CPSC 8570: SECURITY IN ADVANCED NETWORKING TECHNOLOGIES

PROJECT 3

INSTALLATION OF CLICKOS TETBED

Description:

In this project, we are asked to follow a step-by-step guide to setup a virtual machine (VM) that runs on ClickOS and an exercise for simple demonstration of testing ClickOS. The step-by-step guide can be found at

https://bitbucket.org/hongdal/clickos-setup/wiki/Tutorial%20of%20installing%20ClickOS%20testbed

Initial Setup and configuration of VM:

- The Oracle VirtualBox VM was downloaded from https://www.virtualbox.org/wiki/Downloads
 And was installed on my Windows machine
- 2. A pre-configured virtual machine image with Ubuntu 14.04.4 (LTS) 64-bit installed, was made available for us. This image was downloaded from http://people.cs.clemson.edu/~hongdal/Ubuntu_14.04.4-64bit.7z
- **3.** Once the download was complete, the 'Ubuntu_14.04.4-64bit.7z' was extracted.
- **4.** Ubuntu VM for ClickOS was setup on VirtualBox using the 'Ubuntu 14.04.4 (64bit).vdi' which was extracted in the previous step.
- **5.** The username is 'osboxes' and password is 'osboxes.org'.
- **6.** We configured the VM and set the memory to 1024 MB and also set the number of processors to 2.
- 7. All the commands were run with root privileges. We used the command sudo su and used the username and password mentioned in step 5 to switch to root

Install Xen:

Xen is one of the most popular virtualized platforms. In this project, we are going to use Xen to support our Network Function Virtualization (NFV). More information about the Xen project can be found at

http://www.xenproject.org/

1. We install all the dependencies that are required for Xen:

apt-get update

apt-get install build-essential wget

apt-get install bcc bin86 gawk bridge-utils iproute libcurl3 libcurl4-openssl-dev bzip2 module-init-tools transfig tgif

apt-get install texinfo texlive-latex-base texlive-latex-recommended

```
# apt-get install texlive-fonts-extra texlive-fonts-recommended pciutils-dev mercurial
# apt-get install make gcc libc6-dev zlib1g-dev python python-dev python-twisted
# apt-get install libncurses5-dev patch libsdl-dev libjpeg62-dev
# apt-get install libvncserver-dev
# apt-get install iasl libbz2-dev e2fslibs-dev git-core uuid-dev ocaml ocaml-findlib
# apt-get install libx11-dev bison flex xz-utils libyajl-dev
# apt-get install gettext libpixman-1-dev
# apt-get build-dep xen
# apt-get install libglib2.0-dev
# apt-get install libyajl-dev
```

2. Create a new directory called 'tutorial' where all the files are downloaded, built and run:

mkdir tutorial

3. Download Xen-4.4.1 in the tutorial directory:

```
# cd tutorial
# wget http://people.cs.clemson.edu/~hongdal/xen-4.4.1.tar.gz
# tar -xf xen-4.4.1.tar.gz
```

4. Compile and build Xen:

```
# export XEN_ROOT=`pwd`/xen-4.4.1
# cd $XEN_ROOT
# ./configure
# make world
# make install
```

```
Terminal
                                                            👣 🖪 💷 🕩 18:00 🖔
         😰 🖃 🗊 root@osboxes: ~/tutorial/xen-4.4.1
        make[2]: `man1/xenstore.1' is up to date.
        make[2]:
                    man1/xl.1' is up to date.
        make[2]: `man1/xm.1' is up to date.
make[2]: `man5/xend-config.sxp.5' is up
make[2]: `man5/xl.cfg.5' is up to date.
                    man1/xm.1' is up to date.
                    man5/xend-config.sxp.5' is up to date.
        make[2]: `man5/xl.conf.5' is up to date.
        make[2]: `man5/xlcpupool.cfg.5' is up to date.
        make[2]: `man5/xmdomain.cfg.5' is up to date.
        make[2]: Leaving directory `/root/tutorial/xen-4.4.1/docs'
        set -x; make -C figs
        + make -C figs
        make[2]: Entering directory `/root/tutorial/xen-4.4.1/docs/figs
        make[2]: Nothing to be done for `all'.
        make[2]: Leaving directory `/root/tutorial/xen-4.4.1/docs/figs'
      rm -rf //usr/local/share/doc/xen
        install -d -m0755 -p //usr/local/share/doc/xen
install -d -m0755 -p //usr/local/share/man
cp -R man1 //usr/local/share/man
           -R man5 //usr/local/share/man
        [ ! -d html ] || cp -R html //usr/local/share/doc/xen
make[1]: Leaving directory `/root/tutorial/xen-4.4.1/docs'
        root@osboxes:~/tutorial/xen-4.4.1#
```

