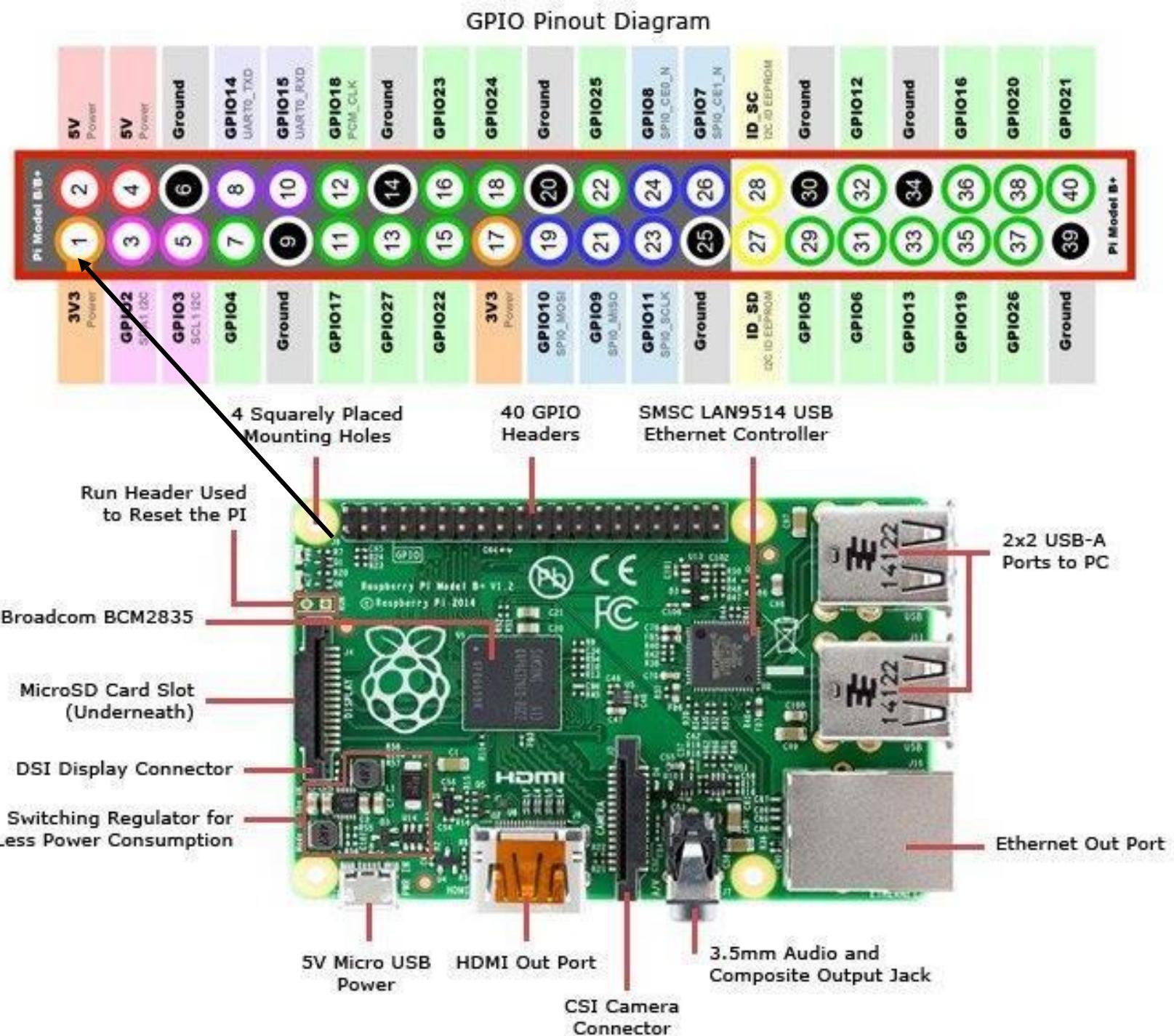
Storage



SDCard Slot
(supports SDcards up to 32GB)

Rpi 3 Module B



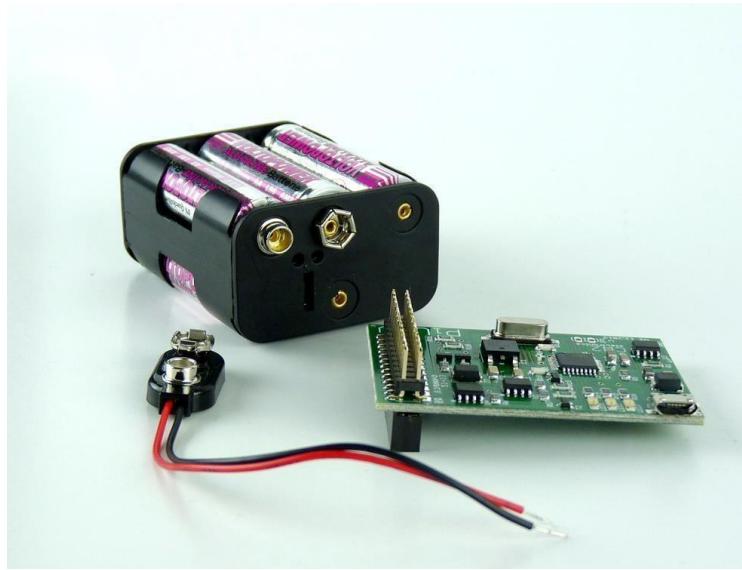
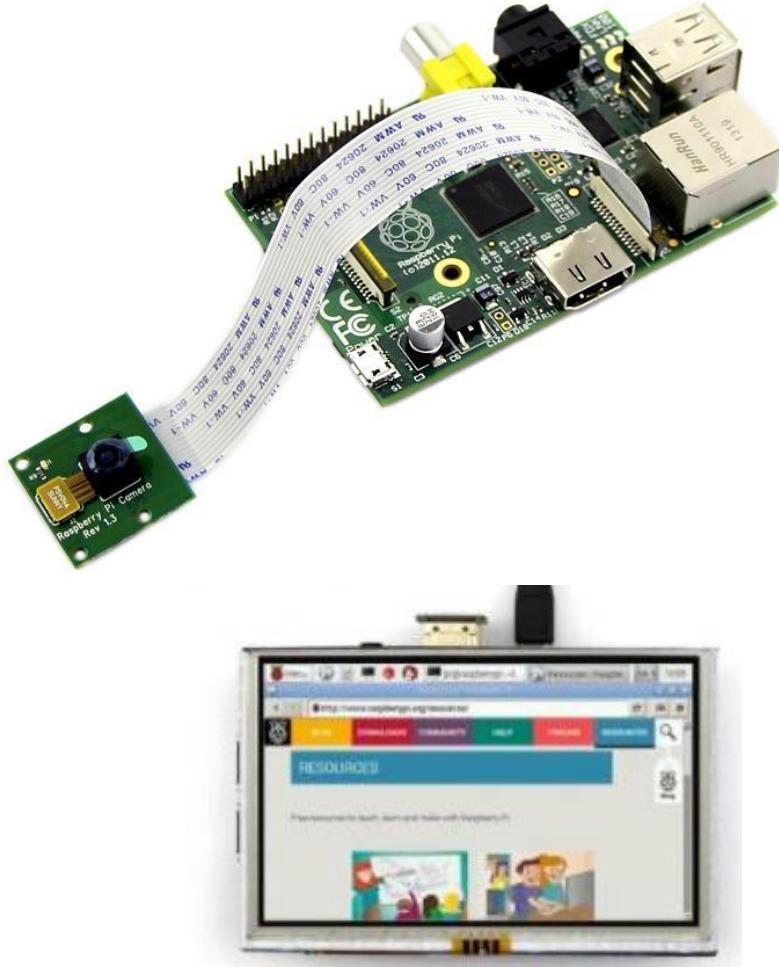


Raspberry Pi 3 Model B (J8 Header)

| GPIO# | NAME | NAME | GPIO# |
|-------|----------------------|--------------------|-------|
| | 3.3 VDC Power | 5.0 VDC Power | |
| 8 | GPIO 8 SDA1 (I2C) | 5.0 VDC Power | |
| 9 | GPIO 9 SCL1 (I2C) | Ground | |
| 7 | GPIO 7 GPCLK0 | Ground | 15 |
| | | GPIO 15 TxD (UART) | |
| 0 | GPIO 0 | Ground | 16 |
| 2 | GPIO 2 | Ground | |
| 3 | GPIO 3 | 3.3 VDC Power | 1 |
| 12 | GPIO 12 MOSI (SPI) | GPIO 5 | 4 |
| 13 | GPIO 13 MISO (SPI) | Ground | 5 |
| 14 | GPIO 14 SCLK (SPI) | Ground | 6 |
| | | GPIO 10 CE0 (SPI) | 10 |
| 30 | SDA0 (I2C ID EEPROM) | Ground | 11 |
| 21 | GPIO 21 GPCLK1 | Ground | 12 |
| 22 | GPIO 22 GPCLK2 | Ground | 24 |
| 23 | GPIO 23 PWM1 | Ground | 26 |
| 24 | GPIO 24 PCM_FS/PWM1 | Ground | 27 |
| 25 | GPIO 25 | Ground | 28 |
| | | GPIO 28 PCM_DIN | 29 |
| 39 | 37 | 35 | 36 |
| | | 33 | 38 |
| | | 31 | 40 |
| | | 29 | 29 |
| | | 27 | 29 |
| | | 25 | 29 |
| | | 23 | 29 |
| | | 21 | 29 |
| | | 19 | 29 |
| | | 17 | 29 |
| | | 15 | 29 |
| | | 13 | 29 |
| | | 11 | 29 |
| | | 9 | 29 |
| | | 7 | 29 |
| | | 5 | 29 |
| | | 3 | 29 |
| | | 1 | 29 |
| | | 2 | 29 |

Attention! The GPIO pin numbering used in this diagram is intended for use with WiringPi / Pi4J. This pin numbering is not the raw Broadcom GPIO pin numbers.

Add-ons



Handle with care

- The Raspberry Pi was built to be used, but not abused. Every P.C.B. should be handled with care.
- **Handle the Pi only by the edges** of the board itself. **Avoid touching or holding** any of the components on the board.
- **Rough Handling** can cause solder points to fail and may result in **short circuits**, but be careful with the **GPIO pins** as well. Best practice: Use the Rpi Case
- While connecting Hardware, double check the connections and then power it up. Raspberry Pi GPIO's are **not 5V tolerant**.

Ground

- The Ground pins on the Raspberry Pi are all electrically connected, so it doesn't matter which one you use if you're wiring up a voltage supply.
- Generally the one that's most convenient or closest to the rest of your connections is tidier and easier, or alternatively the one closest to the supply pin that you use.

WiringPi

- WiringPi is an attempt to bring Arduino-wiring-like simplicity to the Raspberry Pi.
- The goal is to have a single common platform and set of functions for accessing the Raspberry Pi GPIO across multiple languages. WiringPi is a C library at heart, but it's available to both Ruby and Python users who can "gem install wiringpi" or "pip install wiringpi2" respectively.
- WiringPi uses its own pin numbering scheme.

Setting up Raspberry pi (NOOBssetup)

- **How to get and install NOOBS?**
- **BUY PREINSTALLED SD CARD**
- 1. SDcards with NOOBSpreinstalled are available from many distributors and independent retailers, such as [Pimoroni](#), [Adafruit](#) and [The Pi Hut](#). For older models of Raspberry Pi, you'll need a full-size SDcard; for the Pi Zero, A+, B+, Pi 2 and Pi 3 you'll need a micro SDcard.
- **DOWNLOAD**
 1. recommended to use an SDcard with a minimum capacity of 8GB.
 2. Using a computer with an SDcard reader, visit the [Downloads](#) page.
 3. Click on **NOOBS**, then click on the Download ZIP button under 'NOOBS (offline and network install)', and select a folder to save it to.
 4. Extract the files from the zip.

Contd....

- **FORMAT YOUR SD CARD**

1. It is best to format your SDcard before copying the NOOBSfiles onto it.
To do this:
2. Visit the [SDAssociation's website](#) and download [SDFormatter 4.0](#) for either Windows or Mac.
3. Follow the instructions to install the software.
4. Insert your SDcard into the computer or laptop's SDcard reader and make a note of the drive letter allocated to it, e.g. G:/
5. In SDFormatter, select the drive letter for your SDcard and format it.

Contd... .

- **DRAG AND DROP NOOBS FILES**
 1. Once your SDcard has been formatted, drag all the files in the extracted NOOBSfolder and drop them onto the SDcard drive.
 2. The necessary files will then be transferred to your SDcard.
 3. When this process has finished, safely remove the SDcard and insert it into your Raspberry Pi.

Contd....

- **FIRST BOOT**
 1. Plug in your keyboard, mouse, and monitor cables.
 2. Now plug the USBpower cable into your Pi.
 3. Your Raspberry Pi will boot, and a window will appear with a list of different operating systems that you can install. We recommend that you use Raspbian – tick the box next to Raspbian and click on Install.
 4. Raspbian will then run through its installation process. Note that this can take a while.
 5. When the install process has completed, the Raspberry Pi configuration menu (`raspi-config`) will load. Here you are able to set the time and date for your region, enable a Raspberry Pi camera board, or even create users. You can exit this menu by using **Tab** on your keyboard to move to **Finish**.



