

# Schema Theorem for Binary Coded GA

- Proposed by Prof. John Holland
- An attempt to give GA a mathematical foundation

Let us consider a population of binary-strings created at random

1	1	0	0	1	1
0	1	0	1	0	0
⋮	⋮	⋮	⋮	⋮	⋮
1	1	0	1	1	1
1	1	0	0	0	0

Let us assume the following two schemata (templates):

$H_1$ : \* 1 0 \* \* \*

$H_2$ : \* 1 0 \* 0 0

( \* could be either 1 or 0)

$H_1: * 1 0 * * *$

$H_2: * 1 0 * 0 0$

- Order of schema  $O(H)$ :

No. of fixed positions (bits) present in a schema

For example:  $O(H_1) = 2$ ;  $O(H_2) = 4$

- Defining length of schema  $\delta(H)$ :

Distance between the first and last fixed positions in a string

For example:  $\delta(H_1) = 3-2 = 1$ ;  $\delta(H_2) = 6-2 = 4$

- Effect of Selection:

Let  $m(H, t)$  = No. of strings belonging to schema H at  $t^{\text{th}}$  Gen.

$m(H, t+1)$  = No. of strings belonging to schema H at  $(t+1)^{\text{th}}$  Gen.

$$E [m(H, t + 1)] = m(H, t) \frac{f(H)}{\bar{f}}$$

$f(H)$  = Schema fitness or Avg. fitness of the strings represented by schema H

$\bar{f}$  = Avg. fitness of the entire population at t-th Gen.

- Effect of Crossover (Single-point):

Let  $P_c$  = Probability of crossover and

$L$  = String length

A schema is destroyed if crossover site falls within the defining length

$$\text{Probability of destruction} = p_c \frac{\delta(H)}{L-1}$$

$$\text{Probability of survival} = 1 - p_c \frac{\delta(H)}{L-1}$$

- Effect of Mutation (Bit-wise Mutation):

To protect a schema, mutation should not occur at the fixed bits

Let  $p_m$  : probability of mutation

probability of destruction of a single bit =  $p_m$

probability of survival of a single bit =  $1 - p_m$

Probability of survival of the whole schema,

$$p_s = (1 - p_m) (1 - p_m) \dots \dots \dots O(H)$$

$$= (1 - p_m)^{O(H)}$$

$$= 1 - O(H) p_m \quad \text{as } p_m \ll 1$$

Considering the contributions of all three operators,

$$E [m(H, t + 1)] = m(H, t) \frac{f(H)}{\bar{f}} \left[ 1 - p_c \frac{\delta(H)}{L-1} - O(H) p_m \right] \quad (\text{neglecting 2}^{\text{nd}} \text{ order term})$$

### **Building-Block Hypothesis:**

The schemata having low order, short defining length and fitness considerably more than average fitness of the population will have more and more representations in future generations

## Limitations of Binary Coded GA

- Unable to yield any arbitrary precision in the solution → Real Coded GA
- Hamming Cliff problem → creates an artificial hindrance to the gradual search of GA → Gray Coded GA

14 :	0 1 1 1 0	↷	1 change
15 :	0 1 1 1 1	↷	5 changes
16 :	1 0 0 0 0	↷	

## Real Coded GA:

Chromosome:

