

The robot waits half a second before running the program, in case that we want to change something and/or did something wrong. Resets the gyro sensor for accuracy

Runs the program that does the crane using my blocks.

When the select button is pushed on the Ev3, it waits .5 second and then runs the program that does the blocks and architecture

When the select button is pushed on the Ev3, it waits .5 second and then runs the program that does the tan color matching blocks

When the select button is pushed on the Ev3, it waits .5 second and then runs the program that does the red color match blocks



Waits another .2 seconds and reset the gyro sensor between every mission for more accuracy. Runs the swing, elevator, and bridge respectively. When the select button is pushed on the Ev3, it waits then runs the programs, swing, elevator, and bridge.