2

Programming



Office

> BlueJ Java IDE

> Geany Programmer's Editor

> Greenfoot Java IDE



Games



Accessories



Help

Preferences

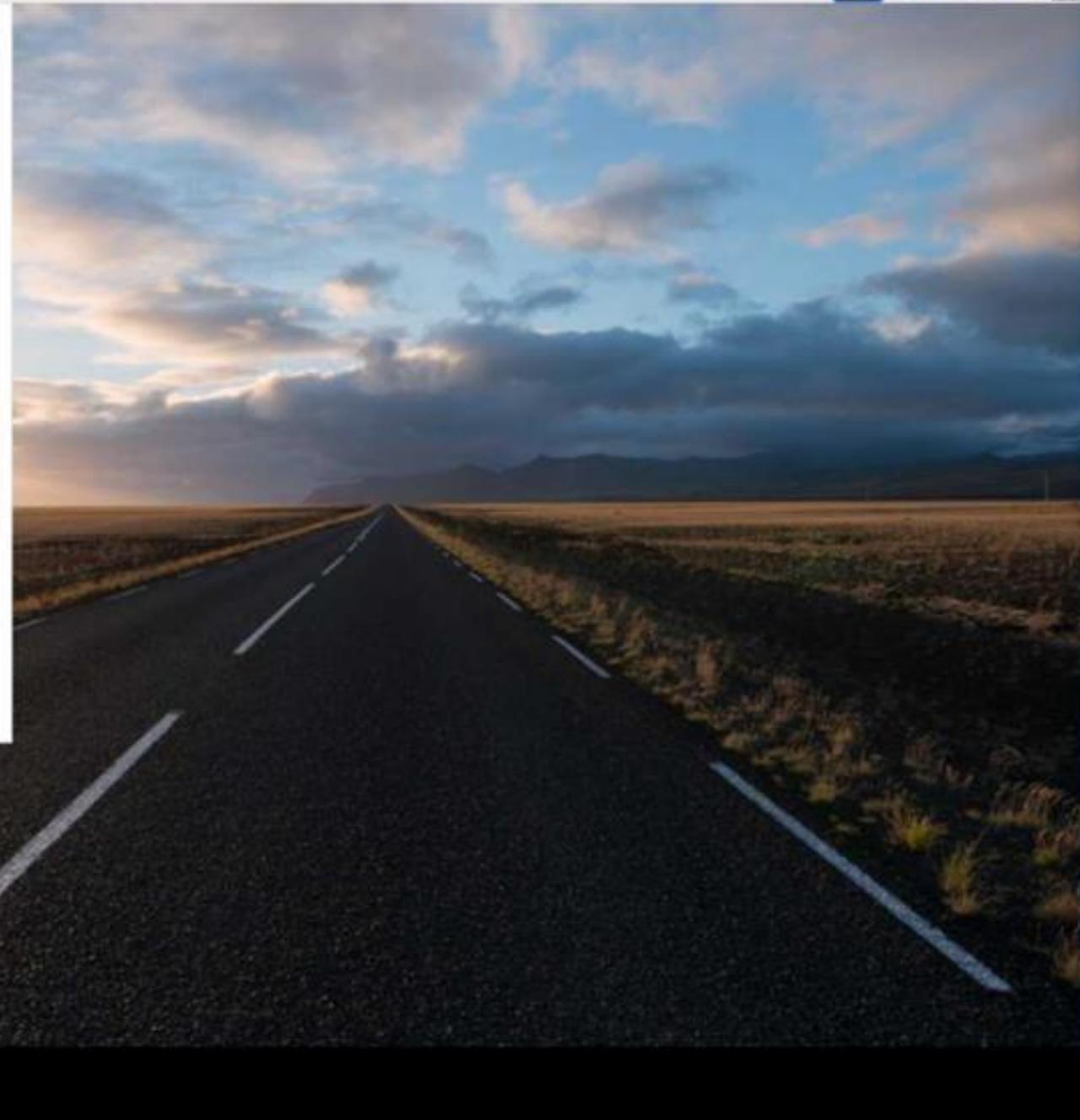


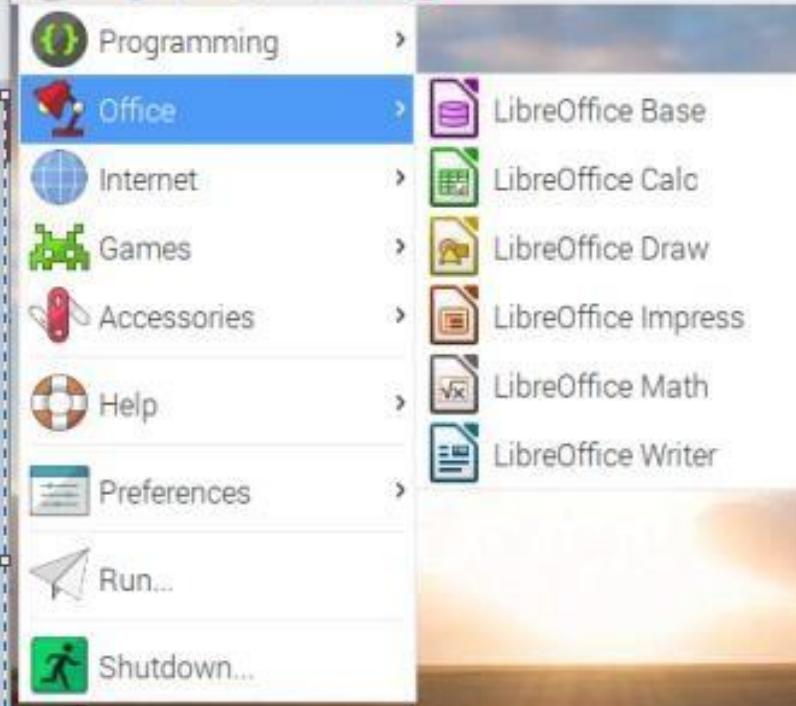
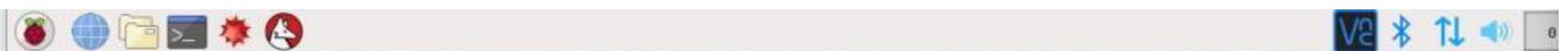
Run...

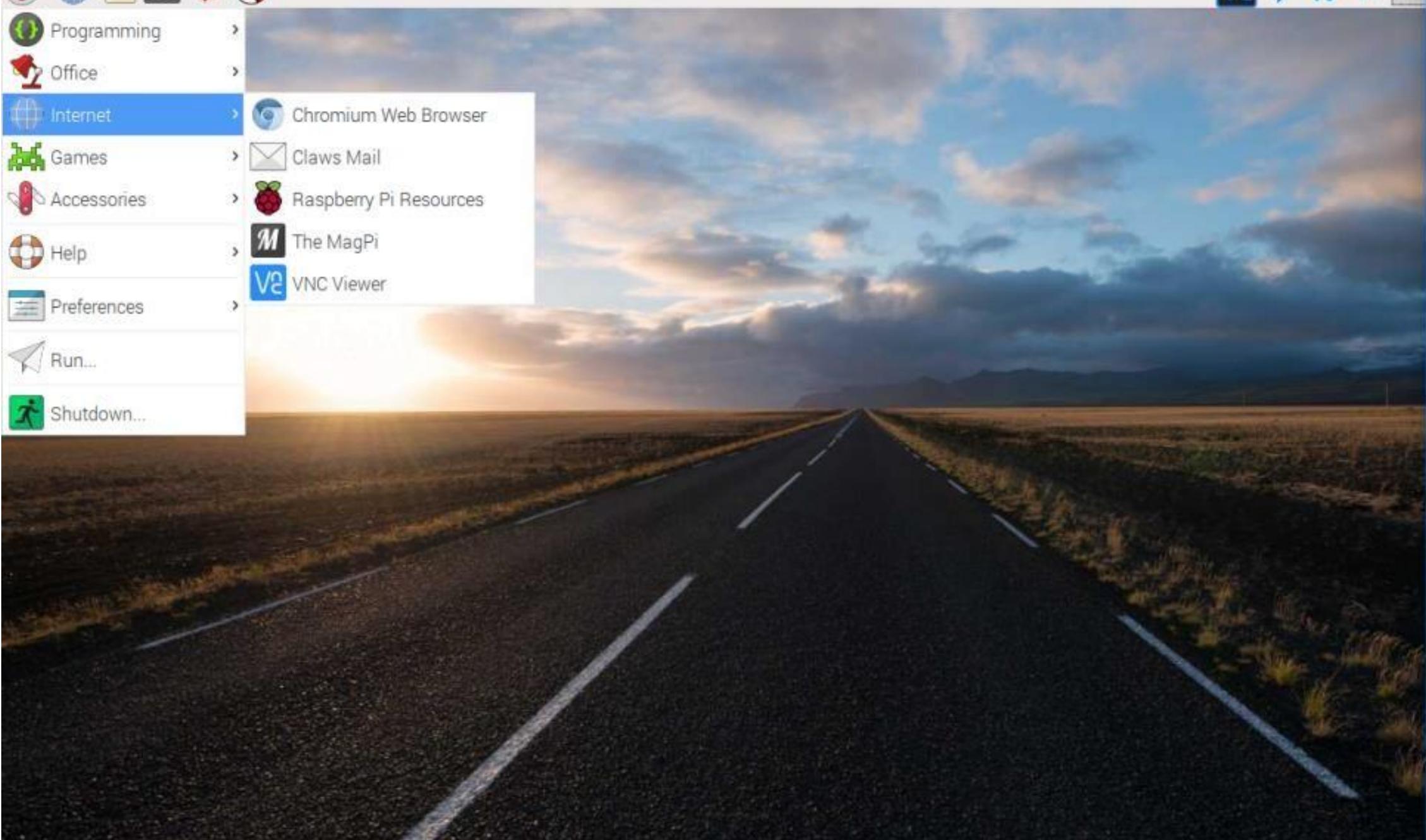
Shutdown...

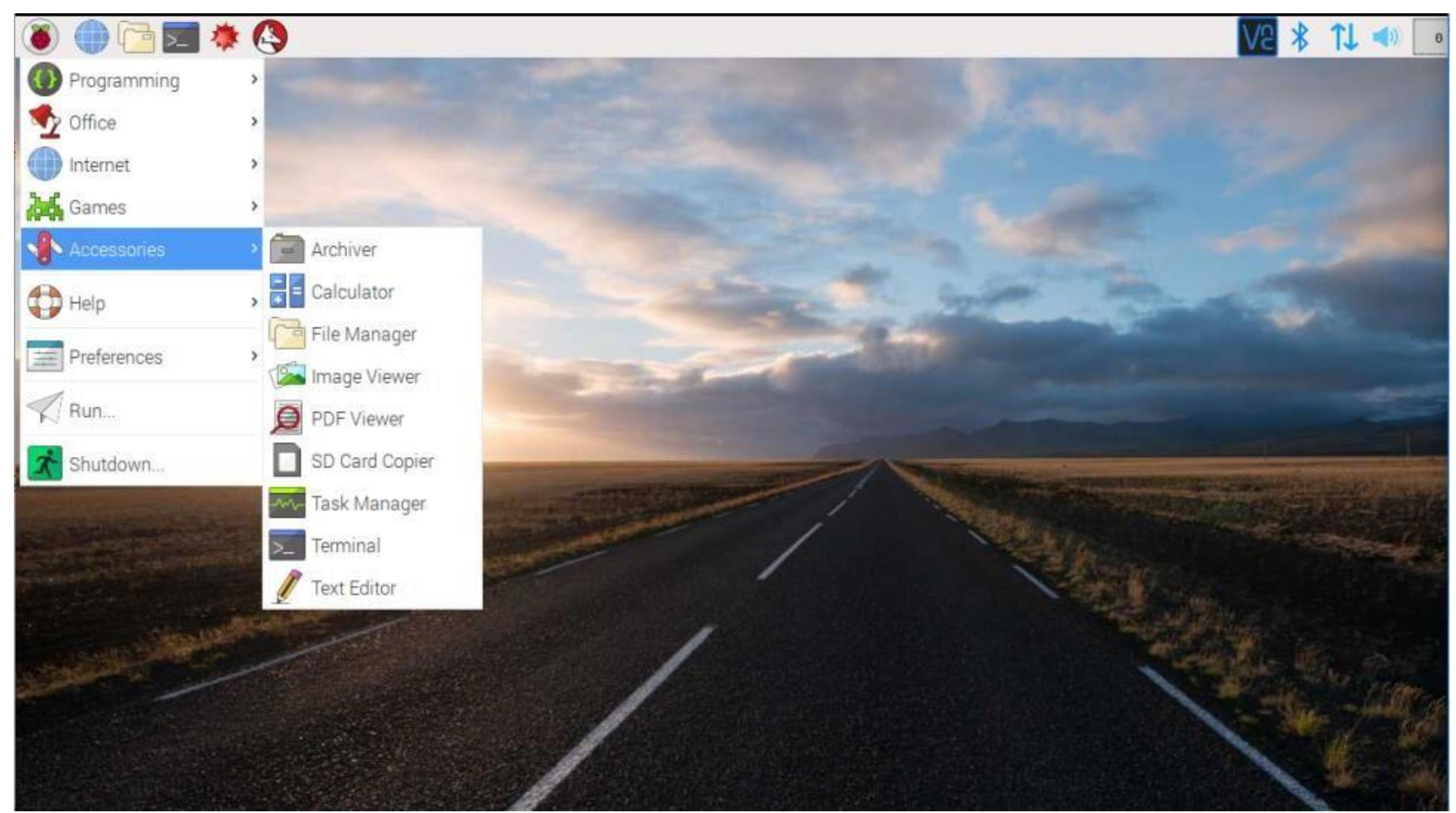


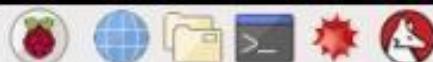
- > BlueJ Java IDE
- > Geany Programmer's Editor
- > Greenfoot Java IDE
- > Mathematica
- > Node-RED
- > Python 2 (IDLE)
- > Python 3 (IDLE)
- > Scratch
- > Scratch 2
- > Sense HAT Emulator
- > Sonic Pi
- > Thonny Python IDE
- > Thonny (Simple Mode)
- > Wolfram









