

Natural Language Understanding, Generation, and Machine Translation

Lecture 7: Sequence-to-sequence Models with Attention

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Based on slides by Frank Keller, Adam Lopez, Rico Sennrich.

Encoding and decoding sequences

RNN for Translation

Translation as String Completion

Encoder-Decoder Architecture

Attention

Attention Distribution over Source Words

Bidirectional RNN

Attention and Alignment

Reading: Sections 7–9 of Neubig (2017).

Agenda for Today

Last week: We saw that we could model a probability distribution over a strings, like $w = w_1 \dots w_{|w|}$:

1. Use the chain rule, $P(w) = \prod_{i=1}^{|w|+1} P(w_i \mid w_1, \dots, w_{i-1})$, and
2. Use *universal function approximators* in the form of neural networks to model the conditional distributions

$$P(w_i \mid w_1, \dots, w_{i-1})$$

The second idea brings many benefits over classic n -gram models. It gives us parameter sharing and representation learning, and it frees us from zero probabilities and independence assumptions.

Today: We will see how to model *conditional probability distributions* like $P(y \mid x)$, where x and y are both sequences of discrete symbols, aka strings.

Encoding and decoding sequences

How would you model translation with n -grams?

Input: Så varför minskar inte vi våra utsläpp?

Output: So why are we not reducing our emissions?

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Let x be the *source* (Swedish) sentence, y be the *target* (English) sentence.

$$x = x_1 \dots x_{|x|}$$

$$y = y_1 \dots y_{|y|}$$

How can we define $P(y \mid x)$?

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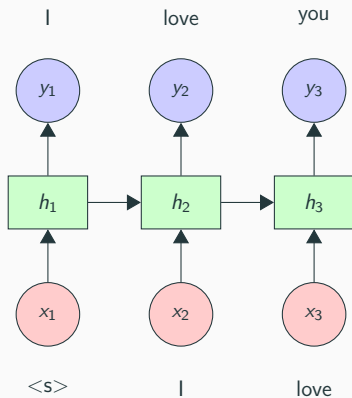
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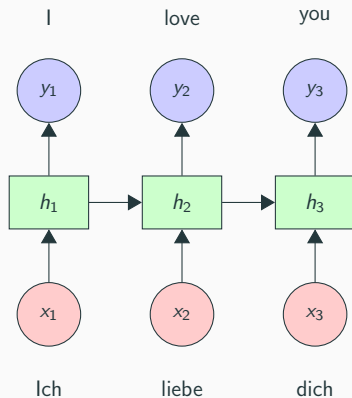
Expand using the chain rule:

$$P(y \mid x) = \prod_{i=1}^{|y|+1} P(y_i \mid y_1, \dots, y_{i-1}, x_1, \dots, x_{|x|})$$

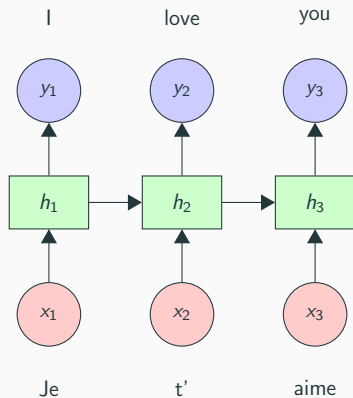
Idea: use RNN language models for translation



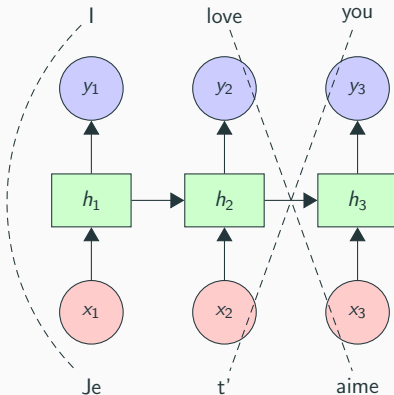
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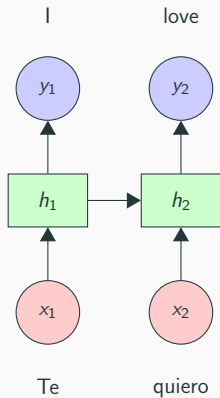


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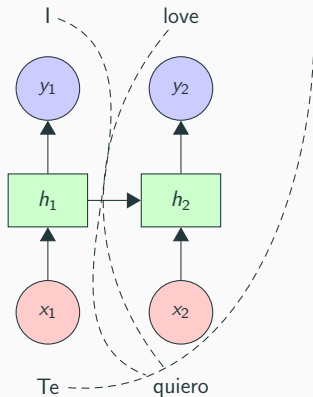


Word order is different!

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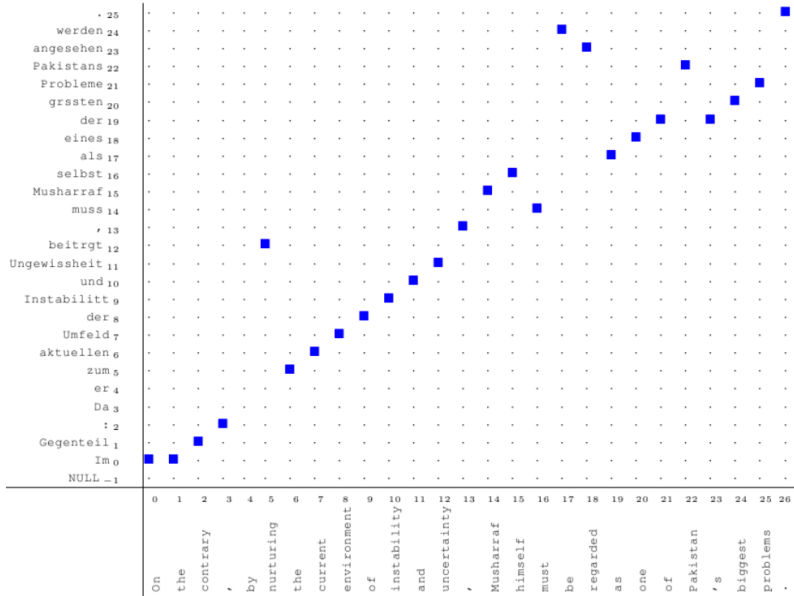


