Implement Naive Bayes models and Bayesian networks. (Demonstrate the diagnosis of heart patients using standard heart disease data set etc)

Algorithm:

- Load and preprocess the dataset (e.g., UCI Heart Disease dataset).
- Calculate prior probabilities for each class (disease present or not).
- Compute likelihood probabilities using conditional probability and the assumption of feature independence (for Naïve Bayes).
- Apply Bayes' Theorem to compute posterior probabilities.
- Classify new patient data based on the highest posterior probability

Code:

X = data.drop(columns=["target"])

```
import pandas as pd
import numpy as np
from sklearn.model_selection import train_test_split
from sklearn.naive_bayes import GaussianNB
from sklearn.metrics import accuracy_score, classification_report
from pgmpy.models import BayesianModel
from pgmpy.estimators import MaximumLikelihoodEstimator
from pgmpy.inference import VariableElimination
dataset_url = "https://archive.ics.uci.edu/ml/machine-learning-databases/heart-disease/processed.cleveland.data"
columns = ["age", "sex", "cp", "trestbps", "chol", "fbs", "restecg", "thalach", "exang", "oklpeak", "slope", "ca", "thal", "target"]
data = pd.read_csv(dataset_url, names=columns, na_values="?")
data.dropna(inplace=True)
data["target"] = (data["target"] > 0).astype(int)
```

```
y = data["target"]

X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=42)

nb_model = GaussianNB()

nb_model.fit(X_train, y_train)

y_pred = nb_model.predict(X_test)

print("Accuracy:", accuracy_score(y_test, y_pred))

print(classification_report(y_test, y_pred))

model = BayesianModel([("age", "target"), ("sex", "target"), ("cp", "target"), ("chol", "target"), ("thal", "target")])

model.fit(data, estimator=MaximumLikelihoodEstimator)

infer = VariableElimination(model)

print("Probability of Heart Disease given cp=3:")

print(infer.query(variables=["target"], evidence={"cp": 3}))
```

Accuracy:	0.9	0.9166666666666666				
		precision	recall	f1-score	support	
	0	0.90	0.97	0. 93	36	
	1	0.95	0.83	0.89	24	
accur	асу			0. 92	60	
macro	avg	0.92	0.90	0.91	60	
weighted	avg	0.92	0.92	0.92	60	

Implement a simple linear regression algorithm to predict a continuous target variable based on a given dataset.

Algorithm:

- Load dataset and preprocess it.
- Define the hypothesis function:Y=mX+b.
- Compute the cost function (Mean Squared Error).
- Use Gradient Descent or Least Squares to optimize m and b.
- Predict values for new inputs and visualize results.

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from sklearn.model_selection import train_test_split
from sklearn.linear_model import LinearRegression
from sklearn.metrics import mean_squared_error, r2_score
from sklearn.datasets import fetch_california_housing
data = fetch_california_housing()
df = pd.DataFrame(data.data, columns=data.feature_names)
df["Price"] = data.target