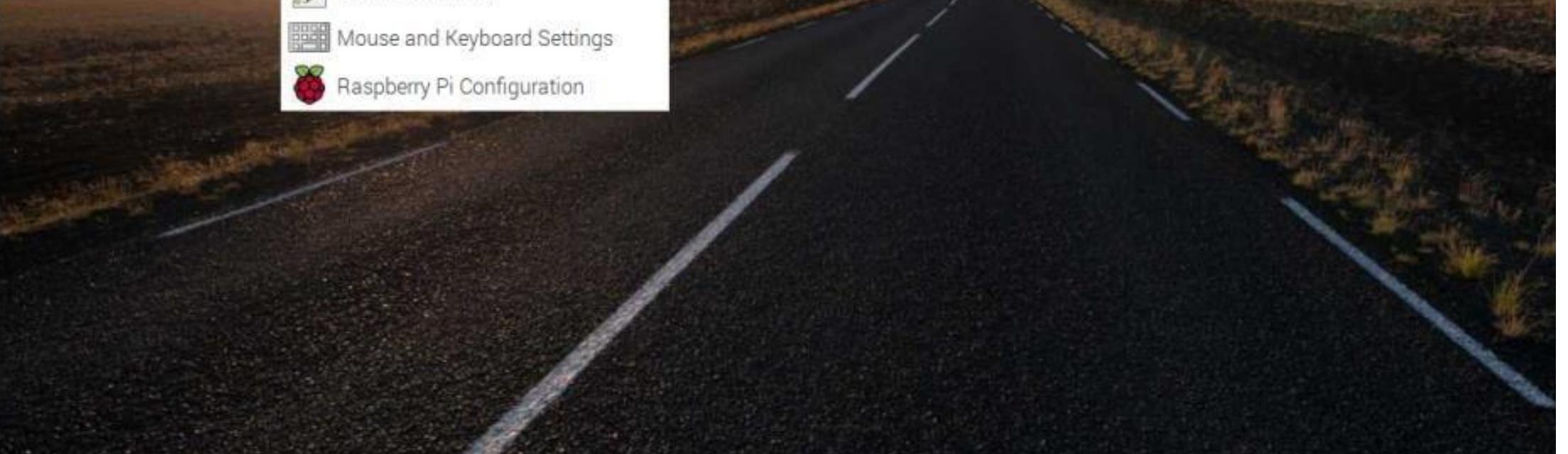


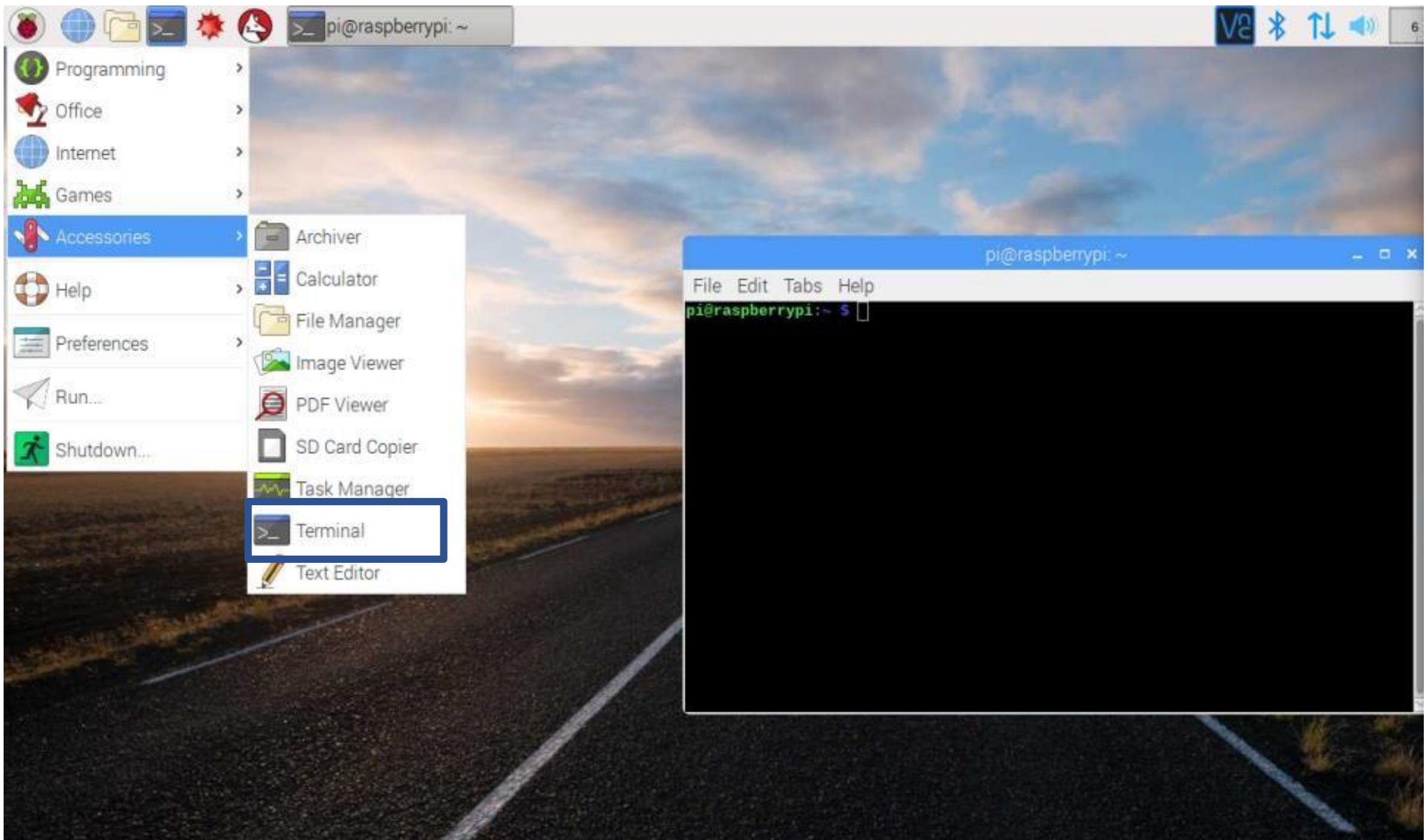
V2 * ↑

- Programming >
- Office >
- Internet >
- Games >
- Accessories >
- Help >

- Preferences >
- Run...
- Shutdown...

- Add / Remove Software
- Appearance Settings
- Audio Device Settings
- Main Menu Editor
- Mouse and Keyboard Settings
- Raspberry Pi Configuration





Powering up the Rpi



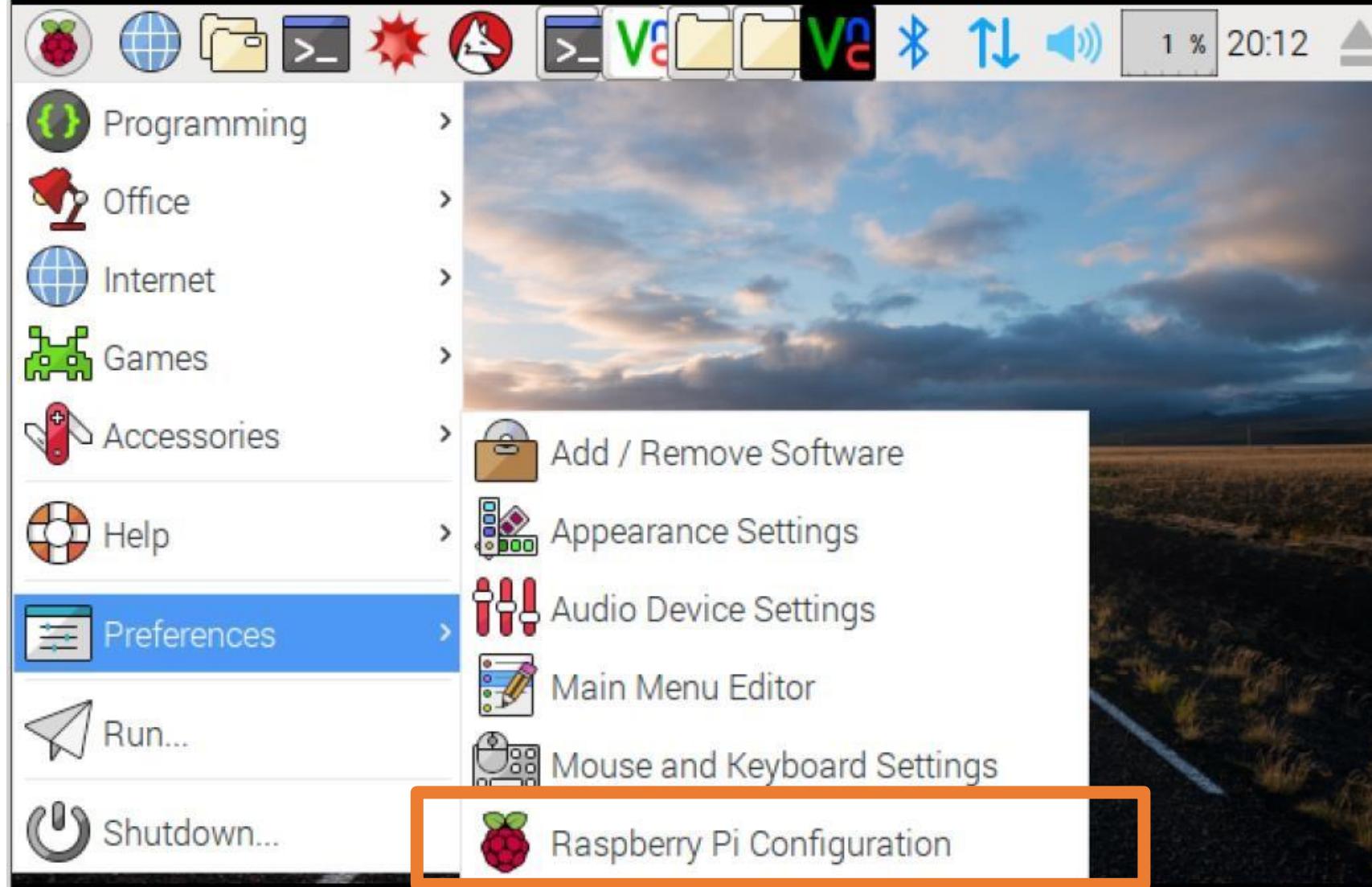
SSH(Secure Shell)

- SSH, or *Secure Shell*, is a protocol used to securely log onto remote systems. It is the most common way to access remote Linux and Unix-like servers.
- ssh `remote_host`
- The *remote_host* in this example is the IP address or domain name that you are trying to connect to.

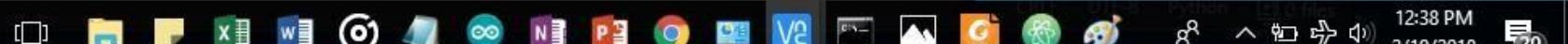
IMP... (Enable SSH)

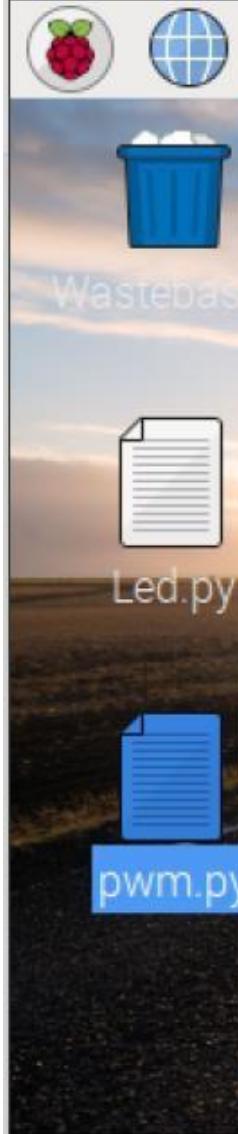
- As of the November 2016 release, Raspbian has the SSHserver disabled by default. It can be enabled manually from the Raspberry pi desktop (must have a keyboard, mouse, and a display attached to the RPI)
- Launch Raspberry Pi Configuration from the Preferences menu
- Navigate to the Interfaces tab
- Select Enabled next to SSH
- Click OK

169.254.47.125



Type here to search

12:38 PM
2/19/2018



Raspberry Pi Configuration

System Interfaces Performance Localisation

| | | |
|--------------|--|--------------------------------|
| Camera: | <input checked="" type="radio"/> Enabled | <input type="radio"/> Disabled |
| SSH: | <input checked="" type="radio"/> Enabled | <input type="radio"/> Disabled |
| VNC: | <input checked="" type="radio"/> Enabled | <input type="radio"/> Disabled |
| SPI: | <input checked="" type="radio"/> Enabled | <input type="radio"/> Disabled |
| I2C: | <input checked="" type="radio"/> Enabled | <input type="radio"/> Disabled |
| Serial: | <input checked="" type="radio"/> Enabled | <input type="radio"/> Disabled |
| 1-Wire: | <input checked="" type="radio"/> Enabled | <input type="radio"/> Disabled |
| Remote GPIO: | <input checked="" type="radio"/> Enabled | <input type="radio"/> Disabled |

Cancel OK

169.254.47.125

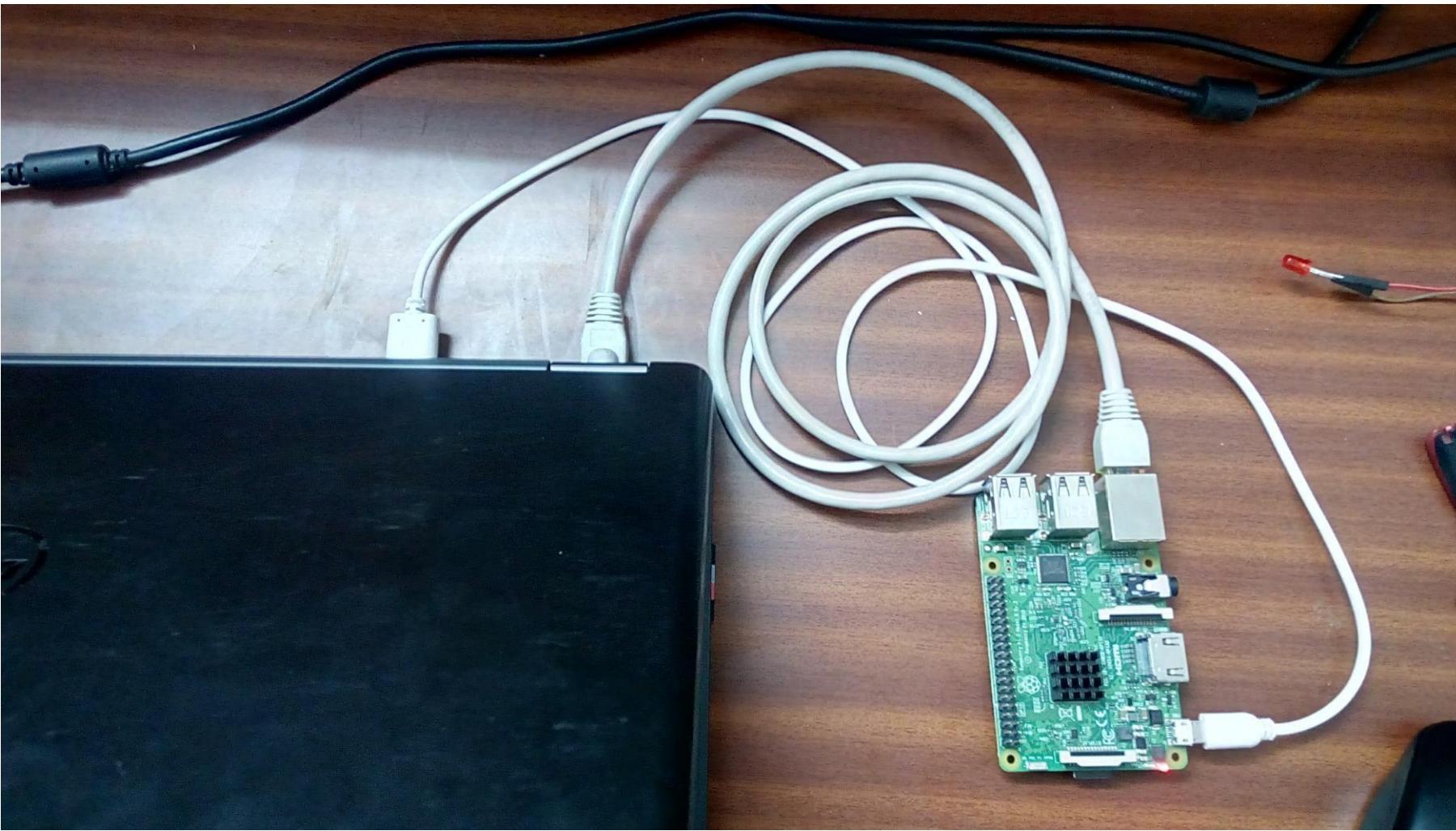


169.254.47.125

Enable SSH on a headless Raspberry Pi (add file to SDcard on another machine)