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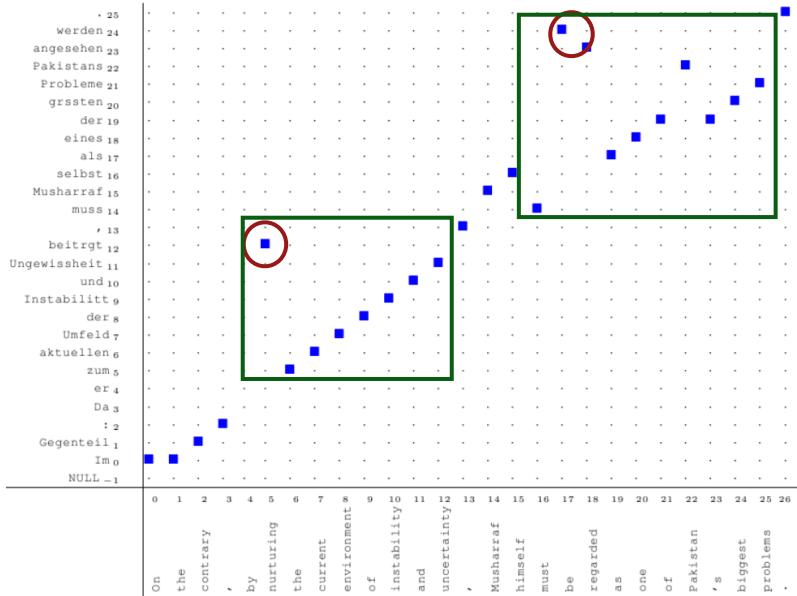


Different number of words!

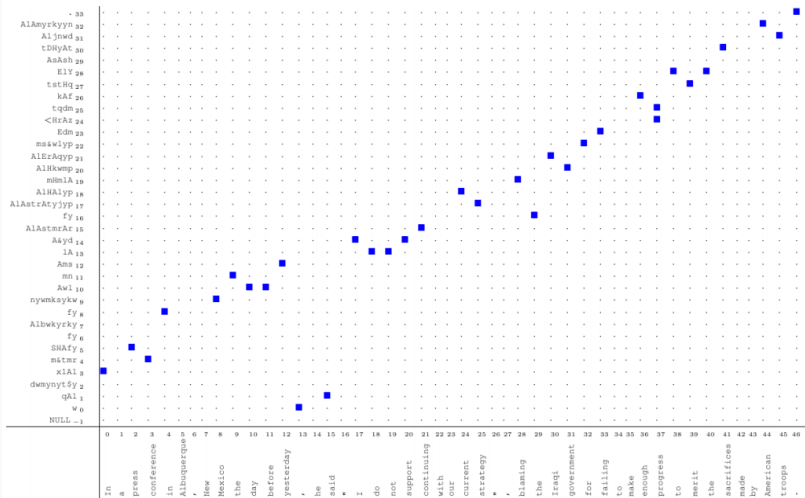
Syntax is very different across languages