X = df[["MedInc"]]
y = df["Price"]
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=42)
model = LinearRegression()
```

model.fit(X_train, y_train)
y_pred = model.predict(X_test)
mse = mean_squared_error(y_test, y_pred)
r2 = r2_score(y_test, y_pred)
print(f'Mean Squared Error: {mse:.2f}'')
print(f'R-squared: {r2:.2f}'')

Output

Mean Squared Error: 0.71

R-squared: 0.46

Develop a program to implement a Support Vector Machine for binary classification. Use a sample dataset and visualize the decision boundary.

Algorithm:

- Load and preprocess dataset.
- Define the SVM objective: maximize margin between two classes.
- Solve the optimization problem using techniques like the SMO algorithm.
- Use kernels (linear, polynomial, RBF) if needed.
- Plot the decision boundary using Matplotlib.

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from sklearn import datasets
from sklearn.model_selection import train_test_split
from sklearn.svm import SVC
from sklearn.metrics import accuracy_score
from mlxtend.plotting import plot_decision_regions
iris = datasets.load_iris()
df = pd.DataFrame(data=iris.data, columns=iris.feature_names)
df['target'] = iris.target
df = df[df['target'] != 2]
X = df[['sepal length (cm)', 'sepal width (cm)']].values
y = df['target'].values
```

```
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=42)

svm_model = SVC(kernel='linear')

svm_model.fit(X_train, y_train)

y_pred = svm_model.predict(X_test)

accuracy = accuracy_score(y_test, y_pred)

print(fAccuracy: {accuracy:.2f}')

plt.figure(figsize=(8,6))

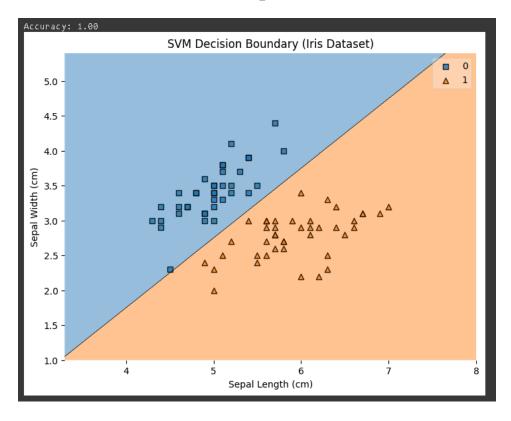
plot_decision_regions(X_train, y_train, clf=svm_model)

plt.xlabel('Sepal Length (cm)')

plt.ylabel('Sepal Width (cm)')

plt.title('SVM Decision Boundary (Iris Dataset)')

plt.show()
```



Write a program to demonstrate the ID3 decision tree algorithm using an appropriate dataset for classification.

Algorithm:

