Underwater Image Enhancement - Shreyas Lal

Subtask 1: Variational Autoencoders (VAEs)

Import necessary libraries

```
import os
import numpy as np
import matplotlib.pyplot as plt
from tensorflow.keras import layers, models
from tensorflow.keras.preprocessing.image import load_img,
img_to_array
import tensorflow as tf
from skimage.metrics import structural_similarity as ssim
```

Set paths

```
train_raw_path = '/kaggle/input/slal-task2-dataset/Train/Raw/'
train_ref_path = '/kaggle/input/slal-task2-dataset/Train/Reference/'
```

Load Images

Function to load and preprocess images

Load training images and reference images

```
train_images = load_images(train_raw_path)
reference_images = load_images(train_ref_path)
```

Visualize a few loaded images

```
for i in range(min(5, len(train_images))):
   plt.imshow(train_images[i])
   plt.axis('off')
   plt.title(f'Training Image {i+1}')
   plt.show()
```

Training Image 1



Training Image 2



Training Image 3



Training Image 4



Training Image 5



```
# Define the VAE model
def build vae():
   inputs = layers.Input(shape=(480, 640, 3)) # Input shape for
images
   # Encoder
   x = layers.Conv2D(32, 3, activation='relu', padding='same')
(inputs) # 1st convolutional layer
   x = layers.MaxPooling2D((2, 2))(x) # Downsample the feature maps
   x = layers.Conv2D(64, 3, activation='relu', padding='same')(x) #
2nd convolutional layer
   x = layers.MaxPooling2D((2, 2))(x) # Further downsampling
   x = layers.Conv2D(128, 3, activation='relu', padding='same')(x) #
3rd convolutional laver
   x = layers.MaxPooling2D((2, 2))(x) # Further downsampling
   # Latent space
   x = layers.Flatten()(x) # Flatten the output
    z mean = layers.Dense(64)(x) # Mean of the latent space
    z log var = layers.Dense(64)(x) # Log variance of the latent
space
   # Sampling layer
    z = layers.Lambda(sampling, output_shape=(64,))([z mean,
z log var]) # Sample from the latent space
   # Decoder
   x = layers.Dense(30 * 40 * 128, activation='relu')(z) # Expand
the latent representation
   x = layers.Reshape((30, 40, 128))(x) # Reshape to a 3D tensor
   # Deconvolutional layers to upsample back to the original image
size
   x = layers.Conv2DTranspose(128, 3, activation='relu',
padding='same')(x) # 1st upsampling step
   x = layers.UpSampling2D((2, 2))(x) # Upsample the feature maps
   x = layers.Conv2DTranspose(64, 3, activation='relu',
padding='same')(x) # 2nd upsampling step
   x = layers.UpSampling2D((2, 2))(x) # Upsample again
   x = layers.Conv2DTranspose(32, 3, activation='relu',
padding='same')(x) # 3rd upsampling step
   x = layers.UpSampling2D((2, 2))(x) # Upsample again
   # Final layer to output the reconstructed image
    outputs = layers.Conv2DTranspose(3, 3, activation='sigmoid',
padding='same')(x) # 3 channels for RGB
```

```
vae = models.Model(inputs, outputs) # Create the VAE model
    return vae
# Function for sampling from the latent space
def sampling(args):
    z_mean, z_log_var = args # Get mean and log variance
   batch = tf.shape(z mean)[0] # Get the batch size
   dim = tf.shape(z mean)[1] # Get the dimension of the latent space
    epsilon = tf.keras.backend.random normal(shape=(batch, dim)) #
Sample epsilon
    return z mean + tf.exp(0.5 * z log var) * epsilon # Return the
sampled latent vector
# Load images
train raw path = '/kaggle/input/slal-task2-dataset/Train/Raw/'
train images = load images(train raw path)
# Compile and train the VAE
vae = build vae() # Build the VAE model
vae.compile(optimizer='adam', loss='binary crossentropy') # Compile
model with Adam optimizer and binary crossentropy loss
vae.fit(train images, train images, epochs=50, batch size=32) # Train