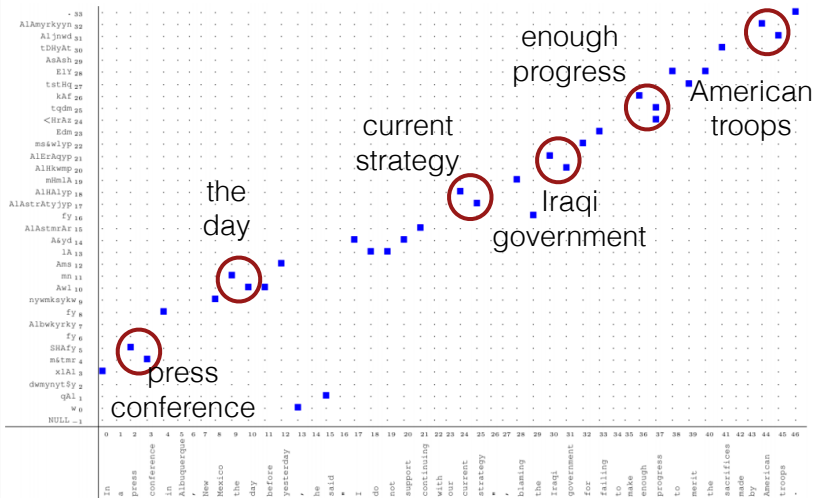
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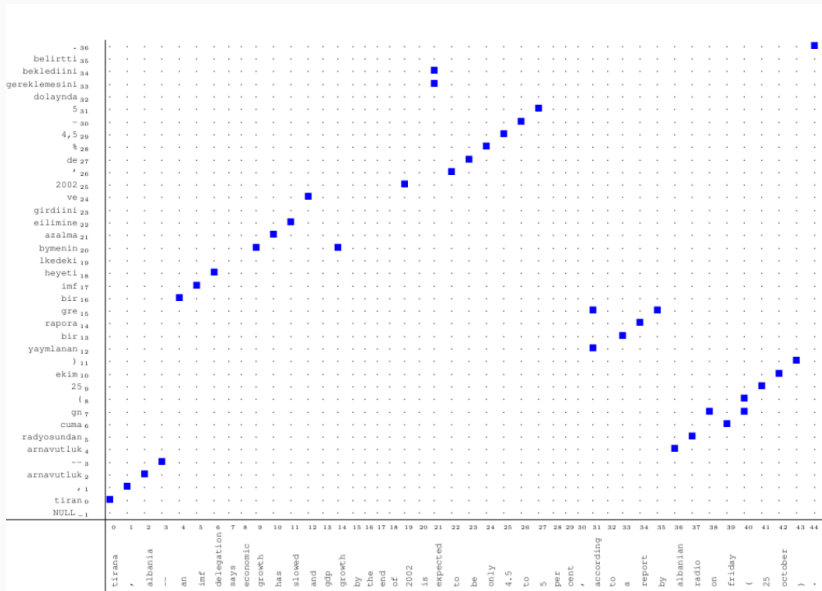
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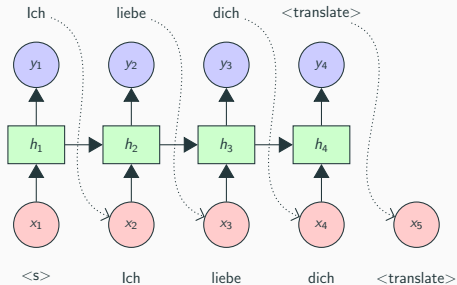


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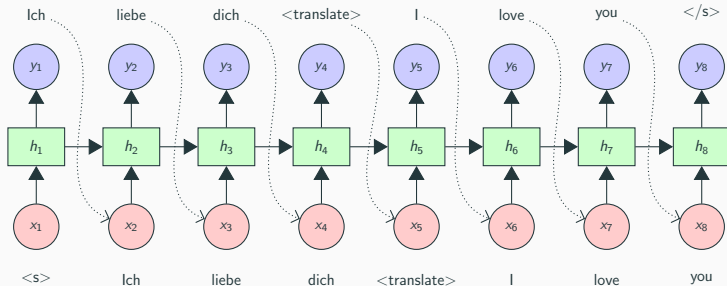
	SUBJECT	VERB	OBJECT
English	I	♥	NY
Welsh	♥	I	NY
Malagasy	♥	NY	I
Japanese	I	NY	♥
Hixkaryana	NY	I	♥
Nadëb	NY	♥	I

Variation in word order is a large area of research in linguistics. In the 1960's, a linguist from Brooklyn, Joseph

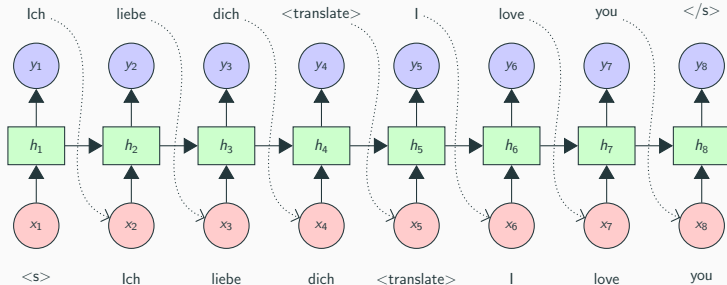
Idea: model translation as string completion



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Does this design make sense? Why or why not?

Translation and Language Modeling are different

Language model:

$$p(y) = \prod_{i=1}^n p(y_i | y_1, \dots, y_{i-1})$$

Translation model:

$$p(y | x) = \prod_{i=1}^n p(y_i | y_1, \dots, y_{i-1}, x_1, \dots, x_{|x|})$$

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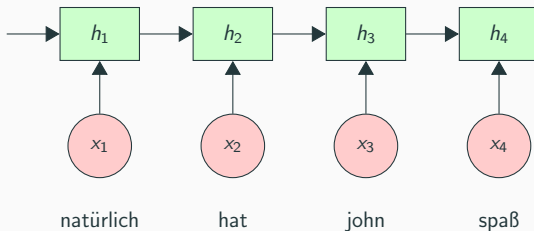
- This is really a model of $P(x, y) = P(x)P(y | x)$.
- But we do not care about $P(x)$!
- The source and target language may have very different vocabulary and morphosyntactic structure.

Insight. We need two RNNs, one for source and one for target.

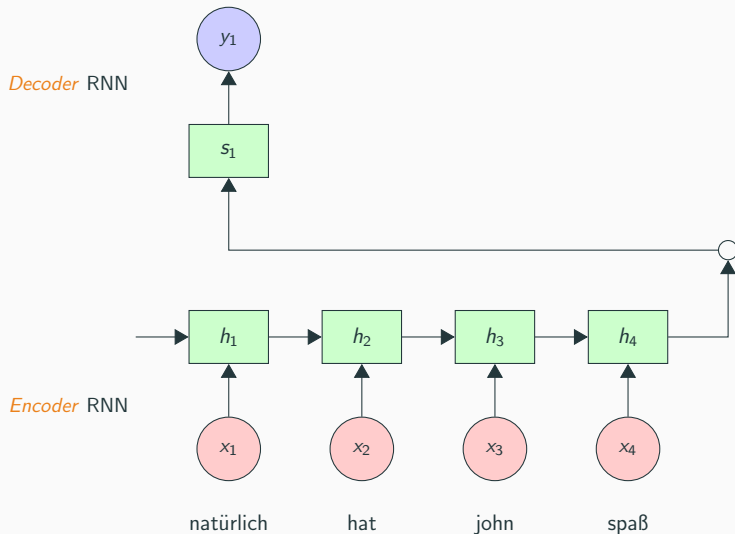
Use one RNN to encode source, another to decode target