- Load dataset and preprocess it.
- Compute entropy and information gain for each feature.
- Select the feature with the highest information gain as the root node.
- Recursively split the dataset based on feature values until all instances belong to the same class.
- Use the trained tree to classify new data points.

```
import pandas as pd

from google.colab import drive

drive.mount('/content/drive')

data=pd.read_csv('/content/drive/MyDrive/workshop/placementdata.csv')

import numpy as np

import seaborn as sns

import matplotlib.pyplot as plt

from sklearn.model_selection import train_test_split

from sklearn.preprocessing import StandardScaler

from sklearn.tree import DecisionTreeClassifier, plot_tree

from sklearn.metrics import accuracy_score,confusion_matrix,classification_report

data.head()

data.duplicated().sum()

data.snull().sum()

data.shape
```

```
data.info()
data.describe()
data['PlacementStatus'].value counts().plot(kind='bar')
data['PlacementStatus'].value counts()/len(data)*100
placement plot=['Internships','Projects','Workshops/Certifications','Extracurricular Activities','Placement
Training']
plt.figure(figsize=(15,12))
for i,graph in enumerate(placement plot):
 plt.subplot(2,3,i+1)
 sns.countplot(x=graph,data=data,hue='PlacementStatus')
 plt.title(fPLacement status based on {graph}')
num col=data.select dtypes('number')
num col.columns.tolist()
non num col=data.select dtypes('object')
non num col.columns.tolist()
data['PlacementStatus'].replace({'Placed':1,'NotPlaced':0},inplace=True)
data['PlacementStatus'].head()
from sklearn.preprocessing import LabelEncoder
le=LabelEncoder()
data['PlacementStatus']=le.fit transform(data['PlacementStatus'])
data['ExtracurricularActivities']=le.fit transform(data['ExtracurricularActivities'])
data['PlacementTraining']=le.fit transform(data['PlacementTraining'])
data.info()
x=data.drop(['PlacementStatus','StudentID'],axis=1)
y=data['PlacementStatus']
x train,x test,y train,y test=train test split(x,y,test size=0.25,random state=42)
```

```
scaler=StandardScaler()
scaler=StandardScaler()
x train scaled=scaler.fit transform(x train)
x test scaled=scaler.transform(x test)
mode |= DecisionTreeClassifier()
model.fit(x_train_scaled,y_train)
plt.figure(figsize=(12,8))
plot tree(model,filled=True,feature names=x.columns,class names=['Placed','NotPlaced'])
plt.show()
clf=DecisionTreeClassifier(max depth=3,min samples leaf=5,min samples split=10)
clf.fit(x train scaled,y train)
plt.figure(figsize=(12,8))
plot tree(clf,filled=True,feature names=x.columns,class names=['Placed','NotPlaced'])
plt.show()
y pred model=model.predict(x test scaled)
y pred clf=clf.predict(x test scaled)
print(classification report(y test,y pred model))
print(classification report(y test,y pred clf))
importances=model.feature_importances_
feature importances df=pd.DataFrame({'feature':x train.columns,'importance':importances})
feature importances df.sort values(by='importance',ascending=False,inplace=True)
feature importances df
x=data.drop(['SoftSkillsRating','Workshops/Certifications','Internships','Projects','PlacementTraining'],a
xis=1)
print(x.head())
x=x.drop(['SoftSkillsRating','SoftSkillsRating','Workshops/Certifications','Internships','Projects','Placem
```

```
entTraining'],axis=1)

y=data['PlacementStatus']

x_train,x_test,y_train,y_test=train_test_split(x,y,test_size=0.25,random_state=42)

scaler=StandardScaler()

scaler=StandardScaler()

x_train_scaled=scaler.fit_transform(x_train)

x_test_scaled=scaler.transform(x_test)

clf=DecisionTreeClassifier(max_depth=3,min_samples_leaf=5,min_samples_split=10)

clf.fit(x_train_scaled,y_train)

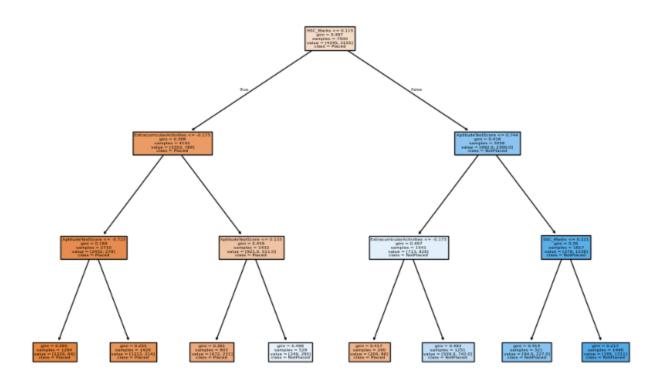
plt.figure(figsize=(12,8))

plot_tree(clf,filled=True,feature_names=x.columns,class_names=['Placed','NotPlaced'])

plt.show()

y_pred_clf=clf.predict(x_test_scaled)

print(classification_report(y_test,y_pred_clf))
```



Implement a KNN algorithm for regression tasks instead of classification. Use a small dataset, and predict continuous values based on the average of the nearest neighbors.

Algorithm:

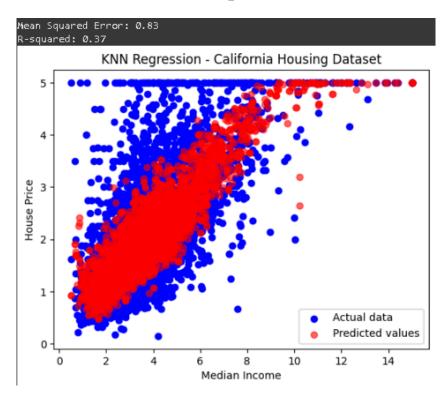
- Load and preprocess dataset.
- Choose the number of neighbors (K).
- Compute the Euclidean distance between the query point and all training samples.
- Select the K nearest neighbors.
- Compute the average of their target values to predict the output.

