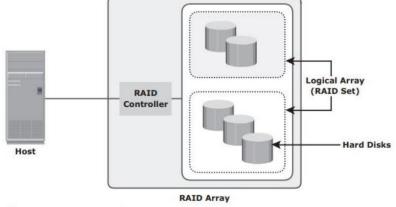
# 1) With the help of neat diagram, explain the components of a RAID array.

**Ans**) A RAID (Redundant Arrays of Independent Disks) combines two or more disk drives in an array into a RAID set or a RAID group.



Components of a RAID array

# 1) **Host:**

- The host is the computer or device that is connected to the RAID array.
- It is responsible for sending data to and receiving data from the array.

# 2) RAID Array:

- The RAID array is the enclosure that contains the RAID controller, Hard disks and Logical array.
- It can be either an external or internal device, depending on the type of RAID array.
- The RAID array must be created and managed by the RAID controller.

# 3) RAID Controller:

- The RAID controller is a hardware device that manages the RAID array.
- It is responsible for organizing and distributing data across the hard disks in the array.
- RAID controller is used for the calculation of parity.
- It provides data redundancy, fault tolerance and performance optimization for the disk array.

# 4) Logical Array:

- The logical array is the virtual disk that is created by the RAID controller and presented to the host.
- It can be partitioned and formatted just like a physical disk.

#### 5) Hard Disks:

- Hard disks are the physical storage devices that make up the RAID array.
- Hard disks must be of the same type, size and speed to be used in a RAID array.
- Hard disks can be replaced or added to the array as needed, without affecting the logical array.

# 2) With a neat diagram, explain different RAID Techniques.

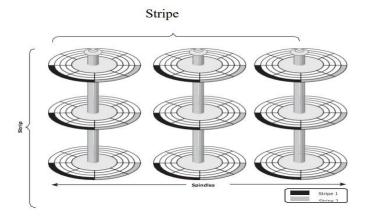
**Ans**) There are three RAID techniques:

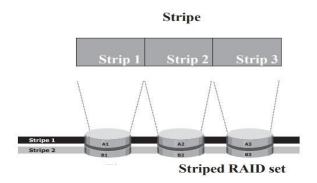
- 1. Striping
- 2. Mirroring
- 3. Parity

# 1) Striping:

- Striping is a technique to spread data across multiple drives to use the drives in parallel.
- All the read-write heads work simultaneously, allowing more data to be processed in a shorter time and increasing performance, compared to reading and writing from a single disk.

- Within each disk in a RAID set, a predefined number of contiguously addressable disk blocks are defined as a strip.
- The set of aligned strips that spans across all the disks within the RAID set is called a stripe.
- Stripe size (also called Stripe depth) describes the number of blocks in a strip.
- Stripe size is the maximum amount of data that can be written to or read from a single disk in the set.
- Stripe width refers to the number of data strips in a stripe.
- Striped RAID does not provide any data protection unless parity or mirroring is used.





#### 2) Mirroring:

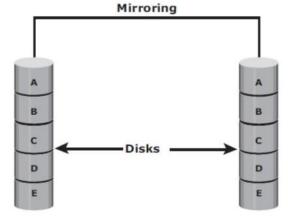
- Mirroring is a technique whereby the same data is stored on two different disk drives, yielding two copies of the data.
- If one of two mirrored disk drives fails, the other drive still has all the data and can continue to work without any interruption.
- When the failed disk is replaced with a new disk, the controller copies the data from the surviving disk of the mirrored pair.
- This activity is transparent to the host.

# Advantages:

- complete data redundancy
- mirroring enables fast recovery from disk failure.
- data protection

# Disadvantages:

- Mirroring involves duplication of data
- Expensive

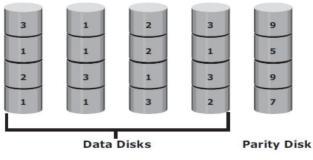


Mirrored disks in an array

#### 3) Parity:

- Parity is a method to protect striped data from disk drive failure without the cost of mirroring.
- An additional disk drive is added to hold parity, a mathematical construct that allows recreation of the missing data.

