```
...
In [2]:
         Implementing Autoencoders in Keras
         Autoencoders are similar to dimensionality reduction techniques like Principal Component Analysis (PCA).
         They project the data from a higher dimension to a lower dimension using linear transformation and
         try to preserve the important features of the data while removing the non-essential parts.
         PCA uses linear transformation whereas
         autoencoders use non-linear transformations
         Dataset Used: NotMNIST -images of font glypyhs for the Letters A through J.
         The OS module in Python provides a way of using operating system dependent functionality
         The functions that the OS module provides allows you to interface with the underlying operating system that
         Python is running on - be that Windows, Mac or Linux
         import os
In [3]: #All imports
         A function that opens the gzip file, reads the file using bytestream.read()
         import keras
         from matplotlib import pyplot as plt
         import numpy as np
         import gzip
         %matplotlib inline
         from keras.layers import Input,Conv2D,MaxPooling2D,UpSampling2D
         from keras.models import Model
         from keras.optimizers import RMSprop
         Using TensorFlow backend.
         ...
In [6]:
         Pass the image dimension and the total number of images to this function
         using np.frombuffer(), you convert the string stored in variable buf
         into a NumPy array of type float32
         Reshape the array into a three-dimensional array or tensor
         where the first dimension is number of images,
         and the second and third dimension being the dimension of the image.
         Finally, return the NumPy array data
         def extract_data(filename, num_images):
             with gzip.open(filename) as bytestream:
                 bytestream.read(16)
                 buf = bytestream.read(28 * 28 * num_images)
                 data = np.frombuffer(buf, dtype=np.uint8).astype(np.float32)
data = data.reshape(num_images, 28,28)
                 return data
In [8]: '''
         call the function extract_data() by passing
         the training and testing files along with their corresponding number of images
         train_data = extract_data('C:/MLCourse/notMNIST-to-MNIST-master/train-images-idx3-ubyte.gz', 60000)
         test_data = extract_data('C:/MLCourse/notMNIST-to-MNIST-master/t10k-images-idx3-ubyte.gz', 10000)
In [9]: def extract_labels(filename, num_images):
             with gzip.open(filename) as bytestream:
                 bytestream.read(8)
                 buf = bytestream.read(1 * num_images)
                 labels = np.frombuffer(buf, dtype=np.uint8).astype(np.int64)
                 return labels
In [10]: train_labels = extract_labels('C:/MLCourse/notMNIST-to-MNIST-master/train-labels-idx1-ubyte.gz',60000)
         test_labels = extract_labels('C:/MLCourse/notMNIST-to-MNIST-master/t10k-labels-idx1-ubyte.gz',10000)
```

```
In [11]:

""

analyze how images in the dataset look like and also see the dimension of the images

""

# Shapes of training set
print("Training set (images) shape: {shape}".format(shape=train_data.shape))

Training set (images) shape: (60000, 28, 28)

In [12]:

# Shapes of test set
print("Test set (images) shape: {shape}".format(shape=test_data.shape))

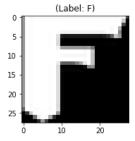
Test set (images) shape: (10000, 28, 28)
```

```
In [14]: plt.figure(figsize=[5,5])
```

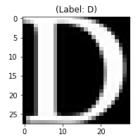
Out[14]: <Figure size 360x360 with 0 Axes>
<Figure size 360x360 with 0 Axes>

```
In [15]: # Display the first image in training data
plt.subplot(121)
curr_img = np.reshape(train_data[0], (28,28))
curr_lbl = train_labels[0]
plt.imshow(curr_img, cmap='gray')
plt.title("(Label: " + str(label_dict[curr_lbl]) + ")")
```

Out[15]: Text(0.5, 1.0, '(Label: F)')