- For headless setup, SSH can be enabled by placing a file named ssh, without any extension, onto the boot partition of the SDcard from another computer. When the Pi boots, it looks for the ssh file. If it is found, SSH is enabled and the file is deleted. The content of the file does not matter; it could contain text, or nothing at all.
- If you have loaded Raspbian onto a blank SDcard, you will have two partitions. The first one, which is the smaller one, is the boot partition. Place the file into this one.

Connect the Rpi by Ethernet to your PC



Clipboard

Image

Tools

Shapes

Colors



Filters ▾

Best match

Command Prompt
Desktop app

Apps

Anaconda Prompt
 Vivado HLS 2016.4 Command Prompt
 Xilinx Software Command Line Tool 2016.4

Search suggestions

cmd - See web results >

Documents (7+)

Command Prompt

Microsoft Windows [Version 10.0.16299.248]
(c) 2017 Microsoft Corporation. All rights reserved.

C:\Users\admin>



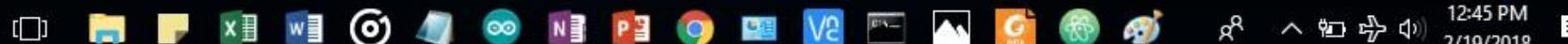
100%



12:45 PM
2/19/2018



cmd



Finding IP address

- For own System

- *Cmd prompt:*

- *ipconfig*

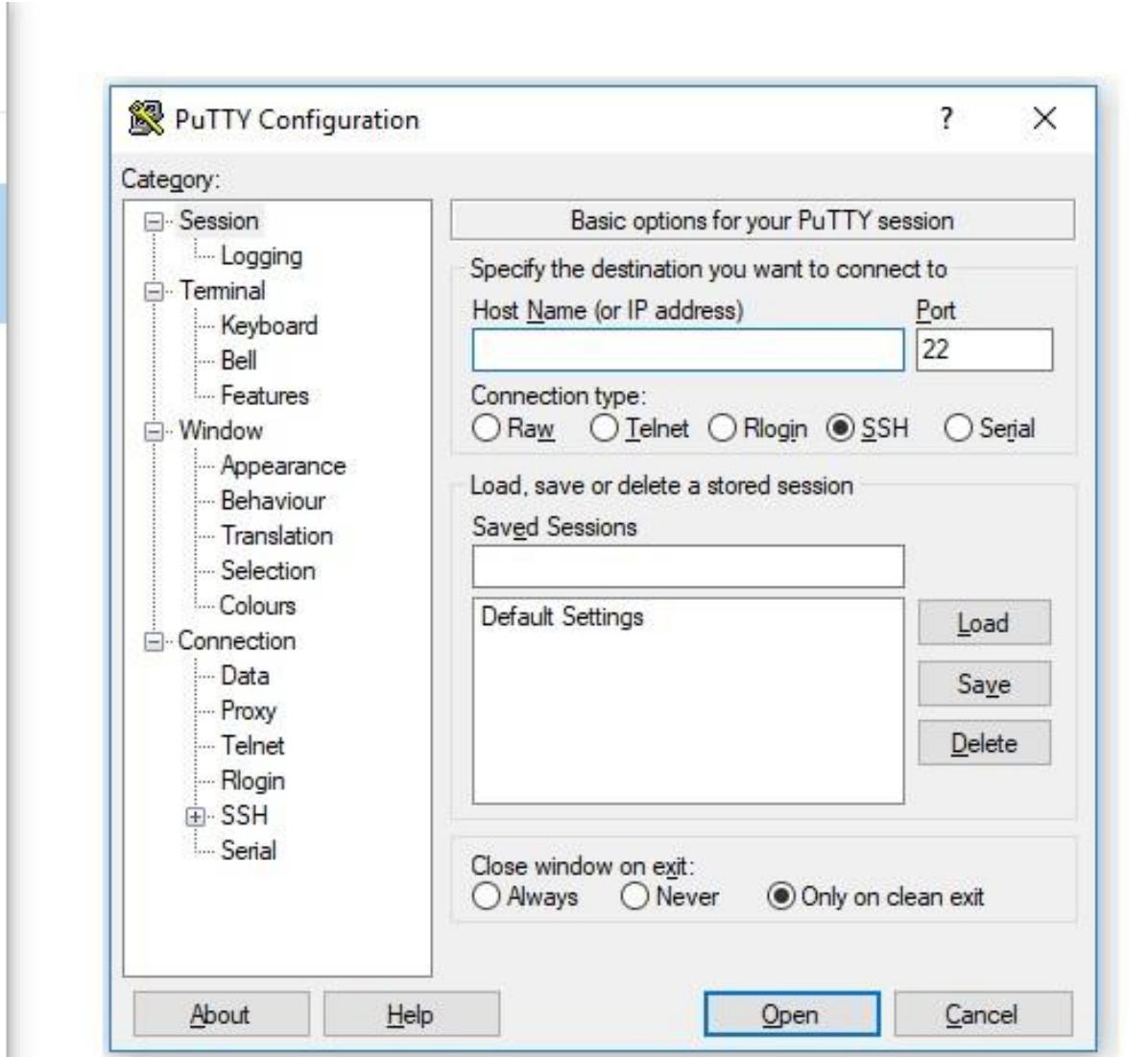
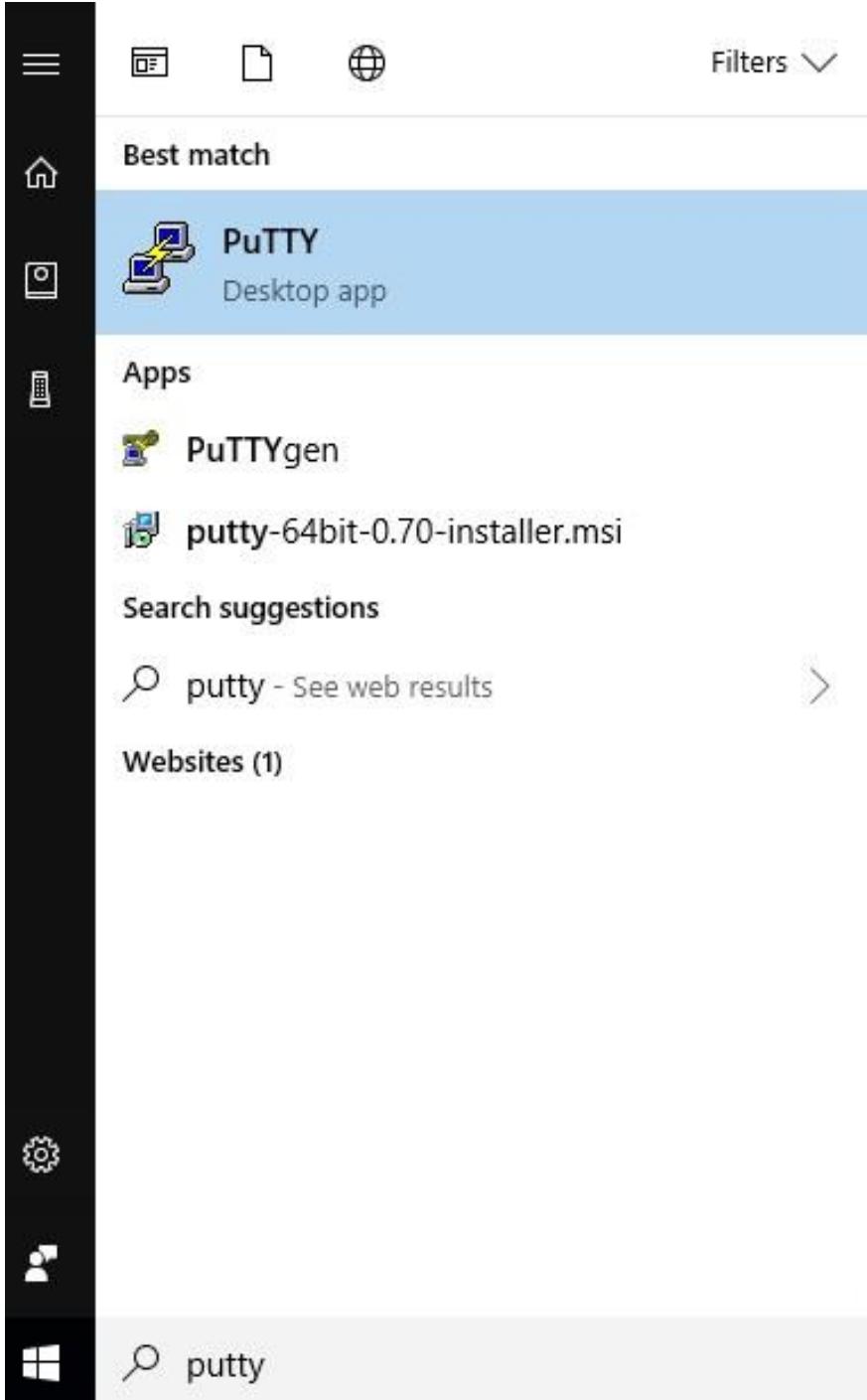
- FOR R-Pi

- Terminal

- *ifconfig*

SSH using Windows (putty)

- In Windows you will need to download an SSHclient. The most commonly used client is called PuTTY. Look for putty.exe under the heading For Windows on Intel x86.
- Type the IP address of the Pi into the Host Name field and click the Openbutton. If nothing happens when you click the Open button, and you eventually see a message saying Network error: Connection timed out, it is likely that you have entered the wrong IP address for the Pi.



Command Prompt

| | | |
|-----------------|-------------------|--------|
| 169.254.255.255 | ff-ff-ff-ff-ff-ff | static |
| 224.0.0.22 | 01-00-5e-00-00-16 | static |
| 224.0.0.251 | 01-00-5e-00-00-fb | static |
| 224.0.0.252 | 01-00-5e-00-00-fc | static |
| 239.255.255.250 | 01-00-5e-7f-ff-fa | static |
| 255.255.255.255 | ff-ff-ff-ff-ff-ff | static |

```
C:\Users\admin>arp -a  
No ARP Entries Found.
```

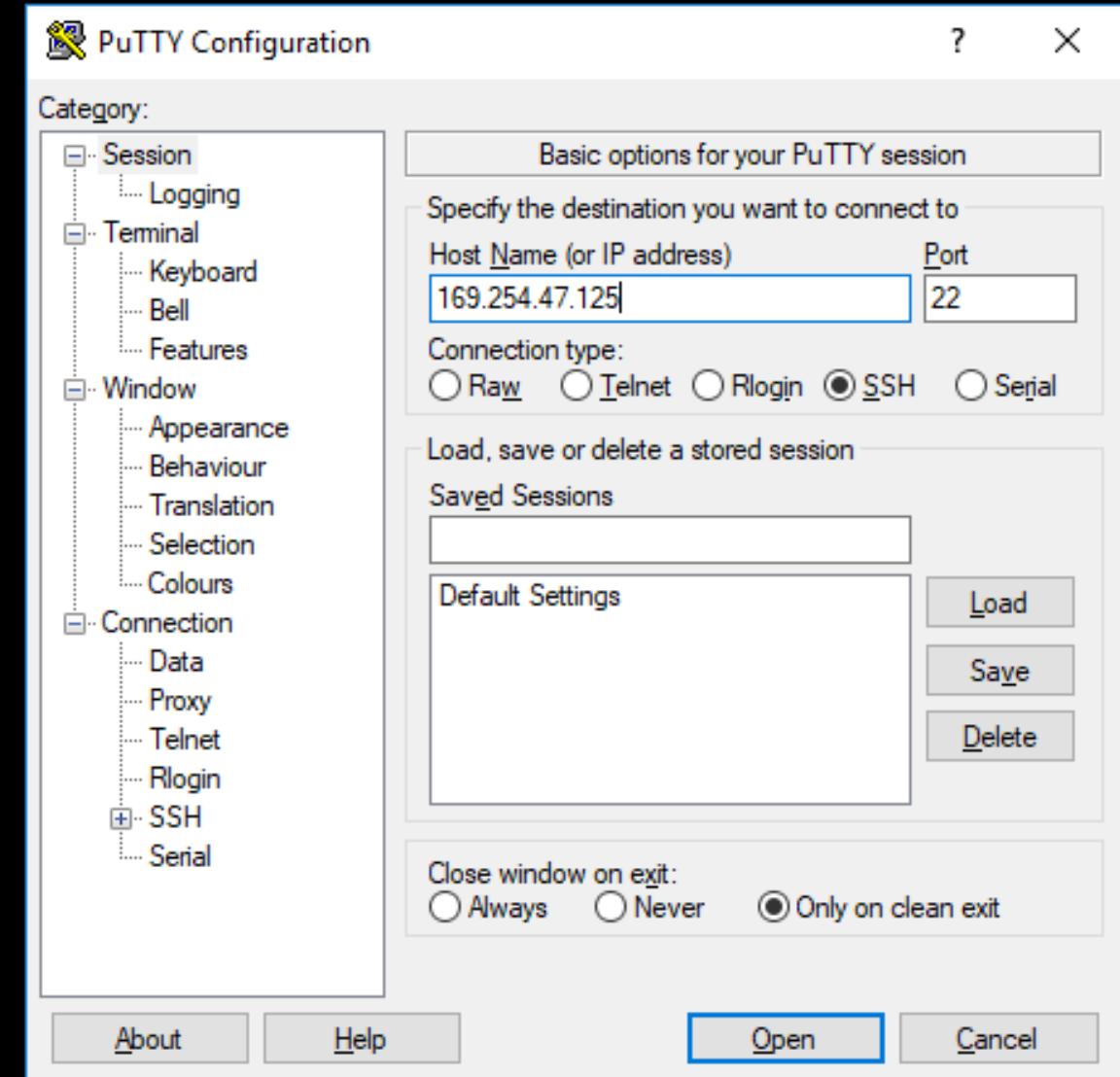
```
C:\Users\admin>arp -a
```

| | | |
|----------------------------------|-------------------|--------|
| Interface: 172.18.10.115 --- 0x9 | | Type |
| Internet Address | Physical Address | static |
| 224.0.0.22 | 01-00-5e-00-00-16 | |
| 255.255.255.255 | ff-ff-ff-ff-ff-ff | static |

```
C:\Users\admin>arp -a
```