- Parity is a redundancy technique that ensures protection of data without maintaining a full set of duplicate data.
- Calculation of parity is a function of the RAID controller.
- In the below figure, the first four disks, labelled "Data Disks," contain the data.
- The fifth disk, labelled "Parity Disk," stores the parity information, which, in this case, is the sum of the elements in each row.



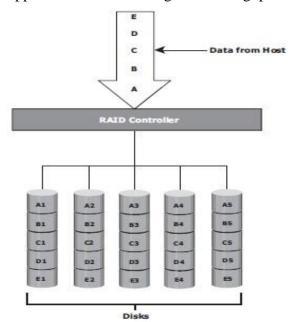
Parity RAID

# 3) Illustrate the following RAID levels:

# i) RAID 0

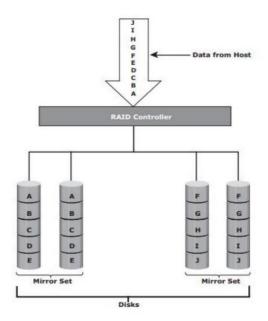
# Ans)

- RAID 0 configuration uses data striping techniques, where data is striped across all the disks within a RAID set.
- To read data, all the strips are put back together by the controller.
- Figure shows RAID 0 in an array in which data is striped across five disks.
- When the number of drives in the RAID set increases, performance improved.
- RAID 0 is a good option for applications that need high I/O throughput.



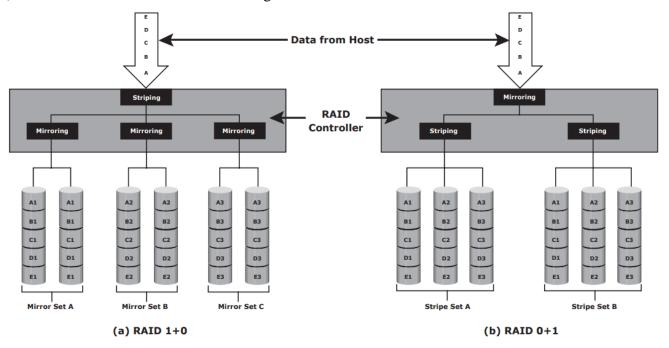
#### ii) RAID 1

- RAID 1 is based on the mirroring technique.
- Here, data is mirrored to provide fault tolerance.
- RAID 1 set consists of two disk drives and every write is written to both disks.
- The mirroring is transparent to the host.
- During disk failure, the impact on data recovery in RAID 1 is the least among all RAID implementations.
- This is because the RAID controller uses the mirror drive for data recovery.
- RAID 1 is suitable for applications that require high availability and cost is no constraint.



# iii) Nested RAID

**Ans**) RAID 1+0 and RAID 0+1 combine together to form a Nested RAID.



# **RAID 1+0**

- RAID 1+0 is also known as RAID 10 (Ten) or RAID 1/0.
- RAID 1+0 is also called striped mirror.
- The basic element of RAID 1+0 is a mirrored pair, which means that data is first mirrored and then both copies of the data are striped across multiple disk drive pairs in a RAID set.
- When replacing a failed drive, only the mirror is rebuilt.
- Data from the surviving disk is copied to the replacement disk.
- Consider an example of six disks forming a RAID 1+0.
- These six disks are paired into three sets of two disks.
- Data is then striped across all the three mirrored sets to form RAID 0.
- Following are the steps performed in RAID 1+0:

Drives 1+2 = RAID 1 (Mirror Set A)

Drives 3+4 = RAID 1 (Mirror Set B)

Drives 5+6 = RAID 1 (Mirror Set C)

#### **RAID 0+1:**

- RAID 0+1 is also called a mirrored stripe.
- The process of striping data across disk drives is performed initially, and then the entire stripe is mirrored.
- In this configuration if one drive fails, then the entire stripe is faulted.
- Six disks are paired into two sets of three disks each.
- Each of two sets, act as a RAID 0 set and then these two sets are mirrored to form RAID 1.
- Following are the steps performed in RAID 0+1

Drives  $1 + 2 + 3 = RAID \ 0$  (Stripe Set A)

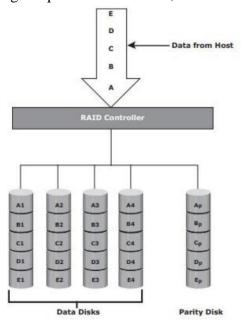
Drives 4 + 5 + 6 = RAID 0 (Stripe Set B)

Now, these two stripe sets are mirrored.

