



# Software Safety Requirements and Architecture

## Lane Assistance

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## Document history

Date	Version	Editor	Description
23/May/2018	1.0	Shreya Srivastava	First Draft

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# 1. Purpose

The Purpose of this document is to capture the software safety requirements for all the technical safety requirements from the technical safety concept. This helps in mitigating the problems with software design which could lead to safety hazards. This takes into account the vehicle as whole.

## 2. Inputs to the Software Requirements and Architecture Document

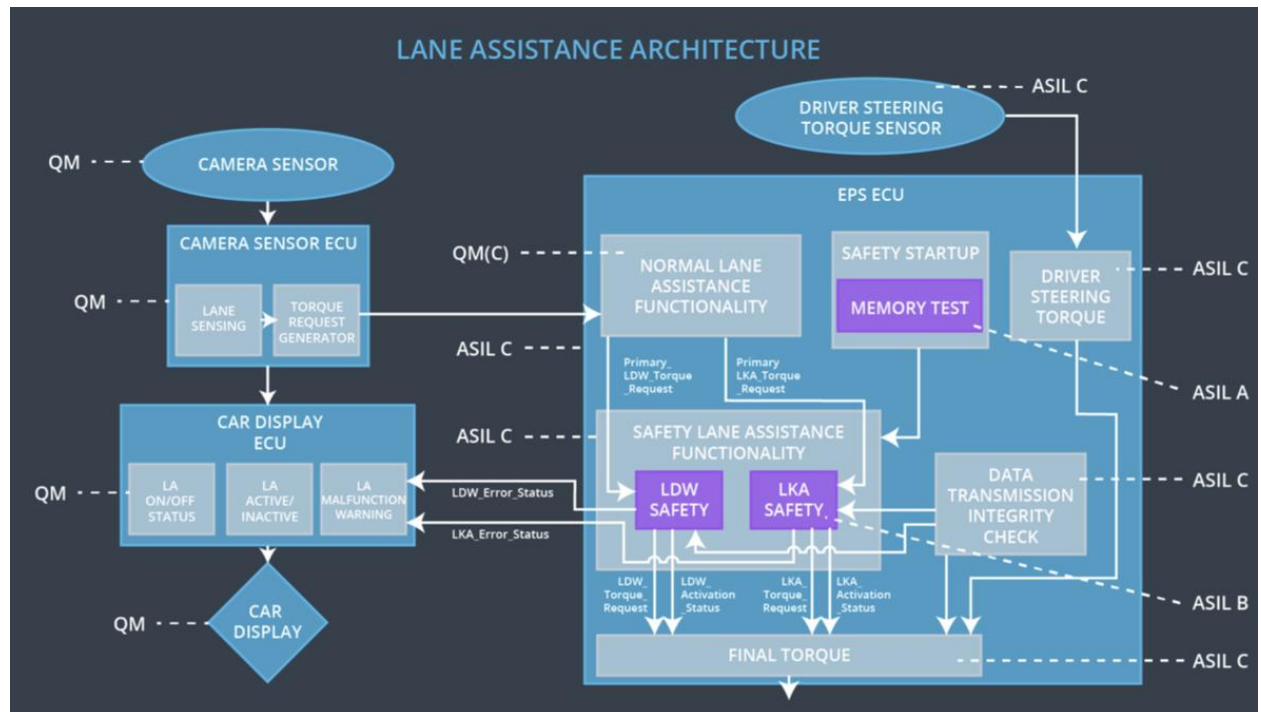
### 2.1 Technical safety requirements

Technical Safety Requirements related to Functional Safety Requirement 01-01 are:

ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Architecture Allocation	Safe State
Technical Safety Requirement 01	The LDW safety component shall ensure the component shall ensure that the amplitude of the LDW_Torque_Request sent to the 'Final electronic power steering torque' component is below "Max_Torque_Amplitude".	C	50 ms	LDW Safety	The lane departure warning torque request amplitude shall be set to zero.
Technical Safety Requirement 02	The validity and the integrity of the data transmission for "LDW_Torque_Request" shall be ensured.	C	50 ms	LDW Safety	The lane departure warning torque request amplitude shall be set to zero.
Technical	As soon as a failure is	C	50 ms	LDW Safety	The lane

Safety Requirement 03	detected by the LDW function it shall deactivate the LDW feature and the “LDW_Torque_Request” shall be set to zero.				departure warning torque request amplitude shall be set to zero.
Technical Safety Requirement 04	As soon as the LDW function deactivates the LDW feature the “LDW Safety” software block shall send a signal to the car display ECU to turn on a warning light.	C	50 ms	LDW Safety	The lane departure warning torque request amplitude shall be set to zero.
Technical Safety Requirement 05	Memory test shall be conducted at the start of the EPS ECU to check for any faults in memory.	A	Ignition cycle	Data Transmission Integrity check	The lane departure warning torque request amplitude shall be set to zero.