the VAE
# Function to generate enhanced images from the VAE
def generate images(model, n=10):
   noise = np.random.normal(size=(n, 64)) # Generate noise in the
latent space size (64)
   generated images = model.predict(noise) # Use the VAE model to
generate images from the noise
    return generated images
# Generate and visualize the enhanced images
generated images = generate images(vae, n=5)
# Evaluate and compare original and generated images
def evaluate_images(original, generated):
   mse scores = [] # Store Mean Squared Error scores
    ssim scores = [] # Store Structural Similarity Index scores
    for orig, gen in zip(original, generated):
        mse = mean_squared_error(orig.flatten(), gen.flatten()) #
Calculate MSE
        ssim_value = ssim(orig, gen, multichannel=True) # Calculate
SSIM
        mse scores.append(mse) # Append MSE score
        ssim scores.append(ssim value) # Append SSIM score
    return mse scores, ssim scores
# Evaluate the first few original images against generated images
```

```
mse scores, ssim scores = evaluate images(train images[:5],
generated images)
# Print evaluation results
print("Mean Squared Errors (MSE):", mse scores)
print("Structural Similarity Indices (SSIM):", ssim scores)
# Visualize original vs generated images
def visualize comparison(original, generated):
    n = min(len(original), len(generated))
    plt.figure(figsize=(15, 6))
    for i in range(n):
        plt.subplot(2, n, i + 1)
        plt.imshow(original[i]) # Original image
        plt.axis('off') # Turn off axis labels
        plt.title("Original")
        plt.subplot(2, n, i + 1 + n)
        plt.imshow(generated[i]) # Generated image
        plt.axis('off') # Turn off axis labels
        plt.title("Generated")
    plt.show()
# Compare the first few original and generated images
visualize comparison(train images[:5], generated images)
Epoch 1/50
ValueError
                                          Traceback (most recent call
last)
Cell In[12], line 58
     56 vae = build vae() # Build the VAE model
     57 vae.compile(optimizer='adam', loss='binary crossentropy') #
Compile model with Adam optimizer and binary crossentropy loss
---> 58 vae.fit(train images, train images, epochs=50, batch size=32)
# Train the VAE
     60 # Function to generate enhanced images from the VAE
     61 def generate images (model, n=10):
File
/opt/conda/lib/python3.10/site-packages/keras/src/utils/traceback util
s.py:122, in filter_traceback.<locals>.error_handler(*args, **kwargs)
            filtered_tb = _process_traceback_frames(e.__traceback__)
    119
    120
            # To get the full stack trace, call:
            # `keras.config.disable traceback filtering()`
    121
--> 122
            raise e.with traceback(filtered tb) from None
    123 finally:
    124
            del filtered tb
```

```
File
/opt/conda/lib/python3.10/site-packages/keras/src/backend/tensorflow/
nn.py:668, in binary crossentropy(target, output, from logits)
    666 for el, e2 in zip(target.shape, output.shape):
           if el is not None and el is not None and el != el:
    667
--> 668
                raise ValueError(
                    "Arguments `target` and `output` must have the
    669
same shape. "
                    "Received: "
    670
    671
                    f"target.shape={target.shape},
output.shape={output.shape}"
    672
    674 output, from logits = get logits(
            output, from logits, "Sigmoid", "binary crossentropy"
    676 )
    678 if from logits:
ValueError: Arguments `target` and `output` must have the same shape.
Received: target.shape=(None, 480, 640, 3), output.shape=(None, 240,
320, 3)
```

