Experiment No 1

LIT System: To find the impulse response of a given system, Solution of difference equation, Verification of Sampling Theorem.

```
i)LIT System
%Without initializing values
%y(n)+0.8y(n-2)+0.6y(n-3)=x(n)+0.7x(n-1)+0.5x(n-2)
clear all;
close all;
b=input('Enter the coefficients of x ');
a=input('Enter the coefficients of y ');
N=input('Enter the length of the input sequence ');
n=0:1: N;
step=1.^n;
imp=[1,zeros(1,N)];
RES1=filter(b,a,step)
RES2=filter(b,a,imp)
subplot(2,2,1)
stem(n,step)
grid on
xlabel('Time');
ylabel('Amplitude');
title('Step Input')
subplot(2,2,2)
stem(n,imp)
grid on
xlabel('Time');
ylabel('Amplitude');
title('Impulse Input')
subplot(2,2,3)
stem(n,RES1)
grid on
xlabel('Time');
ylabel('Amplitude');
title('Step Response')
subplot(2,2,4)
stem(n,RES2)
grid on
xlabel('Input');
ylabel('Output Response');
title('Impulse Response')
```

Result

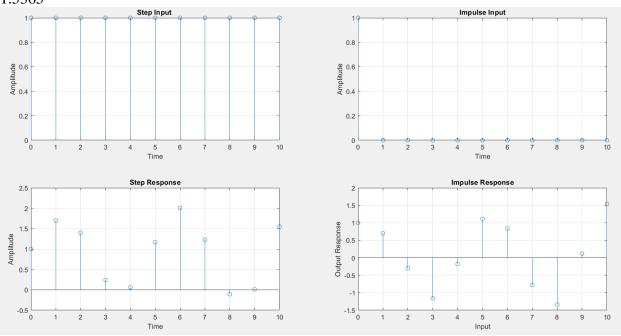
Enter the coefficients of x [1 0.7 0.5] Enter the coefficients of y [1 0 0.8 0.6] Enter the length of the input sequence 10

RES1 =

1.0000 1.7000 1.4000 0.2400 0.0600 1.1680 2.0080 1.2296 -0.1072 0.0115 1.5480

RES2 =

1.0000 0.7000 -0.3000 -1.1600 -0.1800 1.1080 0.8400 -0.7784 -1.3368 0.1187 1.5365

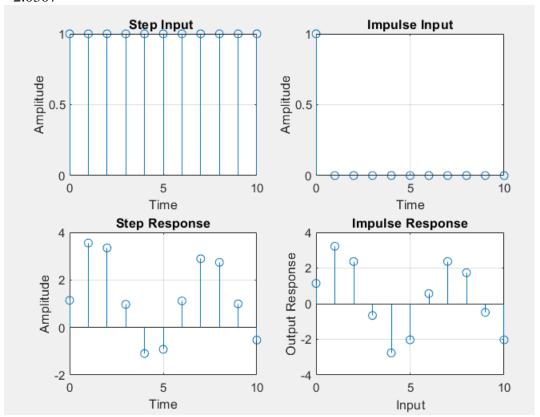


```
Program 2 %Initializing Y values %y(n)=1//3x(n)+1/3x(n-1)+1/3x(n-2)+0.95y(n-1)-0.9025y(n-2) %y(-1)=-2, y(-2)=-3 clear all; close all; b=input('Enter the coefficients of x '); a=input('Enter the coefficients of y '); N=input('Enter the length of the input sequence '); n=0:1:N; step=1.^n;
```

```
imp=[1,zeros(1,N)];
Y=[-2 -3];
XIC=filtic(b,a,Y);
RES1=filter(b,a,step,XIC)
RES2=filter(b,a,imp,XIC)
subplot(2,2,1)
stem(n,step)
grid on
xlabel('Time');
ylabel('Amplitude');
title('Step Input');
subplot(2,2,2)
stem(n,imp)
grid on
xlabel('Time');
ylabel('Amplitude');
title('Impulse Input');
subplot(2,2,3)
stem(n,RES1)
grid on
xlabel('Time');
ylabel('Amplitude');
title('Step Response');
subplot(2,2,4)
stem(n,RES2)
grid on
xlabel('Input');
ylabel('Output Response');
title('Impulse Response');
Result
Enter the coefficients of x [1/3 \ 1/3 \ 1/3]
Enter the coefficients of y [1 -0.95 0.9025]
Enter the length of the input sequence 10
RES1 =
           3.5555 3.3481 0.9719 -1.0984 -0.9206 1.1167 2.8917 2.7393 0.9925
  1.1408
-0.5293
```

RES2 =

1.1408 3.2221 2.3647 -0.6615 -2.7626 -2.0275 0.5671 2.3686 1.7383 -0.4862 -2.0307



%For the given interval (y(n)-y(n-1)+0.9y(n-2)=x(n) for all n (n-5)=5

```
%For the given interval
%y(n)-y(n-1)+0.9y(n-2)=x(n) for all n
%n=-5:5

clear all;
close all;
b=input('Enter the coefficients of x ');
a=input('Enter the coefficients of y ');
n=-5:5;
step=[zeros(1,5) ones(1,5)];
imp=[zeros(1,5) 1 zeros(1,5)];

RES1=filter(b,a,step)
RES2=filter(b,a,imp)
subplot(2,2,1)
```

```
stem(step)
grid on
xlabel('Time');
ylabel('Amplitude');
title('Step Input ');
subplot(2,2,2)
stem(imp)
grid on
xlabel('Time');
ylabel('Amplitude');
title('Impulse Input');
subplot(2,2,3)
stem(RES1)
grid on
xlabel('Time');
ylabel('Amplitude');
title('Step Response');
subplot(2,2,4)
stem(RES2)
grid on
xlabel('Time');
ylabel('Amplitude');
title('Impulse Response');
Result
Enter the coefficients of x 1
Enter the coefficients of y [1 -1 0.9]
RES1 =
   0
        0
          0
                 0
                      0 1.0000 2.0000 2.1000 1.3000 0.4100
RES2 =
```

