```
In [ ]:
             Author: A.Shrikant
In [1]: # Basic libraries
        import numpy as np
        import pandas as pd
         import matplotlib.pyplot as plt
        import seaborn as sns
        # Importing the datasets and the DNN libraries
         import keras
         from keras import datasets
        from keras.layers import Conv2D, MaxPooling2D, Flatten, Dense
        from keras.models import Sequential
In [2]: (x_train, y_train), (x_test, y_test) = datasets.mnist.load_data()
In [3]: # data shape
        print(x_train.shape)
        print(y_train.shape)
        print(x_test.shape)
        print(y_test.shape)
       (60000, 28, 28)
       (60000,)
       (10000, 28, 28)
       (10000,)
In [4]: x_train_min = x_train.min()
        x_train_max = x_train.max()
        print(f'x_train_min: {x_train_min}')
        print(f'x_train_max: {x_train_max}')
       x_train_min: 0
       x_train_max: 255
In [5]: # Scale the data.
        x_{train} = x_{train}/255.0
```

```
x_{test} = x_{test/255.0}
 In [6]: x_train_min = x_train.min()
         x_train_max = x_train.max()
         print(f'x_train_min: {x_train_min}')
         print(f'x_train_max: {x_train_max}')
        x_train_min: 0.0
        x_train_max: 1.0
 In [7]: x_train[0].shape
 Out[7]: (28, 28)
 In [8]: # Unique values in target variable.
         print(np.unique(y_train))
        [0 1 2 3 4 5 6 7 8 9]
 In [9]: from matplotlib import colormaps
In [10]: # plt.rcParams is a dictionary-like object in Matplotlib that stores the default
         # configuration parameters for the Matplotlib library. It contains various
         # settings related to the appearance and behavior of plots.
         # The colormap is a dictionary which maps numbers to colors.
         plt.rcParams['image.cmap']
Out[10]: 'viridis'
In [11]: # Get the default colormap
         default_cmap = colormaps[plt.rcParams['image.cmap']]
         default_cmap
Out[11]: viridis
          under
                                          bad
                                                                          over
```

```
In [12]: # plt.imshow(X, cmap=None)

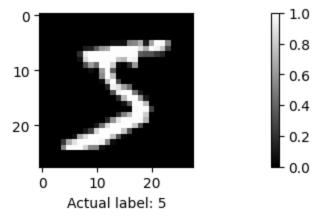
# X is a multidimensional array representing image data.

# When image has shape (M,N,3) or (M,N,4), the values in image are interpreted
# as RGB or RGBA values. In this case the cmap is ignored.
# cmap : str or ~matplotlib.colors.Colormap, default: image.cmap

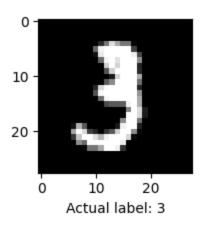
# https://stackoverflow.com/questions/25625952/matplotlib-what-is-the-function-of-cmap-in-imshow

def show_img(idx):
    plt.figure(figsize=(20, 2))
    plt.imshow(x_train[idx, :], cmap='gray')
    plt.xlabel(f'Actual label: {y_train[idx]}')
    plt.colorbar()
    plt.show()
```

## In [13]: show\_img(0)

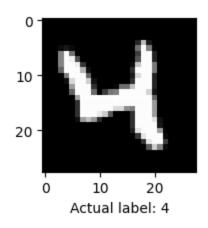


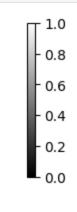
In [14]: show\_img(10)



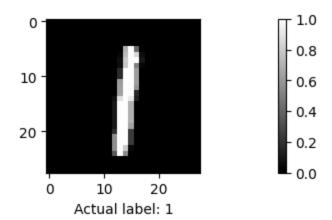


In [15]: show\_img(20)





In [16]: show\_img(40)



## **Building the CNN based model:**

```
# Model Building
In [17]:
         model = Sequential()
         # For Conv2D():
         # kernel_size is the filter size(k). Use odd number of filters in convolution.
         # So that when padding is 'same' the value p comes out as a whole number.
         # padding='valid' by default this means no padding
         # padding='same' means that the padding is automatically calculated.
         # When strides = 1 the output (feature map) has the same spatial dimensions as the input
         # image using the formula p = (k-1)/2.
         # When strides > 1 the output (feature map) has the following spatial dimensions:
         # output_spatial_shape[i] = ceil(input_spatial_shape[i] / strides[i])
         # strides=(1, 1) by default.
         # input_shape=(batchSize, height, width, channels)
         # Specifying the batchSize here in input_shape won't have any effect. The
         # recommended place to specify the batchSize is the model.fit() method.
         model.add(Conv2D(filters=16, kernel_size=(3,3), strides=(1, 1), padding='valid', activation='relu', input_shape=(28)
         # For MaxPooling2D():
```

```
# pool_size=(2, 2) by default
# strides=(2, 2) by default.
# output shape = math.floor((input_shape - pool_size) / strides) + 1
model.add(MaxPooling2D((2,2)))
model.add(Conv2D(filters=16, kernel_size=(3,3), strides=(1, 1), padding='valid', activation='relu'))
model.add(MaxPooling2D((2,2)))
# Flatten layer in Keras converts a multi-dimensional array into a 1D array.
model.add(Flatten())
model.add(Dense(units=16, activation='relu'))
model.add(Dense(units=16, activation='relu'))
model.add(Dense(units=10, activation='softmax'))
# Model compilation
# keras.metrics.SparseCategoricalAccuracy(): Calculates how often predictions
# match integer labels.
# When loss='sparse_categorical_crossentropy', 'accuracy' metric works same
# as keras.metrics.SparseCategoricalAccuracy()
model.compile(optimizer='adam', loss='sparse_categorical_crossentropy',
              metrics=['accuracy'])
# The first dimension in Output Shape tuple is the batch size. None usually
```

```
In [18]: # What does None in the Output Shape column of model.summary() mean?

# The first dimension in Output Shape tuple is the batch size. None usually
# means that the size of that dimension is not fixed and may vary based on the
# input data.

# https://stackoverflow.com/questions/47240348/what-is-the-meaning-of-the-none-in-model-summary-of-keras

# Output shape of the convolution layer = (n-k+2p)/s+1
# Number of paramaters associated with the convolution layer = (k*k+1) * #filters

# Output shape of the max-pooling layer = (n-k)/s+1
model.summary()
```