5. Configure your system to boot from Xen:

Before configuring the system to boot form Xen, it is highly recommended that we take a snapshot of the VM, so that we can restore back if the system crashes. This can be done using the 'update-rc.d' commands as shown:

```
#/sbin/ldconfig
# update-rc.d xencommons defaults 19 18
# update-rc.d xendomains defaults 21 20
# update-rc.d xen-watchdog defaults 22 23
```

6. Modify the linux bootloader – 'grub' to boot as commandline only interface:

We open the file at '/etc/default/grub' and update some of the configuration lines to the following appropriate values:

```
GRUB_DEFAULT=3
GRUB_HIDDEN_TIMEOUT=0
```

Update grub and reboot the system:

update-grub # reboot

7. Verify Xen has been installed successfully:

After rebooting, in my case, the system automatically started a command line Interface (CLI) as the virtual machine does not support GUI in Xen. If the system starts a graphic user interface (GUI) automatically we need to switch to a command line interface (CLI). Press control + alt + F1 to switch to a CLI. input your username and password to log in. After logging in, switch to root privilege.

The following command can be used to verify that Xen has been successfully installed:

xl list

Example output of xl list is:

```
Name ID Mem VCPUs State Time(s)
Domain-0 0 4098 32 r---- 23926.7
```

```
📂 click (Snapshot 1) [Running] - Oracle VM VirtualBox
                                                                       X
File Machine View Input Devices Help
Ubuntu 14.04.4 LTS osboxes tty1
osboxes login: osboxes
Password:
Welcome to Ubuntu 14.04.4 LTS (GNU/Linux 4.2.0–27–generic x86_64)
 * Documentation: https://help.ubuntu.com/
The programs included with the Ubuntu system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/copyright.
Ubuntu comes with ABSOLUTELY NO WARRANTY, to the extent permitted by
applicable law.
osboxes@osboxes:~$ sudo su –
[sudo] password for osboxes:
root@osboxes:~# xl list
Name
                                             ΙD
                                                  Mem VCPUs
                                                                  State
                                                                          Time(s)
Domain-O
                                                  945
                                                                              12.2
root@osboxes:~# _
                                             🛐 🌀 🗐 🥟 i 🜉 🚰 🛄 🚫 💽 Right Ctrl
```

Building ClickOS:

1. Our first task in building the ClickOS is to get the source codes:

```
All the clickos codes are downloaded into our tutorial directory:
# cd tutorial
# wget http://people.cs.clemson.edu/~hongdal/clickos.tar
# wget http://people.cs.clemson.edu/~hongdal/mini-os.tar
# wget http://people.cs.clemson.edu/~hongdal/cosmos.tar
# wget http://people.cs.clemson.edu/~hongdal/toolchain.tar
# tar -xf clickos.tar
# tar -xf mini-os.tar
# tar -xf cosmos.tar
# tar -xf toolchain.tar
```

2. Setting up the environment variables:

```
First we need to make sure 'pwd' ouputs the path — '/root/tutorial'.

# export XEN_ROOT=$(pwd)"/xen-4.4.1/"

# export MINIOS_ROOT=$XEN_ROOT"extras/mini-os/"

# export CLICKOS_ROOT=$(pwd)"/clickos/"

# export TOOLCHAIN_ROOT=$(pwd)"/toolchain/"

# export COSMOS_ROOT=$(pwd)"/cosmos/"
```

Evertime we reboot the system or switch to another user, it is important to check if these variables are still intact. This is done by typing echo \$VARIABLE-NAME

Example:

echo \$XEN_ROOT to check variable \$XEN_ROOT

3. Replacing mini-os:

MiniOS is an operating system that comes with Xen. ClickOS is built based on MiniOS. We need to replace Xen's mini-os with ClickOS's minios.