x1	x2	x3	x4	x5	x6
5.82	1.10	9.22	3.61	8.30	2.99

✓ Selection: Same as Binary Coded GA

✓ Crossover: Single point

### Linear Crossover

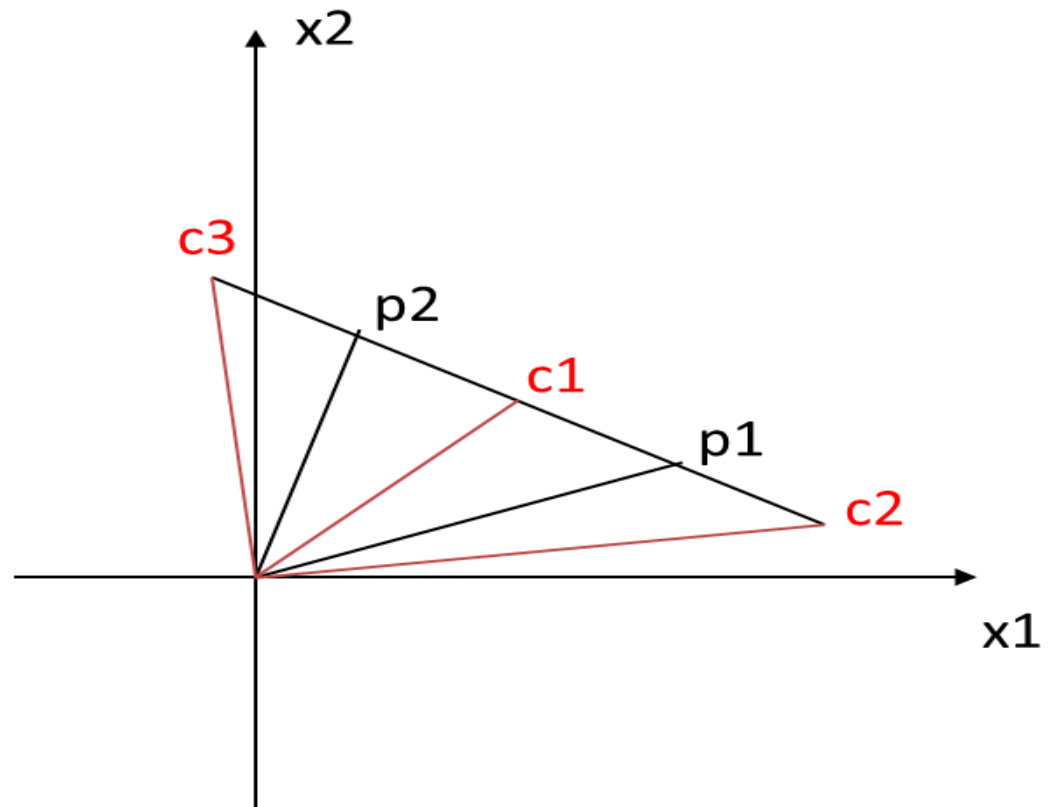
$$\text{Ch1} = 0.5 * \text{Pr1} + 0.5 * \text{Pr2}$$

$$\text{Ch2} = 1.5 * \text{Pr1} - 0.5 * \text{Pr2}$$

$$\text{Ch3} = -0.5 * \text{Pr1} + 1.5 * \text{Pr2}$$

} Best  
Two





$$c_2, c_3 = \frac{P_1 + P_2}{2} \pm (P_1 - P_2)$$

## Blend Crossover

$$\text{Ch1} = (1-\gamma) * \text{Pr1} + \gamma * \text{Pr2}$$

$$\text{Ch2} = \gamma * \text{Pr1} + (1-\gamma) * \text{Pr2}$$

$\gamma = 2 * r - 0.5$  where  $r$  is a uniform random number in  $[0,1]$

i.e.  $\gamma$  is a uniform random number in  $[-0.5,1.5]$

## Simulated Binary Crossover

- ✓ Mutation: Replace a value with a random value in the entire range or in a random neighbourhood  
(neighbourhood may shrink as generation increases)

- Mutation probability in RCGA is more than that in BCGA

Let  $m$  be the string length for a variable  $x_1$  in BCGA

Probability that this variable survives mutation is  $(1 - P_m)^m$   
 $\approx (1 - mP_m)$

Hence,  $(1 - P_m^R) = (1 - mP_m^B)$

$$P_m^R = m P_m^B$$

## **Numerical Example:**

maximize  $f(x_1, x_2) = -x_1^2 - 2x_2^2 - x_1x_2$  ;  $-5 \leq x_1, x_2 \leq 5.0$

Assume the mating pool to be (4,0); (-2,2); (3,1); (3,1)

Consider mating pairs as 1-3 and 2-4

Obtain the next generation by linear crossover.

Assume  $P_c = 1.0$  and  $P_m = 0$ .