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 26, 26, 16)	160
<pre>max_pooling2d (MaxPooling2 D)</pre>	(None, 13, 13, 16)	0
conv2d_1 (Conv2D)	(None, 11, 11, 16)	2320
<pre>max_pooling2d_1 (MaxPoolin g2D)</pre>	(None, 5, 5, 16)	0
flatten (Flatten)	(None, 400)	0
dense (Dense)	(None, 16)	6416
dense_1 (Dense)	(None, 16)	272
dense_2 (Dense)	(None, 10)	170

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Total params: 9338 (36.48 KB)
Trainable params: 9338 (36.48 KB)
Non-trainable params: 0 (0.00 Byte)

In [19]: history = model.fit(x\_train, y\_train, epochs=10, validation\_split=0.2)

```
Epoch 1/10
1 accuracy: 0.9592
Epoch 2/10
1 accuracy: 0.9730
Epoch 3/10
1 accuracy: 0.9778
Epoch 4/10
1 accuracy: 0.9799
Epoch 5/10
1 accuracy: 0.9822
Epoch 6/10
1 accuracy: 0.9828
Epoch 7/10
1 accuracy: 0.9834
Epoch 8/10
1 accuracy: 0.9858
Epoch 9/10
1 accuracy: 0.9861
Epoch 10/10
1 accuracy: 0.9852
```

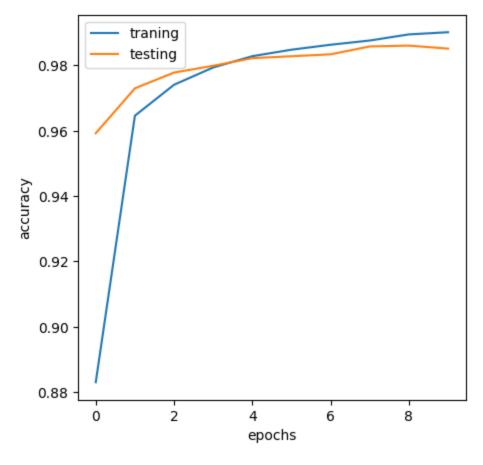
## Evaluating the model:

```
Out[20]: [0.04315326362848282, 0.9861999750137329]
```

```
In [21]: plt.figure(figsize=(5, 5))

plt.plot(history.history['accuracy'])
   plt.plot(history.history['val_accuracy'])
   plt.ylabel('accuracy')
   plt.xlabel('epochs')
   plt.legend(['traning', 'testing'])

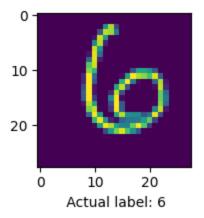
plt.show()
```



```
In [22]: y_pred = model.predict(x_test)
```

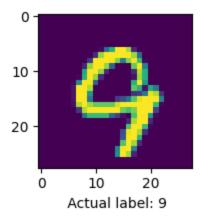
```
313/313 [============ ] - 2s 5ms/step
        y_pred.shape
In [23]:
Out[23]: (10000, 10)
In [24]: # First 10 data points predictions.
         y_pred_class = [np.argmax(element) for element in y_pred]
         y_pred_class[:10]
Out[24]: [7, 2, 1, 0, 4, 1, 4, 9, 5, 9]
In [25]: y_test[:10]
Out[25]: array([7, 2, 1, 0, 4, 1, 4, 9, 5, 9], dtype=uint8)
In [26]: def act_to_pred(val):
           plt.figure(figsize=(20, 2))
           plt.imshow(x_test[val, :])
           plt.xlabel(f' Actual label: {y_test[val]}')
           plt.show()
           print('The predicted image label is:',y_pred_class[val])
        act_to_pred(0)
In [27]:
         0
        10 -
        20 -
            0
                   10
                          20
                Actual label: 7
       The predicted image label is: 7
```

In [28]: act\_to\_pred(100)



The predicted image label is: 6

In [29]: act\_to\_pred(5784)



The predicted image label is: 9

## **Conclusion:**

The CNN based model to predict the hand written digit from image has a **train accuracy of 99.02%**, **validation accuracy of 98.52%** and **test accuracy of 98.62%**.