## 2.2 Refined Architecture Diagram from the Technical Safety Concept



## 3. Software Requirements

### Lane Departure Warning (LDW) Amplitude Malfunction Software Requirements:

ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 01	The LDW safety component shall ensure that the amplitude of the LDW_Torque_Request sent to the Final Electronic Power Steering Torque component is below Max_Torque_Amplitude	C	50 ms	LDW Safety	LDW torque output is set to zero

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 01-01	The input signal "Primary_LDW_Torq_Req" shall be read and pre-processed to determine the torque request coming from the "Basic/Main LAF functionality" SW Component. Signal "processed_LDW_Torq_Req" shall be generated at the end of the processing.	C	LDW_SAFETY_INPUT_PROCESSING	N/A
Software Safety Requirement 01-02	In case the "processed_LDW_Torq_Req" signal has a value greater than "Max_Torque_Amplitude_LDW" (maximum allowed safe torque), the torque signal "limited_LDW_Torq_Req" shall be set to 0, else "limited_LDW_Torq_Req" shall take the value of "processed_LDW_Torq_Req".	C	TORQUE_LIMITER	limited_LDW_Torq_Req = 0 (Nm=Newton-meter)
Software Safety Requirement 01-03	The "limited_LDW_Torq_Req" shall be transformed into a signal "LDW_Torq_Req" which is suitable to be transmitted outside of the LDW Safety component ("LDW Safety") to the "Final EPS Torque" component. Also see SofSafReq02-01 and SofSafReq02-02	C	LDW_SAFETY_OUTPUT_GENERATOR	LDW_Torq_Req = 0 (Nm)

ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 02	The validity and integrity of the data transmission for LDW_Torque_Request signal shall be ensured				

ID	Software Safety Requirement	ASIL	Allocation Software Elements		Safe State
Software Safety Requirement 02-01	Any data to be transmitted outside of the LDW Safety component ("LDW Safety") including "LDW_Torque_Req" and "activation_status" (see SofSafReq03-02) shall be protected by an End2End(E2E) protection mechanism	C	E2ECalc		LDW_Torq_Req = 0 (Nm)
Software Safety Requirement 02-02	Any data to be transmitted outside of the LDW Safety component ("LDW Safety") including "LDW_Torque_Req" and "activation_status" (see SofSafReq03-02) shall be protected by an End2End(E2E) protection mechanism	C	E2ECalc		LDW_Torq_Req = 0 (Nm)
ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety	As soon as a failure is				



Requirement t03-03	detected by the LDW function, it shall deactivate the LDW feature and the LDW_Torque_Request shall be set to zero				
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ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement t03-01	Each of the SW elements shall output a signal to indicate any error which is detected by the element. Error signal = error_status_input(LDW_SAFETY_INPUT_PROCESSING), error_status_torque_limiter(TORQUE_LIMITER), error_status_output_gen(LDW_SAFETY_OUTPUT_GENERATOR)	C	All	N/A
Software Safety Requirement t03-02	A software element shall evaluate the error status of all the other software elements and in case any 1 of them indicates an error, it shall deactivate the LDW feature ("activation_status"=0)	C	LDW_SAFETY_ACTIVATION	Activation_status = 0 (LDW function deactivated)
Software Safety Requirement t03-03	In case of no errors from the software elements, the status of the LDW feature shall be set to activated ("activation_status"=1)	C	LDW_SAFETY_ACTIVATION	N/A
Software Safety Requirement t03-04	In case an error is detected by any of the software elements, it shall set the value of its corresponding torque to 0 so that "LDW_Torq_Req" is set to 0	C	All	LDW_Torq_Req = 0

Software Safety Requirement 03-05	Once the LDW functionality has been deactivated, it shall stay deactivated till the time the ignition is switched from off to on again	C	LDW_SAFETY_ACTIVATION	Activation_status = 0 (LDW function deactivated)
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ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 04	As soon as the LDW function deactivates the LDW feature, the LDW Safety software block shall send a signal to the car display ECU to turn on a warning light	C	50 ms	LDW Safety	LDW torque output is set to zero

ID	Software Safety Requirement	ASIL	Allocation Software Elements	Safe State
Software Safety Requirement 04-01	When the LDW function is deactivated (activation_status set to 0), the activation_status shall be sent to the car display ECU.	C	LDW_SAFETY_ACTIVATION, CarDisplay ECU	All

ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety	Memory test shall be conducted at start up of the	A	Ignition	Memory Test	LDW torque output is set

Requirement t 05	EPS ECU to check for any faults in memory		Cycle		to zero
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ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement t 05-01	A CRC verification check over the software code in the Flash memory shall be done every time the ignition is switched from off to on to check for any corruption of content.	A	MEMORYTEST	Activation_status = 0
Software Safety Requirement t 05-02	Standard RAM tests to check the data bus, address bus and device integrity shall be done every time the ignition is switched from off to on (E.g.walking 1s test, RAM pattern test. Refer RAM and processor vendor recommendations )	A	MEMORYTEST	Activation_status = 0
Software Safety Requirement t 05-03	The test result of the RAM or Flash memory shall be indicated to the LDW_Safety component via the "test_status" signal	A	MEMORYTEST	Activation_status = 0
Software Safety Requirement t 05-04	In case any fault is indicated via the "test_status" signal the INPUT_LDW_PROCESSING shall set an error on error_status_input (=1) so that the LDW functionality is deactivated and the LDWTorque is set to 0	A	LDW_SAFETY_I NPUT_PROCESS ING	Activation_status = 0

## 4. Refined Architecture Diagram