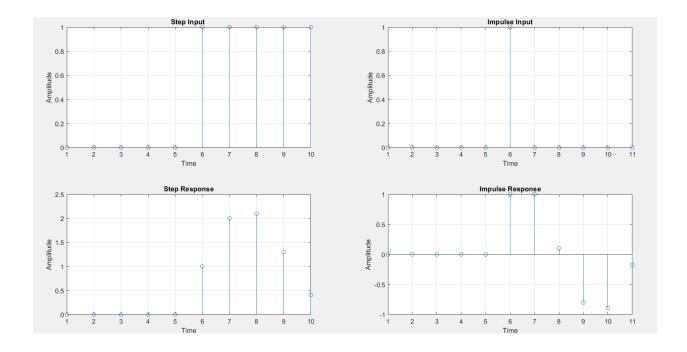
0 1.0000 1.0000 0.1000 -0.8000 -0.8900 -0.1700

0

0

0

0



ii) Sampling Theorem

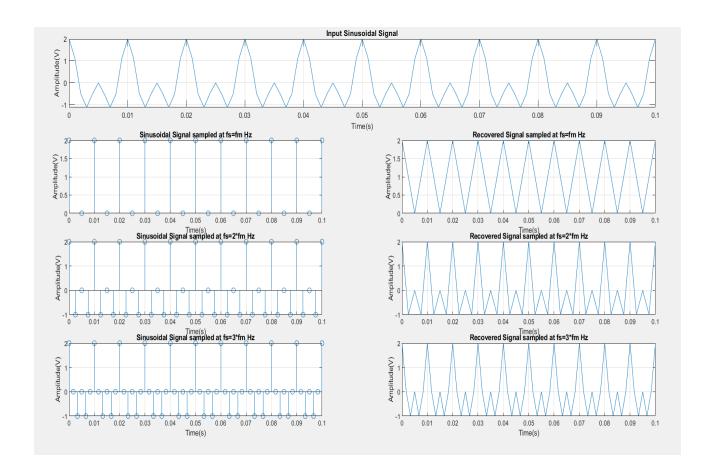
```
close all;
clear all;
t=0:0.001:0.1;
f1=input('Enter the Input Frequency1 = ');
f2=input('Enter the Input Frequency2 = ');
%Input Signal
y=cos(2*pi*f1*t) + cos(2*pi*f2*t);
fm=max(f1,f2);
subplot(4,1,1)
plot(t,y);
grid on;
title('Input Sinusoidal Signal');
xlabel('Time(s)');
ylabel('Amplitude(V)');
%Under Sampling
fs1=fm;
ts1=1/fs1;
tx1=0:ts1:0.1;
y1=cos(2*pi*f1*tx1) + cos(2*pi*f2*tx1)
subplot(4,2,3)
stem(tx1,y1);
grid on;
```

```
title('Sinusoidal Signal sampled at fs=fm Hz');
xlabel('Time(s)');
ylabel('Amplitude(V)');
subplot(4,2,4)
plot(tx1,y1);
grid on;
title('Recovered Signal sampled at fs=fm Hz');
xlabel('Time(s)');
ylabel('Amplitude(V)');
%Right Sampling
fs2=2*fm;
ts2=1/fs2;
tx2=0:ts2:0.1
y2=\cos(2*pi*f1*tx2) + \cos(2*pi*f2*tx2)
subplot(4,2,5)
stem(tx2,y2);
grid on;
title('Sinusoidal Signal sampled at fs=2*fm Hz');
xlabel('Time(s)');
ylabel('Amplitude(V)');
subplot(4,2,6)
plot(tx2,y2);
grid on;
title('Recovered Signal sampled at fs=2*fm Hz');
xlabel('Time(s)');
ylabel('Amplitude(V)');
%Over Sampling
fs3=3*fm;
ts3=1/fs3;
tx3=0:ts3:0.1;
y3 = cos(2*pi*f1*tx3) + cos(2*pi*f2*tx3)
subplot(4,2,7)
stem(tx3,y3);
grid on;
title('Sinusoidal Signal sampled at fs=3*fm Hz');
xlabel('Time(s)');
ylabel('Amplitude(V)');
subplot(4,2,8)
plot(tx3,y3);
```

```
grid on;
title('Recovered Signal sampled at fs=3*fm Hz');
xlabel('Time(s)');
ylabel('Amplitude(V)');
```