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from sklearn.model_selection import train_test_split
from sklearn.meighbors import KNeighborsRegressor
from sklearn.metrics import mean_squared_error, r2_score
from sklearn.datasets import fetch_california_housing
data = fetch_california_housing()
df = pd.DataFrame(data.data, columns=data.feature_names)
df["Price"] = data.target # Target variable

X = df[["MedInc"]] # Median income as predictor
y = df["Price"] # House price as target

X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=42)
knn_model = KNeighborsRegressor(n_neighbors=5)
knn_model.fit(X_train, y_train)
```

```
y_pred = knn_model.predict(X_test)
mse = mean_squared_error(y_test, y_pred)
r2 = r2_score(y_test, y_pred)
print(f'Mean Squared Error: {mse:.2f}'')
print(f'R-squared: {r2:.2f}'')
plt.scatter(X_test, y_test, color='blue', label='Actual data')
plt.scatter(X_test, y_pred, color='red', label='Predicted values', alpha=0.6)
plt.xlabel('Median Income')
plt.ylabel('House Price')
plt.title('KNN Regression - California Housing Dataset')
plt.legend()
plt.show()
```



Implement the k-Nearest Neighbor algorithm to classify the Iris dataset, printing both correct and incorrect predictions

Algorithm:

- Load the Iris dataset.
- Choose K.
- Compute the Euclidean distance between the query point and training points.
- Select K nearest neighbors.
- Assign the most common class among the neighbors to the query point.
- Print correct and incorrect predictions.

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from sklearn import datasets
from sklearn.model_selection import train_test_split
from sklearn.neighbors import KNeighborsClassifier
from sklearn.metrics import accuracy_score, classification_report
iris = datasets.load_iris()
df= pd.DataFrame(data=iris.data, columns=iris.feature_names)
df['target'] = iris.target
X = df[iris.feature_names].values
y = df['target'].values
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=42)
knn model = KNeighborsClassifier(n_neighbors=5)
```

```
knn_model.fit(X_train, y_train)
y_pred = knn_model.predict(X_test)
accuracy = accuracy_score(y_test, y_pred)
print(f'Accuracy: {accuracy:.2f}')
print(classification_report(y_test, y_pred))
```

Accuracy: 1.0	90			
	precision	recall	f1-score	support
Ø	1.00	1.00	1.00	10
1	1.00	1.00	1.00	9
2	1.00	1.00	1.00	11
accuracy			1.00	30
macro avg	1.00	1.00	1.00	30
weighted avg	1.00	1.00	1.00	30

Develop a program to implement the non-parametric Locally Weighted Regression algorithm, fitting data points and visualizing results.

Algorithm:

- Load and preprocess dataset.
- Define a weight function W(x)W(x)W(x) that assigns higher weights to closer points.
- Compute the weighted least squares estimate for a given query point.
- Predict and visualize the regression line.

```
import numpy as np
import matplotlib.pyplot as plt
def gaussian kernel(x, x0, tau):
  return np.exp(-np.sum((x - x0)**2) / (2 * tau**2))
def compute weights(X, x0, tau):
  m = X.shape[0]
  weights = np.zeros(m)
  for i in range(m):
     weights[i] = gaussian kernel(X[i], x0, tau)
  return np.diag(weights)
def locally weighted regression(X, y, x0, tau):
  X b = np.c [np.ones((X.shape[0], 1)), X] # Add intercept term
  x0 b = np.r [1, x0] # Add intercept term to the query point
  W = compute weights(X, x0, tau)
  theta = np.linalg.inv(X b.T @ W @ X b) @ (X b.T @ W @ y)
  return x0 b @ theta
```

```
def plot_lwr(X, y, tau):

X_range = np.linspace(np.min(X), np.max(X), 300)

y_pred = [locally_weighted_regression(X, y, x0, tau) for x0 in X_range]

plt.scatter(X, y, color='blue', label='Data points')

plt.plot(X_range, y_pred, color='red', label='LWR fit')

plt.xlabel('X')

plt.ylabel('y')

plt.title(fLocally Weighted Regression (tau={tau})')

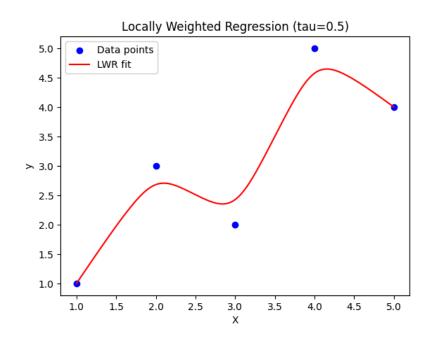
plt.legend()

plt.show()

X = np.array([[1], [2], [3], [4], [5]])

y = np.array([1, 3, 2, 5, 4])

plot_lwr(X, y, tau=0.5)
```