## **Answer:**

(3.5, 0.5); (2.5, 1.5); (0.5, 1.5); (-4.5, 2.5)

## Constraints Handling in GA (also applicable to PSO)

optimize  $f(\underline{x})$

subject to

$$g_j(\underline{x}) \leq 0, j = 1, 2, \dots, m$$

$$h_k(\underline{x}) = 0, k = 1, 2, \dots, p$$

$$\underline{x} = [x_1 \ x_2 \ \dots \ x_n]^T$$

$$\underline{x}_{\min} \leq \underline{x} \leq \underline{x}_{\max}$$

Let  $m+p = q$

Functional constraints

$$\Phi_k(\underline{x}), k = 1, 2, \dots, q$$

## Penalty Function Approach

Fitness function of  $i^{\text{th}}$  solution

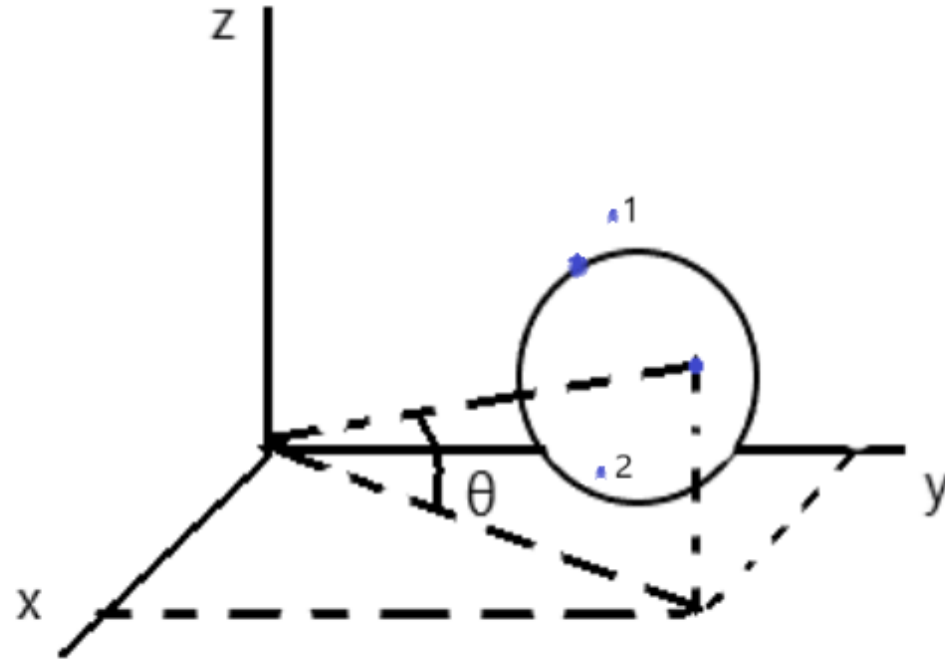
$$F_i(X) = f_i(X) \pm P_i \quad (+ \text{ for minimization problems})$$

where  $P_i$  indicates penalty given by

$$P_i = C \sum_{k=1}^q \{ \varphi_{ik}(X) \}^2$$

$C$  indicates penalty coefficient

**Example:**



## Static Penalty

Fitness of i-th solution

$$F_i(X) = f_i(X) + \sum_{k=1}^q C_{k,r} \{ \varphi_{ik}(X) \}^2$$

where  $C_{k,r}$  :  $r^{\text{th}}$  level violation of  $k^{\text{th}}$  constraint

(amount of violation is divided into various pre-defined levels)



## Dynamic Penalty

Fitness

$$F_i(X) = f_i(X) + (C.t)^\alpha \sum_{k=1}^q |\varphi_{ik}(X)|^\beta$$

where C,  $\alpha$ ,  $\beta$  are user-defined constants

t = number of generations

✓ Penalty increasing with generation number (pressurizing GA)

## Adaptive Penalty

$$\text{Fitness} \quad F_i(X) = f_i(X) + \lambda(t) \sum_{k=1}^q \{\phi_{ik}(X)\}^2$$

where  $t$  : number of generations

$$\lambda(t+1) = \begin{cases} \frac{1}{\beta_1} \cdot \lambda(t), & \text{if best soln. of last } N_f \text{ GEN were feasible} \\ \beta_2 \cdot \lambda(t), & \text{if infeasible} \end{cases}$$

if neither,  $\lambda(t+1) = \lambda(t)$  ( where  $\beta_1 \neq \beta_2$  and  $\beta_1, \beta_2 > 1$  )