Result

Enter the Input Frequency 1 = 100Enter the Input Frequency 2 = 200



Experiment No 2

```
ii) Linear Convolution
```

i=n-k+1;

```
clear all;
close all;
x=input('Enter the first input sequence x[n] ');
h=input('Enter the first input sequence h[n] ');
Lx=length(x);
Lh=length(h);
len=Lx+Lh -1;
for n=1:len
    y(n) = 0;
    for k=1:Lx
         if((n-k) >= 0 & (n-k) < Lh)
             y(n) = y(n) + x(k) \cdot *h(n-k+1);
         end
    end
end
disp('Linear Convolution of x[n] & h[n] is ')
disp(y)
Result
Enter the first input sequence x[n] [1 2 3 4]
Enter the first input sequence h[n] [1 0 1]
Linear Convolution of x[n] & h[n] is
  1 2 4 6 3 4
ii) Circular Convolution
clear all;
close all;
x1=input('Enter the first input sequence x1[n] ');
x2=input('Enter the first input sequence x2[n] ');
Lx1=length(x1);
Lx2=length(x2);
len=max(Lx1,Lx2);
if Lx1<len</pre>
    x1=[x1, zeros(len-Lx1)];
else
    x2=[x2, zeros(len-Lx2)];
end
for n=1:len
    v(n) = 0;
    for k=1:len
```

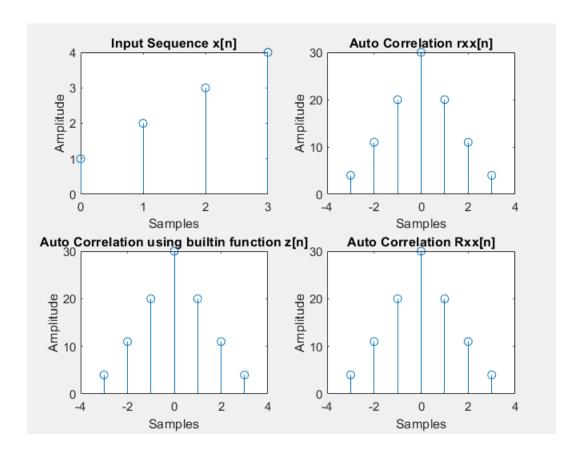
```
if (i<=0)</pre>
              i=i+len;
         end
         y(n) = y(n) + x2(k) *x1(i);
    end
end
disp('Circular Convolution of x1[n] & x2[n] is ')
disp(y)
Result
Enter the first input sequence x1[n] [1 2 3 4]
Enter the first input sequence x2[n] [1 0 1]
Circular Convolution of x1[n] & x2[n] is
  4 6 4 6
iii) Autocorrelation
clear all;
close all;
x=input('Enter the input sequence x[n]');
Lx=length(x)-1;
h=fliplr(x);
rxx=conv(x,h);
disp('Auto Corelation of x[n] is rxx[n]')
disp(rxx)
%Verification using builtin function xcorr()
z=xcorr(x,x);
disp('Auto Corelation of x[n] using builtin function is
z[n]')
disp(z)
%Auto correlation using for loop
len=2*Lx+1;
for n=1:len
    Rxx(n) = 0;
    for k=1:Lx+1
         if((n-k) >= 0 & (n-k) <= Lx)
             Rxx(n) = Rxx(n) + x(k) \cdot *h(n-k+1);
         end
    end
end
disp('Auto Corelation of x[n] is Rxx[n]')
disp(Rxx)
%Ploting the graph
```

```
a=0:Lx;
subplot(2,2,1)
stem(a,x)
title('Input Sequence x[n]')
xlabel('Samples')
ylabel('Amplitude')
b = (-Lx) : Lx;
subplot(2,2,2)
stem(b,Rxx)
title('Auto Correlation rxx[n]')
xlabel('Samples')
ylabel('Amplitude')
subplot(2,2,3)
stem(b,z)
title ('Auto Correlation using builtin function z[n]')
xlabel('Samples')
ylabel('Amplitude')
subplot(2,2,4)
stem(b,z)
title('Auto Correlation Rxx[n]')
xlabel('Samples')
ylabel('Amplitude')
Result
Enter the input sequence x[n][1 \ 2 \ 3 \ 4]
Auto Corelation of x[n] is rxx[n]
  4 11 20 30 20 11 4
```

Auto Corelation of x[n] using builtin function is z[n]

Auto Corelation of x[n] is Rxx[n] 4 11 20 30 20 11 4

4.0000 11.0000 20.0000 30.0000 20.0000 11.0000 4.0000



iv) Cross Correlation

```
clear all;
close all;
x=input('Enter the input sequence x[n]');
Lx=length(x)-1;
h=input('Enter the second sequence h[n]');
Lh = length(h) - 1;
y=fliplr(h);
Rxy=conv(x,y);
disp('Cross Correlation is Rxy[n]')
disp(Rxy)
%Verification using builtin function xcorr()
z=xcorr(x,h);
disp('Cross Correlation using builtin function is z[n]')
disp(z)
%Cross correlation using for loop
len=Lx+Lh+1;
for n=1:len
    rxx(n) = 0;
    for k=1:Lx+1
```

```
if((n-k) >= 0 & (n-k) <= Lh)
             rxx(n) = rxx(n) + x(k) \cdot *y(n-k+1);
        end
    end
end
disp('Cross Correlation of x[n] is Z[n]')
disp(rxx)
a=0:Lx;
subplot(3,2,1)
stem(a,x)
title('First Input Sequence x[n]')
xlabel('Samples')
ylabel('Amplitude')
b=0:Lh;
subplot(3,2,2)
stem(a,h)
title('Second Input Sequence y[n]')
xlabel('Samples')
ylabel('Amplitude')
C = (-LX) : LX;
subplot(3,2,3)
stem(c, Rxy)
title('Cross Correlation Rxy[n] using builtin function
xcorr()')
xlabel('Samples')
ylabel('Amplitude')
subplot(3,2,4)
stem(c, z)
title('Cross Correlation using builtin function xcorr()
z[n]')
xlabel('Samples')
ylabel('Amplitude')
subplot(3, 2, 5:6)
stem(c,rxx)
title('Cross Correlation rxx[n]')
xlabel('Samples')
ylabel('Amplitude')
```