Build an Artificial Neural Network by implementing the Backpropagation algorithm and test it with suitable datasets.

Algorithm:

- Initialize weights randomly.
- Forward propagation: Compute activations using weights.
- Compute error using a loss function (e.g., Mean Squared Error for regression, Cross-Entropy for classification).
- Backpropagation: Compute gradients and update weights using Gradient Descent.
- Repeat until convergence.

```
import numpy as np
import matplotlib.pyplot as plt
from sklearn.datasets import make_moons
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import OneHotEncoder
X, y = make_moons(n_samples=500, noise=0.2, random_state=42)
y = y.reshape(-1, 1)
encoder = OneHotEncoder(sparse_output=False)
y = encoder.fit_transform(y)
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=42)
def sigmoid(x):
    return 1 / (1 + np.exp(-x))
def sigmoid_derivative(x):
    return x * (1 - x)
input_size = X_train.shape[1]
```

```
hidden size = 5
output size = y_train.shape[1]
learning rate = 0.1
epochs = 10000
np.random.seed(42)
W1 = np.random.randn(input size, hidden size)
B1 = np.zeros((1, hidden size))
W2 = np.random.randn(hidden size, output size)
B2 = np.zeros((1, output size))
losses = []
for epoch in range(epochs):
  Z1 = \text{np.dot}(X \text{ train, } W1) + B1
  A1 = sigmoid(Z1)
  Z2 = np.dot(A1, W2) + B2
  A2 = sigmoid(Z2)
  loss = np.mean((A2 - y_train) ** 2)
  losses.append(loss)
  dA2 = A2 - y train
  dZ2 = dA2 * sigmoid_derivative(A2)
  dW2 = np.dot(A1.T, dZ2)
  dB2 = np.sum(dZ2, axis=0, keepdims=True)
  dA1 = np.dot(dZ2, W2.T)
  dZ1 = dA1 * sigmoid derivative(A1)
  dW1 = np.dot(X train.T, dZ1)
  dB1 = np.sum(dZ1, axis=0, keepdims=True)
```

```
W2 -= learning rate * dW2
  B2 -= learning rate * dB2
  W1 -= learning rate * dW1
  B1 -= learning rate * dB1
  if epoch \% 1000 == 0:
     print(f'Epoch {epoch}, Loss: {loss:.4f}")
plt.plot(losses)
plt.xlabel("Epochs")
plt.ylabel("Loss")
plt.title("Training Loss Curve")
plt.show()
def predict(X):
  Z1 = np.dot(X, W1) + B1
  A1 = sigmoid(Z1)
  Z2 = np.dot(A1, W2) + B2
  A2 = sigmoid(Z2)
  return np.argmax(A2, axis=1)
predictions = predict(X test)
y_test_labels = np.argmax(y_test, axis=1)
accuracy = np.mean(predictions == y_test_labels)
print(f'Test Accuracy: {accuracy:.2f}")
```

```
Epoch 0, Loss: 0.3792

Epoch 1000, Loss: 0.0149

Epoch 2000, Loss: 0.0140

Epoch 3000, Loss: 0.0130

Epoch 4000, Loss: 0.0121

Epoch 5000, Loss: 0.0112

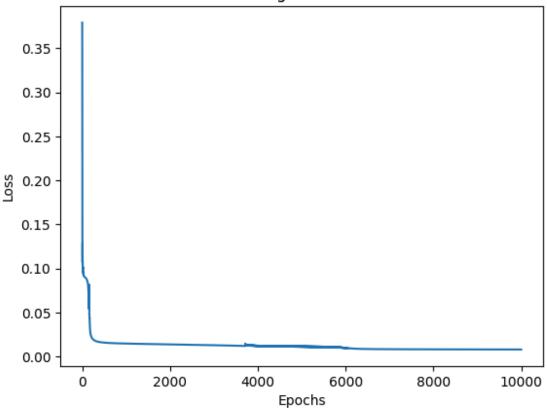
Epoch 6000, Loss: 0.0098

Epoch 7000, Loss: 0.0085

Epoch 8000, Loss: 0.0084

Epoch 9000, Loss: 0.0082
```