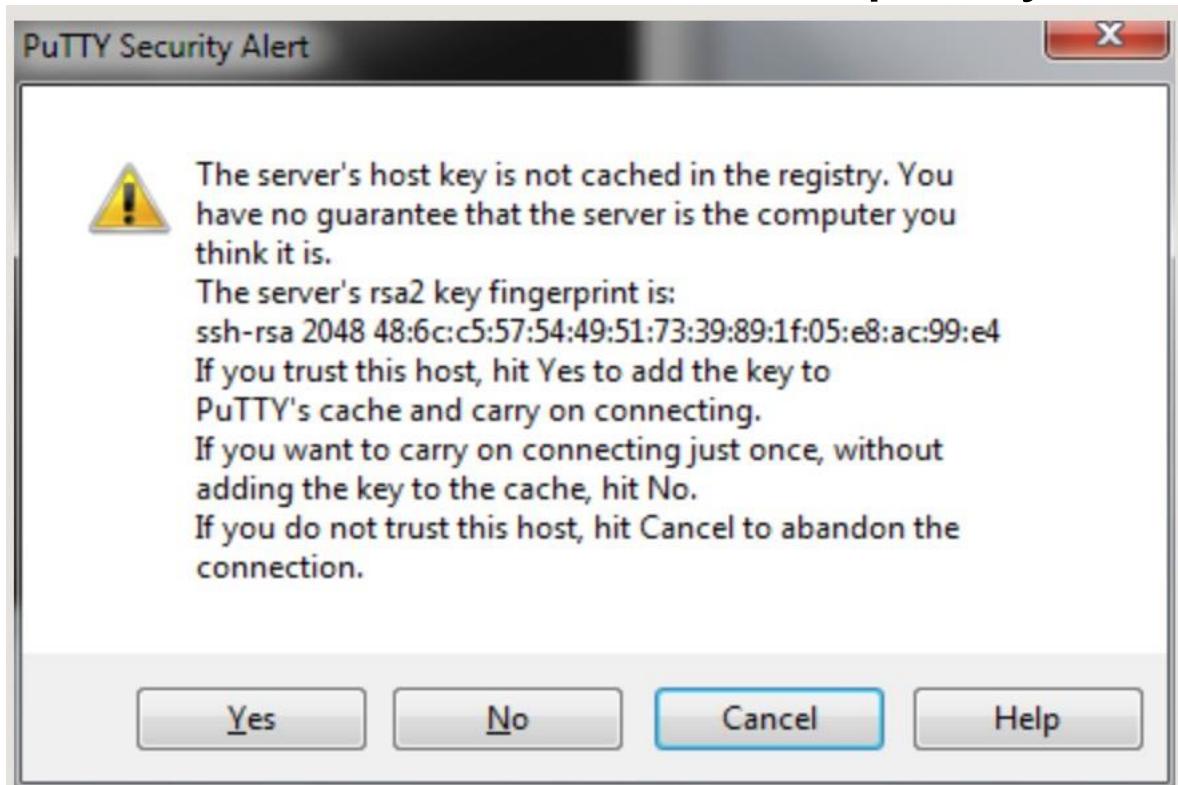
| | | |
|----------------------------------|-------------------|---------|
| Interface: 172.18.10.115 --- 0x9 | | Type |
| Internet Address | Physical Address | dynamic |
| 169.254.47.125 | b8-27-eb-ec-57-a6 | |
| 172.18.10.255 | ff-ff-ff-ff-ff-ff | static |
| 224.0.0.22 | 01-00-5e-00-00-16 | static |
| 224.0.0.251 | 01-00-5e-00-00-fb | static |
| 224.0.0.252 | 01-00-5e-00-00-fc | static |
| 239.255.255.250 | 01-00-5e-7f-ff-fa | static |
| 255.255.255.255 | ff-ff-ff-ff-ff-ff | static |

```
C:\Users\admin>
```



CONNECT

- When the connection works you will see the security warning shown below. You can safely ignore it, and click the 'Yes' button. You will only see this warning the first time PuTTY connects to a Raspberry Pi that it has not seen before.



 169.254.47.125 - PuTTY

- □ ×

```
login as: pi  
pi@169.254.47.125's password: █
```

Contd....

- You will now see the usual login prompt. Log in with the same username and password you would use on the Pi itself. The default login for Raspbian is
- **Login:** pi
- **Password:** raspberry.
- You should now have the Raspberry Pi prompt which will be identical to the one found on the Raspberry Pi itself.
- pi@raspberrypi ~ \$
- Detailed instruction to set up putty.
- <https://www.raspberrypi.org/documentation/remote-access/ssh/windows.md>

 pi@raspberrypi: ~

— □ ×

```
login as: pi  
pi@169.254.47.125's password:
```

```
The programs included with the Debian GNU/Linux system are free software;  
the exact distribution terms for each program are described in the  
individual files in /usr/share/doc/*copyright.
```

```
Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent  
permitted by applicable law.
```

```
Last login: Fri Nov 25 18:39:53 2016
```

```
SSH is enabled and the default password for the 'pi' user has not been changed.  
This is a security risk - please login as the 'pi' user and type 'passwd' to set  
a new password.
```

```
pi@raspberrypi:~ $ █
```

Commonly Used Linux Commands

| Command | Description |
|---------|---|
| man | display details about an instruction |
| ls | list contents of the current directory |
| ls -l | detailed listing of directory contents, shows permissions, owner, etc. |
| ls -a | list all files (including hidden files) |
| ls -la | detailed listing of all files (note that options can be combined) |
| cd | change directory |
| cd .. | backup one level from the current directory |
| pwd | print current working directory |
| touch | create an empty file |
| mkdir | make a new directory |
| rm | remove files and directories |
| rm -rf | recursively remove all files and directories under the specified directory |
| cat | list file contents |
| less | list file contents – one screen at a time |
| tail | list the end of the file (default – displays last 10 lines) |
| tail -n | list the last n lines of a file |
| cp | copy file |
| mv | rename a file |
| echo | echo values to the screen example: echo \$PATH – prints the value of the PATH variable |
| grep | command line text search utility example: grep blue colors.txt – list all lines with the word blue from the colorlist.txt file |
| ps | list currently running processes |



pi@raspberrypi: ~

- □ ×

login as: pi

pi@169.254.231.146's password:

Linux raspberrypi 4.9.41-v7+ #1023 SMP Tue Aug 8 16:00:15 BST 2017 armv7l

The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*copyright.

Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.

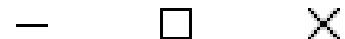
Last login: Thu Sep 7 16:30:47 2017 from 169.254.126.155

SSH is enabled and the default password for the 'pi' user has not been changed.
This is a security risk - please login as the 'pi' user and type 'passwd' to set
a new password.

pi@raspberrypi:~ \$ █



pi@raspberrypi: ~/Desktop/final-working



login as: pi

pi@169.254.231.146's password:

Linux raspberrypi 4.9.41-v7+ #1023 SMP Tue Aug 8 16:00:15 BST 2017 armv7l

The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*copyright.

Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.

Last login: Thu Sep 7 16:30:47 2017 from 169.254.126.155

SSH is enabled and the default password for the 'pi' user has not been changed.
This is a security risk - please login as the 'pi' user and type 'passwd' to set
a new password.

pi@raspberrypi:~ \$ cd Desktop

pi@raspberrypi:~/Desktop \$ ls

final-working

pi@raspberrypi:~/Desktop \$ cd final-working

pi@raspberrypi:~/Desktop/final-working \$ ls

fact.py Led.py pwm.py

pi@raspberrypi:~/Desktop/final-working \$ █



pi@raspberrypi: ~/Desktop/final-working

- □ ×

Linux raspberrypi 4.9.41-v7+ #1023 SMP Tue Aug 8 16:00:15 BST 2017 armv7l

The programs included with the Debian GNU/Linux system are free software;
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permitted by applicable law.

Last login: Thu Sep 7 16:30:47 2017 from 169.254.126.155

SSH is enabled and the default password for the 'pi' user has not been changed.
This is a security risk - please login as the 'pi' user and type 'passwd' to set
a new password.

pi@raspberrypi:~ \$ cd Desktop

pi@raspberrypi:~/Desktop \$ ls

final-working

pi@raspberrypi:~/Desktop \$ cd final-working

pi@raspberrypi:~/Desktop/final-working \$ ls

fact.py Led.py pwm.py

pi@raspberrypi:~/Desktop/final-working \$ python fact.py

factorial of which number5

120

pi@raspberrypi:~/Desktop/final-working \$

Type arp -a on your laptop cmd prompt

```
Command Prompt
Microsoft Windows [Version 10.0.16299.248]
(c) 2017 Microsoft Corporation. All rights reserved.

C:\Users\admin>arp -a

Interface: 169.254.126.155 --- 0x9
Internet Address      Physical Address      Type
169.254.47.125        b8-27-eb-ec-57-a6    dynamic
169.254.255.255        ff-ff-ff-ff-ff-ff    static
224.0.0.22              01-00-5e-00-00-16    static
224.0.0.251             01-00-5e-00-00-fb    static
224.0.0.252             01-00-5e-00-00-fc    static
239.255.255.250         01-00-5e-7f-ff-fa    static
255.255.255.255         ff-ff-ff-ff-ff-ff    static

C:\Users\admin>
```

SSH using MAC

- You can use SSH to connect to your Raspberry Pi from a Linux computer, a Mac, or another Raspberry Pi, without installing additional software
- “`ssh pi@<IP>`”
- Where IP refers to the IP address of raspberry pi found earlier.

VNCremote access to Rpi

- VNC(Virtual Network Computing) is a great technology included with Raspbian. With this tech, you can remotely control your Raspberry Pi from another computer, such as a PCor Mac, or even another Raspberry Pi board.
- Sometimes it's not convenient to work directly on a Raspberry Pi. This can be because it's not easy to access, or because your keyboard and monitor are being used on your main computer.
- Using remote networking, you can open the Raspbian desktop interface from your Raspberry Pi inside a window on your computer.

Contd....

- By default, VNC Server from RealVNC gives you direct control over your Raspberry Pi, just as though you were sitting in front of it.
- However, you will need to enable it yourself. From then on, Server will be loaded every time you switch on your Raspberry Pi.(Just like we enabled SSH)
- [raspi-config](#) can be used in the terminal:
- Enter "sudo raspi-config" in a terminal window (This is once we have already SSHed into the RPi)
- Select Interfacing Options
- Navigate to and select VNC
- Choose Yes
- Select Ok
- Choose Finish



Raspberry Pi Configuration

Interfaces tab selected.

| | | | |
|--------|------------|-------------|--------------|
| System | Interfaces | Performance | Localisation |
|--------|------------|-------------|--------------|

Configuration options:

- Camera: Enabled (radio button selected)
- SSH: Enabled (radio button selected)
- VNC: Enabled (radio button selected)
- SPI: Enabled (radio button selected)
- I2C: Enabled (radio button selected)
- Serial: Enabled (radio button selected)
- 1-Wire: Enabled (radio button selected)
- Remote GPIO: Enabled (radio button selected)