# iv) RAID 3

#### Ans)

- RAID 3 stripes data for high performance and uses parity for improved fault tolerance.
- Parity information is stored on a dedicated drive so that data can be reconstructed if a drive fails.
- For example, of five disks, four are used for data and one is used for parity.
- RAID 3 always reads and writes complete stripes of data across all disks because the drives operate in parallel.
- There are no partial writes that update one out of many strips in a stripe.
- RAID 3 is used in applications that involve large sequential data access, such as video streaming.



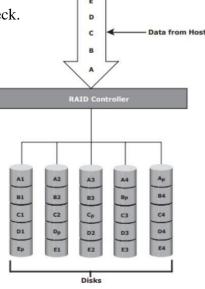
# v) RAID 4

- RAID 4 stripes data for high performance and uses parity for improved fault tolerance.
- Data is striped across all disks except the parity disk in the array.
- Parity information is stored on a dedicated disk so that the data can be rebuilt if a drive fails.
- Striping is done at the block level.
- Unlike RAID 3, data disks in RAID 4 can be accessed independently so that specific data elements can be read or written on single disk without read or write of an entire stripe.
- RAID 4 provides good read throughput and reasonable write throughput

# vi) RAID 5

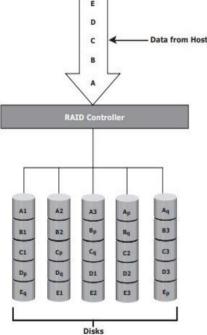
#### Ans)

- RAID 5 is a versatile RAID implementation.
- It is similar to RAID 4 because it uses striping.
- The drives (strips) are also independently accessible.
- The difference between RAID 4 and RAID 5 is the parity location.
- In RAID 4, parity is written to a dedicated drive, creating a write bottleneck for the parity disk.
- In RAID 5, parity is distributed across all disks.
- The distribution of parity in RAID 5 overcomes the Write bottleneck.



# vii) RAID 6

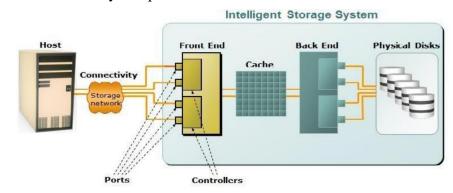
- RAID 6 includes a second parity element to enable survival in the event of the failure of two disks in a RAID group.
- RAID 6 distributes the parity across all the disks.
- The write penalty in RAID 6 is more than that in RAID 5.
- Therefore, RAID 5 writes perform better than RAID 6.
- The rebuild operation in RAID 6 may take longer than that in RAID 5 due to the presence of two parity sets.



# 4) With a neat block diagram, describe the components of Intelligent storage system.

**Ans**) An intelligent storage system consists of four key components:

- 1) Front End
- 2) Cache
- 3) Back end
- 4) Physical Disks



# 1) Front End:

- The front end provides the interface between the storage system and the host.
- It consists of two components:
  - i) Front-End Ports
  - ii) Front-End Controllers.
- A front end has redundant controllers for high availability, and each controller contains multiple frontend ports that enable large numbers of hosts to connect to the intelligent storage system.
- Each front-end controller has processing logic that executes the appropriate transport protocol, such as Fibre Channel, iSCSI, FICON, or FCoE for storage connections.
- Front-end controllers route data to and from cache via the internal data bus.
- When the cache receives the write data, the controller sends an acknowledgment message back to the host.