Training Loss Curve



Test Accuracy: 0.97

Implement a Q-learning algorithm to navigate a simple grid environment, defining the reward structure and analyzing agent performance

Algorithm:

- Define the environment (states, actions, rewards).
- Initialize Q-table with zeros.
- For each episode:
- Select an action using an epsilon-greedy policy.
- Take the action, observe reward, and update the Q-value:

$$Q(s,a)=Q(s,a)+\alpha[r+\gamma \max Q(s',a')-Q(s,a)]$$

• Repeat until convergence and analyze agent performance.

Code:

import numpy as np

import random

import matplotlib.pyplot as plt

GRID SIZE =
$$5$$

ACTION_MAP =
$$\{0: (-1, 0), 1: (1, 0), 2: (0, -1), 3: (0, 1)\}$$

GOAL STATE =
$$(4, 4)$$

PENALTY STATE =
$$(2, 2)$$

GAMMA = 0.9 # Discount factor

ALPHA = 0.1 # Learning rate

EPSILON = 0.1 # Exploration rate

```
EPISODES = 1000
Q table = np.zeros((GRID SIZE, GRID SIZE, len(ACTIONS)))
episode rewards = []
episode steps = []
def take action(state, action):
  new_state = (max(0, min(GRID_SIZE - 1, state[0] + ACTION_MAP[action][0])),
          max(0, min(GRID SIZE - 1, state[1] + ACTION MAP[action][1])))
  if new state == GOAL STATE:
    return new state, 10 # Reward for reaching goal
  elif new state == PENALTY STATE:
    return new state, -10 # Penalty state
  else:
    return new state, -1 # Small penalty for each move
for episode in range(EPISODES):
  state = (0, 0) # Start at top-left corner
  done = False
  total reward = 0
  steps = 0
  while not done:
    # Choose action (ε-greedy policy)
    if random uniform(0, 1) \le EPSILON:
       action = random.randint(0, len(ACTIONS) - 1) # Explore
     else:
       action = np.argmax(Q table[state[0], state[1], :]) # Exploit
    new state, reward = take action(state, action)
```

```
Q table[state[0], state[1], action] += ALPHA * (
                                          reward + GAMMA * np.max(Q\_table[new\_state[0], new\_state[1], :]) - Q\_table[state[0], new\_state[0], :]) - Q\_table[state[0], new\_state[0], :]) - Q\_table[state[0], new\_state[0], :]) - Q\_
state[1], action]
                   )
                   state = new state
                   total reward += reward
                   steps += 1
                   if state == GOAL STATE or state == PENALTY STATE:
                             done = True
         episode rewards.append(total reward)
         episode steps.append(steps)
policy = np.full((GRID SIZE, GRID SIZE), 'X')
for i in range(GRID SIZE):
         for j in range(GRID SIZE):
                  if (i, j) == GOAL STATE:
                            policy[i, j] = 'G'
                  elif(i, j) == PENALTY STATE:
                           policy[i, j] = 'P'
                   else:
                             best action = np.argmax(Q table[i, j, :])
                             policy[i, j] = ACTIONS[best action][0].upper()
print("Optimal Policy:")
print(policy)
plt.figure(figsize=(12, 5))
plt.subplot(1, 2, 1)
plt.plot(episode rewards)
```

```
plt.xlabel("Episodes")

plt.ylabel("Total Reward")

plt.title("Episode Rewards Over Time")

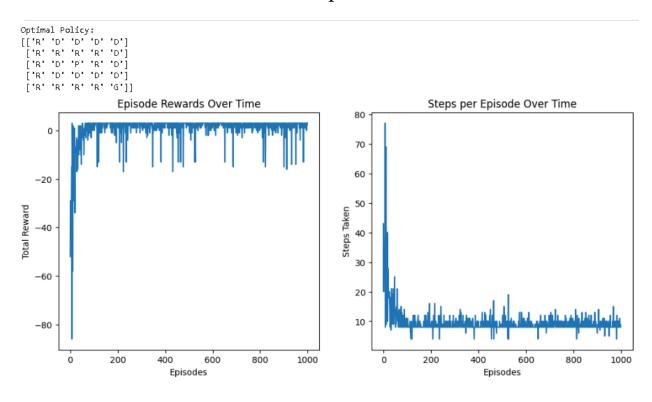
plt.subplot(1, 2, 2)

plt.plot(episode_steps)

plt.xlabel("Episodes")

plt.ylabel("Steps Taken")

plt.title("Steps per Episode Over Time")
```