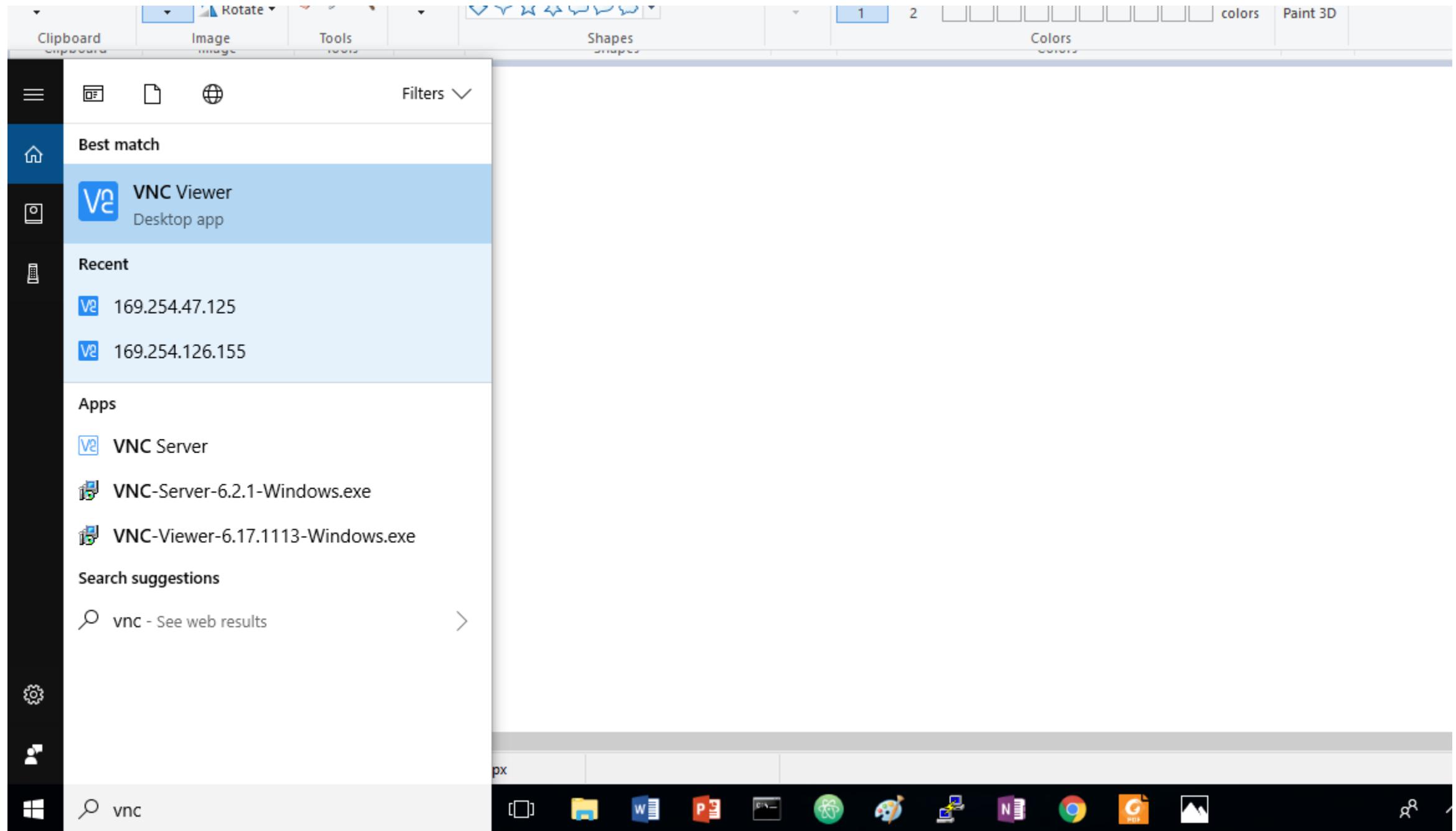
169.254.47.125



169.254.47.125

Contd...

- Download and install VNC Viewer on your computer from [RealVNC](#). Open the app and enter the IP Address of the RPi into the VNC Server field. Ensure Encryption is set to “Let VNC Server choose” and click Connect. OK. The first time you connect it will display a “VNC Server not recognized” alert. Click Continue.
- Enter Pi into the Username field, and “raspberry” (or your Raspbian password) in the Password field. The Raspbian PIXEL interface will appear inside a window on your computer. You can click on the Menu, open programs and run Terminal commands on your Raspberry Pi. If you have your Raspberry Connected to a monitor, you’ll see it move as you remote control it.



V2 VNC Viewer

File View Help

169.254.47.125

 Sign in... ▾



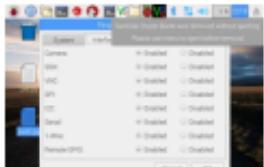
169.254.47.125



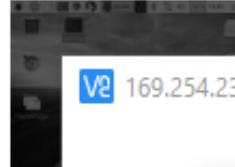
File View Help

169.254.231.146

Sign in... ▾



169.254.47.125



VNC 169.254.231.146 - VNC Viewer

— □ ×

VNC Authentication

VNC Server: 169.254.231.146:5900

Username: pi

Password: [REDACTED]

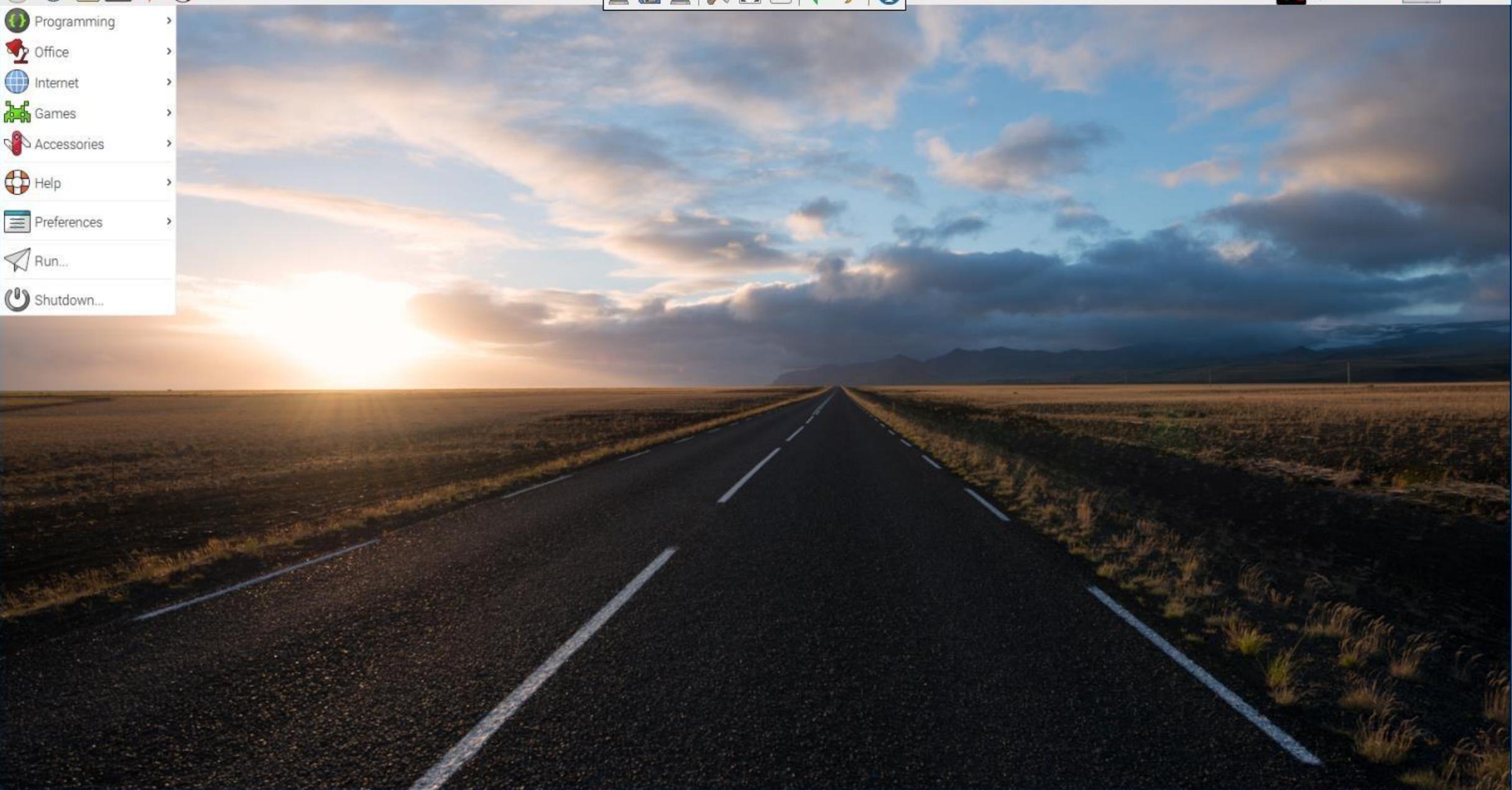
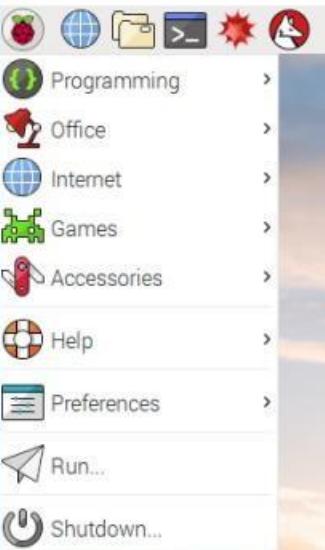
Remember password

Catchphrase: Domain compare puma. Spiral natural blast.

Signature: 8f-52-13-60-7f-5f-3b-ca

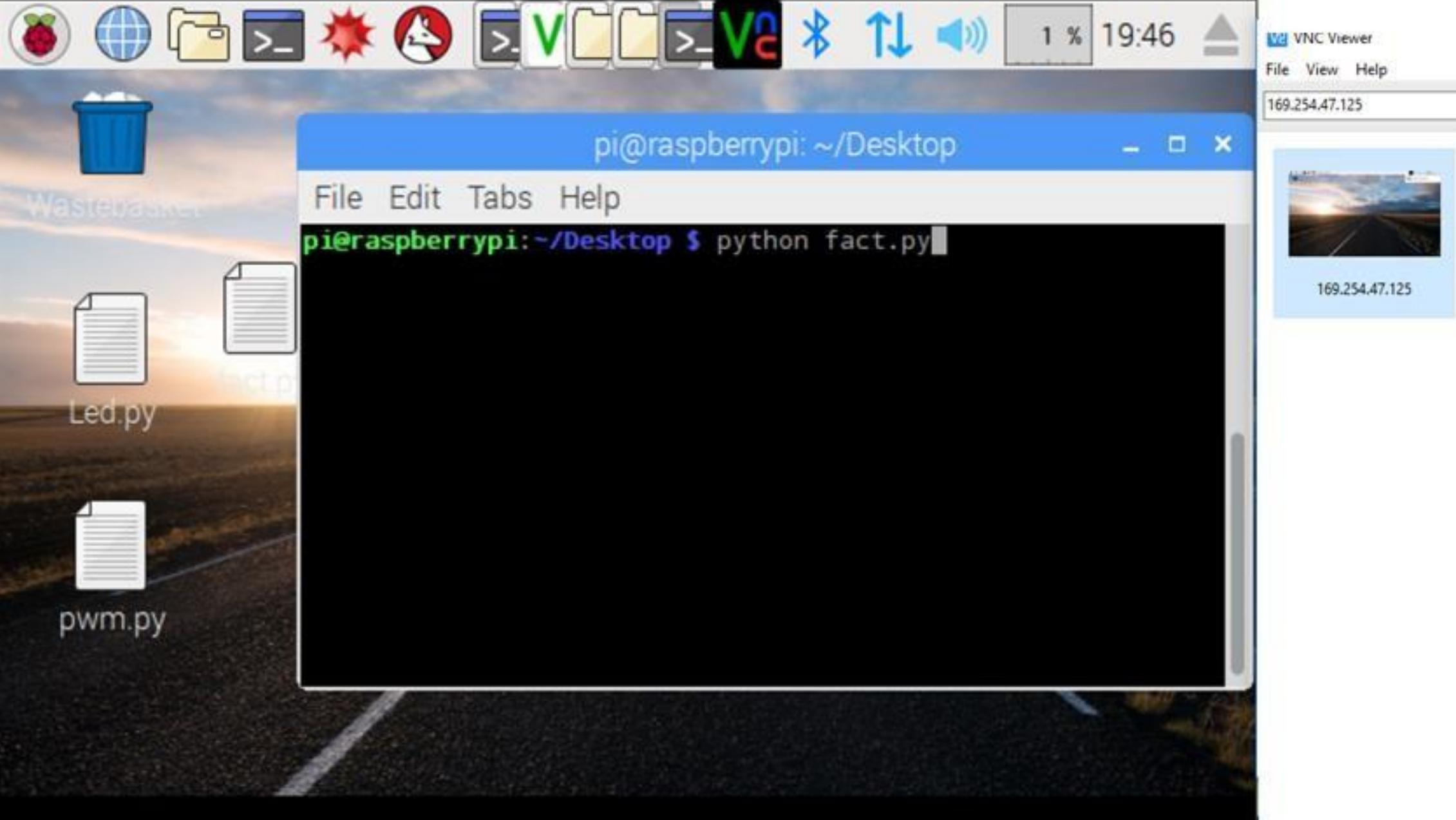
OK Cancel

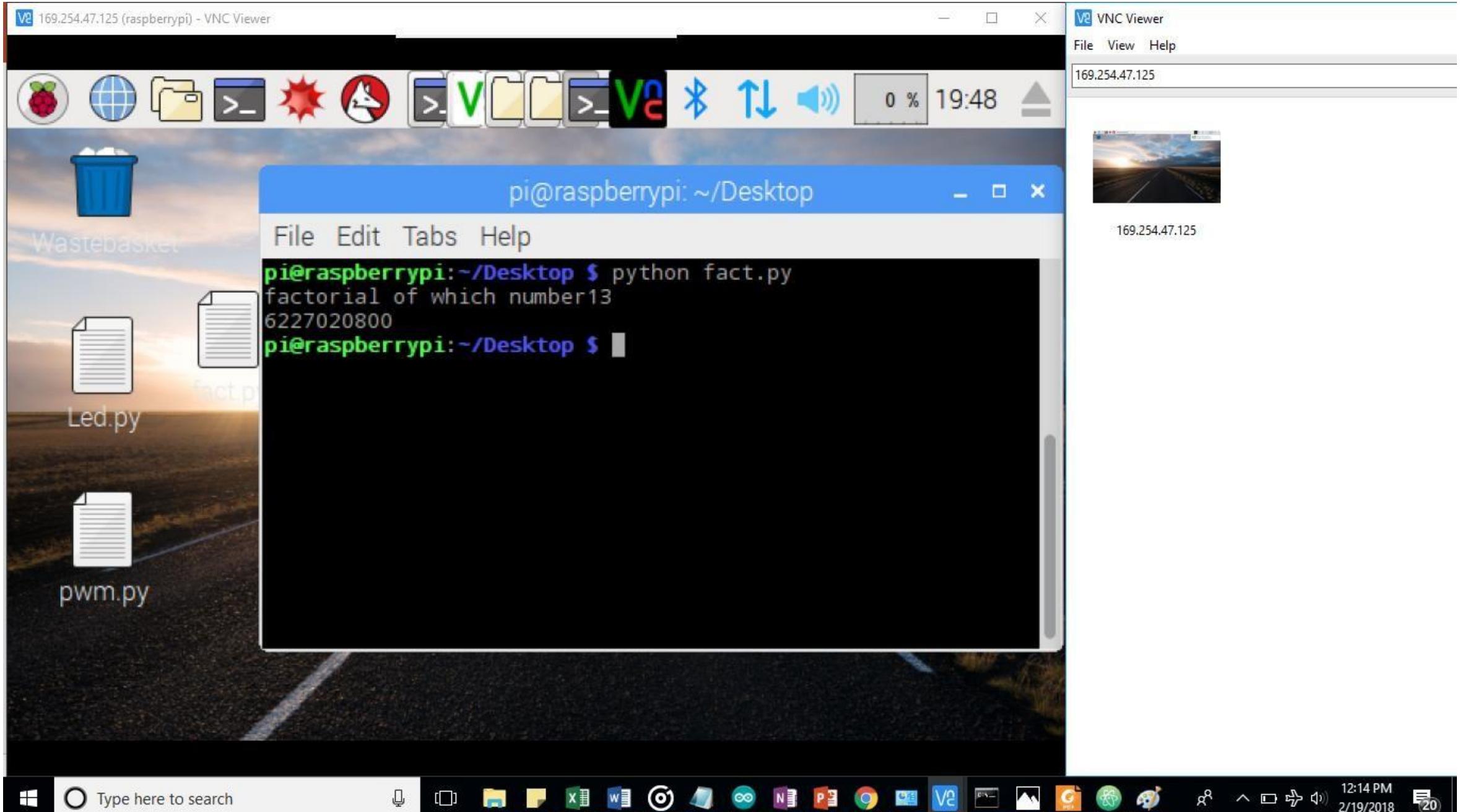
Stop



review

Evaluation Copy, Build 14551.15_prerelease.1005.6-1700





LEDBlink

("Hello World" of Physical computing)

- The simplest thing you can do with an Raspberry Pi to see an actual physical output is to blink an LED! It's more like an electronics version of the classical hello world program that we write when learning a new software language.
- Raspberry Pi has 8 General Purpose Input/Output pins(4,17,18,21,22,23,24,25) which can be configured as input/output and turned on/off via software.
- RPi.GPIO Python library is used to control the LEDfrom RaspberryPi.