# 2) <u>Cache:</u>

- Cache is semiconductor memory where data is placed temporarily to reduce the time required to service I/O requests from the host.
- Cache improves storage system performance.
- Rotating disks are the slowest component of an intelligent storage system.
- Accessing data from rotating disks usually takes several millisecond because of seek time and rotational latency.
- Accessing data from cache is fast and typically takes less than a millisecond.
- On intelligent arrays, write data is first placed in cache and then written to disk.

#### 3) Back end:

- The back end provides an interface between cache and the physical disks.
- It consists of two components:
  - i) Back-end ports
  - ii) Back-end controllers.
- The back end controls data transfers between cache and the physical disks.
- From cache, data is sent to the back end and then routed to the destination disk.
- Physical disks are connected to ports on the back end.
- The back end controller communicates with the disks when performing reads and writes.
- It also provides additional, but limited, temporary data storage.

# 4) Physical Disks:

- A physical disk stores data persistently.
- Physical disks are connected to the back-end storage controller.
- Modern intelligent storage systems provide support to a variety of disk drives with different speeds and types, such as FC, SATA, SAS and flash drives.
- They also support the use of a mix of flash, FC, or SATA within the same array.

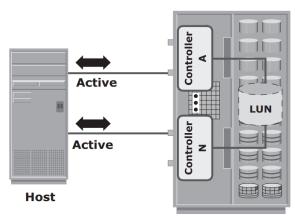
# 5) Explain types of Intelligent System.

**Ans**) Intelligent storage systems are of two types:

- 1) High-end storage systems
- 2) Midrange storage systems

# 1) High-end storage system:

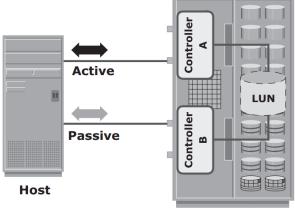
- High-end storage systems are referred to as active-active arrays.
- They are generally used for large enterprise applications.
- These systems are designed with a large number of controllers and cache memory.
- They provide the following capabilities:
  - ► Large storage capacity
  - ➤ Huge cache to service host I/Os
  - > Fault tolerance architecture
  - ➤ Multiple front-end ports and support to interface protocols
  - ➤ High scalability
  - ➤ Ability to handle large amounts of concurrent I/Os
  - Designed for large enterprises
  - ➤ Connectivity to mainframe computers and open systems hosts



**Storage Array** 

# 2) Midrange Storage Systems:

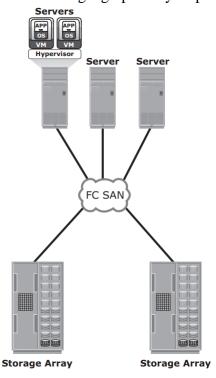
- Midrange storage systems are also referred to as active-passive arrays.
- They are best suited for small-sized and medium-sized enterprise applications.
- They also provide optimal storage solutions at a lower cost.
- Midrange array have two controllers, each with cache, RAID controllers and disk drive interfaces.
- There are less scalable as compared to high-end array.
- They ensure high redundancy and high performance for applications with predictable workloads.



**Storage Array** 

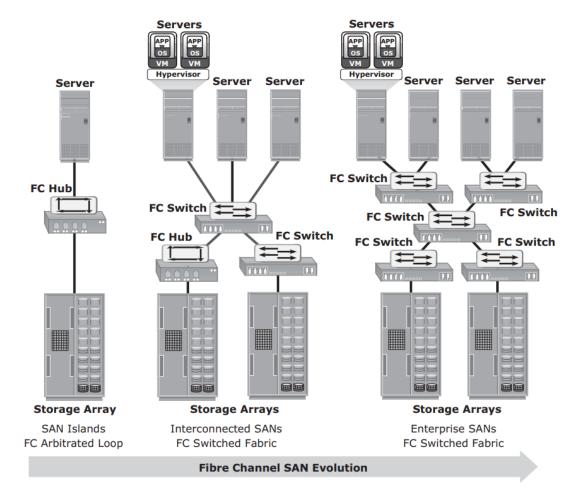
# 6) With a neat diagram, explain San and it's Evolution.