Result

Enter the input sequence $x[n][1\ 2\ 3\ 4]$

Enter the second sequence h[n][4 3 2 1] Cross Correlation is Rxy[n]

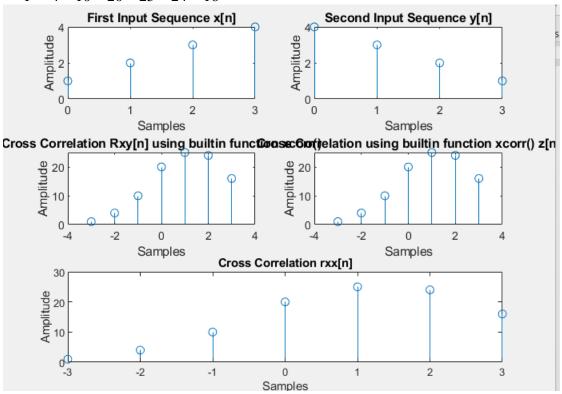
1 4 10 20 25 24 16

Cross Correlation using builtin function is z[n]

1.0000 4.0000 10.0000 20.0000 25.0000 24.0000 16.0000

Cross Correlation of x[n] is Z[n]

1 4 10 20 25 24 16



Experiment No 3

To find DFT and IDFT of a sequence

```
close all;
clear all;
x=input('Enter the input sequence x[n]=')
L=length(x)
N=input('Enter the length of the DFT sequence N =');
if (N<L)
    disp('N should be greater than L')
else
    %Wn=-j*2*pi/N;
    for k=0:N-1
        X(k+1) = 0;
        for n=0:L-1
             X(k+1) = X(k+1) + x(n+1) * exp(-j*2*pi*n*k/N);
        end
    end
    disp('DFT of x[n] is X(K)=')
    disp(X)
end
%Verification
disp('DFT using built in function')
Y = fft(x, N)
disp(Y)
%Inverse DFT
for n=0:N-1
    y(n+1) = 0;
    for k=0:L-1
        y(n+1) = y(n+1) + X(k+1) * exp(j*2*pi*n*k/N);
    end
    y(n+1) = y(n+1)/N;
disp('IDFT of X(K) is y(n) = ')
disp(y)
%Verification
disp('IDFT using built in function ')
Z=ifft(X)
disp(Z)
a=0:L-1;
subplot(3,2,1)
```

```
stem(a, x)
grid on
title('Input Sequence x[n]')
xlabel('Samples')
ylabel('Values')
b=0:N-1;
subplot(3,2,2)
stem(b, X)
grid on
title('DFT Sequence X(K)')
xlabel('Samples')
ylabel('Values')
subplot(3,2,3)
stem(b,abs(X))
grid on
title('DFT magnitude')
xlabel('Samples')
ylabel('Values')
subplot(3,2,4)
stem(b, angle(X))
grid on
title('DFT phase angle')
xlabel('Samples')
ylabel('Values')
subplot(3,2,5)
stem(y)
grid on
title('IDFT sequence y[n]')
xlabel('Samples')
ylabel('Values')
Result:
Enter the input sequence x[n]=[1\ 2\ 3\ 4]
\mathbf{x} =
```

1 2 3 4

L =

Enter the length of the DFT sequence N =4 DFT of x[n] is X(K)= 10.0000 + 0.0000i -2.0000 + 2.0000i -2.0000i -2.0000i -2.0000i -2.0000i

DFT using built in function

Y =

10.0000 + 0.0000i -2.0000 + 2.0000i -2.0000 + 0.0000i -2.0000 - 2.0000i 10.0000 + 0.0000i -2.0000 + 2.0000i -2.0000 + 0.0000i -2.0000 - 2.0000i

IDFT of X(K) is y(n) =

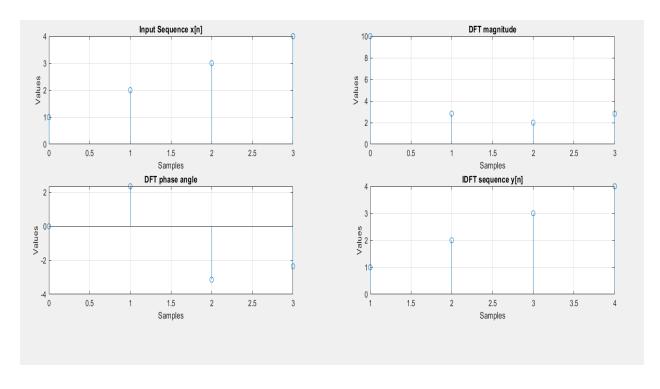
1.0000 - 0.0000i 2.0000 - 0.0000i 3.0000 - 0.0000i 4.0000 + 0.0000i

IDFT using built in function

 $\mathbf{Z} =$

 $1.0000 - 0.0000i \quad 2.0000 - 0.0000i \quad 3.0000 + 0.0000i \quad 4.0000 + 0.0000i$