Only SSH
>> sudo nano Led.py

pi@raspberrypi: ~/Desktop/final-working

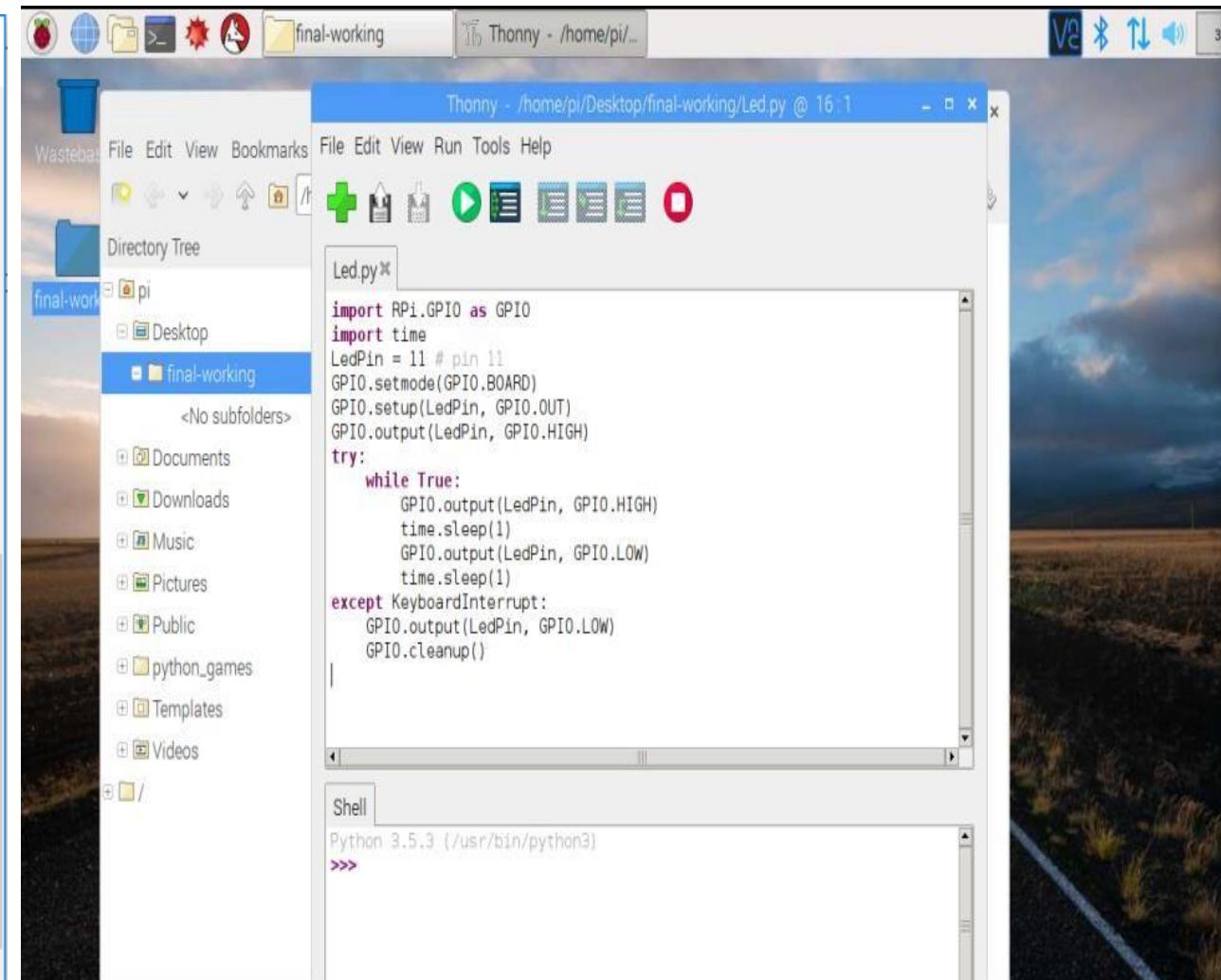
GNU nano 2.7.4 File: Led.py

```
import RPi.GPIO as GPIO
import time
LedPin = 11 # pin 11
GPIO.setmode(GPIO.BOARD)
GPIO.setup(LedPin, GPIO.OUT)
GPIO.output(LedPin, GPIO.HIGH)
try:
    while True:
        GPIO.output(LedPin, GPIO.HIGH)
        time.sleep(1)
        GPIO.output(LedPin, GPIO.LOW)
        time.sleep(1)
except KeyboardInterrupt:
    GPIO.output(LedPin, GPIO.LOW)
GPIO.cleanup()
```

[Read 15 lines (Converted from DOS format)]

^G Get Help ^O Write Out ^W Where Is ^K Cut Text ^J Justify ^C Cur Pos
^X Exit ^R Read File ^\ Replace ^U Uncut Text ^T To Linter ^ Go To Line

With VNC
See in the Rpi desktop



Python (RPi.GPIO) API

- In order to use RPi.GPIO throughout the rest of your Python script, you need to put this statement at the **top of your file**:

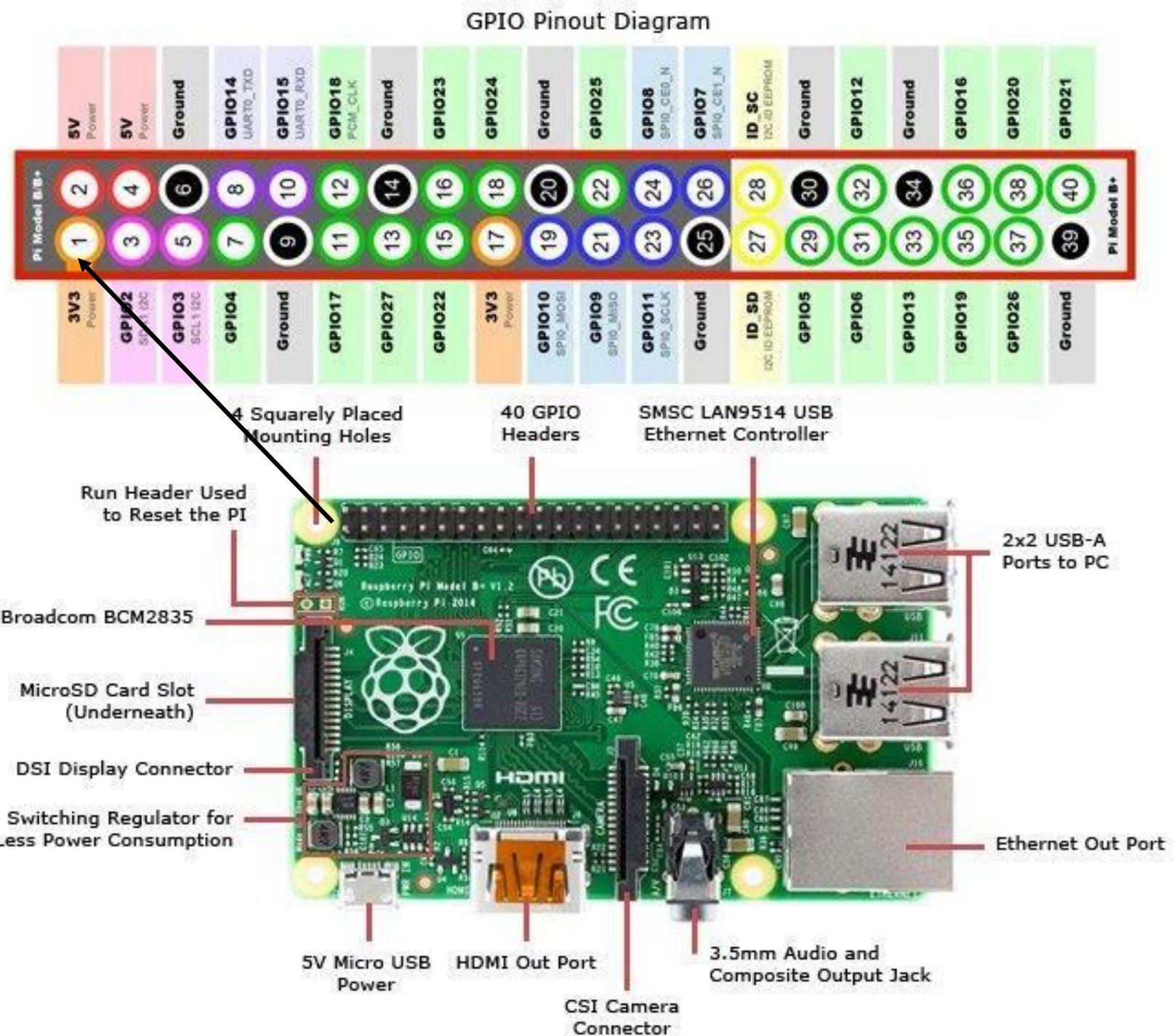
```
import RPi.GPIO as GPIO
```

- This statement “includes” the RPi.GPIO module, and goes a step further by providing a local name – GPIO – which we’ll call to reference the module from here on.

Pin Numbering Declaration

- After you've included the RPi.GPIO module, the next step is to determine the **pin-numbering schemes** you want to use:
- GPIO.BOARD – Board numbering scheme. The pin numbers follow the pin numbers on header P1
- To specify in your code which number-system is being used, use the GPIO.setmode() function.

```
GPIO.setmode(GPIO.BOARD)
```



Raspberry Pi 3 Model B (J8 Header)

| GPIO# | NAME | NAME | GPIO# |
|-----------|-----------------------------------|-----------------------------------|-------|
| | 3.3 VDC Power | 5.0 VDC Power | 2 |
| 8 | GPIO 8 SDA1 (I ₂ C) | 5.0 VDC Power | 4 |
| 9 | GPIO 9 SCL1 (I ₂ C) | Ground | 6 |
| 7 | GPIO 7 GPCLK0 | Ground | 8 |
| 0 | GPIO 0 | Ground | 10 |
| 2 | GPIO 2 | Ground | 12 |
| 3 | GPIO 3 | 3.3 VDC Power | 14 |
| 12 | GPIO 12 MOSI (SPI) | Ground | 16 |
| 13 | GPIO 13 MISO (SPI) | Ground | 18 |
| 14 | GPIO 14 SCLK (SPI) | Ground | 20 |
| 30 | SDA0 (I ₂ C ID EEPROM) | SCL0 (I ₂ C ID EEPROM) | 22 |
| 21 | GPIO 21 GPCLK1 | Ground | 24 |
| 22 | GPIO 22 GPCLK2 | Ground | 26 |
| 23 | GPIO 23 PWM1 | Ground | 28 |
| 24 | GPIO 24 PCM_FS/PWM1 | Ground | 30 |
| 25 | GPIO 25 | Ground | 32 |
| | | | 34 |
| | | | 36 |
| | | | 38 |
| | | | 40 |
| | | | |

Attention! The GPIO pin numbering used in this diagram is intended for use with WiringPi / Pi4J. This pin numbering is not the raw Broadcom GPIO pin numbers.

<http://www.pi4j.com>

Setting a Pin Mode

- If you've used Arduino, you're probably familiar with the fact that you have to declare a "pin mode" before you can use it as either an input or output.
- To set a pin mode, use the `setup([pin], [GPIO.IN, GPIO.OUT])` function. So, if you want to set pin 18 as an output, for example, write:

```
GPIO.setup(18, GPIO.OUT)
```

Outputs

1. Digital Output

- To write a pin high or low, use the `GPIO.output([pin], [GPIO.LOW, GPIO.HIGH])` function. For example, if you want to set pin 18 high, write:

```
GPIO.output(18, GPIO.HIGH)
```

- Writing a pin to `GPIO.HIGH` will drive it to 3.3V, and `GPIO.LOW` will set it to 0V. Alternative to `GPIO.HIGH` and `GPIO.LOW`, you can use either 1, True, 0 or False to set a pin value.

Contd...

2. PWM (“Analog”)Output

- PWM on the Raspberry Pi is about as limited as can be – one, single pin is capable of it: 12
- To initialize PWM, use `GPIO.PWM([pin], [frequency])` function. To make the rest of your script-writing easier you can assign that instance to a variable. Then use `pwm.start([duty cycle])` function to set an initial value. For example

```
pwm = GPIO.PWM(12, 0.6)  
pwm.start(50)
```

- Just don't forget to set the pin as an output before you use it for PWM.
- To turn PWM on that pin off, use the `pwm.stop()` command

Inputs

- If a pin is configured as an input, you can use the GPIO.input([pin]) function to read its value. The input() function will return either a True or False indicating whether the pin is HIGH or LOW. You can use an if statement to test this, for example...

```
if GPIO.input(17):
    print("Pin 11 is HIGH")
else:
    print("Pin 11 is LOW")
```

- It will read pin 17 and print whether it's being read as HIGH or LOW.