- A SAN carries data between servers (or hosts) and storage devices through Fibre Channel network.
- A SAN enables storage consolidation and enables storage to be shared across multiple servers.
- This improves the utilization of storage resources compared to direct-attached storage architecture.
- It reduces the total amount of storage an organization needs to purchase and manage.
- With consolidation, storage management becomes centralized and less complex, which further reduces the cost of managing information.
- SAN also enables organizations to connect geographically dispersed servers and storage.



FC SAN implementation

- In its earliest implementation, the FC SAN was a simple grouping of hosts and storage devices connected to a network using an FC hub as a connectivity device.
- This configuration of an FC SAN is known as a Fibre Channel Arbitrated Loop (FC-AL).
- Use of hubs resulted in isolated FC-AL SAN islands.
- This is because the hubs provide limited connectivity and bandwidth.
- The inherent limitations associated with hubs gave way to high-performance FC switches.
- Use of switches in SAN improved connectivity and performance and enabled FC SANs to be highly scalable.
- This enhanced data accessibility to applications across the enterprise.
- Now, FC-AL has been almost abandoned for FC SANs due to its limitations but still survives as a backend connectivity option to disk drives.



FC SAN evolution

# 7) Explain Components of FC San.

**Ans**) FC SAN infrastructure consists of node ports, cables, connectors and interconnecting devices, along with SAN management software.

# 1) Node Ports:

- In a Fibre Channel network, the end devices, such as hosts, storage arrays and tape libraries, are all referred to as nodes.
- Each node is a source or destination of information.
- Each node requires one or more ports to provide a physical interface for communicating with other nodes.
- Examples of nodes: Hosts, storage and tape library
- Ports are available on:
  - ➤ HBA in host
  - > Front-end adapters in storage
  - Each port has transmit (Tx) link and receive (Rx) link.

# Port 0 Rx Link Node

# 2) Cables:

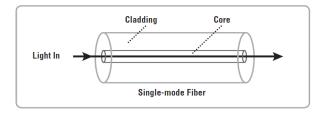
SAN implementation uses:

- Copper cables for short distance
- Optical fiber cables for long distance

Two types of optical cables are:

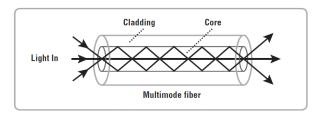
# 1) Single-mode:

- Can carry single beams of light
- Distance up to 10 KM



## 2) Multi-mode:

- Can carry multiple beams of light simultaneously
- Distance up to 500 meters



# 3) Connectors

A connector is attached at the end of a cable to enable swift connection and disconnection of the cable to and from a port.

#### 1) Node Connectors:

- SC Duplex Connectors
- LC Duplex Connectors

# 2) Patch panel Connectors

• ST Simplex Connectors

# 4) Interconnect Devices:

Hubs, switches and directors are the interconnect devices commonly used in FC SAN.

#### i) Hubs:

- Hubs are used as communication devices in FC-AL implementations.
- Hubs physically connect nodes in a logical loop or a physical star topology.
- All the nodes must share the loop because data travels through all the connection points.

#### ii) Switches:

- Switches are more intelligent than hubs and directly route data from one physical port to another.
- Nodes do not share the bandwidth.
- Instead, each node has a dedicated communication path.

#### iii) Directors:

• Directors are high-end switches with a higher port count and better fault-tolerance capabilities.

# 5) SAN Management Software:

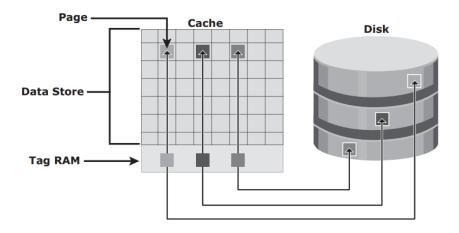
- SAN management software manages the interfaces between hosts, interconnect devices and storage arrays.
- The software provides a view of the SAN environment.
- The software also enables management of various resources from one central console.
- It provides key management functions, including mapping of storage devices, switches and servers.
- This helps in monitoring and generating alerts for discovered devices and zoning.