1.0000 - 0.0000i 2.0000 - 0.0000i 3.0000 + 0.0000i 4.0000 + 0.0000i



ii) To find FFT and IFFT of a sequence

```
close all;
clear all;
x=input('Enter the input Sequnce x[n]');
L=length(x);
N=input('Enter the length of the FFT sequence N =');
if (N<L)
    disp('N should be greater than L')
else
    x=[x zeros(1,N-L)];
end
%Plotting the Input Sequence
d=0:N-1;
subplot(3,2,1)
stem(d, x)
title('Input Sequence x[n]');
%To alter the input sequence ie x[0] x[2] x[1] x[3]
x=bitrevorder(x);
M=log2(N);
h=1;
for stage=1:M
    for index=0:(2^stage):N-1
        for n=0:(h-1)
            pos=n+index+1;
            pow=(2^{(M-stage)*n});
            w = \exp((-i) * (2*pi) *pow/N);
            a=x(pos)+x(pos+h).*w;
            b=x(pos)-x(pos+h).*w;
            x(pos) = a;
            x(pos+h)=b;
        end
    end
    h=2*h;
end
y=x
disp(y);
%Plotting the FFT Sequence
subplot(3,2,2)
stem(d,abs(y))
grid on
```

```
title('FFT magnitude')
xlabel('Samples')
ylabel('Values')
subplot(3,2,3)
stem(d, angle(y))
grid on
title('FFT phase angle')
xlabel('Samples')
ylabel('Values')
y=bitrevorder(y);
h=1;
for stage=1:M
    for index=0:(2^stage):N-1
        for n=0:(h-1)
            pos=n+index+1;
             pow=(2^{(M-stage)*n});
             w = \exp((i) * (2*pi) *pow/N);
             a=y(pos)+y(pos+h).*w;
             b=y(pos)-y(pos+h).*w;
             y(pos) = a;
             y(pos+h)=b;
        end
      end
    h=2*h;
end
z=y/N
disp(z)
%Plotting the IFFT Sequence
subplot(3,2,4)
stem(d, z)
title('IFFT Sequence z[n]');
```

Result:

```
Enter the input Sequnce x[n][1\ 2\ 3\ 4]
Enter the length of the FFT sequence N=4
```

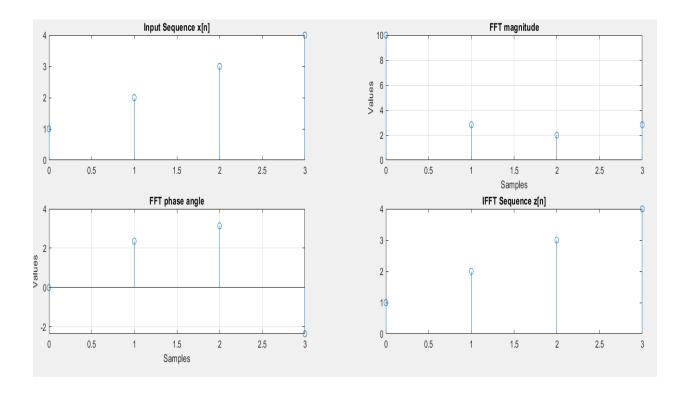
10.0000 + 0.0000i -2.0000 + 2.0000i -2.0000 + 0.0000i -2.0000 - 2.0000i

10.0000 + 0.0000i -2.0000 + 2.0000i -2.0000 + 0.0000i -2.0000 - 2.0000i

z =

1.0000 + 0.0000i 2.0000 + 0.0000i 3.0000 + 0.0000i 4.0000 - 0.0000i

1.0000 + 0.0000i 2.0000 + 0.0000i 3.0000 + 0.0000i 4.0000 - 0.0000i



iii)To find Linear and Circular Convolution using FFT algorithm Linear Convolution

```
clear all;
close all;
x1=input('Enter the first input sequence x1[n] ');
x2=input('Enter the second input sequence x2[n] ');
Lx1=length(x1);
Lx2=length(x2);
N=L\times1+L\times2-1;
X1=fft(x1,N);
X2=fft(x2,N);
Y=X1.*X2;
y=ifft(Y,N);
disp('Linear Convolution of x1[n] and x2[n] is y[n]= ')
disp(y)
%Verification
z=conv(x1,x2);
disp('Linear Convolution of x1[n] and x2[n] using builtin
function is z[n] = ')
disp(z)
a=0:Lx1-1;
subplot(2,2,1)
stem(a, x1)
title('Input Sequence x1[n]')
xlabel('Samples')
ylabel('Values')
b=0:Lx2-1;
subplot(2,2,2)
stem(b, x2)
title('Input Sequence x2[n]')
xlabel('Samples')
ylabel('Values')
c=0:N-1;
subplot(2,2,3)
stem(c, y)
title('Linear Convolution of x1[n] and x2[n]')
xlabel('Samples')
ylabel('Values')
d=0:N-1;
```

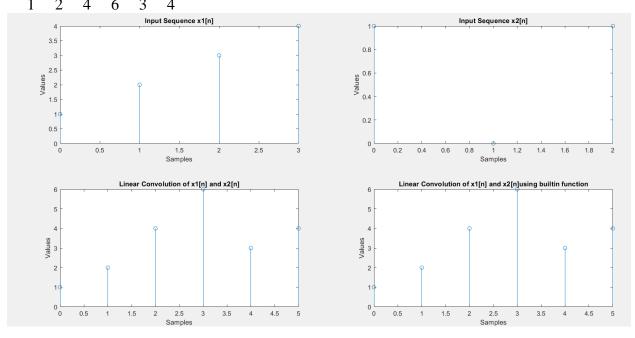
```
subplot(2,2,4)
stem(c,z)
title('Linear Convolution of x1[n] and x2[n]using builtin
function')
xlabel('Samples')
ylabel('Values')
```

Result:

Enter the first input sequence x1[n] [1 2 3 4] Enter the second input sequence x2[n] [1 0 1] Linear Convolution of x1[n] and x2[n] is y[n]=