Decoder RNN

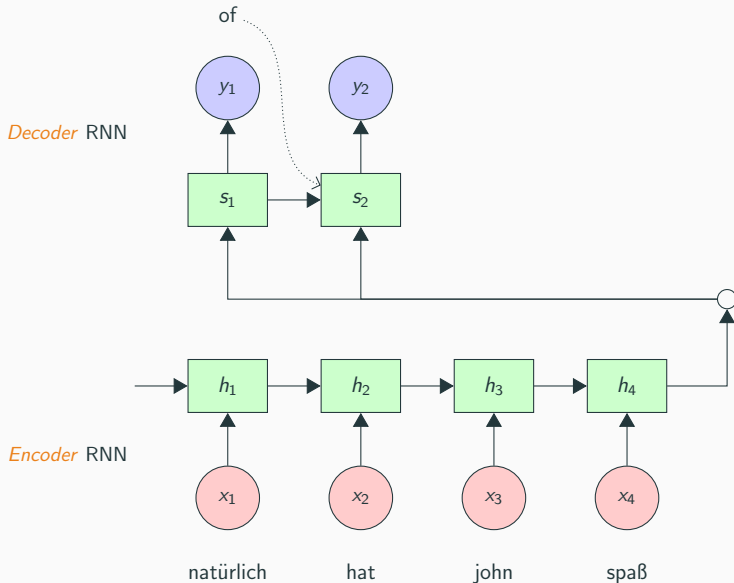
Encoder RNN



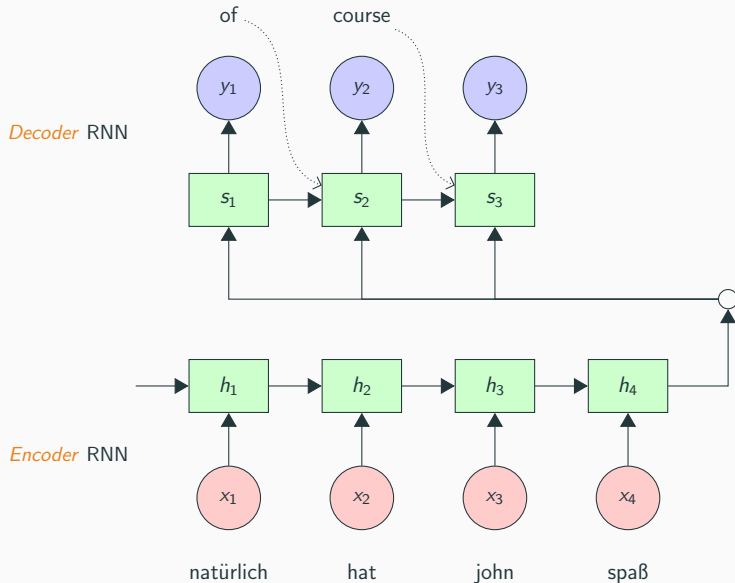
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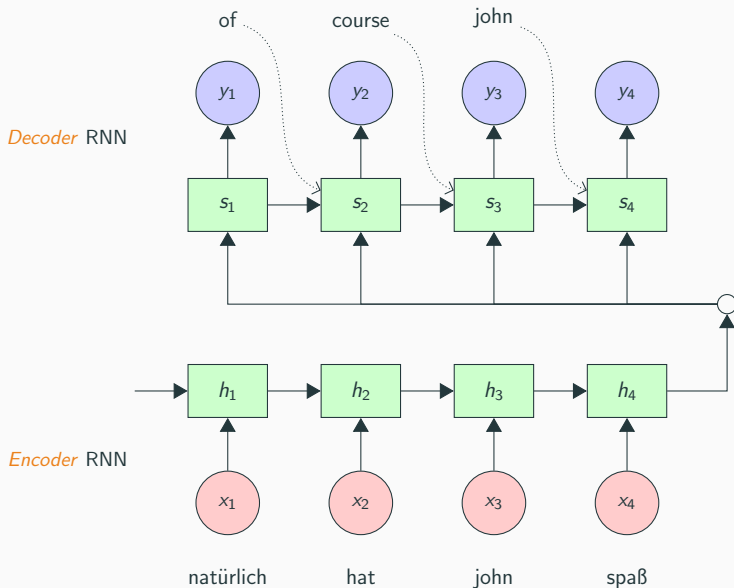
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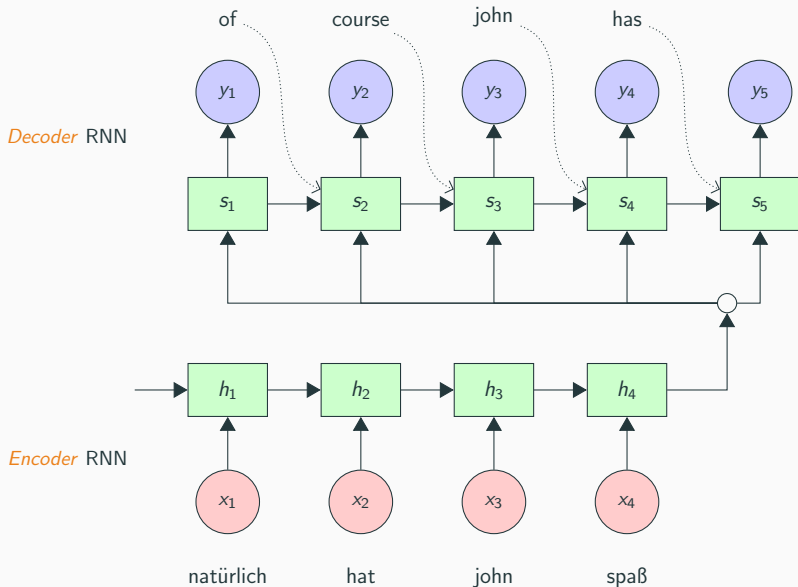
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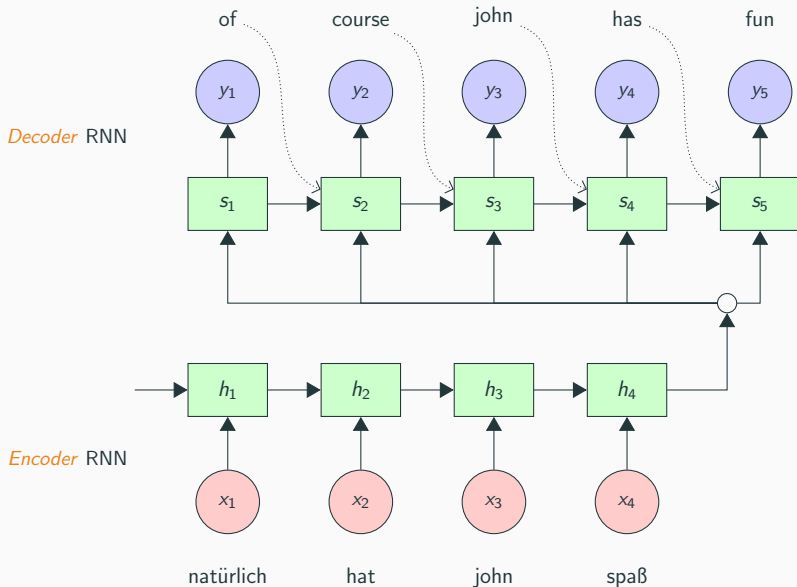
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Formalizing the Encoder-Decoder approach