# 8) With a neat diagram, explain the structure of cache with read and write operations.

**Ans**) Cache is semiconductor memory where data is placed temporarily to reduce the time required to service I/O requests from the host.

#### **Structure of Cache:**

- Cache is organized into pages, which is the smallest unit of cache allocation.
- The size of a cache page is configured according to the application I/O size.
- Cache consists of the data store and tag RAM.
- The data store holds the data.
- The tag RAM tracks the location of the data in the data store and in the disk.

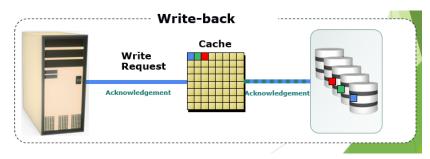


# **Write Operation:**

A write operation with cache is implemented in the following ways:

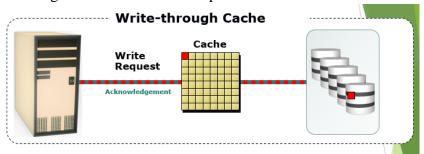
# 1) Write-back cache:

- Data is placed in cache and an acknowledgment is sent to the host immediately.
- Later, data from several writes are committed to the disk.
- Write response times are much faster because the write operations are isolated from the mechanical delays of the disk.
- However, uncommitted data is at risk of loss if cache failures occur.



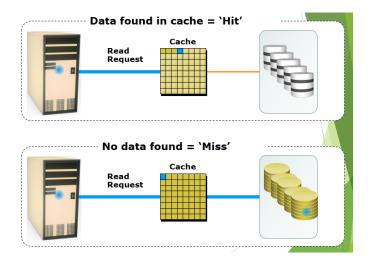
# 2) Write-through cache:

- Data is placed in the cache and immediately written to the disk and an acknowledgment is sent to the host.
- Because the data is committed to disk as it arrives, the risks of data loss are low.
- Write-response time is longer because of the disk operations.



#### **Read Operation:**

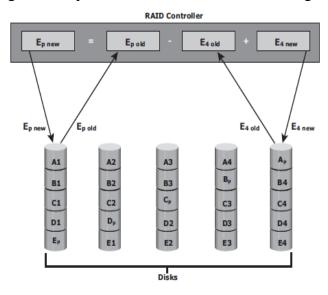
- When a host issues a read request, the storage controller reads the tag RAM to determine whether the required data is available in cache.
- If the requested data is found in the cache, it is called a read cache hit or read hit and data is sent directly to the host, without any disk operation.
- If the requested data is not found in cache, it is called a cache miss and the data must be read from the disk.
- The back end accesses the appropriate disk and retrieves the requested data.
- Data is then placed in cache and finally sent to the host through the front end.
- Cache misses increase the I/O response time.



# 9) Discuss RAID impact on disk performance.

#### Ans)

- In both mirrored and parity RAID configurations, every write operation translates into more I/O overhead for the disks, which is referred to as a write penalty.
- In a RAID 1 implementation, every write operation must be performed on two disks configured as a mirrored pair.
- In a RAID 5 implementation, a write operation may manifest as four I/O operations.
- In RAID 5 configuration, when performing I/Os to a disk, the controller has to read, recalculate and write a parity segment for every data write operation.
- Figure illustrates a single write operation on RAID 5 that contains a group of five disks.



• The new parity  $(E_{p \text{ new}})$  is computed as follows:

$$E_{p \text{ new}} = E_{p \text{ old}} - E_{4 \text{ old}} + E_{4 \text{ new}} \text{ (XOR operations)}$$

- In RAID 5, for every write operation the controller performs two disk reads and two disk writes and the write penalty is 4.
- In RAID 6, the controller performs six I/O operations for each write I/O, and the write penalty is 6.

# 10) Explain cache management and data protection methods.

#### Ans)

# **Cache Management:**

- Cache is a finite and expensive resource that needs proper management.
- When all cache pages are filled, some pages have to be freed up to accommodate new data and avoid performance degradation.