2 4 6 3

Linear Convolution of x1[n] and x2[n] using builtin function is z[n]=



Circular Convolution

```
clear all;
close all;
x1=input('Enter the first input sequence x1[n] ');
x2=input('Enter the second input sequence x2[n] ');
Lx1=length(x1);
Lx2=length(x2);
N=max(Lx1,Lx2);
X1=fft(x1,N);
X2=fft(x2,N);
Y=X1.*X2;
y=ifft(Y,N);
disp('Circular Convolution of x1[n] and x2[n] is y[n] = ')
disp(y)
%Verification
z=cconv(x1,x2,N);
disp('Circular Convolution of x1[n] and x2[n] using builtin
function is z[n]= ')
disp(z)
a=0:Lx1-1;
subplot(2,2,1)
stem(a, x1)
title('Input Sequence x1[n]')
xlabel('Samples')
ylabel('Values')
b=0:Lx2-1;
subplot(2,2,2)
stem(b, x2)
title('Input Sequence x2[n]')
xlabel('Samples')
ylabel('Values')
c=0:N-1;
subplot(2,2,3)
stem(c, y)
title('Circular Convolution of x1[n] and x2[n]')
xlabel('Samples')
ylabel('Values')
d=0:N-1;
subplot(2,2,4)
stem(c,z)
```

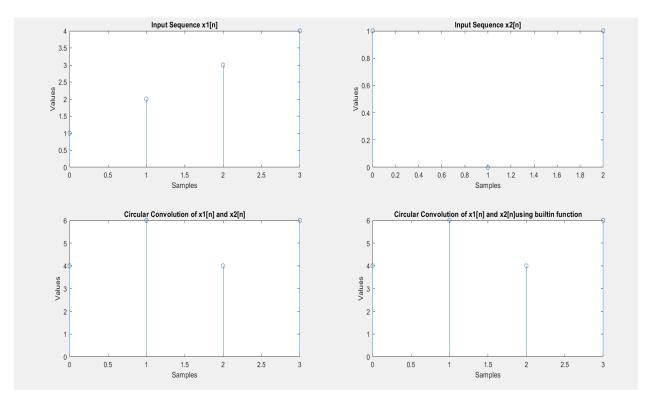
```
title('Circular Convolution of x1[n] and x2[n]using builtin
function')
xlabel('Samples')
ylabel('Values')
```

Result:

Enter the first input sequence x1[n] [1 2 3 4] Enter the second input sequence x2[n] [1 0 1] Circular Convolution of x1[n] and x2[n] is y[n]=
4 6 4 6

Circular Convolution of x1[n] and x2[n] using builtin function is z[n]=

4 6 4 6



iv)To find Linear and Circular Convolution using FFT algorithm Linear Convolution

```
clear all;
close all;
x1=input('Enter the first input sequence x1[n] ');
x2=input('Enter the second input sequence x2[n] ');
Lx1=length(x1);
Lx2=length(x2);
N=Lx1+Lx2-1;
X1=FFT_L(x1,N);
X2=FFT_L(x2,N);
Y=X1.*X2;
y=IFFT_L(Y,N);
disp('Linear Convolution of x1[n] & x2[n] is ')
disp(y)
```

Result

Enter the first input sequence x1[n] [1 2 3 4] Enter the second input sequence x2[n] [1 1 1 1] Linear Convolution of x1[n] & x2[n] is 1.0000 - 0.0000i 3.0000 - 0.0000i 6.0000 - 0.0000i 10.0000 + 0.0000i 9.0000 + 0.0000i 7.0000 + 0.0000i 0.0000 - 0.0000i 0.0000 - 0.0000i

Circular convolution

```
clear all;
close all;
x1=input('Enter the first input sequence x1[n]');
x2=input('Enter the first input sequence x2[n]');
Lx1=length(x1);
Lx2=length(x2);
N=max(Lx1,Lx2);
if Lx1<N
 x1=[x1, zeros(N-Lx1)];
else
 x2=[x2, zeros(N-Lx2)];
end
X1=FFT L(x1,N);
X2=FFT L(x2,N);
Y=X1.*X2;
y=IFFT L(Y,N);
disp('Circular Convolution of x1[n] & x2[n] is ')
disp(y)
%Verification
z=cconv(x1,x2,N);
```

```
disp('Circular Convolution of x1[n] and x2[n] using builtin
function is z[n] = ')
disp(z)
```

Result

Enter the first input sequence x1[n][1 2 3 4] Enter the first input sequence x2[n][1 0 1] Circular Convolution of x1[n] & x2[n] is 4 6 4 6

Circular Convolution of x1[n] and x2[n] using builtin function is z[n]=

4 6 4 6

Functions

FFT

```
function y=FFT L(x,N)
L=length(x);
M=nextpow2(N);
R=rem(N,2);
if(R\sim=0)
 x=[x zeros(1,(2^M)-L)];
end
%To alter the input sequence ie x[0] x[2] x[1] x[3]
x=bitrevorder(x);
h=1:
N=2^M;
for stage=1:M
 for index=0:(2^stage):N-1
 for n=0:(h-1)
 pos=n+index+1;
 pow=(2^{(M-stage)*n});
 w = \exp((-i) * (2*pi) *pow/N);
 a=x(pos)+x(pos+h).*w;
 b=x(pos)-x(pos+h).*w;
 x(pos) = a;
 x(pos+h)=b;
 end
 end
 h=2*h;
end
y=x;
```