rm -rf \$MINIOS_ROOT # cp -rf \$(pwd)"/mini-os/" \$MINIOS_ROOT

4. Building toolchain:

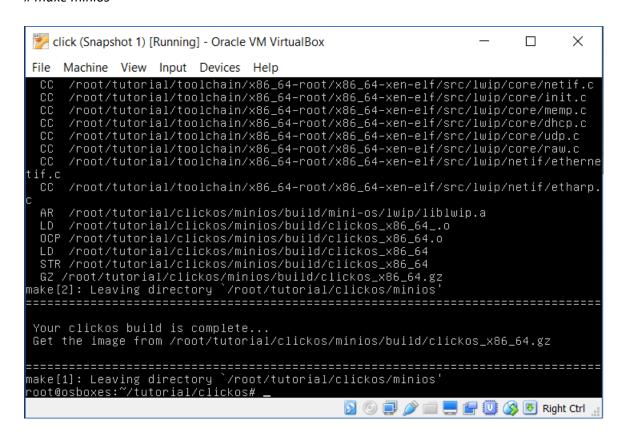
```
This toolchain is for ClickOS's C++ library
# cd $TOOLCHAIN_ROOT
# make
# export NEWLIB_ROOT=$TOOLCHAIN_ROOT"/x86_64-root/x86_64-xen-elf"
# export LWIP_ROOT=$TOOLCHAIN_ROOT"/x86_64-root/x86_64-xen-elf"
```

```
📂 click (Snapshot 1) [Running] - Oracle VM VirtualBox
                                                                                        X
                                                                                П
File Machine View Input Devices Help
                                                  ] 684,894
                                                                   --.-K/s
                                                                               in 0.01s
2017–03–24 20:54:57 (60.7 MB/s) – 'lwip–a310bc1.tar.gz' saved [684894]
m –rf lwip–a310bc1 lwip–a310bc1
tar xzf lwip–a310bc1.tar.gz
[ "lwip–a310bc1" != "lwip–a310bc1" ] && mv lwip–a310bc1 lwip–a310bc1 || true
touch _lwip-src
mkdir -p /root/tutorial/toolchain/x86_64-root/x86_64-xen-elf/src/lwip
mkdir -p /root/tutorial/toolchain/x86_64-root/x86_64-xen-elf/include/lwip
cp -a lwip-a310bc1/src/api /root/tutorial/toolchain/x86_64-root/x86_64-xen-elf/
c/lwip/
p –a lwip–a310bc1/src/core /root/tutorial/toolchain/x86_64–root/x86_64–xen–elf:
src/lwip/
p -a lwip-a310bc1/src/netif /root/tutorial/toolchain/x86_64-root/x86_64-xen-el
src/lwip/
p –a lwip–a310bc1/src/include/* /root/tutorial/toolchain/x86_64–root/x86_64–xen
-elf/include/lwip/
touch _lwip-install
root@osboxes:~/tutorial/toolchain# export NEWLIB_ROOT=$TOOLCHAIN_ROOT"/x86_64-ro
ot/x86_64-xen-elf"
root@osboxes:~/tutorial/toolchain# export LWIP_ROOT=$TOOLCHAIN_ROOT"/x86_64-root
/x86_64-xen-elf"
oot@osboxes:~/tutorial/toolchain#
                                                   👂 🌀 🗐 🥟 📄 🜉 🚰 🕕 🐼 🖲 Right Ctrl
```

5. Building ClickOS kernel:

cd \$CLICKOS ROOT

./configure --enable-minios --with-xen=\$XEN_ROOT --with-minios=\$MINIOS_ROOT # make minios



6. Building cosmos:

cosmos is a tool used for booting ClickOS kernel.
cd \$XEN_ROOT
cd tools
make -C include

```
👺 click (Snapshot 1) [Running] - Oracle VM VirtualBox
                                                                                      X
 File Machine View Input Devices Help
      /root/tutorial/clickos/minios/build/clickos_x86_64_.o
      /root/tutorial/clickos/minios/build/clickos_x86_64.o
/root/tutorial/clickos/minios/build/clickos_x86_64
  STR /root/tutorial/clickos/minios/build/clickos_x86_64
Your clickos build is complete...
Get the image from /root/tutorial/clickos/minios/build/clickos_x86_64.gz
root@ospoxes: /tutorial/clickos# cd $xEn_Roof
root@osboxes:~/tutorial/xen–4.4.1# cd tools
root@osboxes:~/tutorial/xen–4.4.1/tools# make –C include
make: Entering directory `/root/tutorial/xen–4.4.1/tools/include'
make −C xen−foreign
make[1]: Entering directory `/root/tutorial/xen–4.4.1/tools/include/xen–foreign
./checker > tmp.size
diff –u reference.size tmp.size
rm tmp.size
make[1]: Leaving directory `/root/tutorial/xen–4.4.1/tools/include/xen–foreign'
make: Leaving directory `/root/tutorial/xen–4.4.1/tools/include'
root@osboxes:~/tutorial/xen–4.4.1/tools# _
                                                       🛐 🌀 🗐 🥟 i 🜉 🚰 🛄 🚫 🛂 Right Ctrl
```

cd \$COSMOS_ROOT # make DOMLIB=xl

We need to set the 'PATH' environmental variable # export PATH=\$PATH":/\$COSMOS_ROOT/dist/bin"

Install Open vSwitch:

We will be suing Open vSwitch (OVS) as a software switch. More information about OVS can be found at

http://openvswitch.org/

1. Install Open vSwitch:

```
# cd tutorial
# wget http://openvswitch.org/releases/openvswitch-2.5.0.tar.gz
# tar -xf openvswitch-2.5.0.tar.gz
# cd openvswitch-2.5.0/
# ./configure --with-linux=/lib/modules/`uname -r`/build
# make
```

make install # make modules install

2. Configure and run OVS:

The following commands need to be executed in the directory—
'tutorial/openvswitch-2.5.0/'

#/sbin/modprobe openvswitch

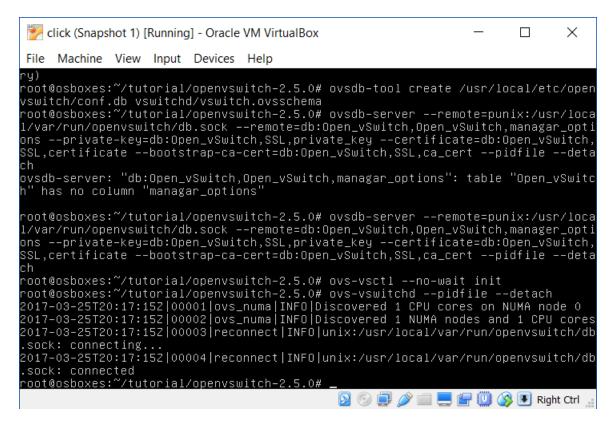
mkdir -p /usr/local/etc/openvswitch

ovsdb-tool create /usr/local/etc/openvswitch/conf.db vswitchd/vswitch.ovsschema

ovsdb-server --remote=punix:/usr/local/var/run/openvswitch/db.sock -remote=db:Open_vSwitch,Open_vSwitch,manager_options --privatekey=db:Open_vSwitch,SSL,private_key --certificate=db:Open_vSwitch,SSL,certificate -bootstrap-ca-cert=db:Open_vSwitch,SSL,ca_cert --pidfile --detach

ovs-vsctl --no-wait init

ovs-vswitchd --pidfile --detach



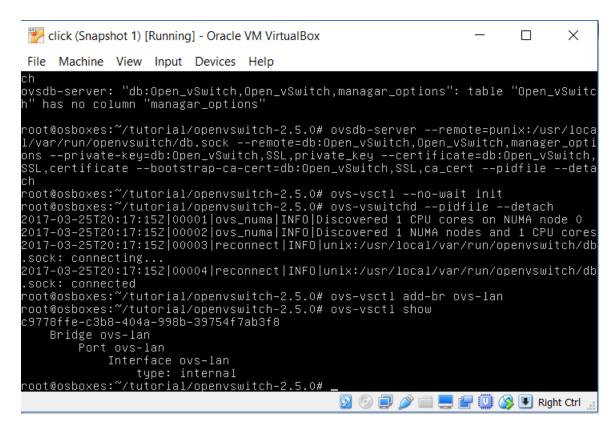
Everytime the system is rebooted; we need to repeat the above commands to reconfigure the OVS.

3. Create a bridge on OVS:

ovs-vsctl add-br ovs-lan

We use – 'ovs-vsctl show' to verify that the OVS is running correctly.

```
Example screen dump of 'ovs-vsctl show':
e6d82000-68d3-49cc-a5d0-3e51508ad772
Bridge ovs-lan
Port ovs-lan
Interface ovs-lan
type: internal
```



Starting a ClickOS Instance:

1. Create a configuration file for Xen:

```
Change your working directory to - 'tutorial/clickos/minios'.
```

We will use an existing Xen configuration file and update some of the values in 'config.xen' file:

```
kernel = './build/clickos_x86_64'
vcpus = '1'
vif = ['script=vif-openvswitch,mac=00:00:00:00:01:00,bridge=ovs-lan']
name = 'click0'
```

We delete the following line from 'config.xen' file as it may create some problems: cpus = '2'

```
click (Snapshot 1) [Running] - Oracle VM VirtualBox — X

File Machine View Input Devices Help

kernel = './build/clickos_x86_64'
vcpus = '1'

memory = '12'
vif = ['script=vif-openvswitch,mac=00:00:00:00:01:00,bridge=ovs-lan']
name = 'clicko'
on_crash = 'preserve'

:wq!_
```

2. Create configuration file for Click:

Click is a scripting language that can define network functions based on Click Modular.

Refer to the Click Element website, to write more complicated network functions using Click. Link to Click Element website is:

http://read.cs.ucla.edu/click/elements

Some examples could be found here:

http://read.cs.ucla.edu/click/examples

The Click configuration file describes the functionality that a ClickOS instance will implement.