VAE Modelling

```
# Sampling function for the reparameterization trick in VAEs
def sampling(args):
    z mean, z log var = args
    batch = tf.shape(z mean)[0]
    dim = tf.shape(z mean)[1]
    epsilon = tf.keras.backend.random normal(shape=(batch, dim))
    return z mean + tf.exp(0.5 * z log var) * epsilon
# Build the VAE model
def build vae():
    # Input shape adjusted for 640x480 RGB images
    inputs = layers.Input(shape=(480, 640, 3))
    # Encoder
    x = layers.Conv2D(32, 3, activation='relu', padding='same')
(inputs)
    x = layers.MaxPooling2D()(x)
    x = layers.Conv2D(64, 3, activation='relu', padding='same')(x)
    x = layers.MaxPooling2D()(x)
    # Latent space representation
    x = layers.Flatten()(x)
    x = layers.Dense(128, activation='relu')(x) # Increased dense
layer for complexity
```

```
# Mean and log variance for the latent space
    z mean = layers.Dense(32)(x)
    z \log var = layers.Dense(32)(x)
    # Sample a point in latent space
    z = layers.Lambda(sampling)([z mean, z log var])
    # Decoder
    x = layers.Dense(120 * 160 * 64, activation='relu')(z) # Adjust
based on downsampling
    x = layers.Reshape((120, 160, 64))(x)
    x = layers.Conv2DTranspose(64, 3, activation='relu',
padding='same')(x)
    x = layers.UpSampling2D()(x)
    x = layers.Conv2DTranspose(32, 3, activation='relu',
padding='same')(x)
    x = layers.UpSampling2D()(x)
    # Final layer to output the reconstructed image with the same
shape as the input
    outputs = layers.Conv2DTranspose(3, 3, activation='sigmoid',
padding='same')(x)
    # Define the VAE model
    vae = models.Model(inputs, outputs)
    # Encoder and decoder models for optional use
    encoder = models.Model(inputs, z mean)
    # Decoder input is latent space, then generate the image
    latent inputs = layers.Input(shape=(32,))
    x = layers.Dense(120 * 160 * 64, activation='relu')(latent_inputs)
    x = layers.Reshape((120, 160, 64))(x)
    x = layers.Conv2DTranspose(64, 3, activation='relu',
padding='same')(x)
    x = layers.UpSampling2D()(x)
    x = layers.Conv2DTranspose(32, 3, activation='relu',
padding='same')(x)
    x = lavers.UpSampling2D()(x)
    decoded output = layers.Conv2DTranspose(3, 3,
activation='sigmoid', padding='same')(x)
    decoder = models.Model(latent inputs, decoded output)
    return vae, encoder, decoder
# Compile and train the VAE
vae, encoder, decoder = build_vae()
```

```
vae.compile(optimizer='adam', loss='binary crossentropy')
# Assuming 'train images' is your dataset of underwater images
# Normalize train images to the range [0, 1]
train images = train images / 255.0
vae.fit(train images, train images, epochs=50, batch size=32)
# Function to generate images from random latent space vectors
def generate images(decoder, n=10):
    noise = np.random.normal(size=(n, 32)) # Generate random vectors
in latent space
    generated images = decoder.predict(noise) # Generate images using
decoder
    return generated images
# Generate and visualize the generated images
generated_images = generate_images(decoder)
for i in range(len(generated images)):
    plt.imshow(generated images[i])
    plt.axis('off')
    plt.show()
def build vae():
    # Define the input shape for the encoder; here it's set for
128x128 RGB images
    inputs = layers.Input(shape=(128, 128, 3))
    # Encoder
    #Start with a convolutional layer followed by max pooling
    x = layers.Conv2D(32, 3, activation='relu', padding='same')
(inputs)# 32 filters, kernel size of 3x3
    x = layers.MaxPooling2D()(x) # Downsample the feature maps
    # Another convolutional layer to extract more features
    x = layers.Conv2D(64, 3, activation='relu', padding='same')(x) #
64 filters
    x = layers.MaxPooling2D()(x) # Further downsampling
    # Latent space
    #Flatten the output from the convolutional layers to create a
vector representation
    latent space = layers.Flatten()(x) # Convert to a 1D vector
    latent space = layers.Dense(32)(latent_space) # Dense layer for
latent representation
    # Decoder
    # Reconstruct the image from the latent space
    x = layers.Dense(64 * 32 * 32, activation='relu')(latent space) #
```

```
Dense layer to expand the latent representation
    x = layers.Reshape((32, 32, 64))(x) # Reshape into a 3D tensor
(32x32 feature maps with 64 channels)
    # Deconvolutional layers to upsample back to the original image
size
    x = layers.Conv2DTranspose(64, 3, activation='relu',
padding='same')(x) # First upsampling step
    x = layers.UpSampling2D()(x) # Upsample the feature maps
    x = layers.Conv2DTranspose(32, 3, activation='relu',
padding='same')(x) # Second upsampling step
    x = layers.UpSampling2D()(x) # Unsample again
    # Final layer to output the reconstructed image with same
dimensions as input
    outputs = layers.Conv2DTranspose(3, 3, activation='sigmoid',
padding='same')(x)
    # Create the VAE model combining inputs and outputs
    vae = models.Model(inputs, outputs)
    return vae
# Compile and train the VAE
vae = build vae() # Build the VAE model
vae.compile(optimizer='adam', loss='binary crossentropy') # Compile
model with Adam optimizer and binary crossentropy loss
vae.fit(train_images, train_images, epochs=50, batch_size=32) # Train
the VAE, using images as both input and output
# Function to generate enhanced images from the VAE
def generate images (model, n=10):
    # Create an array of random noise with the same shape as the
images
    noise = np.random.normal(size=(n, 128, 128, 3)) # Sample random
noise
    generated images = model.predict(noise) # Use the VAE model to
generate images from the noise
    return generated images
# Generate and visualize images
generated images = generate images(vae) # Call the function to
generate a specified number of images
for i in range(len(generated images)): # Loop through generated images
    plt.imshow(generated images[i])
    plt.axis('off')
    plt.show()
Epoch 1/50
22/22 -
                         - 25s 985ms/step - loss: 0.6609
```