Write a python program

- a. to perform tokenization by word and sentence using nltk.
- b. to eliminate stop words using nltk.
- c. to perform stemming using nltk.
- d. to perform Parts of Speech tagging using nltk.

Algorithm:

a. Tokenization (Splitting text into words/sentences)

- Use nltk.word tokenize(text) for word tokenization.
- Use nltk.sent_tokenize(text) for sentence tokenization.

b. Remove Stop Words

• Use nltk.corpus.stopwords to filter out common words like "the", "is", etc.

c. Stemming (Reducing words to root form)

• Use nltk.stem.PorterStemmer to transform words (e.g., "running" → "run").

d. POS Tagging (Assigning part-of-speech labels to words)

• Use nltk.pos tag(tokens) to label words as nouns, verbs, etc.

```
user_input = input("Enter some text: ")
upper_input = user_input.upper()
upper_input
import nltk
from nltk.stem import PorterStemmer
from nltk.tokenize import word_tokenize
text=input("Enter some text: ")
```

```
text = text.lower()
words = word tokenize(text)
ps = PorterStemmer()
stemmed_words = [ps.stem(w) for w in words]
stemmed\_words
import nltk
from nltk.tokenize import word_tokenize
text=input("Enter some text: ")
text = text.lower()
words = word_tokenize(text)
pos_tags = nltk.pos_tag(words)
pos_tags
import spacy
nlp=spacy.load('en_core_web_sm')
doc=nlp('she saw a bear')
for word in doc:
 print (word.text,word.pos_)
```

A.

Enter some text: Once upon a time, in a quaint village nestled between rolling hills and lush forests, there lived a young girl named Aria. Aria had a special gift: she could communicate with animals. Every morning, she would wander into the forest, where the birds would sing her songs, and the deer would share their secrets. One day, a mysterious creature appeared, and Aria's life changed forever...

```
['onc',
'upon',
'a',
'time',
',
'in',
'a',
'quaint',
'villag',
'nestl',
'between',
```

B.

Enter some text: Once upon a time, in a quaint village nestled between rolling hills and lush forests, there lived a young girl named Aria. Aria had a special gift: she could communicate with animals. Every morning, she would wander into the forest, where the birds would sing her songs, and the deer would share their secrets. One day, a mysterious creature appeared, and Aria's life changed forever...

C.

she PRON saw VERB a DET bear NOUN