IIFT

```
function z=IFFT L(y,N)
L=length(y);
M=nextpow2(N);
R=rem(N,2);
if(R\sim=0)
y=[y zeros(1,(2^M)-L)];
y=bitrevorder(y);
h=1;
N=2^M;
for stage=1:M
 for index=0:(2^stage):N-1
 for n=0:(h-1)
 pos=n+index+1;
 pow=(2^{(M-stage)*n});
 w=\exp((i)*(2*pi)*pow/N);
 a=y(pos)+y(pos+h).*w;
 b=y(pos)-y(pos+h).*w;
 y(pos) = a;
 y(pos+h)=b;
 end
 end
h=2*h;
end
z=y/N;
```

Experiment No 4

i) To find the 2N point DFT using N point DFT

```
close all;
clear all;
v=input('Enter the Input sequence v[n]');
N=length(v)/2
for n=0:N-1
    q(n+1) = v((2*n)+1);
    h(n+1) = v((2*n)+2);
end
[G,H]=myN Point(g,h);
for k=0:(2*N)-1
    w(k+1) = exp((-i*pi*k)/N);
end
m=0;
for k=1:2
    for n=0:N-1
        V(m+n+1) = G(n+1) + (w(m+n+1) *H(n+1));
    end
    m=4;
end
disp('2N -Point DFT using N point DFT is V(K)')
disp(V)
*********
function[G,H]=myN Point(g,h)
N=length(g);
%x[n] = g[n] + jh[n]
for i=0:N-1
    x(i+1) = q(i+1) + h(i+1) * j;
end
%Finding DFT of x[n] i.e X[K]
X = mydftusingfft(x, N);
%Finding Conjugate of X(K) i.e X*(K)
Z=conj(X);
```

```
%X*[(N-K)N]
%n=0:N-1
%Z \pmod{(-n,N)+1}
for k=0:N-1
    n=N-k;
    if(n==N)
        y(k+1) = Z(k+1);
    else
        y(k+1) = Z(n+1);
    end
end
G=zeros(1,N);
H=zeros(1,N);
for k=1:N
    G(k) = (1/2) * (X(k) + y(k));
    H(k) = (X(k) - y(k)) / (2*j)
end
end
**************
function y=mydftusingfft(x,N)
%to alter the input sequence is X[0] \times [1] \times [3]
x=bitrevorder(x);
% To find n from 2^n i.e No of stages
%p=nextpow2(N);
M=log2(N);
h=1;
for stage = 1:M
    for index = 0:(2^stage):N-1
        for n=0:(h-1)
            pos =n+index+1;
            pow= (2^{(M-stage)*n});
            w = \exp((-i) * (2*pi) *pow/N);
            a=x(pos)+x(pos+h).*w;
            b=x(pos)-x(pos+h).*w;
            x(pos) = a;
            x(pos+h)=b;
```

```
end
      end
      h=2*h;
end
y=x;
end
Result
Enter the Input sequence v[n] [1 2 2 2 0 1 1 1]
N =
  4
H =
  6 \ 0 \ 0 \ 0
H =
 6.0000 + 0.0000i 1.0000 - 1.0000i 0.0000 + 0.0000i 0.0000 + 0.0000i
H =
 6.0000 + 0.0000i 1.0000 - 1.0000i 0.0000 + 0.0000i 0.0000 + 0.0000i
H =
 6.0000 + 0.0000i 1.0000 - 1.0000i 0.0000 + 0.0000i 1.0000 + 1.0000i
2N -Point DFT using N point DFT is V(K)
 10.0000 + 0.0000i \quad 1.0000 - 2.4142i \quad -2.0000 + 0.0000i \quad 1.0000 - 0.4142i \quad -2.0000 - 0.0000i
```

1.0000 + 0.4142i -2.0000 + 0.0000i 1.0000 + 2.4142i

ii)To find the N point DFT of two sequences using single N point DFT(Using FFT algorithm to find DFT)

```
close all;
clear all;
g=input('Enter the first sequence g[n]');
h= input('Enter the second sequence h[n]');
N=length(g)
for i=0:N-1
    x(i+1) = q(i+1) + h(i+1) * j;
end
disp(x)
%Finding DFT of x[n] i.e X[K]
X = mydftusingfft(x, N)
%Finding Conjugate of X(K) i.e X*(K)
Z=conj(X)
%X*[(N-K)N]
%n=0:N-1
%Z \pmod{(-n,N)+1}
for k=0:N-1
    n=N-k;
    if(n==N)
         y(k+1) = Z(k+1);
    else
        y(k+1) = Z(n+1);
    end
end
disp(y)
G=zeros(1,N);
H=zeros(1,N);
for k=1:N
    G(k) = (1/2) * (X(k) + y(k));
    H(k) = (X(k) - y(k)) / (2*j);
end
disp('N Point DFT of two sequences using N point DFT')
disp(G)
disp(H)
```

```
function y=mydftusingfft(x,N)
%to alter the input sequence is X[0] \times [1] \times [3]
x=bitrevorder(x);
% To find n from 2^n i.e No of stages
%p=nextpow2(N);
M=log2(N);
h=1;
for stage = 1:M
    for index = 0:(2^stage):N-1
         for n=0:(h-1)
              pos =n+index+1;
              pow= (2^{(M-stage)*n});
              w = \exp((-i) * (2*pi) *pow/N);
              a=x(pos)+x(pos+h).*w;
              b=x(pos)-x(pos+h).*w;
              x(pos) = a;
              x(pos+h)=b;
         end
    end
    h=2*h;
end
y=x;
end
Result:
Enter the first sequence g[n] [1 2 0 1]
Enter the second sequence h[n] [ 2 2 1 1]
N =
  4
 1.0000 + 2.0000i 2.0000 + 2.0000i 0.0000 + 1.0000i 1.0000 + 1.0000i
X =
```

```
4.0000 + 6.0000i 2.0000 + 0.0000i -2.0000 + 0.0000i 0.0000 + 2.0000i
```