Out[16]: Text(0.5, 1.0, '(Label: D)')



```
In [17]: #Data Preprocessing
         first convert each 28 \times 28 image of train and test set
          into a matrix of size 28 x 28 x 1,
         which you can feed into the network
         train data = train data.reshape(-1, 28,28, 1)
         test_data = test_data.reshape(-1, 28,28, 1)
         train_data.shape, test_data.shape
Out[17]: ((60000, 28, 28, 1), (10000, 28, 28, 1))
In [18]: '''
         make sure to check the data type of the training and testing NumPy arrays,
         it should be in float32 format, if not you will need to convert it into this format
         train_data.dtype, test_data.dtype
Out[18]: (dtype('float32'), dtype('float32'))
          ...
In [19]:
          rescale the training and testing data with the
         maximum pixel value of the training and testing data
         Maximum pixel value was 255
         np.max(train_data), np.max(test_data)
Out[19]: (255.0, 255.0)
In [20]: train_data = train_data / np.max(train_data)
         test_data = test_data / np.max(test_data)
In [21]:
          verify the maximum value of training and testing data
         which should be 1.0 after rescaling it
         np.max(train_data), np.max(test_data)
Out[21]: (1.0, 1.0)
In [22]:
         train the model on 80% of the data and validate it on 20% of the remaining training data
         from sklearn.model_selection import train_test_split
         train X,valid X,train ground,valid ground = train test split(train data,
                                                                        train_data,
                                                                        test size=0.2,
                                                                        random_state=13)
         We don't need training and testing labels.
         Why ??? Because we will pass the training images twice.
          Training images will both act as the input as well as the ground truth
         similar to the labels you have in classification task.
          . . .
 In [ ]: #The Convolutional Autoencoder
          The images are of size 28 \times 28 \times 1 or a 784-dimensional vector
         Convert the image matrix to an array, rescale it between 0 and 1,
         reshape it so that it's of size 28 \times 28 \times 1, and
          feed this as an input to the network
```

```
In [24]: '''
          will use a batch size of 128
          using a higher batch size of 256 or 512 is also preferable
          it all depends on the system you train your model
          It contributes heavily in determining the learning parameters and affects the prediction accuracy.
          train your network for 50 epochs.
          batch\_size = 128
          epochs = 50
          inChannel = 1
          x, y = 28, 28
          input_img = Input(shape = (x, y, inChannel))
 In [ ]: '''
          Autoencoder is divided into two parts: there's an encoder and a decoder
          Encoder
          The first layer will have 32 filters of size 3 x 3, followed by a downsampling (max-pooling) layer,
          The second layer will have 64 filters of size 3 x 3, followed by another downsampling layer,
          The final layer of encoder will have 128 filters of size 3 x 3.
          The first layer will have 128 filters of size 3 \times 3 followed by a upsampling layer,/li>
          The second layer will have 64 filters of size 3 x 3 followed by another upsampling layer,
          The final layer of encoder will have 1 filter of size 3 \times 3.
In [25]: # Defining the autoencoder module
          def autoencoder(input_img):
              #encoder
              \#input = 28 \times 28 \times 1 \text{ (wide and thin)}
              conv1 = Conv2D(32, (3, 3), activation='relu', padding='same')(input_img) #28 x 28 x 32
              pool1 = MaxPooling2D(pool_size=(2, 2))(conv1) #14 \times 14 \times 32
              conv2 = Conv2D(64, (3, 3), activation='relu', padding='same')(pool1) #14 \times 14 \times 64 pool2 = MaxPooling2D(pool_size=(2, 2))(conv2) #7 \times 7 \times 64
              conv3 = Conv2D(128, (3, 3), activation='relu', padding='same')(pool2) #7 x 7 x 128 (small and thick)
              #decoder
              conv4 = Conv2D(128, (3, 3), activation='relu', padding='same')(conv3) #7 x 7 x 128
              up1 = UpSampling2D((2,2))(conv4) # 14 \times 14 \times 128
              conv5 = Conv2D(64, (3, 3), activation='relu', padding='same')(up1) # 14 x 14 x 64
              up2 = UpSampling2D((2,2))(conv5) # 28 \times 28 \times 64
              decoded = Conv2D(1, (3, 3), activation='sigmoid', padding='same')(up2) # 28 x 28 x 1
              return decoded
In [29]: '''
          After the model is created,
          compile it using the optimizer to be RMSProp.
          autoencoder = Model(input_img, autoencoder(input_img))
          autoencoder.compile(loss='mean_squared_error', optimizer = RMSprop())
In [30]:
         #visualize the layers created
          autoencoder.summary()
          Model: "model_3"
         Layer (type)
                                                                   Param #
                                        Output Shape
          ______
          input_2 (InputLayer)
                                        (None, 28, 28, 1)
                                                                   0
          model_2 (Model)
                                        (None, 28, 28, 1)
                                                                   314625
          Total params: 314,625
          Trainable params: 314,625
          Non-trainable params: 0
```