As a simple test, the following scripts describe a simple network function that receives packets from the network interface, prints the packets, and sends the packets back to the network. To achieve this, we create the following script as a file – *mirror.click*:

FromDevice -> Print('OK') -> EtherMirror -> ToDevice

3. Start ClickOS Instance:

We will use 'cosmos' to start a ClickOS instance. Check whether '\$COSMOS_ROOT' is intact by typing 'echo \$COSMOS_ROOT' and set it appropriately.

xl create config.xen

#\$COSMOS ROOT/dist/bin/cosmos start click0 mirror.click

Type 'xl list', to verify that the ClickOS instance is running. Example screendump of 'xl list':

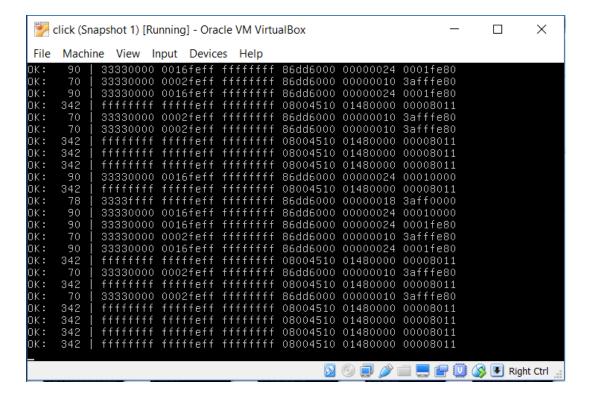
```
        Name
        ID Mem VCPUs
        State
        Time(s)

        Domain-0
        0 4098
        32 r----
        23926.7

        click0
        1 12 1 r----
        234.5
```

```
👺 click (Snapshot 1) [Running] - Oracle VM VirtualBox
                                                                                                     Х
 File Machine View Input Devices
'mirror.click" 2 lines, 54 characters written
oot@osboxes:~/tutorial/clickos/minios# xl create config.xen
Parsing config from config.xen
Poot@osboxes:~/tutorial/clickos/minios# $COSMOS_ROOT/dist/bin/cosmos start click
O mirror.click
Domain ID for clickO: 4
Location of click script: mirror.click
root@osboxes:~/tutorial/clickos/minios# xl
                                                              list
Name
                                                                       Mem VCPUs
                                                                                             State
                                                                                                         Time(s)
⊃omain–O
                                                                                                            381.7
                                                                       914
                                                                                                              8.9
click0
root@osboxes:~/tutorial/clickos/minios#
                                                                🔊 🌀 🗐 🥟 i 🜉 🚰 🗓 🚫 💽 Right Ctrl
```

To watch the output of click0, type 'xl console click0'. To quit the console, press 'control +]'



Exercise:

ICMP Responder:

In this exercise, we are given a template script to create a Click configuration file – 'icmp.click'. We need to set the IP address and MAC address appropriately and make it print our name on the click0 console window. The screendump of the icmp.click file after making the changes to print my name is as shown below:

We need to kill existing ClickOS instance at clickO using: xl destroy clickO

We then start a new instance at click0:

xl create config.xen

#\$COSMOS_ROOT/dist/bin/cosmos start click0 icmp.click

We need to add our VM's network interface OVS so that you can ping the ClickOS instance from your VM:

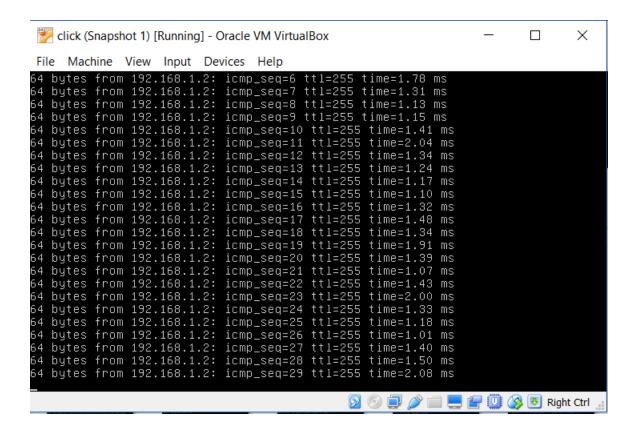
ifconfig eth0 0

ovs-vsctl add-port ovs-lan eth0

ifconfig ovs-lan 192.168.1.1 netmask 255.255.255.0 up

Now we need to ping ClickOS instance from our VM:

ping 192.168.1.2



To watch the outputs of the ClickOS instance:

xl console click0