An RNN is a function of a hidden state and new input vector, returning a hidden state (so any RNN variant can be used).

Encoder:

$$\mathbf{h}_i = \text{RNN}_{\text{enc}}(\mathbf{x}_i, \mathbf{h}_{i-1})$$

Decoder:

$$\mathbf{s}_i = \text{RNN}_{\text{dec}}(\mathbf{y}_{i-1}, \mathbf{s}_{i-1})$$

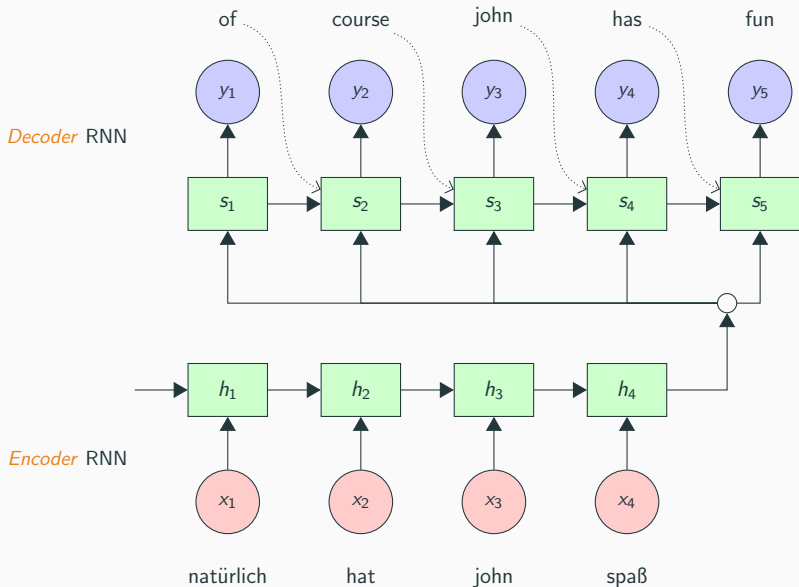
$$P(y_i \mid y_1, \dots, y_{i-1}, x_1, \dots, x_{|x|}) = \text{softmax}(\mathbf{W} \text{concat}(\mathbf{s}_i, \mathbf{h}_{|x|}) + \mathbf{b})$$

Final encoder hidden state $\mathbf{h}_{|x|}$ is *context* for decoder softmax.

