

Iterative Deepening Depth First Search

Shreyas.M

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```
class graph:
    def __init__(self, vertices):
        self.v = vertices vertices
        self.node_arr = []
        self.graph = defaultdict(list)

    def addEdges(self, x, y):
        self.graph[x].append(y)

    def DLS(self, target, depth, arr, src):
        if src == target:
            arr.append(src)
            return True

        if depth <= 0:
            return False
            arr.append(src)

        for i in self.graph[src]:
            if (self.DLS(i, target, depth - 1, arr)):
                return True

        arr.pop()
        return False
```

G = graph(7)

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g.addedge(0,1)

g.addedge(0,2)

g.addedge(0,3)

g.addedge(1,4)

g.addedge(2,5)

g.addedge(2,6)

target = 8;

depth = 6;

src = 0

if g.DFS(src, target, depth) == true:

print("Source can reach target")

else:

print("~~g~~ Source cannot reach target")

print(g.nodes)