Delays

- If you need to slow your Python script down, you can add delays. To incorporate delays into your script, you'll need to include another module: time. This line, at the top of your script, will do it for you:

include time

- Then, throughout the rest of your script, you can use `time.sleep(seconds)` to give your script a rest. You can use decimals to precisely set your delay. For example, to delay 250 milliseconds, write:

time.sleep(0.25)

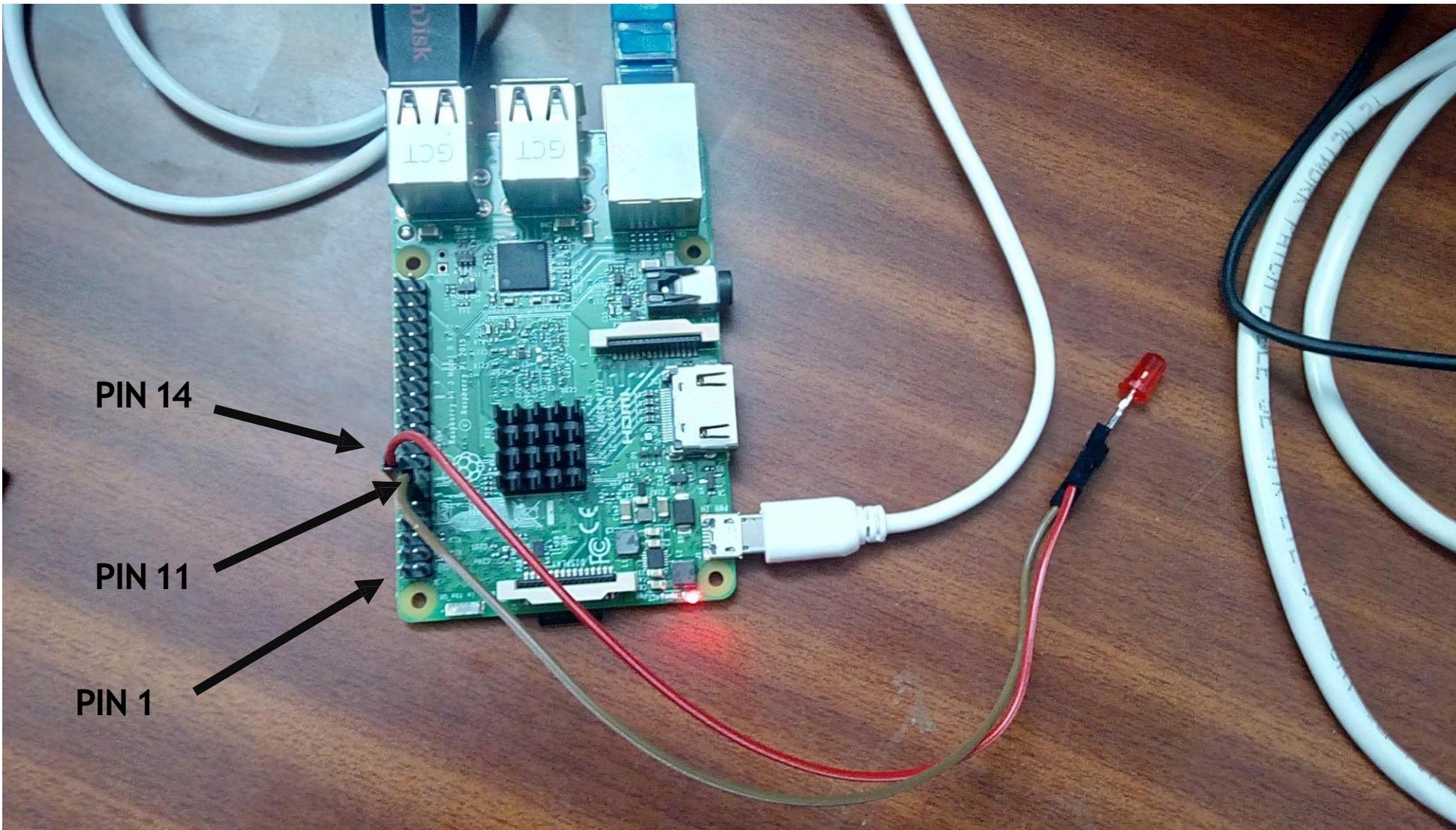
Garbage Collecting

- Once your script has run its course, be kind to the next process that might use your GPIOs by cleaning up after yourself. Use the `GPIO.cleanup()` command at the end of your script to release any resources your script may be using.
- Your Pi will survive if you forget to add this command, but it is good practice to include wherever you can.

Finally “LED Blink”

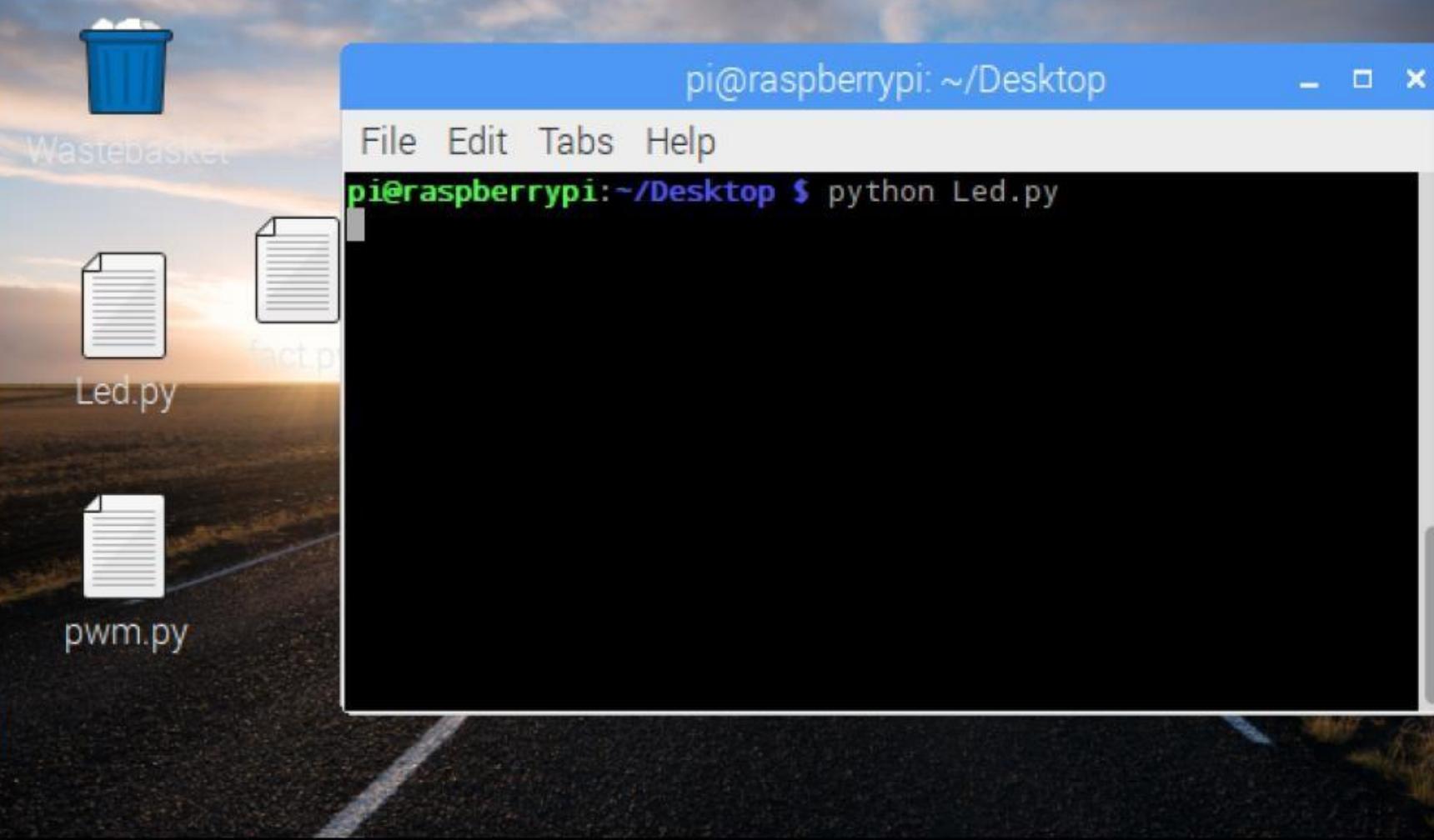
- Write a python code in the text editor provided in the raspberry pi desktop accessories to blink an LED after every 1 sec.
- Save the file in “.py” format at the desktop or wherever you may wish.
- Then run the command “python filename.py” on the terminal after changing directory to Desktop using “cd Desktop” command.

LEDblink



Code

```
import RPi.GPIO as GPIO
import time
LedPin = 11      # pin11
GPIO.setmode(GPIO.BRD)          # Numbers GPIOs by physical location
GPIO.setup(LedPin, GPIO.OUT)    # Set LedPin's mode is output
GPIO.output(LedPin, GPIO.HIGH)  # Set LedPin high(+3.3V) to turn on led
try:
    while True:
        GPIO.output(LedPin, GPIO.HIGH)  # led on
        time.sleep(1)
        GPIO.output(LedPin, GPIO.LOW)   # led off
        time.sleep(1)
except KeyboardInterrupt:
    GPIO.output(LedPin, GPIO.LOW)   # led off
    GPIO.cleanup()                 # Release resource
```

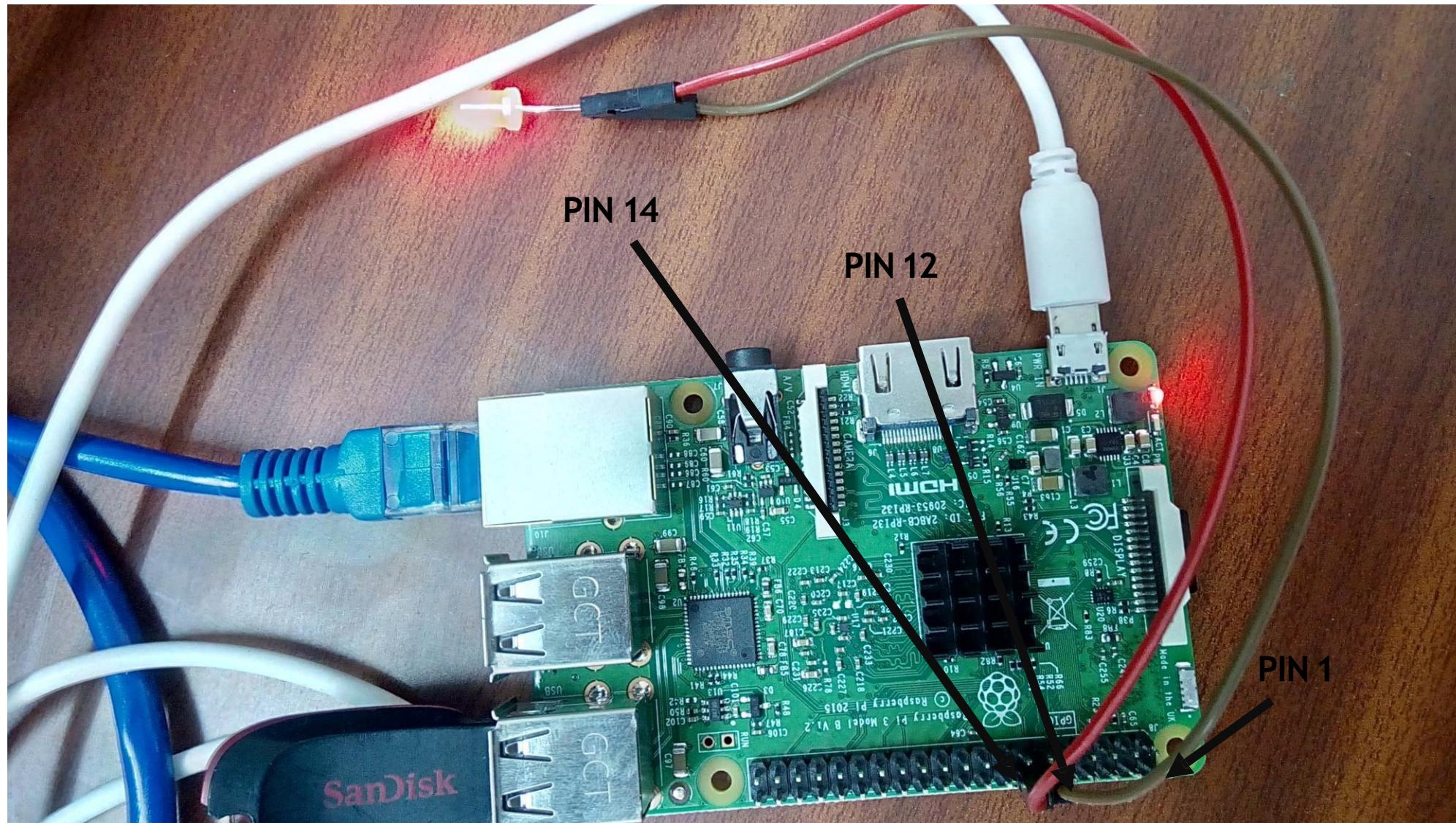


169.254.47.125



169.254.47.125

PWM



PWM

```
1 import RPi.GPIO as GPIO
2 import time
3 GPIO.setmode(GPIO.BOARD)
4 GPIO.setup(12, GPIO.OUT)
5 pwm12 = GPIO.PWM(12,50)
6 pwm12.start(0)
7 try:
8     while True:
9         for dutyCycle in range(0,100,5):
10             pwm12.ChangeDutyCycle(dutyCycle)
11             time.sleep(0.1)
12         for dutyCycle in range(100,0,-5):
13             pwm12.ChangeDutyCycle(dutyCycle)
14             time.sleep(0.1)
15     except KeyboardInterrupt:
16         pwm12.stop()
17     GPIO.cleanup()
```