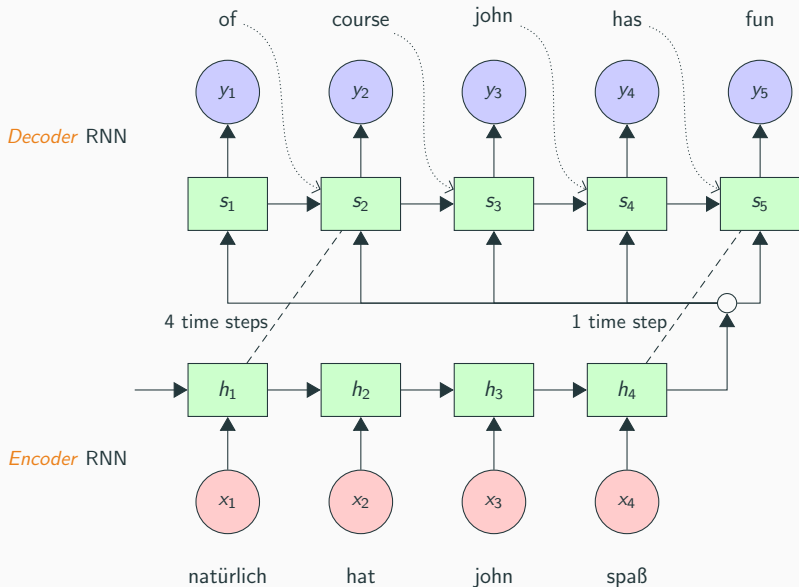
Interpreting the Encoder-Decoder approach

- Given a conditional probability $P(y \mid x)$, we can design two neural architectures: one to *encode* x into a hidden representation, and one to *decode* y from that representation.
- In machine translation, RNNs are a reasonable choice for both encoder and decoder.
- The hidden representation from the encoder is supplied as input to the decoder *at every time step*.
- But the idea is general. Encoder and decoder can be designed to suit the task.
- The encoder RNN does not need to compute $P(x)$. It only needs to compute a representation.

Q: Does this architecture make sense for translation?



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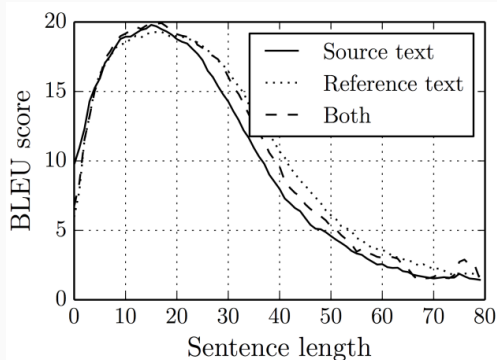


Encoder-decoder models must consider structure of input

- Hidden representation is a *bottleneck*: it must be able to represent a sentence of any length, but its size is fixed.
- RNNs *and their variants* suffer from vanishing gradients.
- So, representation from the encoder also has a *recency bias*: it mostly represents final words of the input sentence.
- Target words whose corresponding source words are at the beginning of the sentence therefore depend on information that originates further away in the computation graph.

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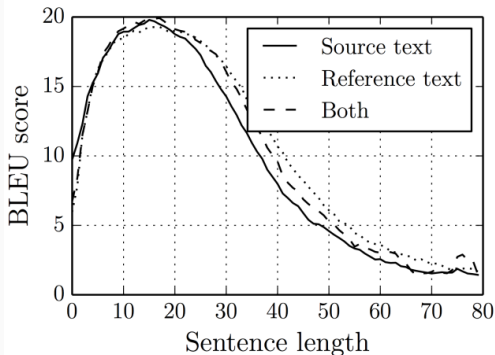
- Empirically, this means the model *forgets* first words of input!
- Reversing input order makes model forget final words of input.



Source: <https://devblogs.nvidia.com/introduction-neural-machine-translation-gpus-part-3/>

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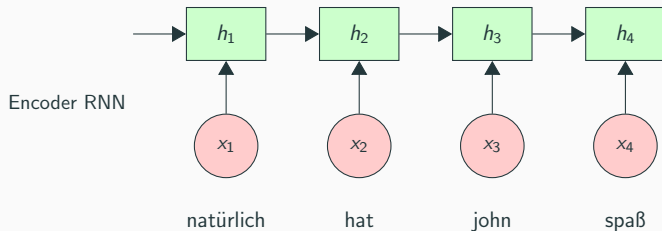
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Q. What can we do?