- Cache management algorithms are:
  - ➤ Least Recently Used (LRU)
  - ➤ Most Recently Used (MRU)

# **Cache Management using Watermarking:**

- Flushing is the process that commits data from cache to the disk.
- On the basis of the I/O access rate and pattern, high and low levels called watermarks are set in cache to manage the flushing process.

**High watermark (HWM)**: It is the cache utilization level at which the storage system starts high-speed flushing of cache data.

Low watermark (LWM): It is the point at which the storage system stops flushing data to the disks.

Watermark manages peak I/O requests "bursts" through three important techniques - Idle flushing, High Watermark flushing and Forced flushing.

# **Cache Data Protection:**

Protecting cache data against failure can be done in two ways:

# 1) Cache mirroring:

Each write to the cache is held in two different memory locations on two independent memory cards.

# 2) Cache vaulting:

Cache is exposed to the risk of uncommitted data loss due to power failure.

In the event of power failure, uncommitted data is dumped to a dedicated set of drives called vault drives.

# **Problems:**

RAID	Write Penalty
0	1
1	2
3	4
5	4
6	6
DP	2
10	2

(You need to know these above values for the calculation of Disk Load).

- 1) Consider an application that generates 7,200 IOPS, with 60 percent of them being reads.
- i) Show the disk load in RAID 1, RAID 5 and RAID 6.
- ii) If a HDD with the specification of maximum 180 IOPS for the application needs to be used, show the number of disks required to meet the workload for RAID 1, RAID 5 and RAID 6.

# Ans) i)

Disk Load for RAID 
$$1 = 7200*0.6 + (2*0.4*7200) = 10080 \text{ IOPS}$$

Disk Load for RAID 
$$5 = 7200*0.6 + (4*0.4*7200) = 15840 \text{ IOPS}$$

Disk Load for RAID 
$$6 = 7200*0.6 + (6*0.4*7200) = 21600 \text{ IOPS}$$

**ii)** Number of drives required to support the application in different RAID environments, drives with a rating of 180 IOPS.

```
For RAID 1 = 10080 /180 = 56 disks
For RAID 5 = 15840 /180 = 88 disks
For RAID 6 = 21600 /180 = 120 disks
```

- 2) Consider an application that generates 11,200 IOPS, with 60 percent of them being reads.
- i) Show the disk load in RAID 1, RAID 5 and RAID 6.
- ii) If a HDD with the specification of maximum 130 IOPS for the application needs to be used, show the number of disks required to meet the workload for RAID 1, RAID 5 and RAID 6.

# Ans) i)

```
Disk Load for RAID 1 = 11200*0.6 + (2*0.4*11200) = 15680 IOPS Disk Load for RAID 5 = 11200*0.6 + (4*0.4*11200) = 24640 IOPS Disk Load for RAID 6 = 11200*0.6 + (6*0.4*11200) = 33600 IOPS
```

**ii)** Number of drives required to support the application in different RAID environments, drives with a rating of 130 IOPS.

```
For RAID 1 = 15680 /130 = 121 disks
For RAID 5 = 24640 /130 = 190 disks
For RAID 6 = 33600 /130 = 258 disks
```

- 3) Consider an application that generates 5,200 IOPS, with 60 percent of them being reads.
- i) Show the disk load in RAID 1, RAID 5 and RAID 6.
- ii) If a HDD with the specification of maximum 180 IOPS for the application needs to be used, show the number of disks required to meet the workload for RAID 1, RAID 5 and RAID 6.

# Ans) i)

```
Disk Load for RAID 1 = 5200*0.6 + (2*0.4*5200) = 7280 IOPS
Disk Load for RAID 5 = 5200*0.6 + (4*0.4*5200) = 11440 IOPS
Disk Load for RAID 6 = 5200*0.6 + (6*0.4*5200) = 15600 IOPS
```

**ii)** Number of drives required to support the application in different RAID environments, drives with a rating of 180 IOPS.

```
For RAID 1 = 7280 /180 = 40 disks
For RAID 5 = 11440 /180 = 64 disks
For RAID 6 = 15600 /180 = 87 disks
```