Epoch	2/50	21-	021mc/c+c-	000	0 6210	
Epoch	3/50					
Epoch 22/22 Epoch 22/22 Epoch 22/22	4/50					
	5/50	41s	952ms/step - lo	oss:	0.6244	
	6/50	41s	959ms/step - lo	oss:	0.6160	
		21s	935ms/step - lo	oss:	0.6054	
22/22		21s	935ms/step - lo	oss:	0.5972	
Epoch 22/22 Epoch 22/22 Epoch 22/22 Epoch 22/22 Epoch 22/22 Epoch 22/22 Epoch 22/22 Epoch 22/22 Epoch 22/22 Epoch 22/22 Epoch 22/22 Epoch 22/22 Epoch	8/50	41s	949ms/step - lo	oss:	0.5949	
	9/50					
	10/50		970ms/step - lo			
	11/50	213	1. /stan 1	033.	0.3003	
	12/50					
	13/50					
	14/50	20s	925ms/step - lo	oss:	0.5786	
		21s	967ms/step - lo	oss:	0.5787	
		40s	923ms/step - lo	oss:	0.5820	
		21s	957ms/step - lo	oss:	0.5718	
	17/50	20s	929ms/step - lo	oss:	0.5743	
	18/50		942ms/step - lo			
	19/50		946ms/step - lo			
	20/50		•			
Epoch	21/50		943ms/step - lo			
-	22/50	41s	941ms/step - lo	oss:	0.5743	
-	23/50	21s	936ms/step - lo	oss:	0.5770	
22/22		41s	954ms/step - lo	oss:	0.5741	
22/22		20s	928ms/step - lo	oss:	0.5635	
22/22		20s	907ms/step - lo	oss:	0.5668	
Epoch	26/50					

-	27/50	21s	935ms/step	-	loss:	0.5685	
22/22		20s	902ms/step	-	loss:	0.5660	
	28/50	21s	949ms/step	-	loss:	0.5707	
	29/50		910ms/step				
Epoch	30/50		945ms/step				
Epoch	31/50		•				
Epoch	32/50						
Epoch	33/50						
22/22	34/50	41s	935ms/step	-	loss:	0.5666	
22/22		41s	921ms/step	-	loss:	0.5629	
22/22		21s	946ms/step	-	loss:	0.5572	
	36/50	21s	955ms/step	-	loss:	0.5650	
Epoch	37/50		949ms/step				
Epoch	38/50		•				
Epoch	39/50		941ms/step				
Fnoch	40/50						
22/22 Epoch	41/50	20s	923ms/step	-	loss:	0.5650	
22/22	-	21s	962ms/step	-	loss:	0.5632	
22/22		21s	952ms/step	-	loss:	0.5619	
22/22	43/50	20s	915ms/step	-	loss:	0.5648	
	44/50	21s	958ms/step	-	loss:	0.5619	
	45/50		936ms/step				
Epoch	46/50		·				
Epoch	47/50		996ms/step				
Epoch	48/50		971ms/step				
-	49/50	22s	1s/step - 1	los	ss: 0.5	6602	
22/22		21s	937ms/step	-	loss:	0.5589	
Lpocii	30/30						



