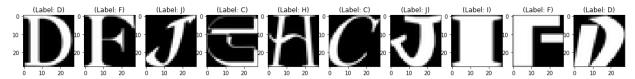
In [31]: autoencoder_train = autoencoder.fit(train_X, train_ground, batch_size=batch_size,epochs=epochs,verbose=1,validation
 _data=(valid_X, valid_ground))

```
Train on 48000 samples, validate on 12000 samples
Epoch 1/50
Epoch 2/50
48000/48000 [=
      Epoch 3/50
Epoch 4/50
48000/48000 [==
     Epoch 5/50
48000/48000 [
      Epoch 6/50
48000/48000
      Epoch 7/50
48000/48000 [
      Epoch 8/50
48000/48000 [=============== ] - 187s 4ms/step - loss: 0.0036 - val_loss: 0.0040
Epoch 9/50
Epoch 10/50
48000/48000 [=
     Epoch 11/50
48000/48000 [
       Epoch 12/50
48000/48000 [
     Epoch 13/50
48000/48000 [=
         Epoch 14/50
48000/48000 [============= ] - 1885 4ms/step - loss: 0.0026 - val loss: 0.0025
Epoch 15/50
Epoch 16/50
48000/48000 [
           ========] - 187s 4ms/step - loss: 0.0024 - val_loss: 0.0026
Epoch 17/50
48000/48000 [
      Epoch 18/50
48000/48000 [
       Epoch 19/50
Epoch 20/50
48000/48000 [============= ] - 214s 4ms/step - loss: 0.0022 - val loss: 0.0023
Epoch 21/50
48000/48000 [
      Epoch 22/50
48000/48000 [=
           ========] - 194s 4ms/step - loss: 0.0021 - val_loss: 0.0020
Epoch 23/50
48000/48000 [
      Epoch 24/50
48000/48000 [
          ========] - 203s 4ms/step - loss: 0.0020 - val_loss: 0.0024
Epoch 25/50
Epoch 26/50
48000/48000 [================ ] - 193s 4ms/step - loss: 0.0019 - val loss: 0.0019
Epoch 27/50
48000/48000 [
            =======] - 192s 4ms/step - loss: 0.0019 - val_loss: 0.0019
Epoch 28/50
48000/48000 [
        Epoch 29/50
      48000/48000 [
Epoch 30/50
Epoch 31/50
48000/48000 [============== ] - 194s 4ms/step - loss: 0.0018 - val_loss: 0.0017
Epoch 32/50
48000/48000 [
     Epoch 33/50
48000/48000 [
           Epoch 34/50
48000/48000 [
      Epoch 35/50
48000/48000 [
      Epoch 36/50
48000/48000 [=============== ] - 209s 4ms/step - loss: 0.0017 - val_loss: 0.0019
Epoch 37/50
48000/48000 [
      Epoch 38/50
48000/48000 [
       Epoch 39/50
48000/48000 [=
      Epoch 40/50
Epoch 41/50
48000/48000 [
       Epoch 42/50
48000/48000 [
       Epoch 43/50
```

```
Epoch 44/50
       48000/48000 [
                      Epoch 45/50
       Epoch 46/50
       48000/48000
                         Epoch 47/50
       Epoch 48/50
       Epoch 49/50
       48000/48000
                       Epoch 50/50
       48000/48000 [=
                  In [32]: '''
       Trained the model on Not-MNIST for 50 epochs,
       Plot the loss plot between training and validation data to visualise the model performance
       loss = autoencoder_train.history['loss']
       val_loss = autoencoder_train.history['val_loss']
       epochs = range(epochs)
       plt.figure()
       plt.plot(epochs, loss, 'bo', label='Training loss')
plt.plot(epochs, val_loss, 'b', label='Validation loss')
       plt.title('Training and validation loss')
       plt.legend()
       plt.show()
                   Training and validation loss
        0.035
                                    Training loss
                                    Validation loss
        0.030
        0.025
        0.020
        0.015
        0.010
        0.005
        0.000
In [ ]:
       The validation loss and the training loss both are in sync.
       It shows that your model is not overfitting:
       the validation loss is decreasing and not increasing, and
       there rarely any gap between training and validation loss.
In [33]:
       to reconstruct the test images using the predict() function of Keras and see
       how well the model is able reconstruct on the test data
       Predicting the trained model on the complete 10,000 test images and plot few of the
       reconstructed images to visualize how well
       model is able to reconstruct the test images
Out[33]: '\nto reconstruct the test images using the predict() function of Keras and see \nhow well the model is able recon
       struct on the test data\n\nPredicting the trained model on the complete 10,000 test images and plot few of the \nr
       econstructed images to visualize how well\nmodel is able to reconstruct the test images\n'
In [34]: pred = autoencoder.predict(test_data)
In [35]: pred.shape
Out[35]: (10000, 28, 28, 1)
```

```
In [36]: plt.figure(figsize=(20, 4))
    print("Test Images")
    for i in range(10):
        plt.subplot(2, 10, i+1)
        plt.imshow(test_data[i, ..., 0], cmap='gray')
        curr_lbl = test_labels[i]
        plt.title("(Label: " + str(label_dict[curr_lbl]) + ")")
    plt.show()
```

Test Images



```
In [37]: plt.figure(figsize=(20, 4))
    print("Reconstruction of Test Images")
    for i in range(10):
        plt.subplot(2, 10, i+1)
        plt.imshow(pred[i, ..., 0], cmap='gray')
    plt.show()
```

Reconstruction of Test Images

