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CODE:-
print(f"SHREYASGOWDA C (1BM23CS319)")
MAX VISITED DISPLAY = 10
NUM_INTERMEDIATE_STATES = 3
MAX DEPTH LIMIT = 50
def print state(state):
  for row in state:
     print(' '.join(str(x) for x in row))
  print()
def is goal(state, goal state):
  return state == goal_state
def find_zero(state):
  for i in range(3):
     for j in range(3):
        if state[i][j] == 0:
          return i, j
def get_neighbors(state):
  neighbors = []
  x, y = find zero(state)
  directions = [(1,0), (-1,0), (0,1), (0,-1)]
  for dx, dy in directions:
     new x, new y = x + dx, y + dy
     if 0 \le \text{new } x \le 3 \text{ and } 0 \le \text{new } y \le 3:
        new_state = [row[:] for row in state]
        new_state[x][y], new_state[new_x][new_y] = new_state[new_x][new_y], new_state[x][y]
        neighbors.append(new state)
  return neighbors
def is solvable(state):
  flat = [num for row in state for num in row if num != 0]
  inv count = 0
  for i in range(len(flat)):
     for j in range(i + 1, len(flat)):
        if flat[i] > flat[j]:
          inv count += 1
  return inv count % 2 == 0
def dls(current state, goal state, depth limit, path, visited, visited states display):
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8 PUZZLE USING IDDFS
  Depth-Limited Search helper for IDDFS.
  Returns:
     path if goal found else None
  if len(path) - 1 > depth limit:
     return None
  visited states display.append(current state)
  if len(visited states display) <= MAX VISITED DISPLAY:
     print(f"Visited state #{len(visited states display)}:")
     print state(current state)
  if is_goal(current_state, goal_state):
     return path
  for neighbor in reversed(get_neighbors(current_state)):
     neighbor tuple = tuple(tuple(row) for row in neighbor)
     if neighbor_tuple not in visited:
       visited.add(neighbor tuple)
       result = dls(neighbor, goal state, depth limit, path + [neighbor], visited,
visited_states_display)
       if result is not None:
          return result
       visited.remove(neighbor tuple)
  return None
def iddfs(start_state, goal_state, max_depth=MAX_DEPTH_LIMIT):
  Iterative Deepening DFS:
  Tries DFS with increasing depth limits until goal found or max depth exceeded.
  print("Starting Iterative Deepening DFS traversal...\n")
  for depth in range(max depth + 1):
     print(f"Trying depth limit: {depth}")
     visited states display = []
     visited = set()
     visited.add(tuple(tuple(row) for row in start state))
     path = dls(start_state, goal_state, depth, [start_state], visited, visited_states_display)
     if path is not None:
       print(f"\nGoal reached at depth {depth}!")
       print(f"Total visited states in last iteration: {len(visited states display)}")
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return path
     print(f"No solution found at depth {depth}\n")
  print(f"No solution found within max depth limit {max depth}")
  return None
def read state(name):
  print(f"Enter the {name} state, row by row (use space-separated numbers, 0 for empty):")
  state = []
  for _ in range(3):
     row = input().strip().split()
     if len(row) != 3:
       raise ValueError("Each row must have exactly 3 numbers.")
     row = list(map(int, row))
     state.append(row)
  return state
initial_state = read_state("initial")
goal state = read state("goal")
if not (is_solvable(initial_state) == is_solvable(goal_state)):
  print("The puzzle is unsolvable.")
  exit()
solution path = iddfs(initial state, goal state)
if solution path:
  cost = len(solution path) - 1
  print(f"\nSolution found with cost: {cost}\n")
  print("Solution path:")
  total_steps = len(solution_path) - 1
  print("Initial State:")
  print_state(solution_path[0])
  if total steps > 1:
     step indices = list(range(1, total steps))
     if len(step_indices) > NUM_INTERMEDIATE_STATES:
       interval = len(step indices) // (NUM INTERMEDIATE STATES + 1)
       selected_indices = [step_indices[i * interval] for i in range(1,
NUM_INTERMEDIATE_STATES + 1)]
     else:
       selected indices = step indices
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for idx in selected_indices:
    print(f"Intermediate State (Step {idx}):")
    print_state(solution_path[idx])

print("Final State:")
print_state(solution_path[-1])
else:
print("No solution found")
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# **OUTPUT:-**

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