Z =

4.0000 - 6.0000i 2.0000 - 0.0000i -2.0000 + 0.0000i 0.0000 - 2.0000i

4.0000 - 6.0000i 0.0000 - 2.0000i -2.0000 + 0.0000i 2.0000 - 0.0000i

N Point DFT of two sequences using N point DFT

4.0000 + 0.0000i 1.0000 - 1.0000i -2.0000 + 0.0000i 1.0000 + 1.0000i

6.0000 + 0.0000i 1.0000 - 1.0000i 0.0000 + 0.0000i 1.0000 + 1.0000i

Experiment 5

Sectioned Convolution: Overlap Save and Overlap Add Method for long Duration Sequences

Overlap save

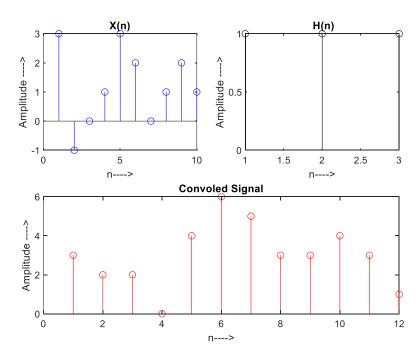
```
clc;
clear all;
close all;
x=input('Enter 1st Sequence X(n) = ');
h=input('Enter 2nd Sequence H(n) = ');
N=input('Enter length of each block N = ');
% Code to plot X(n)
subplot(2,2,1);
stem(x, 'blue');
xlabel ('n--->');
ylabel ('Amplitude --->');
title('X(n)');
%Code to plot H(n)
subplot(2,2,2);
stem(h, 'black');
xlabel ('n--->');
ylabel ('Amplitude --->');
title(' H(n)');
% Code to perform Convolution using Overlap Save Method
lx=length(x);
lh=length(h);
m=1h-1;
x=[zeros(1,m) \times zeros(1,N)];
h=[h zeros(1,N-lh)];
L=N-lh+1;
k=floor(lx/L);
for i=0:k
y=x(1,i*L+1:i*L+N);
q=cconv(y,h,N)
%q=C Conv(y,h); %Call the C Conv function.
p(i+1,:)=q;
end
p1=p(:,lh:N)';
p=p1(:)'
% Representation of the Convoled Signal
```

```
subplot(2,2,3:4);
stem(p,'red');
xlabel ('n--->');
ylabel ('Amplitude --->');
title('Convoled Signal');
```

Output

Enter 1st Sequence X(n)= [3,-1,0,1,3,2,0,1,2,1] Enter 2nd Sequence H(n)= [1, 1,1] Enter length of each block L = 8 p =

3 2 2 0 4 6 5 3 3 4 3 1



```
Overlap add
close all;
clear all;
x=input('Enter First Sequence x[n]= ');
h=input('Enter Second Sequence h[n]= ');
N=input('Enter length of each block N = ');
Lx = length(x);
M=length(h);
L=N-M+1;
K=ceil(Lx/L)
R=rem(Lx,L);
%Padding zeros to input sequences to make length equal to N
if R>0
 x=[x zeros(1,L-R)]
end
h=[h zeros(1,N-M)]
%Initialising the Output
y=zeros(N,K);
%Padding zeros to Input sequence at the end of the sequence
z=zeros(1,M-1);
%To perform Circular Convolution of two input sequences
for i=0:K-1
 Xn=x(L*i+1:L*i+L);
 Xi = [Xn z];
 u(i+1,:) = cconv(Xi,h,N) %u(i+1,:) = C Conv(Xi(i,:),h);
end
Y=u';
M1 = M - 1;
p=L+M1;
for i=1:K-1
 u(i+1,1:M-1)=u(i,p-M1+1:p)+u(i+1,1:M-1);
end
z1=u(:,1:L)'
y1=(z1(:))'
y = [y1 u(K, (M:N))]
%Ploting the Input Sequences
subplot (2,2,1);
stem(x);
title('First Sequence x[n]');
xlabel ('Samples');
ylabel ('Amplitude');
subplot (2,2,2);
stem(h);
title ('Second Sequence h[n]');
xlabel ('Samples');
```

```
ylabel ('Amplitude');
%Plotting of the Convoled Signal
subplot (2,2,3:4);
stem(y);
title ('Convolved Signal');
xlabel ('Samples');
ylabel ('Amplitude');
Result
Enter First Sequence x[n]= [1 2 -1 2 3 -2 -3 -1 1 1 2 -1]
Enter Second Sequence h[n]=[12]
Enter length of each block N = 4
\mathbf{K} =
  4
h =
  1 2 0 0
u =
  1 4 3 -2
\mathbf{u} =
      4 3 -2
  1
  2 7 4 -4
u =
```

1 4 3 -2 2 7 4 -4 -3 -7 -1 2 u =

1 4 3 -2 2 7 4 -4 -3 -7 -1 2 1 4 3 -2

z1 =

0 -7 3 1 **4 3** 7 -7 4 4 -1 3

y1 =

1 4 3 0 7 4 -7 -7 -1 3 4 3

y =

4 3 0 7 4 -7 -7 -1 3 1 4 3 4 3 -2