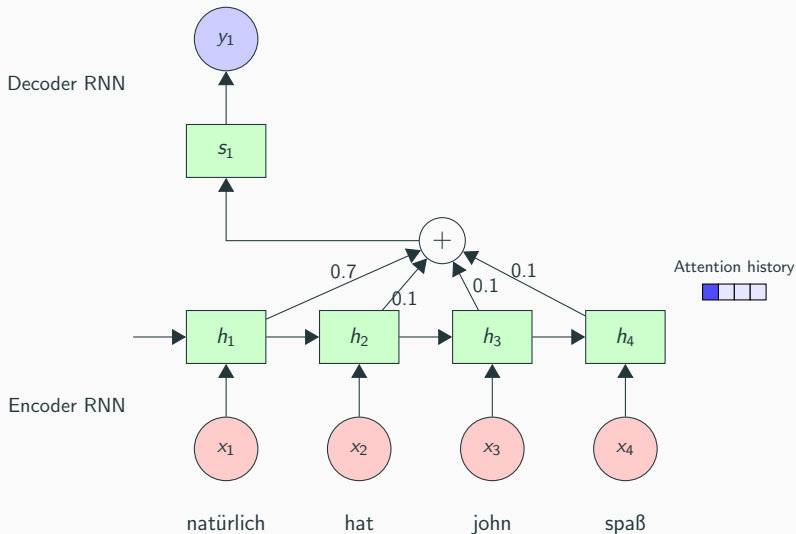
Attention

Decoder attends to relevant input at each step

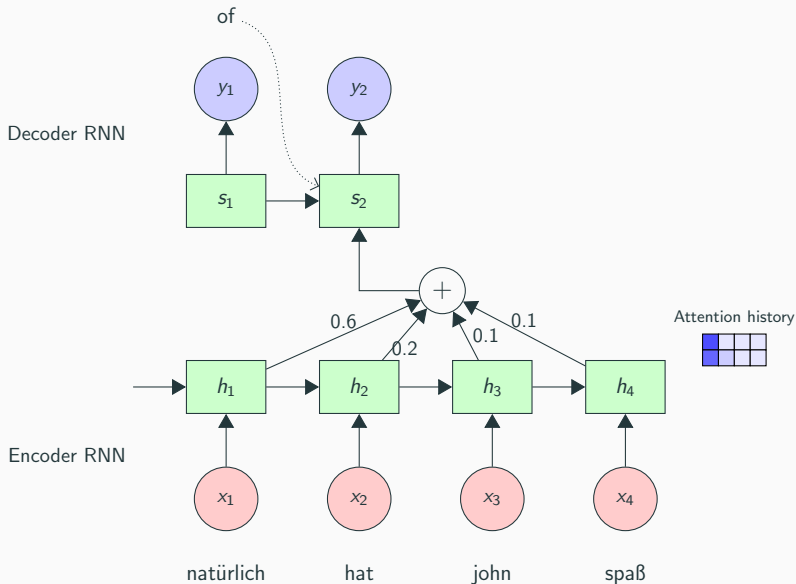
Decoder RNN



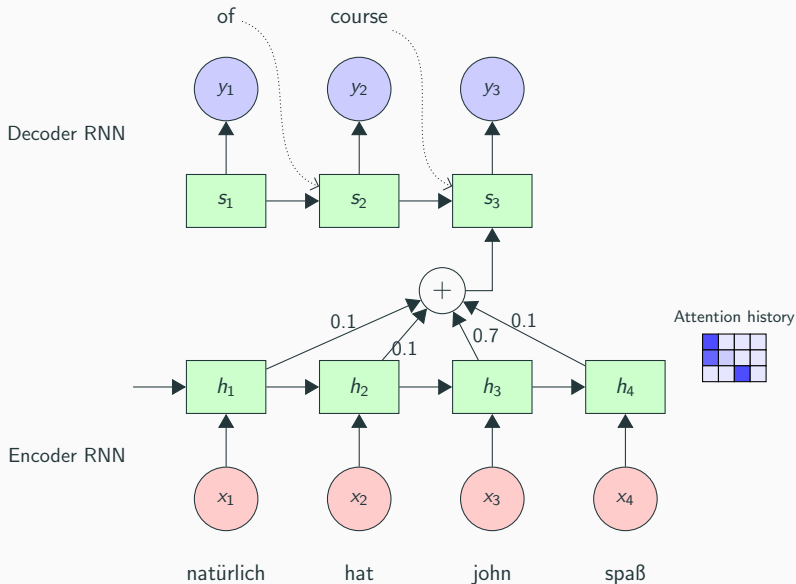
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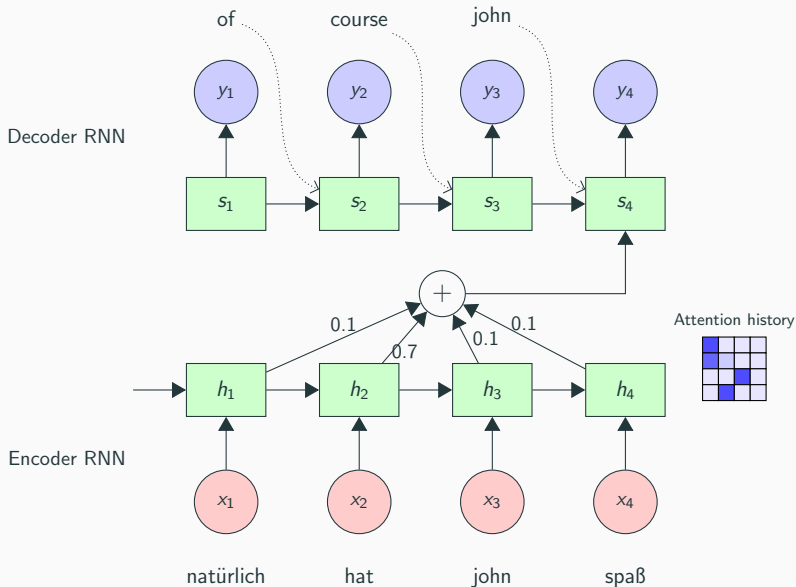
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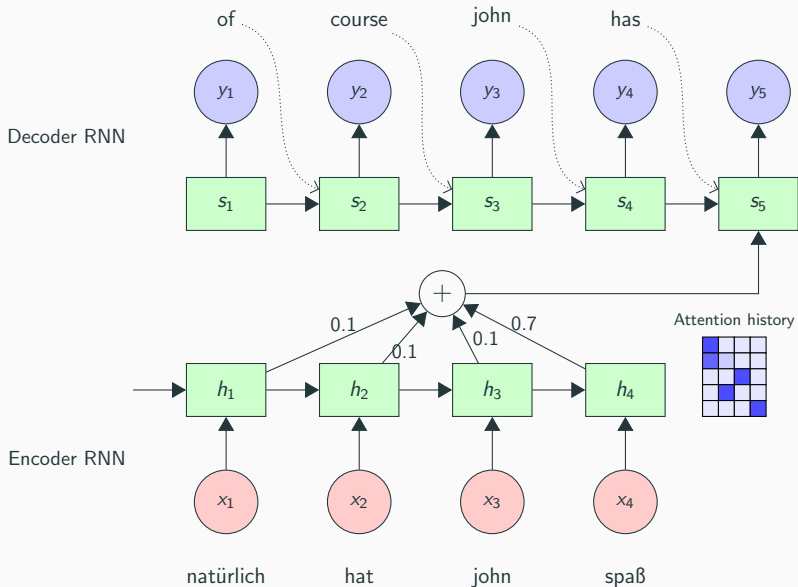
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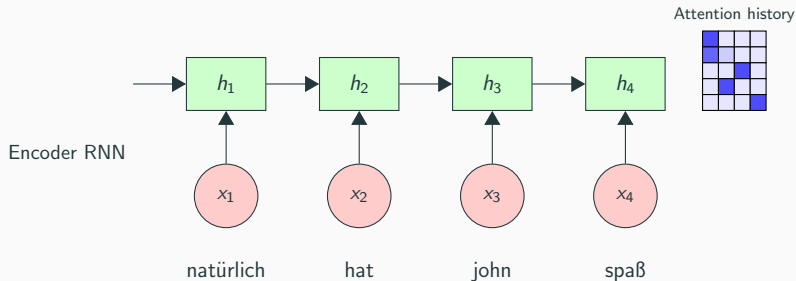
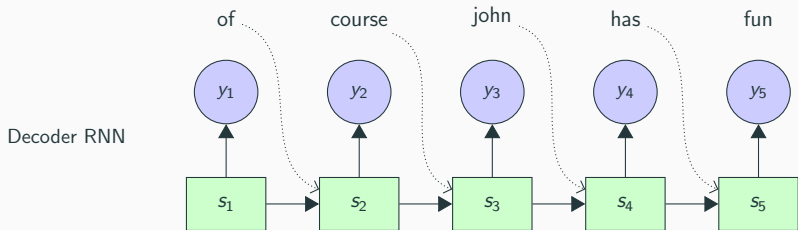
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Attention computes a distribution over source words

In decoder softmax, the *context* is now a *weighted average* of source hidden state vectors:

$$P(y_i \mid y_1, \dots, y_{i-1}, x_1, \dots, x_{|x|}) = \text{softmax}(\mathbf{W} \text{concat}(\mathbf{s}_i, \mathbf{c}_i) + \mathbf{b})$$

$$\mathbf{c}_i = \sum_{j=1}^{|x|} \alpha_{i,j} \mathbf{h}_j$$

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Notice that α_i is a *distribution* over elements of x . But the length of x can vary! So how can we compute it? A simple solution:

$$a_{i,j} = \mathbf{s}_i \cdot \mathbf{h}_j \quad \text{query.key/sum}$$
$$\alpha_i = \text{softmax}(\mathbf{a}_i) \quad (\text{query.keys})$$

Interpreting attention

$$a_{i,j} = \mathbf{s}_i \cdot \mathbf{h}_j$$

$$\alpha_i = \text{softmax}(\mathbf{a}_i)$$

- *Attention* solves a problem: we have a variable length input, and we want to summarize it into a fixed vector, focusing only on the *relevant* parts of the input.
- But relevance depends on current prediction task! So we compute a function of the *output hidden state* (the *query*) and each of the available input vectors (the *keys*).

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- This computation can take many alternative forms:

$$a_{i,j} = \mathbf{s}_i \mathbf{V} \mathbf{h}_j \quad \text{(bilinear model)}$$

$$a_{i,j} = \text{FFN}(\mathbf{s}_i, \mathbf{h}_j) \quad \text{(feedforward neural network)}$$

Aside: RNN hidden states encode words in context

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Q. Can decoders be bidirectional? **A.** No! Right context missing.

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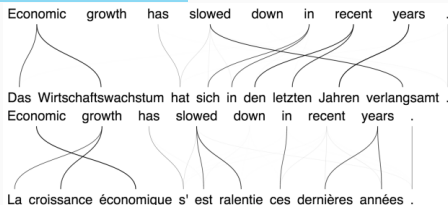
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- Our neural model has no Markov assumptions. *Attention* is *deterministic*, not *stochastic*. It does not represent a probabilistic choice and we do not marginalize it out.
- Practically: attention looks somewhat like alignment, but since information can flow along recurrent connections, it is more difficult to interpret.



Attention is a widespread design pattern



a little girl sitting on a bench holding an umbrella.



a herd of sheep grazing on a lush green hillside.



a close up of a fire hydrant on a sidewalk.



a yellow plate topped with meat and broccoli.



a zebra standing next to a zebra in a dirt field.



a stainless steel oven in a kitchen with wood cabinets.



two birds sitting on top of a tree branch.



an elephant standing next to rock wall.



a man riding a bike down a road next to a body of water.

Encoder-decoder with attention is a common design pattern

We surveyed many applications in the first lecture.

Task	Input type	Output type
Question answering	string	string
Sentiment analysis	string	label
Syntactic parsing	string	tree
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Generation	table	
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Q. How might you use encoder-decoder with attention to model text classification?

Summary

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- A *bidirectional* encoder uses both left and right context.
- A decoder can choose to *attend* to different elements of the encoded input. This shortcut avoids long distances between encoded and decoded elements.
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Next lecture. Transformers. Then we'll have covered most of the key modeling ideas in the course!

References

- Neural Machine Translation and Sequence-to-sequence Models: A Tutorial (2017), Neubig, arXiv 1703.01619.